

Review

Signal acquisition of brain–computer interfaces: A medical-engineering crossover perspective review

Yike Sun^{a,1}, Xiaogang Chen^{b,1,*}, Bingchuan Liu^a, Liyan Liang^c, Yijun Wang^d, Shangkai Gao^a, Xiaorong Gao^{a,*}^a Department of Biomedical Engineering, Tsinghua University, Beijing 100084, China^b Institute of Biomedical Engineering, Chinese Academy of Medical Sciences and Peking Union Medical College, Tianjin 300192, China^c Center for Intellectual Property and Innovation Development, China Academy of Information and Communications Technology, Beijing 100161, China^d Institute of Semiconductors, Chinese Academy of Sciences, Beijing 100083, China

ARTICLE INFO

Article history:

Received 23 December 2023

Received in revised form 1 April 2024

Accepted 7 April 2024

Available online 16 April 2024

Keywords:

Brain–computer interface

Signal acquisition technologies

Surgery

Detection

Human computer interaction

ABSTRACT

Brain-computer interface (BCI) technology represents a burgeoning interdisciplinary domain that facilitates direct communication between individuals and external devices. The efficacy of BCI systems is largely contingent upon the progress in signal acquisition methodologies. This paper endeavors to provide an exhaustive synopsis of signal acquisition technologies within the realm of BCI by scrutinizing research publications from the last ten years. Our review synthesizes insights from both clinical and engineering viewpoints, delineating a comprehensive two-dimensional framework for understanding signal acquisition in BCIs. We delineate nine discrete categories of technologies, furnishing exemplars for each and delineating the salient challenges pertinent to these modalities. This review furnishes researchers and practitioners with a broad-spectrum comprehension of the signal acquisition landscape in BCI, and deliberates on the paramount issues presently confronting the field. Prospective enhancements in BCI signal acquisition should focus on harmonizing a multitude of disciplinary perspectives. Achieving equilibrium between signal fidelity, invasiveness, biocompatibility, and other pivotal considerations is imperative. By doing so, we can propel BCI technology forward, bolstering its effectiveness, safety, and dependability, thereby contributing to an auspicious future for human-technology integration.

1. Brain–computer interface

In 1924, Hans Berger achieved a seminal milestone in neuroscience by recording the first electroencephalogram (EEG) from a 17-year-old college student who presented with cranial defects, utilizing clay electrodes for this purpose. This pioneering endeavor marked the inception of a scientific method for monitoring human brain activity [1,2]. Subsequently, the intersection between human brain signals and computer systems has been an area of intense research, propelled by the evolution of computer technology which inherently relies on electrical signals for communication. The concept of a brain–computer interface (BCI) was first articulated by Jacques Vidal in 1973 [3] and since that proclamation, the field has witnessed substantial advancements [4–7]. These developments have led to the emergence of a variety of BCI systems and an expanded conceptualization of BCI technology. At the inaugural international conference in 1999, a BCI was delineated as “a communication system that does not rely on the brain’s normal output pathways of peripheral nerves and muscles” [8]. A decade later, in 2012, BCI tech-

nology was redefined by researchers as “a new non-muscular channel” for interaction [9]. Continuing this trend, in 2021, the scope of BCI was further broadened with the introduction of the concept of a generalized BCI, characterized as “any system with direct interaction between a brain and an external device” [10].

Fig. 1 illustrates a schematic representation of a typical Brain–Computer Interface (BCI) system. The components of BCI systems can be categorized into four main parts: signal acquisition, processing, output, and feedback. The effectiveness of a BCI system is predominantly contingent upon its signal acquisition module, which bears the critical responsibility for the detection and recording of cerebral signals. This component constitutes the central emphasis of the present paper. The processing component analyzes the recorded brain activity by utilizing specialized methods and algorithms to interpret the participant’s intended action. BCI processing involves preprocessing with techniques like independent component analysis [11] and decoding that integrates machine learning approaches such as support vector machines [12], with recent shifts towards specialized algorithms like canonical correlation

* Corresponding authors.

E-mail addresses: chenxg@bme.cams.cn (X. Chen), gxr-dea@mail.tsinghua.edu.cn (X. Gao).¹ These authors contributed equally to this work.

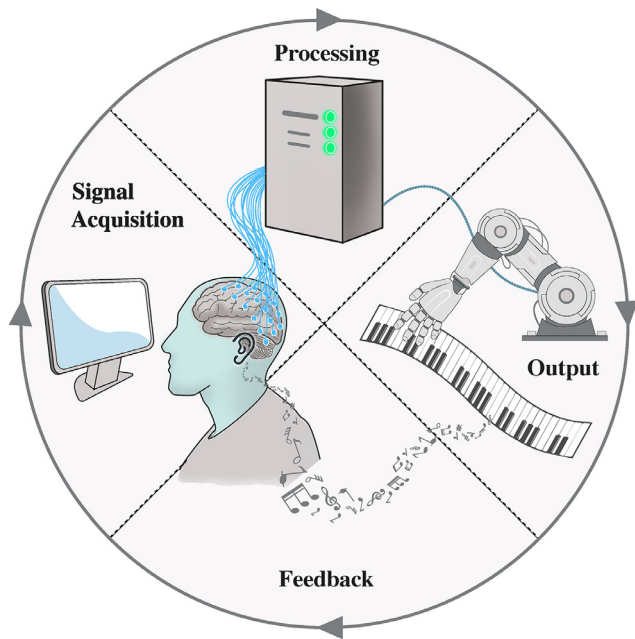


Fig. 1. System structure of a typical BCI. It includes four parts: signal acquisition, processing, output, and feedback.

analysis for steady state visually evoked potential [13] and deep learning for general paradigm-agnostic solutions [14]. The output component aims to execute the participant's intended action, typically achieved through the use of a robotic arm or speller using the processed information from the previous component. The feedback component informs the participant about the computer's interpretation of their intended action and conveys the final execution results through various sensory forms, including visual and auditory feedback. This allows for adjustments and supports closed-loop design.

2. Classification of signal acquisition technology for BCI

According to Jacques Vidal, a BCI is a device that utilizes EEG signals [3]. However, the diversification of signal acquisition methods due to technological advancements has made it challenging to precisely categorize BCI signal acquisition technologies. While the majority of researchers classify BCIs as non-invasive or invasive depending on the requirement of surgery, some have attempted to refine this categorization. In 2020, He et al. proposed a classification of flexible electrodes, categorizing them as non-intrusive, intrusive, and semi-intrusive [15]. This classification takes into account the degree of invasiveness and intrusion of the electrodes into the user's body. In 2021, Eric et al. classified the signal acquisition technology of BCIs into three categories: non-invasive, embedded, and intracranial [16]. This method considers the sensor's location relative to the brain and the degree of invasiveness.

However, the relentless advancement of technology has outpaced the parameters of the original classification systems, particularly evident in the material and medical sectors. Innovations such as vascular stent electrodes and tissue electrodes have emerged, which elude the confines of established categorization frameworks. Consequently, there is a pressing need to not only expand the existing classification methods but also to ensure they are sufficiently forward-looking to foster the advancement of the field.

To facilitate cross-disciplinary dialogue and collaboration among researchers from diverse domains, we have carefully curated the extant literature to present an innovative and comprehensive perspective: a two-dimensional overview of BCI signal acquisition techniques with a focus on surgical applications. This overview delivers an exhaustive examination of extant and emergent BCI technologies, delineating their

advantages, limitations, challenges, and prospective applications. It is poised to serve as an indispensable resource and instrument for guiding future research and development endeavors in the BCI domain.

3. A two-dimensional view of BCI signal acquisition technologies

The development of BCI systems is fundamentally an interdisciplinary endeavor that necessitates the collaboration of two principal stakeholders: clinicians and engineers. Clinicians are chiefly engaged in the aspect of surgical design, with a particular emphasis on mitigating surgical trauma. Conversely, engineers are integral to the process of signal acquisition, with a focus on ensuring the optimal performance of the sensor. Despite the critical nature of their respective roles, the current state of collaboration between clinicians and engineers falls short of expectations. Evidence from the literature indicates that clinicians possess a limited comprehension of both the end-user profile for BCI technologies and the intricacies of the technology itself [17]. Similarly, engineers often find their advancements in BCI technology to be insufficiently informed by the guiding principles of neuroscience and the exigencies of clinical practice [18].

This study introduces a meticulous and holistic methodology for the evaluation of BCI signal acquisition techniques. Diverging from previous research that tended to concentrate on isolated facets or dimensions, our investigation encompasses a dual-perspective analysis: the surgical and the sensorial. By synthesizing these two critical perspectives, we have established a comprehensive classification model that thoroughly integrates the surgical considerations with the variances inherent in different sensor operational modes.

