Classifications of Multispectral Colorectal Cancer Tissues Using Convolution Neural Network

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Received: 10 June 2016

Accepted: 20 January 2017

Published: 28 February 2017

Abstract

Background: Colorectal cancer (CRC) is the third most common cancer among men and women. Its diagnosis in early stages, typically done through the analysis of colon biopsy images, can greatly improve the chances of a successful treatment. This paper proposes to use convolution neural networks (CNNs) to predict three tissue types related to the progression of CRC: benign hyperplasia (BH), intraepithelial neoplasia (IN), and carcinoma (Ca). **Methods:** Multispectral biopsy images of thirty CRC patients were retrospectively analyzed. Images of tissue samples were divided into three groups, based on their type (10 BH, 10 IN, and 10 Ca). An active contour model was used to segment image regions containing pathological tissues. Tissue samples were classified using a CNN containing convolution, max-pooling, and fully-connected layers. Available tissue samples were split into a training set, for learning the CNN parameters, and test set, for evaluating its performance. **Results:** An accuracy of 99.17% was obtained from segmented image regions, outperforming existing approaches based on traditional feature extraction, and classification techniques. **Conclusions:** Experimental results demonstrate the effectiveness of CNN for the classification of CRC tissue types, in particular when using presegmented regions of interest.

Keywords: Active contour segmentation, colorectal cancer, convolution neural networks, multispectral optical microscopy

INTRODUCTION

Colorectal cancer (CRC), also known as colon cancer, is due to the abnormal growth of cells proliferating throughout the colon.^[1] The American Cancer Society estimates that almost 136,830 people will be diagnosed and 50,310 will die due to CRC in 2016,^[2] and that the average lifetime risk of developing this type of cancer is one in 20 (5%). As with most types of cancer, the early detection of CRC is key to improving the chances of a successful treatment. CRC is typically diagnosed through the microscopic analysis of colon biopsy images. However, this process can be time consuming and subjective, often leading to significant inter/intraobserver variability. As a result, many efforts have been made toward the development of reliable techniques for the automated detection of CRC.

A number of studies have investigated the development of automated methods for the assessment and classification of CRC tissue. In Fu *et al.*,^[3] a computer-aided diagnostic system was developed to classify colorectal polyp types using sequential image feature selection and support vector

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machine (SVM) classification. A processing pipeline, including microscopic image segmentation, feature extraction, and classification, was also proposed in Kumar *et al.*^[4] for the automated detection of cancer from biopsy images. In Jass,^[5] a study based on clinical, morphological, and molecular features showed the usefulness of using such features for the diagnosis and treatment of CRC. A combination of geometric, morphological, texture, and scale invariant features was also investigated in Rathore *et al.*^[6] classifying colon biopsy images with an accuracy of 99.18%. In Rathore *et al.*^[7] a similar set of hybrid features was used with an ensemble classifier to enhance the classification accuracy. In Rathore *et al.*^[8] structural

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asp?2017/8/1/1/201108

How to cite this article: Haj-Hassan H, Chaddad A, Harkouss Y, Desrosiers C, Toews M, Tanougast C. Classifications of multispectral colorectal cancer tissues using convolution neural network. J Pathol Inform 2017;8:1. Available FREE in open access from: http://www.jpathinformatics.org/text.

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features based on the white run length and percentage cluster area were also shown to be useful for the classification of biopsy images. A few studies have also focused on the detection of CRC using multispectral microscopy images. One such work, presented in Chaddad *et al.*,^[9] uses three-dimensional gray-level co-occurrence matrix features to classify CRC tissue types in multispectral biopsy images.

Recently, convolution neural network (CNN) models have resulted in state of the art performance on a broad range of computer vision tasks such as face recognition,^[10] large-scale object classification,^[11] and document analysis.^[12] Unlike methods based on handcrafted features, such models have the ability to build high-level features from low-level ones in a data-driven fashion.^[13] In medical image analysis, CNNs have shown great potential for various applications such as medical image pattern recognition,^[14] abnormal tissue detection,^[15] and tissue classification.^[16,17]

In this paper, we propose a new approach for assessing CRC progression that applies CNNs to multispectral biopsy images. In this approach, the progression of CRC is modeled using three types of pathological tissues: (1) benign hyperplasia (BH) representing an abnormal increase in the number of noncancerous cells, (2) intraepithelial neoplasia (IN) corresponding to an abnormal growth of tissue that can form a mass (tumor), and (3) carcinoma (Ca), in which the abnormal tissue develops into cancer. A CNN is used to determine the tissue type of biopsy images acquired with an optical microscope at different wavelengths. By identifying this tissue type, our approach can determine and track the progression of CRC, thereby facilitating the selection of an optimal treatment plan. To the best of our knowledge, this work is the first to use CNNs to model the progression of CRC tissues based on multispectral microscopy images.

