

**Review Article** 

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# Robotic Surgery for Rectal Cancer: An Update in 2015

During the last decade, robotic surgery for rectal cancer has rapidly gained acceptance Jung Myun Kwak, MD, PhD among colorectal surgeons worldwide, with well-established safety and feasibility. The lower Seon Hahn Kim, MD, PhD conversion rate and better surgical specimen quality of robotic compared with laparoscopic surgery potentially improves survival. Earlier recovery of voiding and sexual function after robotic total mesorectal excision is another favorable outcome. Long-term survival data are sparse with no evidence that robotic surgery offers major benefits in oncological outcomes. Although initial reports are promising, more rigorous scientific evaluation in multicenter, randomized clinical trials should be performed to definitely determine the advantages of robotic rectal cancer surgery. Colorectal Division, Department of Surgery, Korea University Anam Hospital, Korea University College of Medicine, Seoul, Key words Korea Rectal neoplasms, Robotics, Laparoscopy, Total mesorectal excision Correspondence: Seon Hahn Kim, MD, PhD Colorectal Division, Department of Surgery, Korea University Anam Hospital, Korea University College of Medicine, 73 Inchon-ro, Seongbuk-gu, Seoul 02841, Korea Tel: 82-2-920-6644 Fax: 82-2-928-1631 E-mail: drkimsh@korea.ac.kr Received December 11, 2015 Accepted January 19, 2016 Published Online February 3, 2016

# Introduction

Since a robotic surgical system was developed in the early 1990s and the first robotic-assisted radical prostatectomy (RARP) was reported in 2001 [1], robotic surgery has spread in many surgical specialties, changing surgical management. In the United States, RARP has increased steeply from 8% of radical prostatectomies in 2004 to 67% in 2010 [2]. Likewise, the number and indications for robotic gynecological surgery

have continued to expand [3].

Over the past decade, robotic surgery has undergone substantial changes for pelvic procedures and been applied to colorectal surgery. Colorectal surgeons expected that robotic surgery would resolve technical difficulties associated with laparoscopic surgery, which has a steep learning curve. Since the first report of robotic-assisted colectomies by Weber et al. [4] in 2002, a variety of colorectal procedures have used robot assistance for a range of diseases [5-8].

Currently, compared to other colorectal procedures,

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robotic surgery appears to offer great benefits for total mesorectal excision (TME) for rectal cancer. For example, abdominal cavity procedures such as right hemicolectomy and high anterior resection are relatively uncomplicated and can be performed easily by laparoscopic surgery. According to a recent study that analyzed nationwide data on current surgical management for colorectal cancer surgery in Korea, robotic surgery was used for 185 cases of rectal cancer in 2008, increasing steadily to 490 cases in 2013. In contrast, robotic colon cancer surgery decreased from 110 cases in 2009 to only 10 cases in 2013 [9]. Furthermore, robotic colorectal surgery is more expensive than conventional laparoscopy.

Most relevant recent reports have focused on the clinical benefits of robotic rectal cancer surgery compared with laparoscopic surgery [10-27]. The indications for robotic and laparoscopic rectal cancer surgery are not different. No contraindications apply solely to robotic surgery for rectal cancer. However, no clear advantage supporting the use of this expensive technology has been demonstrated. For robotic rectal cancer surgery to become the preferred minimally invasive option, it must demonstrate that it does not have the technical difficulties and steep learning curve of laparoscopic surgery. Therefore, we reviewed current evidence to compare surgical, pathological, functional, and oncological outcomes of robotic and laparoscopic surgery for rectal cancer.

## **Materials and Methods**

We searched the MEDLINE database with PubMed for all articles published between 2002 and 2015 using the keywords "robot\*," "da Vinci," "colo\*," and "\*rectal." We also manually searched articles using references from related articles. The final search was performed in November 2015. Only papers published in English were included; studies with only abstracts and meeting reports were excluded. Articles were chosen for their relationship to the topic. When multiple studies used the same patient population, the most recent publication was used.