Through the utilization of this model, we can simultaneously enhance guidance for surgery and sensor design, while comprehending the strengths, weaknesses, and potential risks associated with different BCI technologies. Moreover, we can ascertain the trade-offs and challenges involved in selecting and designing an optimal BCI signal acquisition technique for a specific application or user group. In the following sections, we will expound upon the characteristics of these two dimensions and provide a detailed comparison and evaluation of different BCI signal acquisition techniques based on this model. It is important to note that our objective is not to utilize two totally orthogonal vectors as a means to encompass all technologies. Rather, we aspire that this multi-perspective approach will enhance readers' comprehension of brain-computer interface technology and provide guidance for future advancements.

3.1. Surgery dimension: invasiveness of procedures

The dimension of surgery significantly influences the feasibility of employing these techniques. This dimension is primarily classified from the clinician's perspective and refers to the invasiveness of the surgical procedure involved in signal acquisition techniques. It encompasses three levels: non-invasive, minimal-invasive, and invasive, as depicted in Fig. 2a.

The categorization of the three dimensions of surgical intervention is predicated on the extent of invasiveness inherent to the signal acquisition procedure. A method is designated as 'non-invasive' if the surgical actions undertaken during signal procurement do not induce anatomically discernible trauma to the subject. In contrast, a procedure is considered 'minimally invasive' if it incurs anatomical trauma visible, provided it spares the brain tissue from any impact. Lastly, a technique is classified as 'invasive' if it causes anatomically discernible trauma at the micron scale or larger, specifically affecting the brain tissue, throughout the requisite surgical operation for signal collection (Fig. 3).

As we move across the spectrum of surgery dimensions, from non-invasive to invasive, there is a proportional increase in the degree of surgical trauma. Correspondingly, the ethical considerations linked to each signal acquisition technology progressively intensify. Moreover, as the surgical risks augment, there emerges an elevated necessity for pristine medical conditions, which in turn progressively heightens the challenges

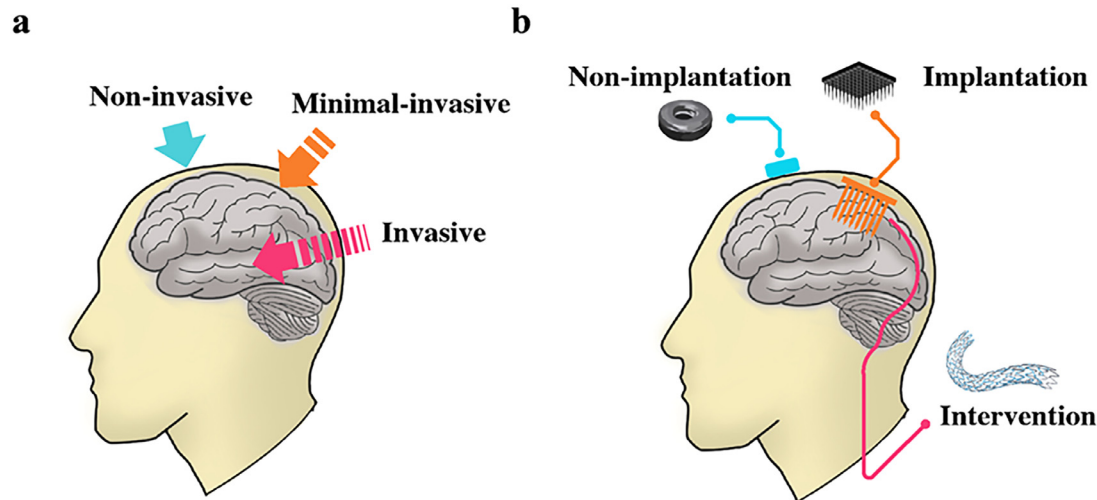


Fig. 2. Classification of BCI signal acquisition technologies. (a) is the classification diagram of the surgery dimension, which includes three levels: non-invasive, minimal-invasive, and invasive. (b) shows the classification diagram of the detection dimension, which includes three levels: non-implantation, intervention, and implantation.

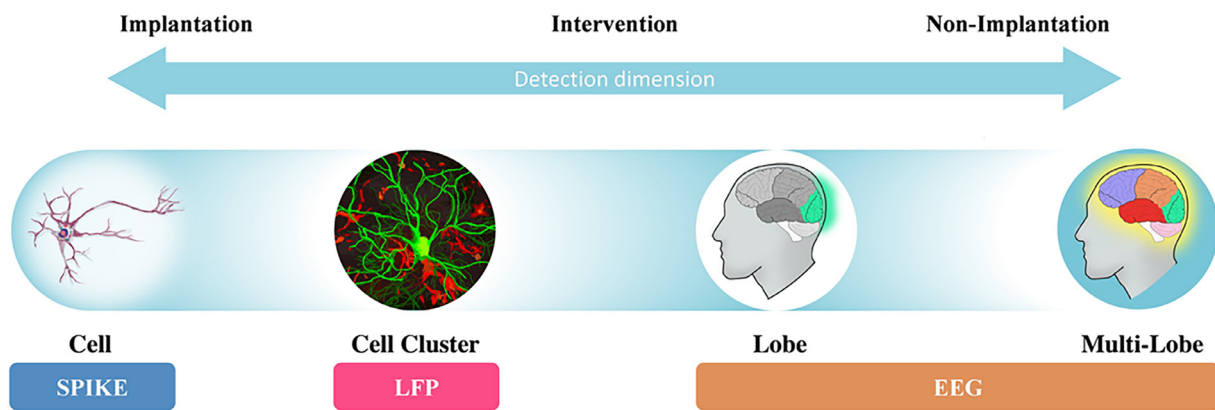


Fig. 3. Schematic depiction of the Detection dimension concerning the acquired signal. Implantation technology primarily records signals at both the cellular and cell cluster levels. Intervention techniques gather signals from cell cluster clusters, alongside background signals originating from various brain regions. Conversely, non-implantation techniques yield signals either from the entire brain or specific brain regions. Specifically, the spike signal corresponds to the electrical activity on a cellular scale, while LFP pertains to the electrical signal originating at the level of cell clusters. In contrast, EEG corresponds to the electrical signal originating from a singular brain lobe or multiple brain lobes simultaneously.

tied to the implementation of these techniques. Non-invasive methods typically obviate the need for continuous clinical oversight, while most minimally invasive approaches necessitate the engagement of neurology or neurosurgery experts. In contrast, virtually all invasive methodologies require the direct involvement of experienced neurosurgeons. It is imperative to weigh these considerations when assessing the viability and clinical utility of BCI signal acquisition modalities.

3.2. Detection dimension: operating location of sensors

Detection dimension is a crucial aspect of BCI technology, approached from an engineering perspective, which is directly related to operating location of sensors. Additionally, this dimension is directly linked to the theoretical upper limit of signal quality achievable with this technology, as well as to biocompatibility risk and other indicators. As illustrated in Fig. 2b, the dimensions are divided into three levels: non-implantation, intervention, and implantation.

The classification in detection dimension is primarily determined by the sensor's location during operation. A BCI technology is categorized as 'non-implantation' if the signal is acquired through a sensor on the surface of the body. On the other hand, 'intervention' is adopted from clinical medicine procedures in the field of interventional cardiac catheterization [19,20]. Sensors used in interventions leverage naturally

existing cavities within the human body, such as blood vessels, to function without causing harm to the integrity of the original human tissue. If the signal source relies on a sensor located within the body's natural cavity, it is classified as an 'intervention' technology. In cases where the signal is collected from an implanted sensor within human tissue, the technology is labeled as an 'implantation' technology. This dimensional framework is proposed to serve as a valuable reference for engineers in sensor design. Moreover, it is important to acknowledge that many intervention and implantation technologies, owing to their direct tissue contact, are prone to becoming integrated with the tissue over extended periods, which complicates their removal.

The theoretical upper limit of signal quality depends on the distance from the signal source and the type of interlayer. For example, detecting brain activity is analogous to listening to a chorus of students in a classroom. Non-implantation methods are like listening from outside the building, where only a large-scale sum of neuronal activity can be heard amid many sources of noise. Intervention methods are like listening in the corridor, where more information can be collected and less interference can be encountered than non-implantation methods, but the noise from the internal environment (tissue fluid, blood, etc.) is still significant. Implantation methods are like listening inside the classroom, where the signal is clearer and less interfered. However, signal quality also depends on other factors, such as spatial resolution and sensor

material properties. The above discussion only considers the maximum signal quality that can be achieved at a single point.

3.3. Relationship of detection dimension with signal

Current research in BCI signal acquisition has primarily centered on the detection aspect. Various methods, including implantation, intervention, and non-implantation techniques, are often considered in competition. Nonetheless, these three approaches operate within distinct anatomical locations, leading to limitations in their convergence. It is plausible that they will continue to develop independently.