The rest of this paper is organized as follows: Section 2 describes the data used in this study, the preprocessing steps, and the proposed CNN-based model. Section 3 then presents the experimental methodology and results, highlighting the performance of our model. In section 4, we discuss the main results and limitations of this study. Finally, we conclude by summarizing the contributions of this work and proposing some potential extensions.

METHODS

Figure 1 presents the pipeline of the proposed approach. Multispectral CRC biopsy images are first acquired using an optical microscope system with a charge-coupled device (CCD) camera and a liquid crystal tunable filter (LCTF). These images are then used as input to the CNN classifier, both for training the model and classifying the tissue type of a new image. Alternatively, a segmentation technique based on active contours can be used to extract regions of interest corresponding to pathological tissues, before the classification step. In section 3, we show that presegmenting images can

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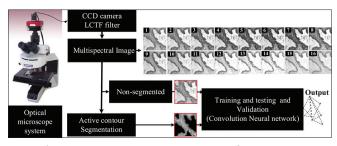


Figure 1: Flowchart of the proposed pipeline. Convolutional neural network classification of colorectal cancer tissues based on multispectral biopsy images

improve the classification accuracy of the proposed approach. Individual steps of the pipeline are detailed in the following subsections.

Data acquisition

Histological CRC data are obtained from anatomical pathology at the CHU Nancy Brabois Hospital. Part of these data was used in a previous study for classifying the abnormal PT from texture features.^[9] Tissue samples were obtained from sequential colon resections of thirty patients with CRC. Sections of 5 μ m thickness were extracted and stained using hematoxylin and eosin to reduce image processing requirements. Multispectral images of 512 × 512 pixels were then acquired using a CCD camera integrated with a LCTF in an optical microscopy system.^[18] For each tissue sample, the LCTF was used to provide 16 multispectral images sampled uniformly across the wavelength range of 500–650 nm.^[19] Since multispectral imaging considers a broader range of wavelengths, it can capture physiological characteristics of tissues beyond those provided by standard grayscale or trichromatic photography.

As mentioned before, the progression of CRC was modeled by considering three types of pathological tissues: BH, IN, and Ca. Each of the thirty biopsy samples used in this study was labeled by a senior histopathologist, for a total of ten BH samples, ten IN samples, and ten Ca samples.

Pathological tissue segmentation

Although unsegmented images can also be used directly, a segmentation step is added in the proposed pipeline to isolate the CRC tissues from nonrelevant tissues and structures such as lumen. For this step, we used a semi-automatic segmentation technique based on the active contour algorithm, which can accurately delineate the boundaries of irregularly shapes and has been shown to perform well for tissue segmentation.^[20] Briefly, the active contour model can be described as a self-adaptive search for a minimal energy state E_{AC} , defined as the sum of an internal energy and an external energy E_{ext} .^[21] The segmentation contour in an image I(x, y) is represented as a parametric function P(s) = (x (s), y (s)), s [0, 1] and is updated iteratively to minimize E_{AC} . The internal energy is defined as

$$E_{\rm int} = \frac{1}{2} \alpha |p'(s)|^2 + \beta |p''(s)|^2 \tag{1}$$

Where p'(s) and p''(s) represent the first and second derivatives of P(s), respectively, and α and β are constants weighting the relative importance of the derivatives. Intuitively, the internal energy favors short and smooth contour configurations. Likewise, the external energy is defined as:

$$E_{\text{ext}} = -\left|\nabla\left(G_{\sigma}\left(x,y\right)\right)*I\left(x,y\right)\right|^{2}$$
⁽²⁾

Where $G_{\sigma}(x, y)$ is the 2D Gaussian function with standard deviation σ and ∇ is the gradient operator. The external energy ensures agreement between the contour and image gradient information arising from tissue boundaries. Segmentation contours were initialized as centered rectangles of 508×508 pixels.