#### Short-Term Surgical Outcomes of Safety and Feasibility

Robotic surgery for rectal cancer has been established as safe and feasible. Short-term surgical outcomes of robotic Initially, a longer operating time was generally accepted to be a drawback of robotic rectal cancer surgery compared with laparoscopic procedures. However, recent studies report equivalent or even shorter operating times for robotic surgery for rectal cancer [10,13,16,21]. As most studies were published by highly experienced laparoscopic colorectal surgeons, the main reason underlying the initially reported lengthy operating times for robotic surgery was likely a difference in the level of mastery for the two operative techniques. Operating time does not appear to be an issue after surgeons accumulate experience and overcome the learning curve.

An excellent conversion rate is consistently reported in initial studies of robotic surgery. Because converted patients have higher complication rates and worse oncological outcomes, the low conversion rate for robotic rectal cancer surgery suggests expected better postoperative courses and improved oncological outcomes [28-31]. Postoperative recovery appears to be similar for robotic and laparoscopic surgery. Postoperative complication rates are also similar for these two procedures.

## Pathological and Oncological Outcomes

Pathological outcomes for several prognostic indicators for robotic and laparoscopic surgery groups are in Table 2 [10-27]. It is well established that increasing the number of retrieved lymph nodes has a strong impact on prognosis [32]. Circumferential resection margin (CRM) involvement in surgical specimens is a well-known prognostic factor for local recurrence [33,34]. The length of the distal resection margin and TME completeness are thought to reflect surgical quality and affect long-term oncological outcomes.

Most studies did not find significant differences between robotic and laparoscopic rectal cancer surgery in number of retrieved lymph nodes. Based on recommendations from the College of American Pathologists about the minimum number of nodes to be dissected, the reported mean and median numbers of retrieved lymph nodes are acceptable [35]. The length of distal resection margins was not significantly different for robotic, laparoscopic (or open) surgery for patients who underwent rectal cancer surgery. The rate of CRM involvement was also not different between the two groups in all except one series [21].

Macroassessment and microassessment of surgical specimens quality are made by pathologists to determine TME