Implantable sensors, owing to their close proximity to nerve cells, excel in capturing precise, high-frequency signals such as Local Field Potentials (LFP) and spike signals which indicative of single-unit and multi-unit activities. The latter denotes the firing of an individual neuron, manifesting a frequency exceeding 300 Hz. Conversely, LFP signals typify synchronized oscillations from small clusters of neurons within the 300 Hz frequency spectrum. Confrontationally, intervention techniques lack direct contact with neurons due to their isolation from soft tissues, including meninges and blood vessels. This isolation complicates the retrieval of spike signals, which are dominated by LFP signals. Non-implantation techniques are confined to acquiring large-scale synchronized discharges with frequencies of 100 Hz or less, such as EEG, particularly when investigated on the surface of the body.

Recent advancements in neuroscience have elucidated that electrophysiological signals, including spikes, LFP, and EEG, are not mere superpositions; they reveal significant scaling effects [21]. To delineate these concepts, we designate the system that employs an array of signal acquisition modalities as a global brain–computer interface (G-BCI) and the system that relies on precisely localized signal detection as a local brain–computer interface (L-BCI). For example, L-BCIs can capture more accurate signals but may not entirely reflect the complex cognitive processes of the human brain, as they depend on a limited number of neurons. Consequently, the implantation of minute electrodes for signal acquisition in domains such as affective computing could impair signal fidelity and, thus, the effectiveness of biometric applications. In contrast, G-BCIs, such as EEG, face challenges in identifying specific motor control regions due to the potential for subtle signal nuances to be obscured by the diffuse nature of neuronal firing. Hence, systems that utilize finer-scale signals could potentially exhibit enhanced performance in tasks requiring precise motor control localization.

4. The surgery-detection two-dimensional panorama of signal acquisition technologies in BCI

The surgery-detection two-dimensional panorama categorizes all BCI signal acquisition technologies into nine distinct categories (3×3), based on the aforementioned dimensions. This method furnishes a comprehensive and enlightening overview of the diverse signal acquisition techniques employed in BCI. Such an overview proves valuable in the selection and development of appropriate techniques for varying applications.

To facilitate a comprehensive and meticulous classification analysis, an exhaustive search was conducted in the Web of Science database for articles pertaining to BCI or brain–machine interfaces (BMI). Articles indexed in the Science Citation Index (SCI), Emerging Sources Citations Index (ESCI), and Social Sciences Citation Index (SSCI) from 2012 to August 2022 were included. A thorough screening of the articles was conducted to exclude papers that focused solely on algorithms or reviews. Our filtering criteria were centered on the presence of signal acquisition experiments. Articles containing such experiments were included in the total count, while those lacking them were excluded, resulting in a total of 6679 articles obtained. These articles were classified utilizing our proposed classification model. Due to the space limitations, not all of these articles are shown in the reference section.

The outcomes of the classification, along with their corresponding proportions, are presented in Fig. 4. Currently, the dominant approach in BCI/BMI research is non-invasive non-implantation technology, constituting approximately 85.87% of the studies. In contrast, the utilization of non-invasive intervention technology, minimal-invasive non-implantation technology, and minimal-invasive intervention technology is still in its nascent stages, collectively representing only 0.13%, 0.02%, and 0.06% of the studies, respectively. Minimal-invasive implantation technology, characterized by numerous clinical studies, primarily focuses on experiments involving epilepsy and paralysis patients, accounting for 4.84% of the studies. Lastly, invasive implantation technology, predominantly employed in animal and patients with paralysis studies, accounts for 9.08% of the studies.

This section, dedicated to the classification of technology in existing articles, serves the purpose of providing readers with a rapid comprehension of the present research landscape within the field. It is important to note that the prevalence of signal acquisition technologies over time does not inherently dictate the quality or effectiveness of their deployment. Looking ahead, significant shifts are anticipated in the distribution of each technology's prevalence. Non-invasive, non-implantable technologies are expected to witness a gradual decline in deployment complexity due to ongoing advancements in clinical and materials domains. In parallel, the proportion of other technologies is projected to experience a noteworthy upsurge.

Each BCI signal acquisition technology encompasses unique application scenarios, along with corresponding advantages and disadvantages. The subsequent sections offer a comprehensive survey of the customary techniques within each classification category.

4.1. Non-invasive non-implantation technology

Non-invasive non-implantation technologies are for signal acquisition due to their portability and applicability and applicability without implants. Electromagnetic and blood flow signals are two main categories of non-invasive non-implantation methods. The electromagnetic signal category includes Electroencephalogram (EEG) and Magnetoencephalogram (MEG). EEG is widely used for its low cost and ease of use [22], which has an excellent time resolution [23,24]. However, its signal quality can be degraded by tissues [25,26] and other bioelectric interference [27–29]. Most EEG devices use wet electrodes [30–32], but dry electrodes are being explored [33–35], such as microneedle [36–40] and direct-contact electrodes [41–44]. MEG, like EEG, has an excellent temporal resolution [45–47] but more channels [48]. MEG equipment usually rely on SQUID as the core [49], which requires exceptionally high magnetic shielding [24,50,51] and liquid nitrogen for cooling, which is costly [52]. Recently, optically pumped magnetometer (OPM) devices have been proposed to address these issues to some extent [53,54]. Moreover, the signals obtained by EEG and MEG are somewhat complementary [24], which suggests the possibility of combining them [55]. It is noteworthy to mention that the electromagnetic signals obtained through non-invasive non-implantable techniques constitute the vague outcome of collaborative neuronal activity involving a substantial number of neurons. These signals predominantly manifest within the realm of low frequencies.

Blood flow signals are indirect measures of neuronal activity, unlike electromagnetic signals, so blood flow signals have a natural disadvantage in time resolution [56]. Three technologies that detect changes in blood flow signals are functional Near-infrared Spectroscopy (fNIRS), functional Transcranial Doppler (fTCD), and functional Magnetic Resonance Imaging (fMRI). fNIRS uses near-infrared light to detect changes in oxygen content in the blood [57,58], offering high spatial resolution [59,60]. However, the skull is also a poor conductor of near-infrared light [61], limiting the depth of information that can be received. At the same time, when the distance between the near-infrared emitter and the receiver is less than one centimeter, the collected signal is mostly derived from the skin [62]. fTCD uses ultrasound Doppler imaging, which

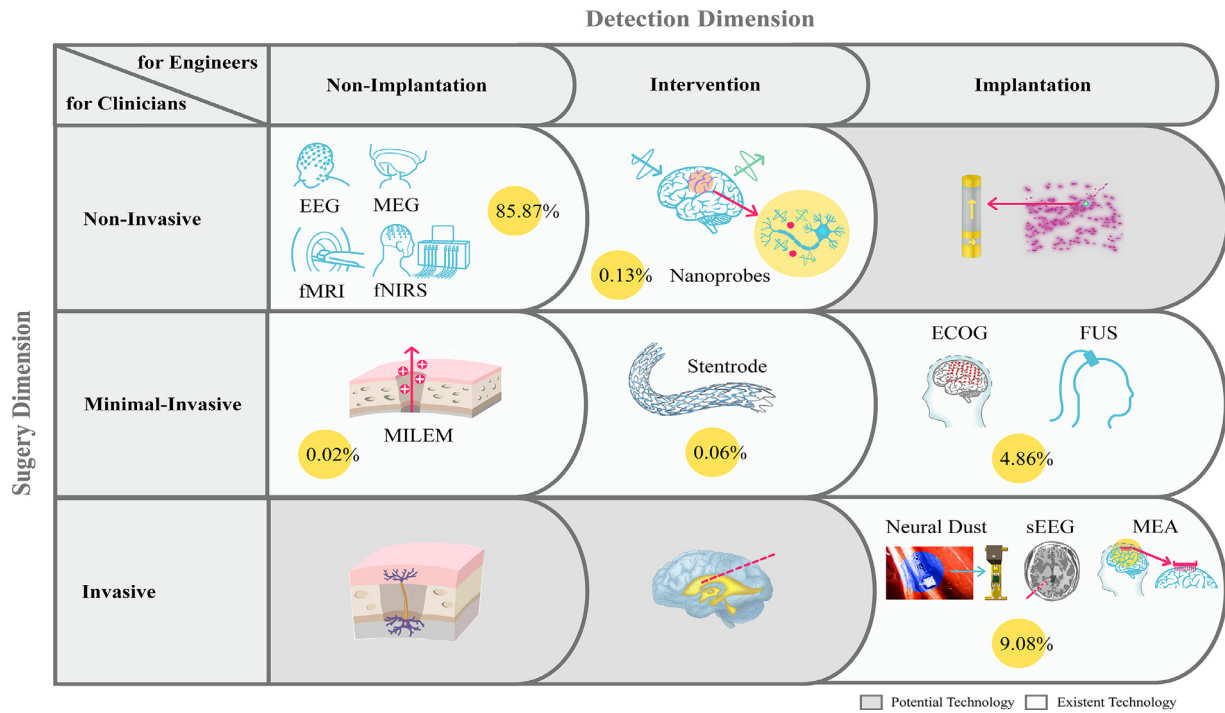


Fig. 4. The surgery-detection two-dimensional panorama of signal acquisition technologies in BCI. It includes two dimensions, totaling 9 (3 × 3) technology types. We surveyed 6679 research articles in this decade and obtained the proportion of each technology. They are non-invasive non-implantation technology (85.87%), minimal-invasive non-implantation technology (0.02%), non-invasive intervention technology (0.13%), minimal-invasive intervention technology (0.06%), minimal-invasive implantation technology (4.84%) and invasive implantation technology (9.08%). Grids with white backgrounds in the figure represent existing technologies and grids with gray backgrounds represent potential ones, which will be detailed below.

has a high imaging rate [63–65]. Some researchers also suggest fTCD can be a high resolution replacement for fNIRS [66]. However, fTCD requires couplant, which reduces its convenience. fMRI has a very high spatial resolution, up to a fraction of a millimeter [67], but traditional imaging has a high delay [68,69]. Although some fast-imaging methods are available [70], the temporal resolution of fMRI still falls behind other BCI signal acquisition techniques [71]. Blood flow signal techniques are commonly used in multimodal BCI studies for good electromagnetic compatibility [72–82].