As shown in Figure 2, the segmentation algorithm partitions the image in two nonoverlapping regions, containing pixels that are on one side or the other of the segmentation contour. In a postprocessing step, a trained user (e.g., a pathologist) is asked to select the region of interest as one of the two segmented regions [Figure 2c]. Although outside the scope of this paper, a supervised learning model such as SVM could also be trained to select the region of interest automatically.

To evaluate the performance of our segmentation model, we used manually annotated ground truth provided by the CHU Nancy-Brabois Hospital. The Jaccard similarity coefficient (JSC), dice similarity coefficient (DSC),^[22,23] false positive rate (FPR),^[24] and false negative rate (FNR)^[25] were considered as performance metrics. The JSC and DSC metrics evaluate the degree of the correspondence between two segmentations (i.e., segmentation output and ground truth) and are defined as:

$$JSC(A,B) = \frac{TP}{TP + FP + FN}$$
(3)

$$DSC(A,B) = \frac{2TP}{2TP + FP + FN}$$
(4)

Where *A* and *B* represent the compared segmentations, TP/TN is the number of correctly classified foreground/background pixels (i.e., true positives/negatives) and FP/FN is the number of incorrectly labels foreground/background pixels (i.e., false positives/negatives). Moreover, FPR/FNR is the ratio between the number of pixels incorrectly labeled as foreground/background and the total number of background/foreground pixels:

$$FPR(A,B) = \frac{FP}{TF + FP}$$
(5)

$$FNR(A,B) = \frac{FN}{TP + FN}$$
(6)

We compared the performance of our active contour model with two standard segmentation approaches: Otsu's thresholding method^[26] and edge detection.^[27]

Convolutional neural network-based classification

As in most CNN-based classification approaches, we adopted an architecture consisting of three types of layers:

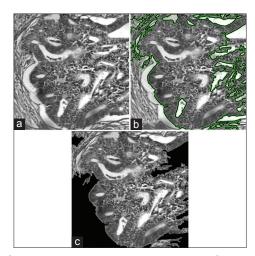


Figure 2: Example of tissue segmentation.(a) Original image, (b) segmentation obtained by the active contour model, (c) selected region of interest

convolution layers, subsampling (max-pooling) layers, and a fully-connected output layer.^[28] These types of layer can be described as follows:

Convolution layer

This layer type receives as input either the image to classify or the output or the previous layer and applies a set of N_1 convolution filters to this input. The output of the layer corresponds to N_1 feature maps, each one the result of a convolution filter and some additive bias. The parameters learned during training correspond to the convolution filter and bias weights. Note that the convolution process trims output maps by a border of $M_1 - 1$ pixels, where $M_1 \times M_1$ is the size of convolution filters.

Subsampling (pooling) layer

This parameter-less type of layer reduces the size of input feature maps through subsampling, thereby supporting local spatial invariance. It divides the input maps into nonoverlapping subregions and applies a specific pooling function to each one of them. In our architecture, we considered the max-pooling strategy, which outputs the maximum value of each subregion. Note that the pooling process reduces the feature maps by a factor of M_1 , where $M_1 \times M_1$ is the size of pooling subregions.

Output (fully-connected) layer

This type of layer captures the relationship between the final layer feature maps and class labels. The output of the layer is a vector of K elements, each one representing the score of a class (e.g., K = 3 in our network). Fully-connected layers can be seen as convolution operations, in which filters have the same size as their input maps.

Figure 3 shows the proposed CNN architecture. This architecture is composed of two convolution layers (C_1 and C_3), each one followed by max-pooling layers (S_2 and S_4), and an output layer (F_6). Although not represented in the figure, a layer of Rectified Linear Units (ReLUs) is added after each max-pooling layer to improve the convergence of the learning

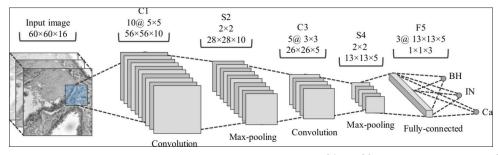


Figure 3: Proposed convolutional neural network architecture with two convolution layers (C1 and C3), two max-pooling layers (S2 and S4), and one fully-connected layer (F5). For each layer, the filter size and number of output features are given

process, which is based on the stochastic gradient descent algorithm. Further details on implementing CNNs may be obtained from.^[28]