Reference	Country (year)	Study design	Surgery	Sample size	Operating time (min)	EBL (mL) C	Conversion (%)	Hospital stay (day) cc	Total complications (%)
Allemann et al. [10]	Switzerland (2015)	Case matched	Robot	20	291	58±76	ъ	NA	40
			Lap	40	313	219±421	20	NA	35
Cho et al. [11]	Korea (2015)	Case matched	Robot	278	$361.6 \pm 91.9^*$	$179.0\pm 236.5$	0.4	$10.4\pm 5.6$	25.9
			Lap	278	272.4±83.8	$147.0\pm 295.3$	0.7	$10.7\pm6.6$	23.7
Kim et al. [12]	Korea (2015)	Case matched	Robot	33	$441.0\pm90.2^{*}$	$232.0\pm 180.0$	6.1	$10.9 \pm 6.2$	45.6
			Lap	99	277.0±83.2	$205.0\pm 163.8$	0.0	$13.1\pm 12.8$	39.4
Levic et al. [13]	Denmark (2015)	Nonrandomized	Robot	56	247 (130-511)	50(0-400)	5.4	$8(4-100)^{*}$	23.2
		comparative	Single port lap	36	295 (108-465)	35 (0-400)	0.0	7 (3-51)	27.8
Serin et al. [14]	Turkey (2015)	Nonrandomized	Robot	14	182 (140-220)*	NA	0.0	5(4-10)	14.3
		comparative	Lap	65	140 (90-300)	NA	3.1	6 (2-32)	24.6
Yamaguchi et al. [15]	Japan (2015)	Nonrandomized	Robot	203	232.9±72.0	$15.4\pm 26.4^{*}$	0.0*	7.3±2.3*	8.9
		comparative	Lap	239	227.6±62.6	$39.1\pm 85.1$	3.3	9.3±6.7	22.6
Park et al. [16]	Korea (2015)	Nonrandomized	Robot	133	205.7±67.3	$77.6\pm 153.2$	0.0*	$5.86 \pm 1.43^{*}$	7.5
		comparative	Lap	84	$208.8\pm 81.2$	$82.3\pm185.5$	7.1	$6.54 \pm 2.65$	9.5
Barnajian et al. [17]	USA (2014)	Case matched	Robot	20	240 (150-540)	125 (50-650)	0.0	6 (4-31)	40
			Lap	20	180 (140-480)	175 (50-900)	10	7 (5-36)	10
			Open	20	240 (115-475)	250 (50-800)	NA	7 (3-16)	15
Ghezzi et al. [18]	Italy (2014)	Nonrandomized	Robot	65	$299.0\pm 58.0^{*}$	0 (0-175)*	1.5	6 (5-8)*	41.5
		comparative	Open	109	$207.5\pm 56.5$	150 (0-400)	NA	9(8-10)	41.3
Ielpo et al. [19]	Spain (2014)	Nonrandomized	Robot	56	$309\pm 84^{*}$	280±35.3	3.5	$13\pm 10.5$	26.8
		comparative	Lap	87	252±90	$240\pm 53.7$	11.5	$10 \pm 3.6$	23
Tam et al. [20]	USA (2014)	Nonrandomized	Robot	21	260 (189-449)*	150 (30-2,000)	5.0	6 (4-23)*	42.9
		comparative	Lap	21	240 (171-360)	100 (50-1,200)	0.0	5 (3-14)	33.3
D'Annibale et al. [21] <sup>a)</sup> Italy (2013)	) Italy (2013)	Nonrandomized	Robot	50	270 (240-315)	NA	•0.0	8 (7-11)*	10
		comparative	Lap	50	280 (240-350)	NA	12.0	10(8-14)	22
Fernandez et al. [22]	USA (2013)	Nonrandomized	Robot	13	528 (416-700)*	157 (50-550)	8	13±29	NA
		comparative	Lap/HAL	59	344 (183-735)	200 (25-1,500)	17	$8 \pm 45$	NA
Kim et al. [23]	Korea (2012)	Case matched	Robot	100	$188 \pm 45$	NA	0.0	$7.1\pm 2.1$	NA
			Open	100	$103 \pm 23$	NA	NA	$6.9 \pm 1.5$	NA
Kwak et al. [24] <sup>a)</sup>	Korea (2011)	Case matched	Robot	59	270 (241-325)*	NA	0.0	NA	32.2
			Lap	59	228 (177-254)	NA	3.4	NA	27.1
Park et al. [25]	Korea (2011)	Case matched	Robot	41	$231.9\pm 61.4^{*}$	NA	0.0	$9.9 \pm 4.2$	29.3
			Lap	82	$168.6 \pm 49.3$	NA	0.0	$9.4 \pm 2.9$	23.2
Bianchi et al. [26]	Italy (2010)	Case matched	Robot	25	240 (170-420)	NA	0.0	6.5 (4-15)	16
			Lap	25	237 (170-545)	NA	4	6.0 (4-20)	24
Patriti et al. [27]	Italy (2009)	Nonrandomized	Robot	29	202±12	$137.4\pm 156$	0.0*	$11.9\pm7.5$	30.6
		comparative	Lap	37	208±7	$127\pm169$	29.2	9.6±6.9	18.9