4.2. Minimal-invasive non-implantation technology

The minimal-invasive non-implantation technologies aim to solve the technical obstacles of non-implantation technology by using minimally invasive surgery. The main obstacle for recording EEGs, as Hans Berger struggled for 27 years is the interference from various tissues in the human body [83], especially the skull, which has low electrical conductivity [25]. To enhance signal transmission, researchers developed the Minimally Invasive Local-Skull Electrophysiological Modification (MILEM) technology [84,85], which uses ultrasonic vibration to create a small hole in the skull, improving the electric field distribution on the scalp. MILEM preserves high time resolution and significantly increases the signal-to-noise ratio compared to conventional EEG methods. Although this technology does not avoid surgery completely, it does avoid implantation. This tech can be a potential solution for future applications.

4.3. Non-invasive intervention technology

Intervention methods aim to place sensors in the natural cavity of the human body to avoid problems such as inflammation. Non-invasive intervention is a promising direction for BCI research for safety and universality. Research in this field can be divided into two categories based on the implanted cavity: blood vessel and ear canal. The blood

vessel category uses nanoprobes to obtain the signal remotely, while the ear canal category records EEG. The nanoprobes method has been widely studied [86–88] as a medical imaging method, but only Neuro-SWARM3 used this method in the BCI signal acquisition [89], which utilizes nanoprobes functionalized with lipid coatings injected into the circulatory system [90,91]. However, there is no clear evidence for the signal quality and no report of in vivo experiments. In-ear EEG is a non-invasive method that uses an ear canal to record EEG. The device is similar to earplugs [92–94], and the signal characteristics are similar to the T7, and T8 leads in the 10–20 lead system [95]. However, there is a challenge in selecting ground and ref leads, with some studies placing them on the outer ear or scalp [94,96,97], compromising portability advantages. Alternatively, other studies have put them together in the ear canal [95], affecting signal quality.

4.4. Minimal-invasive intervention technology

Minimally-invasive intervention technologies facilitate the acquisition of more precise and profound neurophysiological signals when compared to non-invasive methods. The stent-electrode recording array, known as Stentrode, introduced by Oxley et al. in 2016, stands as an exemplar within this domain, targeting the vascular system. This approach involves the insertion of a stent electrode array into the cerebral venous system via minimally invasive surgery, capitalizing on endovascular routes to deploy sensors, thus potentially mitigating certain immune responses [98,99]. Specifically, Stentrode employs venous sinus stenting techniques to position a self-expanding scaffold electrode array within the desired locus. Clinical evaluations have affirmed the procedure's safety [100–102], and it has demonstrated satisfactory biocompatibility [103,104]. Notably, the Stentrode can record signals with a bandwidth of up to 226 Hz [105], capturing predominantly LFPs proximate to the site of implantation [106].

Nonetheless, the technology is not devoid of limitations, including the procedural complexity and the risk of serious complications, such as

intracranial hemorrhage and thrombosis [107]. Additionally, the requisite implantation of a signal transmitter subclavicularly [108] augments the operational costs. Moreover, given that the underlying medical vascular stent—a foundational component of the Stentrode—is permanently implanted, the technology is characterized by an inherent irreversibility, even in instances of device failure. Consequently, the practical application and long-term potential of Stentrode warrant further empirical validation.

4.5. Minimal-invasive implantation technology

Minimal-invasive implantation technologies represent an emerging area of research in BCI development. This field encompasses two categories of technologies: acoustic and electrical. Acoustic signal technologies, such as focused ultrasound imaging (FUS), employ ultrasound as the signal transmission medium and implanted sensors to acquire and analyze brain signals. Unlike conventional ultrasound techniques such as fTCD, FUS is a minimally invasive neuroimaging technique that involves direct implantation of transmitter and transducer elements outside the dura to produce high-resolution signals with high sensitivity [109–112]. It mainly detects blood movement [113], which makes it useful for motion decoding studies [114,115]. However, FUS is still in the development, and its applications and limitations need further investigation.

In electrical signal technologies, subcutaneous EEG (sqEEG) is a long-term [116] wearable system that consists of a small subcutaneous implant and an outer part that provides power [117], which has similar signal characteristics to conventional EEG [118,119], and it offers advantages in motion artifact suppression. Currently, sqEEG is mainly used in epilepsy detection but holds significant potential in BCI research [117]. Electrocorticogram (ECoG), a method first proposed in the 1950s for epilepsy localization [120], has higher spatial resolution and bandwidth than EEG [121,122], and is less susceptible to EMG and EOG interference [123,124]. However, ECoG requires risky surgery for implantation [125], limiting its acceptance for non-therapeutic purposes. Nevertheless, ECoG-based BCI research is prominent, as most EEG-based BCI paradigms can be reproduced with ECoG, yielding better results [126–128]. ECoG also has considerable potential in speech and action decoding [129–131], shown by a 2019 study that directly converted neural activity into speech using ECoG signals [132]. As research progresses, these technologies may revolutionize the field of BCI and offer groundbreaking therapeutic applications.

4.6. Invasive implantation technology

Invasive implantation technologies are a popular category in current research because of their spatial resolution and signal bandwidth advantages, which allow for excellent decoding operations [133]. They are utilized in BCI solutions such as BrainGate [134] and can be classified into cortical and depth signal classes. The cortical signal class mainly consists of Neuralink, Neural Dust, and intracortical microelectrode arrays (MEAs). Neuralink proposed a scalable high-bandwidth brain-computer interface platform in 2019 comprising high-density electrodes, an automated surgical robot, and a small implantable processing device [135]. Although Neuralink's solution has the potential to result in a high-quality stereo signal with less surgical trauma, the specific performance of the technology has not been thoroughly evaluated due to a lack of research reports. Neural Dust is a tiny sensor cluster that can monitor and stimulate neuronal activity in the brain or other body parts by ultrasound [136]. It is powered remotely by ultrasound without battery implantation [137] and can wirelessly transmit data for processing and analysis [138,139]. Although the Neural Dust has so far only been performed experimentally on peripheral nerves [140], it was originally designed to be able to performed as a central neural interface [138]. We still consider it a BCI technology.

The commonly used MEAs include the Utah Array [141] and Michigan probes [142]. MEAs are utilized in the decoding tasks of motion [143], vision [144], and speech [145]. In 2021, Willett et al. employed the BrainGate system to achieve a brain-to-text communication scheme by interpreting handwriting [146]. The primary signals consist of LFP (low-frequency) and spike (high-frequency) signals. MEAs have been continuously used for several months to several years after implantation [147]. However, the spike signal weakens shortly after implantation due to pin loss and frequency band reduction caused by the immune response. LFP signal components primarily serve as the basis for long-term MEAs [148,149]. Over the years, researchers have made significant advancements in the field of flexible MEA. For example, in 2019, Guan et al. proposed the Neural Matrix [150], which is an electrode developed using flexible silicon film transistors known for their excellent scalability. In 2020, Zhao et al. introduced ultra-flexible neural electrodes that utilize bio-dissolvable adhesive, facilitating long-term stable intracortical recording [151]. Some researchers have utilized carbon nanotubes in the development of flexible electrodes, which possess characteristics such as low toxicity and excellent electromagnetic compatibility [152]. In 2022, Zhou et al. presented an implantable electrode created from silk protein, which can avoid contact with tissues like blood vessels and effectively minimize the invasiveness of implantation [153]. The longest known MEA implanted is a neurotrophic electrode, a method of growing neurites into the electrode tip [154], which an implantation time is 13 years [155].