For training and evaluating the CNN, the data were split based on the patients. We randomly selected the data of 21 patients (7 BH, 7 IN and 7 Ca) for training and used the data of the remaining 9 patients (3 BH, 3 IN, and 3 Ca) for testing. Furthermore, the biopsy images of three training patients were held out in a validation set and used to determine the optimal network architecture and number of training epochs. For each patient in the training, validation, and testing sets, we obtained multiple examples by running a $60 \times 60 \times 16$ sliding window across the original $512 \times 512 \times 16$ multispectral images. These examples were given the same label as the original image and used as input to the CNN. For segmented images, only examples whose center is within the region of interest were kept. Thus, training examples obtained from segmented images contain more relevant information for the target classification problem. Accuracy, which corresponds to the percentage of correctly classified examples, was used as a measure of classification performance.

RESULTS

In this section, we evaluate the performance of our CRC tissue classification method. Since this method uses segmentation as preprocessing step, we first assess the ability of the proposed segmentation algorithm to extract regions of interest corresponding to CRC tissues.

Table 1 gives the average performance of the three tested segmentation methods (Otsu's thresholding, edge detection, and active contour) on tissue samples corresponding to BH, IN, and Ca. We observe that our active contour method outperforms the other two approaches, for all performance metrics and tissue types (with P < 0.01 in a paired *t*-test). With respect to tissue types, the best performance of our method is obtained for Ca, with a JSC of 0.86, compared to 0.80 and 0.82 for BH and IN, respectively. Examples of segmentation results, for each tissue type, are shown in Figure 4. We see that the active contour method finds more consistent regions that better delineate the CRC tissues in the image.

Classification results are summarized in Table 2, showing the accuracy obtained on examples of the test set by our proposed CNN model, with and without the image segmentation step. For comparison, we also report accuracy values obtained by various tissue classification approaches on the same data. These approaches are categorized according to the type of texture or shape features used (e.g., gray-level co-occurrence matrix [GLCM], and statistical moments), classifier model (e.g., SVM and nearest-neighbors), and whether image segmentation is required or not. Note that these approaches work by quantifying a region (segmented or the whole image) with generic features and using these features as input to a classifier. In contrast, our proposed CNN method learns the features from training data, providing a better representation of the different CRC tissue types.

From these results, we observe that extracting regions of interest through segmentation enhances the accuracy of our method. Thus, while an accuracy of 79.23% is obtained without segmentation, the accuracy of our method reaches 99.17% on presegmented images. While this could be due to various other factors, extracting regions corresponding to CRC tissues provide more discriminative examples to train the CNN. In comparison to other tissue segmentation approaches, our CNN method with segmentation provides the highest accuracy (i.e., 99.17% vs. 98.92% for Chaddad *et al.*). Although relatively small, such improvement in accuracy can have a significant impact considering that the problem is cancer detection.

To illustrate the convergence of the parameter optimization phase (i.e., stochastic gradient optimization), Figure 5 shows the mean squared error (MSE) measured after each training epoch, corresponding to the mean squared difference between the network output Y_i and target label vector Y_i :

$$MSE = \frac{1}{n} \sum_{i=1}^{n} Y_{i}^{'} - Y_{i}^{2}$$
(7)

We see that the optimization converges after 500 epochs and that the MSE upon convergence is nearly 0. This shows that the proposed architecture is complex enough to learn a discriminative representation of tissue types and that the learning rate is adequate. In practice, the best number of epochs is selected based on the validation accuracy.