I able 2. Comparison of pathological outcomes	r or paulouogical out	•						
Reference	Country (year)	Study design	Surgery	Sample	No. of retrieved LNs	DRM (cm) <sub>ii</sub>	CRM involved (%)	TME completeness (%)
Allemann et al. [10]	Switzerland (2015)	Case matched	Robot	20	24±14	NA	10	95*
			Lap	40	20±7	NA	25	55
Cho et al. [11]	Korea (2015)	Case matched	Robot	278	$15.0\pm 8.1$	$2.0\pm1.4$	5.0	NA
			Lap	278	$16.2\pm 8.1$	$2.2 \pm 1.4$	4.7	NA
Kim et al. [12]	Korea (2015)	Case matched	Robot	33	22.3±11.7	2.2±1.5	16.1	97
			Lap	99	$21.6\pm 11.0$	2.2±1.7		91
Levic et al. [13]	Denmark (2015)	Nonrandomized comparative	Robot	56	21 (7-83)*	3.0 (0.5-0.8)		60.7
			Single port lap	36	13 (3-33)	3.0 (0.5-0.75)		72.2
Serin et al. [14]	Turkey (2015)	Nonrandomized comparative	Robot	14	32 (17-56)*	2.75 (0.5-6.0)*	NA	100
			Lap	65	23 (4-67)	1.5(1.0-7.0)		80
Yamaguchi et al. [15]	Japan (2015)	Nonrandomized comparative	Robot	203	$30.0\pm10.3$	$2.8\pm 1.9$	NA	NA
			Lap	239	29.3±11.8	3.2±2.2	NA	NA
Park et al. [16]	Korea (2015)	Nonrandomized comparative	Robot	133	$16.34\pm 8.79$	$2.75\pm 2.14$	6.8	NA
			Lap	84	$16.63 \pm 10.24$	$2.87\pm1.63$	7.1	NA
Barnajian et al. [17]	USA (2014)	Case matched	Robot	20	14 (3-22)	2.1 (0.5-5.0)	NA	80
			Lap	20	11 (4-18)	2.2 (0.1-5.5)	NA	95
			Open	20	12 (4-20)	2.1 (0.1-4.5)	NA	95
Ghezzi et al. [18]	Brazil/Italy (2014)	Nonrandomized comparative	Robot	65	$20.1\pm10.3*$	2.7(1.6-4.4)	0	NA
			Open	109	$14.1 \pm 6.2$	2.2 (1.5-3.0)	1.8	NA
Ielpo et al. [19]	Spain (2014)	Nonrandomized comparative	Robot	56	$10\pm 8$	NA	3.6	NA
			Lap	87	$9{\pm}4.8$	NA	2.3	NA
Tam et al. [20]	USA (2014)	Nonrandomized comparative	Robot	21	$17 (8-40)^{*}$	3.9(1.0-18)	0.0	NA
			Lap	21	15 (8-21)	5.5 (0.5-8)	4.7	NA
D'Annibale et al. [21]	Italy (2013)	Nonrandomized comparative	Robot	50	$16.5\pm7.1$	$3\pm 1.1$	0.0*	NA
			Lap	50	$13.8 \pm 6.7$	$3\pm 1.6$	12.0	NA
Fernandez et al. [22]	USA (2013)	Nonrandomized comparative	Robot	13	$16\pm 2.0$	NA	0.0	69
			Lap/HAL	59	20±2.0	NA	1.7	73
Kim et al. [23]	Korea (2012)	Case matched	Robot	100	20±6.9	$2.7 \pm 1.7^{*}$	1.0	NA
			Open	100	$19.6\pm 8.5$	$1.9\pm 1.3$	1.0	NA
Kwak et al. [24] <sup>a)</sup>	Korea (2011)	Case matched	Robot	59	20 (12-27)	2.2 (1.5-3.0)	1.7	NA
			Lap	59	21 (14-28)	2.0 (1.2-3.5)	0.0	NA
Park et al. [25]	Korea (2011)	Case matched	Robot	41	$17.3 \pm 7.7$	$2.1 \pm 1.4$	4.9	NA
			Lap	82	$14.2\pm 8.9$	$2.3 \pm 1.5$	3.7	NA
Bianchi et al. [26]	Italy (2010)	Case matched	Robot	25	18 (7-34)	NA	0.0	NA
			Lap	25	17 (8-37)	NA	4.0	NA
Patriti et al. [27]	Italy (2009)	Nonrandomized comparative	Robot	29	$10.3 \pm 4$	$2.1 \pm 0.9$	0.0	NA
			Lap	37	$11.2\pm 5$	$4.5 \pm 7.2$	0.0	NA

le; DRM, distal resection margin; CRM, circumferential resection margin; TME, total mesorectal excision; NA, not available; Lap, laparoscopic; HAL,	coscopic. $*p < 0.05$ . <sup>a</sup> Values in parentheses are interquartile ranges.
LN, lymph node; DRM, distal resectio	hand-assisted laparoscopic. $*p < 0.05$ .