Depth signal class technologies, such as stereotactic electroencephalography (sEEG), Neuropixels, and fully implantable BCI, offer enhanced insights into the depth dimension of the signal. sEEG is a deep implantable signal acquisition technology with higher bandwidth, signal amplitude, and spatial resolution compared to standard EEG [123,156,157]. This makes it valuable for localizing epileptic lesions [158,159] and decoding speech [160] and motion [161]. Neuropixels is a type of fully-integrated silicon complementary metal-oxide semiconductor (CMOS) digital neural probe [162] that falls under the category of MEAs. It possesses the capability to simultaneously record cell-level signals at a highly reduced electrode scale [163], as well as exhibiting excellent performance in deep signal recording [164]. Due to its distinctive attributes, Neuropixels is regarded as a separate entity. In vivo animal experiments have extensively utilized Neuropixels [165], and in recent years, successful human experiments have also been conducted [165,166]. Notably, in 2021, researchers introduced Neuropixels 2.0, which enables more stable and prolonged recording compared to its predecessor [167]. Fully Implantable BCI is a technique that utilizes completely implanted electrodes and signal transmission units, effectively mitigating the risks associated with exposed wires and devices [168–170]. The most prevalent application of this technology is closed-loop BCI systems [171,172]. However, it is critical to acknowledge that Neuropixels, while revolutionary, are not engineered for prolonged-duration recordings [162,167]. Their fragile nature and vulnerability to tissue interference present significant challenges. These limitations, particularly concerning long-term implantation, continue to constrain their utility in the development of BCIs (Figs. 5, 6).

5. Potentially feasible technology

5.1. Non-invasive implantation technology: tissue penetration nanorobot

The investigation of nanorobots has been stimulated by naturally occurring nanoscale mechanical structures, such as bacterial flagella and rotors [173]. Within the medical domain, nanorobots represent nanostructures with the capacity to perform surgical procedures, facilitate drug delivery, enable imaging, and conduct analysis [174,175]. While the majority of nanorobots are transported through the bloodstream and function within blood vessels, nanorobots with tissue-penetrating capabilities can access tissues inaccessible to blood by employing magnetic drilling and acoustic micro-cannon techniques [176,177]. In 2019,

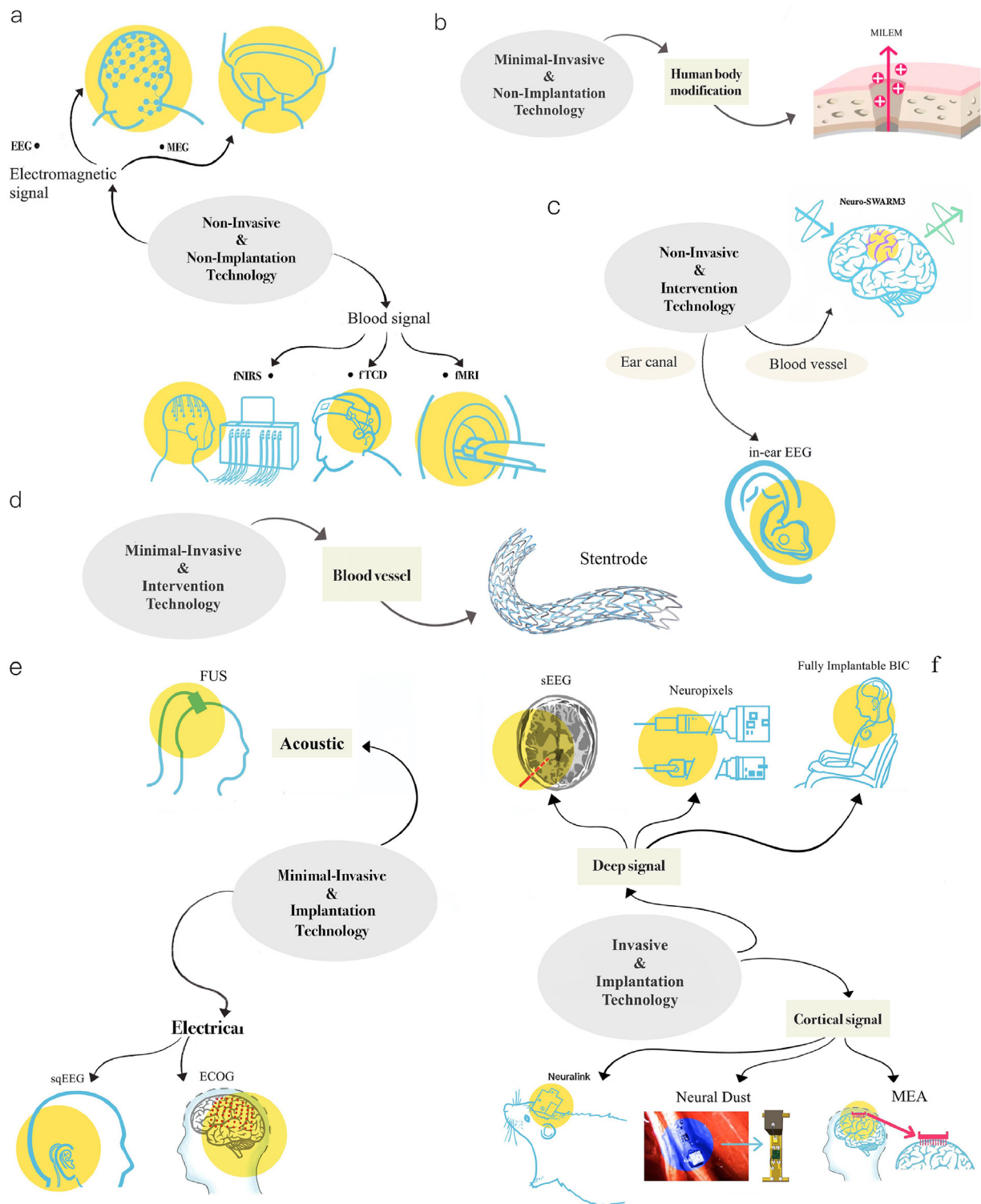


Fig. 5. Representative technologies in each category. (a) Non-invasive non-implantation technology includes the electromagnetic signal category and blood signal category. The representative technologies of the electromagnetic signal are EEG [30] and MEG [51]. The representative blood signal technologies include fNIRS [58], fTCD [65], and fMRI [82]. (b) The main idea of minimal-invasive non-implantation technology is human body transformation, and MILEM [84] is the representative technology in this field. (c) Non-invasive intervention technology can be divided into the blood vessel category and ear canal category according to the type of implanted cavity. The representative technique in the blood vessel is Neuro-SWARM3 [89], and the representative technique of the ear canal is in-ear EEG [95]. (d) The representative minimal-invasive intervention technology is Stentrode [98], which places the sensor in the cerebral venous sinus through vascular navigation and belongs to the blood vessel category. (e) Minimal-invasive implantation technology includes acoustic and electrical categories. The representative technology of the acoustic category is FUS [114]. The representative technologies of the electrical category are sqEEG [118] and ECoG [125]. (f) Invasive implantation technology is mainly concentrated in cortical and depth signal categories. The cortical signal category's representative technologies are Neuralink [135], Neural Dust [140], and MEAs [141]. sEEG [159], Neuropixels [167], and fully implantable BCI [168] belong to the depth signal category.

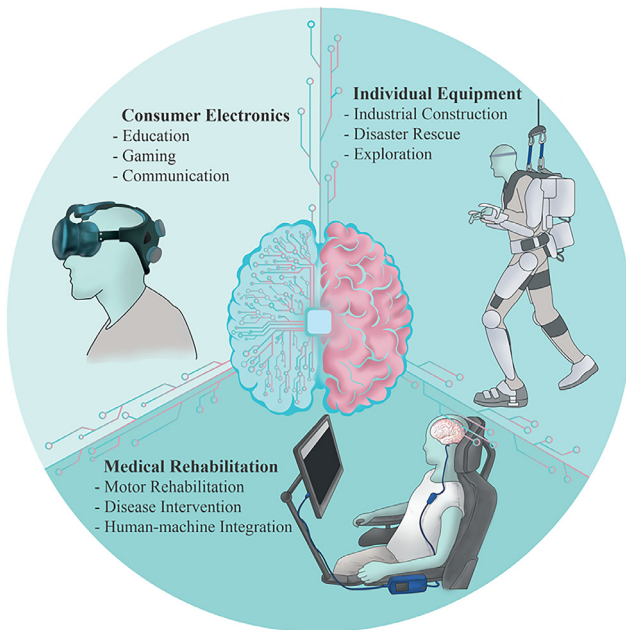


Fig. 6. A prospective map of the future development of BCI technology. In the foreseeable future, non-invasive non-implantation technology has excellent room for development in consumer electronics, such as education, gaming, and communication. For individual equipment control in complex scenarios, there is more significant potential for signal acquisition technologies that provide stable signals with less trauma, including minimal-invasive non-implantation, intervention, and implantation technologies. For medical rehabilitation, minimal-invasive and invasive implantation technologies would bring more breakthrough possibilities.