Metrics	Otsu's thresholding			Edge detection			Active contour		
	BH	IN	Ca	BH	IN	Ca	BH	IN	Ca
JSC	0.57	0.59	0.62	0.45	0.46	0.48	0.80	0.82	0.86
	(0.05)	(0.04)	(0.05)	(0.08)	(0.06)	(0.07)	(0.07)	(0.05)	(0.04)
DSC	0.51	0.56	0.58	0.42	0.39	0.41	0.82	0.86	0.90
	(0.05)	(0.06)	(0.04)	(0.13)	(0.15)	(0.04)	(0.18)	(0.06)	(0.01)
FPR	0.24	0.21	0.18	0.19	0.26	0.15	0.21	0.13	0.08
	(0.04)	(0.03)	(0.02)	(0.07)	(0.05)	(0.02)	(0.04)	(0.31)	(0.01)
FNR	0.21	0.23	0.24	0.26	0.31	0.34	0.01	0.15	0.14
	(0.05)	(0.07)	(0.05)	(0.08)	(0.09)	(0.08)	(0.01)	(0.06)	(0.04)

Standard deviation values are in parenthesis

	Accuracy (%)	Feature types	Classifier models	Segmentation	
Chaddad et al. ^[9]	98.92	Laplacian of Gaussian filter	LDA	Yes	
		Discrete wavelets	Decision trees		
		GLCM	Nearest neighbors		
Peyret et al.[29]	91.30	Local binary patterns	SVM	No	
		GLCM	Random forest		
		Local intensity order patterns			
Kumar et al. ^[4]	92.19	Clinically significant	Nearest neighbors	Yes	
		biologically features	SVM		
Rathore et al. [7]	98.85	Statistical moments	SVM	No	
		GLCM			
Elgamal et al. [30]	97.50	Discrete wavelets	Nearest neighbors	Yes	
-			Neural Networks		
Ours (unsegmented)	79.23	CNN	CNN	No	
Ours (segmented)	99.17	CNN	CNN	Yes	

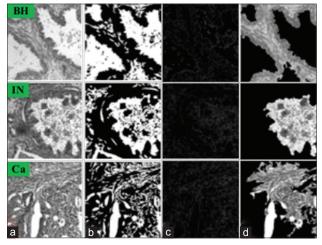
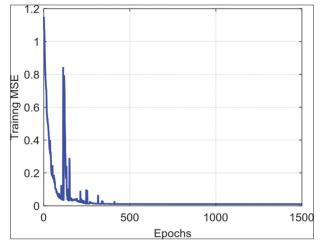


Figure 4: Examples of results obtained by the segmentation methods for the benign hyperplasia, intraepithelial neoplasia, and carcinoma tissue types. (a) Original image, (b) Otsu's thresholding, (c) edge detection, (d) active contour

However, eight segmented images were tested, and the performance metrics were increased with MSE and accuracy value of 0.0001 and 99.168%, respectively.





DISCUSSION

The CRC tissue classification approaches presented in Table 2 are based on the assumption that such tissues can be effectively described using a generic texture or morphological features.^[4,7,9,29,30] For example, Chaddad *et al.* used texture

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features derived from GLCMs, discrete wavelet transforms, and Laplacian of Gaussian filters, computed on presegmented regions, to classify the same images with an accuracy of 98.92%.^[9] Likewise, Peyret *et al.* computed texture features such as local binary and local intensity order patterns, on unsegmented to images, obtaining an accuracy of 91.3%.^[29] In contrast, we proposed a data-driven method, based on CNNs, to learn an optimal representation of tissues from training data. Our experiments showed this method outperforms existing approaches, even with a small number of tissue samples, with an accuracy of 99.17%. Results have also shown the usefulness of using presegmented images, which significantly improves the accuracy by focusing computation on relevant tissue regions within the image.

While results are promising, this study also has several limitations. First, it is based on a single small cohort of thirty patients. Having a larger set of biopsy images from different patients would help capture the full variability of tissues in the progression of CRC. Moreover, to obtain an optimal accuracy, our method currently requires the pathologist to select the region of interest from a segmented image. To have a fully automated pipeline, this step should be replaced by a supervised learning model which would determine the region of interest from training data.

CONCLUSIONS

We have presented a method for the classification of CRC tissues from multispectral biopsy images, based on active contour segmentation and CNNs. Unlike traditional approaches, which extract generic texture or shape features from the image, our method learns a discriminative representation directly from the data. Experiments on multispectral images of thirty patients show our method to outperform traditional approaches when using presegmented images. In future work, we will extend this study by including a larger number of patients and using a fully automated segmentation step.

Financial support and sponsorship

The University of Lorraine supports all the work of this research project.

Conflicts of interest

There are no conflicts of interest.

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