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Table 3. Compi	arison of long-term	Table 3. Comparison of long-term oncological outcomes between robotic, laparoscopic, and open surgery for rectal cancer	n robotic, l	aparoscopic, a	nd open surger	y for rectal	cancer		
Reference	Country (year)	Study design	Surgery	Sample size	Follow-up period (mo)	5-Yr OS (%)	5-Yr DSS (%)	5-Yr DFS (%)	5-Yr cumulative local recurrence rate (%)
Cho et al. [11]	Korea (2015)	Case matched	Robot	278	$51.0\pm 13.1$	92.2	93.6	81.8	5.9
			Lap	278	$52.5\pm 17.1$	93.1	95.5	79.6	3.9
Park et al. [16]	Korea (2015)	Nonrandomized comparative	Robot	133	$54.4\pm 17.3$	92.8	NA	81.9	2.3
			Lap	84		93.5	NA	78.7	1.2
Ghezzi et al. [18]	Brazil/Italy (2014)	Ghezzi et al. [18] Brazil/Italy (2014) Nonrandomized comparative	Robot	65	$46.7\pm 11.5$	85	86.6	73.2	3.2*
			Open	109	$55.1\pm 12.2$	76.1	78.3	69.5	16.1
OS, overall surv	ival; DSS, disease-	OS, overall survival; DSS, disease-specific survival; DFS, disease-free survival; Lap, laparoscopic; NA, not available. $*p < 0.05$ .	free surviv	al; Lap, laparc	scopic; NA, not	available.	*p < 0.05.		

completeness, another predictor of local recurrence [36]. Baik et al. [37] indicated that the macroscopic completeness of TME for surgical specimens represents TME quality more precisely than CRM involvement, because CRM involvement is influenced by surgical quality and location, size and progression of the tumor and metastatic lymph nodes. Baik et al. [37] reported that macroscopic TME grading of specimens was significantly better in a robotic surgery group (92.9% for robotic vs. 75.4% for laparoscopic surgery, p=0.033). Allemann et al. [10] also reported significantly better TME quality in a robotic than a laparoscopic group (complete TME: 95% vs. 55%, p=0.0003) and a trend for a lower rate of CRM involvement in the robotic group (10% vs. 25%, p=0.1). However, other studies failed to demonstrate the superiority of robotic over laparoscopic surgery for TME quality or reported quantitatively poorer TME quality for robotic than laparoscopic surgery [12-14,17]. Because demonstrating the clinical benefits of robotic surgery for rectal cancer is difficult, some studies have evaluated TME quality as the primary endpoint. However, no evidence indicates that better TME quality translates into better survival from robotic rectal cancer surgery [10,16,37].

Long-term survival data are sparse (Table 3). Cho et al. [11] performed case-matched analyses of long-term oncological outcomes for fully robotic and laparoscopic TME patients, excluding hybrid robotic surgery. No significant differences were found between the two groups for 5-year overall, or disease-specific, disease-free, or local recurrence-free survival. Another study from the same institution by Park et al. [16] compared 133 hybrid-robotic surgeries and 84 laparoscopic low-anterior resections for rectal cancer by a single surgeon. The mean follow-up period was 54.4 months. The 5-year overall survival and disease-free survival rates were not different between the two groups. Cumulative incidence of local recurrence was excellent in both groups: 2.3% in the robotic group and 1.2% in the laparoscopic group (p=0.649). Ghezzi et al. [18] compared survival in robotic and open rectal cancer surgery groups. Mean follow-up was 46.7 and 55.1 months, respectively. Five-year overall, disease-specific, and disease-free survival rates were not different between the robot and open groups; however, the 5-year cumulative local recurrence rate was significantly lower in the robot group (3.2% vs. 16.1%, p=0.024).

At present, no evidence supports that robotic surgery offers major benefits in surgical or oncological outcomes. Currently, several randomized controlled trials are underway to address whether robotic surgery has more favorable surgical and oncological outcomes compared with laparoscopic surgery. However, oncological outcomes should be equal, regardless of surgical approach, with strict adherence to surgical principles. For prostate cancer, multiple RARP series have demonstrated the safety, efficiency, and reproducibility of the procedure, although it does not have superior oncological outcomes compared to laparoscopic or open surgery [38-40]. Despite the higher medical cost and lack of advantages, a growing number of radical prostatectomies are performed with robotic assistance. We anticipate an increase in rectal cancers treated with robotic surgery without waiting for clear demonstration of its oncological benefits.