Jafari et al. effectively showcased the feasibility of introducing nanorobots into the brains of rats using magnetic drilling under the guidance of an external magnetic field [178]. This technology holds promise for applications involving the non-invasive implantation of BCIs. The envisioned scenario entails the injection of nanorobots into bloodstream of the brain, with an external magnetic field orchestrating their penetration into the cerebral cortex. Subsequently, these nanorobots could convey neural activity within the brain through ultrasound or near-infrared light.

5.2. Minimal-invasive implantation technology: in vivo assembly interface

An alternative strategy for minimal-invasive implantable technology involves leveraging the inherent biological processes to assemble electrode materials post-injection, thereby circumventing excessive surgical trauma. In vivo 3D bioprinting exemplifies this approach, wherein biocompatible inks containing electrode components are injected and subsequently structured using near-infrared light to form the desired configurations [179,180]. In 2023, researchers including Sha introduced a novel method involving a colloid of nanosheets, administered to specific neural targets via a jet injector to create an electrically conductive and biodegradable interface [181]. Concurrently, Strakosas and colleagues have innovated the in-situ synthesis of soft, conductive materials devoid of a solid substrate, through the injection of a sophisticated precursor system, marking a significant step towards the realization of in vivo synthesized electronics integrated with the nervous system [182]. Despite these advancements, a key challenge persists in the exclusive capacity for in vivo fabrication of electrode interfaces, while the components required for signal transmission and processing still rely on traditional surgical implantation techniques. Consequently, this technology, although promising, remains within the realm of minimally invasive procedures.

5.3. Invasive non-implantation technology: living autologous neural device

The utilization of autologous living cells as a foundational substrate for constructing implantable electronic devices has been regarded as a promising avenue for circumventing immune and inflammatory reactions [183]. Currently, the application of this technology within the realm of BCI remains limited. In 2017, Serruya et al. pioneered the development of an autologous living-cell neural interface, employing neuronal clusters to establish a micro columnar architecture; notably, this interface is encased within a biodegradable hydrogel that naturally degrades in vivo [184]. Likewise, in 2021, Prox et al. devised a DBS device, wherein autologous neuronal cells and cardiomyocytes are enshrined within an agar gel shell [185]. This innovation facilitates the utilization of autologous cells to transmit signals directly from a targeted brain region externally, obviating the need for sensor implantation. Nevertheless, this approach necessitates invasive surgical implantation within the brain tissue, thus falling under the purview of invasive methods. It is important to acknowledge that despite the use of autologous cells, the human body may still mount an immune response to cells originating from distinct sites, underscoring the critical significance of judicious cell type selection within this research trajectory.

5.4. Invasive intervention technology: cannula implantation in brain ventricular system

The ventricular brain system, which comprises four interconnected brain ventricles [186], is an integral component the brain. Extensive research has been conducted on the implantation of cannulas into brain ventricles for therapeutic or surgical procedures [187–189]. Moreover, studies have demonstrated the utility of electrical signals obtained from the ventricular brain system for BCI research [190]. Electrodes can be introduced into the ventricular brain system through a cannula implantation procedure, facilitating direct transmission of brain activity signals from the ventricles to external recording devices. Nevertheless, this procedure carries the potential risk of damaging brain tissue owing to osmotic pressure variations within the cerebrospinal fluid. Hence, this methodology is categorized as an invasive intervention technology. Nonetheless, considering that the neural tissue associated with consciousness resides on the dorsal aspect of the brain [191], while the ventricles are positioned within the ventral region, this method holds the potential to yield distinctive signals in contrast to conventional methodologies. These distinctive signals entail diverse application scenarios and signal characteristics.

6. Prospective directions of BCI signal acquisition technologies

Following a comprehensive review of various signal acquisition technologies, this paper concludes by exploring the potential future directions of brain-computer interface (BCI) technology. Central to advancing BCIs towards real-world applications is the development of high-performance acquisition technology within system-integrated solutions. For example, the establishment of stable signal acquisition and the creation of theoretically robust interaction paradigms can lead to significant improvements in patient well-being, enhancement of individual capabilities, provision of greater daily convenience, and assurance of user safety. It is important to note that the assessments put forward in this discussion are not intended to define the limits of application for any single technology. Rather, we advocate for the view that all examined technologies possess inherent potential for further development and refinement. However, it is also clear that certain technologies may exhibit more pronounced benefits or limitations in particular contexts or use-cases. By providing valuable references and guidance, this paper aims to inspire new ideas and innovations in this dynamic and promising field of research and development.

6.1. Non-invasive non-implantation technology heads for consumer electronics

The realm of BCI technology offers a plethora of potential applications in the realm of consumer electronics. These applications span various domains, including education [192], gaming [193,194], and communication [13,195]. Particularly, non-invasive, non-implantation technology stands out due to its remarkable social acceptance, evident cost-efficiency, and well-established technical maturity. Although it is acknowledged that this technology may exhibit lower signal quality compared to implantation technologies, its aptness for the target demographic of consumer electronics—comprising generally healthy individuals—is undeniable. This is especially relevant given the unlikelihood of such individuals pursuing surgical interventions for consumptive purposes. Hence, the present context strongly supports the preference for non-invasive non-implantation technology within the realm of consumer electronics. However, it is pertinent to acknowledge that challenges persist within consumer electronics applications, notably in cases where EEG is employed. Issues stemming from hair interference and device dimensions continue to pose hurdles. This calls for a dedicated focus on industrial research aimed at enhancing both electrodes and algorithms pertinent to non-invasive non-implantation technology.

Recent times have witnessed substantial strides in the practical deployment of non-invasive non-implantation BCI technology. Within the healthcare sphere, this technology has found valuable application in aiding stroke patients' motor rehabilitation [196,197]. The clinical validation of this application has rendered it a staple in clinical practice. Furthermore, the technology's real-time monitoring capability has been harnessed to gauge patients' anesthetic statuses during surgical procedures, thereby enabling dynamic anesthesia through closed-loop mechanisms [198,199]. This, in turn, has proven instrumental in mitigating the risks linked to anesthetic drug overdose. The convergence of non-invasive non-implantation neuromodulation technology has yielded products capable of effecting closed-loop sleep regulation, thereby enhancing sleep quality among patients [200,201].

Beyond the medical realm, this technology has manifested its utility in safety-critical operations. It has been instrumental in monitoring the cognitive states of specialized operators, thereby preempting conditions like severe fatigue [202]—particularly relevant to miners or truck drivers. The education sector also benefits from non-invasive non-implantation technology, employing them to assess group learning dynamics and bolster user concentration by tracking attention levels [203]. In the realm of entertainment, these interfaces facilitate users' meditation training and attainment of mind-flow states [204]. A noteworthy innovation comes in the form of virtual reality all-in-one devices, seamlessly integrating non-invasive non-implantation BCI technology to monitor brain states during gaming and enable brain-computer interaction [205,206]. Notably, brain-controlled mice founded on non-implantable brain-computer interfaces expand interaction possibilities for special populations, albeit at a slight performance trade-off compared to traditional mice.

In summary, the application landscape for non-invasive non-implantation BCI technology is broad and promising, especially within contexts emphasizing lightweight design, user-friendliness, and cost-effectiveness. This potential is particularly pronounced within consumer electronics and light medical applications.

6.2. Individual equipment control in complex scenarios requires a reliable and stable signal source

BCI technology extends its utility beyond the realm of disability, demonstrating equal effectiveness for individuals without impairments. Through direct interfacing with personal devices like mechanical exoskeletons, BCI technology holds the potential to significantly augment the capabilities and survivability of individuals facing hazardous scenarios, such as those encountered in network-deprived environments

like mines. This technology unveils novel prospects for navigating intricate settings like industrial construction, disaster relief operations, and exploratory ventures. Ongoing research in the field of BCI concentrates on the control of exoskeletons [207,208], unmanned aerial vehicles (UAVs/UGVs) [209,210], and prosthetic devices [211,212].

However, the acquisition of reliable BCI signals within intricate real-world situations remains a formidable challenge. Prevailing non-invasive techniques, frequently employed, suffer from suboptimal signal fidelity. The employed sensors often struggle to discriminate between brain-derived signals and other extraneous physiological noises. Conversely, implantation techniques directly within the cerebral cortex offer superior signal quality but are susceptible to damage and infections. The brain's immune response tends to encapsulate implanted devices over time, consequently degrading signal quality. Thus, the pursuit of minimal-invasive non-implantation, as well as minimal-invasive intervention methodologies, emerges as a plausible resolution. The placement of temporary electrodes within the cranial cavity, albeit external to the brain, emerges as a promising compromise between signal fidelity and safety. Another viable avenue involves the development of diminutive, more pliable, and less intrusive implants specifically designed for minimally invasive implantation techniques. The employment of advanced neural materials and electrode configurations that elicit minimal immune response from the brain presents the potential to facilitate the creation of safer, enduring implantation solutions.

Nevertheless, the ethical quandaries surrounding privacy, security, and identity necessitate thorough consideration, given the sensitive nature of neural data. The establishment of regulatory frameworks designed to forestall any potential misuse will assume paramount importance as BCIs gain wider traction. In the forthcoming decades, the convergence of robotics and neurotechnology stands poised to revolutionize our interactions with machines and to amplify human capabilities in profound ways.

6.3. Implantation technologies bring breakthroughs in medical rehabilitation

The implementation of BCI signal acquisition devices for therapeutic or rehabilitative purposes has gained acceptance among patients with amyotrophic lateral sclerosis (ALS) conditions [169,213]. These patients typically experience minimal changes in their living environment, thereby maximizing the potential benefits derived from the superior signal accuracy and low surgical risk offered by minimal-invasive implantation technology. This technology has demonstrated significant advancements in domains such as motor rehabilitation and disease intervention. While invasive implantation technology currently experiences limited employment within clinical practice, its capacity to procure high-precision, cell-level signals hold the promise of future medical breakthroughs.

To illustrate, implanted BCIs have the potential to empower ALS patients with complete paralysis to exert control over external devices such as computer cursors or robotic limbs solely through their cognitions of limb movement [214,215]. Although the technology remains imperfect, ongoing strides in neural decoding algorithms and the longevity and biocompatibility of implantable devices are propelling rapid advancements.

In the future, implanted BCIs could transcend their role in aiding communication and mobility among paralyzed patients. Furthermore, implanted BCIs could intervene in debilitating neurological disorders like epilepsy or Parkinson's disease [216,217]. In the context of epilepsy, real-time detection and mitigation of seizures through electrical stimulation could be achieved by recording from electrode arrays positioned in seizure-prone brain regions. In the case of Parkinson's disease, BCIs could capture signals from dysregulated areas and administer targeted stimulation to reinstate normal dynamics. The precise closed-loop modulation of pathological brain activity bears the capacity to substantially enhance outcomes for these conditions. In addition, implantable tech-

nology has potential applications in psychiatric disorders, such as depression.

Amidst these promising prospects, the adoption of invasive BCIs for medical applications necessitates rigorous validation of long-term safety and efficacy through comprehensive clinical trials. Additionally, the assurance of cybersecurity is imperative. Nevertheless, given the transformative restoration of function already demonstrated, implanted BCIs appear primed to extend medical capabilities and significantly enhance patient outcomes in the forthcoming years. With collaborative efforts across disciplines, these emerging neural technologies could potentially bestow millions grappling with neurological conditions with the restoration of health, autonomy, and quality of life.

6.4. Application of AI in BCI signal acquisition

The integration of Artificial Intelligence (AI) into BCI systems has significantly enhanced BCI efficacy. AI's proficiency in processing complex neural signals has led to advanced pattern recognition and decoding abilities, which are crucial for converting brain activity into executable commands. BCIs are increasingly leveraging AI's sophisticated algorithms to discern nuanced patterns in the brain's electrical activity, thereby augmenting the system's proficiency in interpreting user intentions with heightened precision and rapidity [10,218,219].

Within the domain of signal acquisition, from a clinical perspective, the application of AI in the analysis of medical imaging data has proven indispensable. The utilization of AI algorithms for the interpretation of imaging outcomes enables clinicians to ascertain the most advantageous positioning for electrodes with unparalleled accuracy [220,221]. This improvement not only amplifies the fidelity of the captured signals but also diminishes the risks tied to the surgical implantation of electrodes. The procurement of high-quality signals is fundamental to the success of BCIs, especially in scenarios where there is little tolerance for error.

Engineers have also harnessed AI to inform the design and fabrication of electrode materials and architectures [222,223]. Predictive AI-driven simulations can forecast interactions between various materials and designs with the human tissue, facilitating the creation of more robust and enduring human-machine interfaces [224]. The application of AI in this design process can considerably prolong the service life of implanted electrodes, curtail the need for repeated surgeries, and enhance the overall sustainability of BCI systems.

The application of AI in BCI signal acquisition spans multiple dimensions, influencing aspects ranging from surgical precision and electrode durability to system adaptability and user experience. As AI technologies advance, their incorporation within BCI systems is poised to amplify their capabilities, ensuring not only an upsurge in effectiveness but also broadening accessibility for those who stand to benefit from their transformative power.

7. Conclusion

This article presents a comprehensive analysis of the multifaceted challenges present in BCI technology, emphasizing the critical importance of signal acquisition. Signal acquisition constitutes an essential component of BCI systems, integrating considerations such as invasiveness, resolution, fidelity, cost, usability, and safety. Our examination of contemporary literature spanning the last ten years culminated in the introduction of an innovative classification schema—the “surgery-detection two-dimensional panorama”. This schema systematically organizes the various signal acquisition methodologies employed in BCI research.

Our assessment provides a cogent and contemporary overview of cutting-edge signal acquisition technologies in BCI, delineating their respective advantages and limitations, as well as their appropriateness for distinct BCI applications. The classification framework proposed herein

furnishes a methodical means to evaluate and juxtapose these technologies, thereby enhancing comprehension of the field's extant status and informing prospective investigative trajectories.

Through this systematic categorization, we endeavor to enrich the ongoing discourse within the BCI scholarly community and foster interdisciplinary collaboration. Our conviction is that this contribution lays the foundational work for subsequent progress in BCI signal acquisition and heralds the inception of more refined, accessible, and effective BCI systems.

Authors' contribution

Y. S. and X. C. wrote this article. X. G. and S. G. provided idea as well as financial support for this study. B. L., L. L. and Y. W. revised this article.

Declaration of competing interest

The authors declare that they have no conflicts of interest in this work.

Acknowledgments

This work is supported by the National Natural Science Foundation of China (U2241208, 62171473, 61671424), the National Key Research and Development Program of China (2022YFC3602803, 2023YFF1205300), Key Research and Development Program of Ningxia (2023BEG02063). Authors would like to thank Ziyu Zhang from Xiamen University and Yuqing Zhao from the Central Academy of Fine Arts for their help in drawing the pictures in this article. The authors would also like to thank Prof. Guo Liang for his guidance in writing this paper.

References

- [1] D. Millett, Hans Berger: From psychic energy to the EEG, *Perspect Biol. Med.* 44 (4) (2001) 522–542.
- [2] L.F. Haas, Hans Berger (1873-1941), Richard Caton (1842-1926), and electroencephalography, *J. Neurol. Neurosurg. Psychiatry* 74 (1) (2003) 9.
- [3] J.J. Vidal, Toward direct brain-computer communication, *Annu. Rev. Biophys. Bioeng.* 2 (1) (1973) 157–180.
- [4] M.A. Bockbrader, G. Francisco, R. Lee, et al., Brain computer interfaces in rehabilitation medicine, *PMR* 10 (9 Suppl 2) (2018) S233–S243.
- [5] J.J. Daly, J.R. Wolpaw, Brain-computer interfaces in neurological rehabilitation, *Lancet Neurol.* 7 (11) (2008) 1032–1043.
- [6] V. Kohli, U. Tripathi, V. Chamola, et al., A review on virtual reality and augmented reality use-cases of brain computer interface based applications for smart cities, *Microprocess Microsyst.* 88 (2022) 104392.
- [7] A. Lecuyer, F. Lotte, R.B. Reilly, et al., Brain-computer interfaces, virtual reality, and videogames, *Computer (Long Beach Calif)* 41 (10) (2008) 66–72.
- [8] J.R. Wolpaw, N. Birbaumer, W.J. Heetderks, et al., Brain-computer interface technology: A review of the first international meeting, *IEEE Trans. Rehabil. Eng.* 8 (2) (2000) 164–173.
- [9] L.F. Nicolas-Alonso, J. Gomez-Gil, Brain computer interfaces, a review, *Sensors* 12 (2) (2012) 1211–1279.
- [10] X. Gao, Y. Wang, X. Chen, et al., Interface, interaction, and intelligence in generalized brain-computer interfaces, *Trends Cogn. Sci.* 25 (8) (2021) 671–684.
- [11] S. Makeig, A. Bell, T.-P. Jung, et al., Independent component analysis of electroencephalographic data, *Adv. Neural Inf. Process Syst.* 8 (1995). <https://ieeexplore.ieee.org/document/1180091>.
- [12] A. Rakotomamonjy, V. Guigue, BCI competition III: Dataset II-ensemble of SVMs for BCI P300 speller, *IEEE Trans. Biomed. Eng.* 55 (3) (2008) 1147–1154.
- [13] X. Chen, Y. Wang, S. Gao, et al., Filter bank canonical correlation analysis for implementing a high-speed SSVEP-based brain-computer interface, *J. Neural Eng.* 12 (4) (2015) 046008.
- [14] V.J. Lawhern, A.J. Solon, N.R. Waytowich, et al., EEGNet: A compact convolutional neural network for EEG-based brain-computer interfaces, *J. Neural Eng.* 15 (5) (2018) 056013.
- [15] G.W. He, X.F. Dong, M. Qi, From the perspective of material science: A review of flexible electrodes for brain-computer interface, *Mater. Res. Express* 7 (10) (2020) 102001.
- [16] E.C. Leuthardt, D.W. Moran, T.R. Mullen, Defining surgical terminology and risk for brain computer interface technologies, *Front. Neurosci.* 15 (2021) 599549.
- [17] S. Letourneau, E.T. Zewdie, Z. Jadavji, et al., Clinician awareness of brain computer interfaces: A Canadian national survey, *J. Neuroeng. Rehabil.* 17 (1) (2020) 1–14.
- [18] U. Chaudhary, N. Birbaumer, A. Ramos-Murguialday, Brain-computer interfaces for communication and rehabilitation, *Nat. Rev. Neurol.* 12 (9) (2016) 513–525.