# **Functional Outcomes**

Voiding and sexual dysfunctions after rectal cancer surgery are common and well-known sequelae. The incidences of postoperative urinary and sexual dysfunction have decreased notably since the introduction of TME and autonomic nerve preservation techniques. Nonetheless, these adverse events remain a serious problem, with 4%-10% of TME patients reporting urinary dysfunction and 5%-30% reporting sexual dysfunction [41-44]. Regardless of the advantages of a laparoscopic approach such as magnified view and direct visualization of the low pelvis, the technical difficulties associated with laparoscopic surgery increase the risk of inadvertent damage to autonomic nerves. In the MRC CLASICC trial, laparoscopic rectal resection did not cause voiding dysfunction but tended to adversely affect male sexual function. Particularly, TME and conversion to open surgery were identified as independent risk factors for worse male sexual function [45].

Robotic TME is hypothesized to achieve better preservation of urinary and sexual functions than laparoscopic TME. Technological advantages in robotic surgical systems, including advanced three-dimensional views, finer dissection using the freely articulating EndoWrist, and stable traction with a third robotic arm are expected to result in greater preservation of autonomic nerves than with laparoscopic surgery. The low conversion rate of robotic TME compared to laparoscopic TME supports this hypothesis and currently available evidence is promising. Kim et al. [46] compared voiding and sexual function before and after robotic or laparoscopic TME for rectal cancer. The study demonstrated that voiding and sexual function recovered earlier in a robotic TME group than a laparoscopic group [46]. Park et al. [47] compared functional outcomes of robotic and laparoscopic intersphincteric resection for low rectal cancer, and reported a trend toward earlier recovery of male sexual function in the robotic than the laparoscopic group. A report by D'Annibale et al. [21] demonstrated that erectile function was preserved in all sexually active patients who underwent robotic TME. However, function was preserved only in 43% of patients who underwent laparoscopic TME and this difference was statistically significant (p=0.045) [21]. These results should be interpreted with caution because of the relatively small number of patients enrolled in the three studies. Publication bias is another consideration.

#### **Technical Evolution and Future Perspectives**

Recently developed robotic instruments and new robotic platform technologies require further investigation. An example is the robotic stapler (da Vinci EndoWrist Stapler 45), which we have used in our recent rectal surgery practice. This stapler is fully controlled from a surgeon's console, provides a full cone of articulation, and features SmartClamp feedback. Software detects adequate closure of the stapler jaws on the target tissue based on tissue thickness. We are interested in determining whether use of this instrument results in better clinical outcomes, particularly for anastomotic leakage.

FireFly fluorescence imaging with current surgical robotic systems provides integrated fluorescence images using nearinfrared technology. The images allow surgeons to distinguish cancerous from normal tissue and evaluate organ and tissue perfusion. Although indications for fluorescence imaging are limited to assessment of anastomotic perfusion in colorectal surgery, future technological advances and development of new fluorescent agents will expand its clinical applications [48-50].

Undoubtedly, future robotic systems will have little resemblance to the machines that are in use today. The extent to which current robotic surgical systems will undergo evolutionary changes over the next decades is unclear. Many research and development groups are working to develop robotic technologies. The development of artificial intelligence [51,52], miniaturization of surgical robots [53,54], incorporation of nanotechnology [51], and development of telepresence surgery with improved communication systems are all likely to impact robotic surgery in the near future.

## Conclusion

Although robotic rectal cancer surgery is expensive, its safety and feasibility are well established. Its lower conversion rate and better surgical specimen quality compared to laparoscopic surgery may potentially improve survival. Although initial reports are promising, randomized clinical trials should be performed to definitely determine the safety, efficacy, and long-term oncological and functional benefits of robotic rectal cancer surgery.

As the technology for surgical robots continues to advance rapidly, future robotic systems will become increasingly affordable and more refined. Adoption of new technology occurs over time, and technological advantages will ensure that robotic surgical systems are eventually part of the normal armamentarium for routine surgical tasks.

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## **Conflicts of Interest**

Conflict of interest relevant to this article was not reported.

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