- [19] R.L. Mueller, T.A. Sanborn, The history of interventional cardiology: Cardiac catheterization, angioplasty, and related interventions, *Am. Heart J.* 129 (1) (1995) 146–172.
- [20] J. Pihkala, D. Nykanen, R.M. Freedom, et al., Interventional cardiac catheterization, *Pediatr. Clin. N. Am.* 46 (2) (1999) 441–464.
- [21] M.X. Cohen, Where does EEG come from and what does it mean? *Trends Neurosci.* 40 (4) (2017) 208–218.
- [22] M. Xu, F. He, T.-P. Jung, et al., Current challenges for the practical application of electroencephalography-based brain-computer interfaces, *Engineering* 7 (12) (2021) 1710–1712.
- [23] S. Vaid, P. Singh, C. Kaur, EEG signal analysis for BCI interface: A review, 2015 Fifth International Conference On Advanced Computing & Communication Technologies, IEEE, (2015). <https://ieeexplore.ieee.org/document/7079068>.
- [24] P. Hansen, M. Kringelbach, R. Salmelin, MEG: An Introduction to Methods, Oxford University Press, 2010.
- [25] C. Gabriel, A. Peyman, E.H. Grant, Electrical conductivity of tissue at frequencies below 1MHz, *Phys. Med. Biol.* 54 (16) (2009) 4863–4878.
- [26] B.N. Cuffin, Effects of local variations in skull and scalp thickness on EEG's and MEG's, *IEEE Trans. Biomed. Eng.* 40 (1) (1993) 42–48.
- [27] D.V. Moretti, F. Babiloni, F. Carducci, et al., Computerized processing of EEG-EOG-EMG artifacts for multi-centric studies in EEG oscillations and event-related potentials, *Int. J. Psychophysiol.* 47 (3) (2003) 199–216.
- [28] A. Schlogl, C. Keirath, D. Zimmermann, et al., A fully automated correction method of EOG artifacts in EEG recordings, *Clin. Neurophysiol.* 118 (1) (2007) 98–104.
- [29] I.I. Goncharova, D.J. McFarland, T.M. Vaughan, et al., EMG contamination of EEG: Spectral and topographical characteristics, *Clin. Neurophysiol.* 114 (9) (2003) 1580–1593.
- [30] H. Hinrichs, M. Scholz, A.K. Baum, et al., Comparison between a wireless dry electrode EEG system with a conventional wired wet electrode EEG system for clinical applications, *Sci. Rep.* 10 (1) (2020) 5218.
- [31] G.L. Li, S.Z. Wang, Y.W.Y. Duan, Towards conductive-gel-free electrodes: Understanding the wet electrode, semi-dry electrode and dry electrode-skin interface impedance using electrochemical impedance spectroscopy fitting, *Sens. Actuators B-Chem.* 277 (2018) 250–260.
- [32] G.B. Tsegahai, B. Malengier, K.A. Fante, et al., The status of textile-based dry Eeg electrodes, *Autex Res. J.* 21 (1) (2021) 63–70.
- [33] B.A. Taheri, R.T. Knight, R.T. Smith, A dry electrode for EEG recording, *Electroencephalogr. Clin. Neurophysiol.* 90 (5) (1994) 376–383.
- [34] X. Xing, Y. Wang, W. Pei, et al., A high-speed SSVEP-based BCI using dry EEG electrodes, *Sci. Rep.* 8 (1) (2018) 14708.
- [35] F. Popescu, S. Fazli, Y. Badower, et al., Single trial classification of motor imagination using 6 dry EEG electrodes, *PLoS One* 2 (7) (2007) e637.
- [36] R.X. Wang, X.M. Jiang, W. Wang, et al., A microneedle electrode array on flexible substrate for long-term EEG monitoring, *Sens. Actuators B-Chem.* 244 (2017) 750–758.
- [37] A.K. Srivastava, B. Bhartia, K. Mukhopadhyay, et al., Long term biopotential recording by body conformable photolithography fabricated low cost polymeric microneedle arrays, *Sens. Actuators A-Phys.* 236 (2015) 164–172.
- [38] G. Stavrinidis, K. Michelakis, V. Kontomitrou, et al., SU-8 microneedles based dry electrodes for Electroencephalogram, *Microelectron. Eng.* 159 (2016) 114–120.
- [39] S.P. Davis, B.J. Landis, Z.H. Adams, et al., Insertion of microneedles into skin: Measurement and prediction of insertion force and needle fracture force, *J. Biomech.* 37 (8) (2004) 1155–1163.
- [40] P. Griss, H.K. Tolvanen-Laakso, P. Merilainen, et al., Characterization of micro-machined spiked biopotential electrodes, *IEEE Trans. Biomed. Eng.* 49 (6) (2002) 597–604.
- [41] X. Guo, W. Pei, Y. Wang, et al., Developing a one-channel BCI system using a dry claw-like electrode, 2016 38th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC), IEEE, (2016). <https://ieeexplore.ieee.org/document/7592019>.
- [42] Y.J. Huang, C.Y. Wu, A.M. Wong, et al., Novel active comb-shaped dry electrode for EEG measurement in hairy site, *IEEE Trans. Biomed. Eng.* 62 (1) (2015) 256–263.
- [43] S. Lee, Y. Shin, A. Kumar, et al., Two-wired active spring-loaded dry electrodes for EEG measurements, *Sensors (Basel)* 19 (20) (2019) 4572.
- [44] F. Marini, C. Lee, J. Wagner, et al., A comparative evaluation of signal quality between a research-grade and a wireless dry-electrode mobile EEG system, *J. Neural Eng.* 16 (5) (2019) 054001.
- [45] P.T. Lin, K. Sharma, T. Holroyd, et al., A high performance MEG based BCI using single trial detection of human movement intention, in: *Functional Brain Mapping and the Endeavor to understand the Working Brain*, Intech Open, 2013, pp. 17–36.
- [46] S.T. Foldes, D.J. Weber, J.L. Collinger, MEG-based neurofeedback for hand rehabilitation, *J. Neuroeng. Rehabil.* 12 (1) (2015) 85.
- [47] D. Dash, A. Wisler, P. Ferrari, et al., MEG sensor selection for neural speech decoding, *IEEE Access* 8 (2020) 182320–182337.
- [48] J.S. Ebersole, S.M. Ebersole, Combining MEG and EEG source modeling in epilepsy evaluations, *J. Clin. Neurophysiol.* 27 (6) (2010) 360–371.
- [49] D. Pantazis, Imaging the human brain with Magnetoencephalography, in: *Medical Informatics: Concepts, Methodologies, Tools, and Applications*, IGI Global, 2009, pp. 881–889.
- [50] R. Hari, O.V. Lounasmaa, Recording and interpretation of cerebral magnetic fields, *Science* 244 (4903) (1989) 432–436.
- [51] R.A. Seymour, N. Alexander, S. Mellor, et al., Interference suppression techniques for OPM-based MEG: Opportunities and challenges, *Neuroimage* 247 (2022) 118834.
- [52] K. Sternickel, A.I. Braginski, Biomagnetism using SQUIDS: Status and perspectives, *Supercond. Sci. Technol.* 19 (3) (2006) S160–S171.
- [53] M.J. Brookes, J. Leggett, M. Rea, et al., Magnetoencephalography with optically pumped magnetometers (OPM-MEG): The next generation of functional neuroimaging, *Trends Neurosci.* 45 (8) (2022) 621–634.
- [54] U. Marhl, A. Jodko-Wladzinska, R. Brühl, et al., Comparison between conventional SQUID based and novel OPM based measuring systems in MEG, In *European Medical and Biological Engineering Conference*, Springer, 2020. doi:10.1007/978-3-030-64610-3_30.
- [55] X. Li, J. Chen, N. Shi, et al., A hybrid steady-state visually evoked response-based brain-computer interface with MEG and EEG, *Expert Syst. Appl.* (2023) 119736.
- [56] P. Pinti, I. Tachtsidis, A. Hamilton, et al., The present and future use of functional near-infrared spectroscopy (fNIRS) for cognitive neuroscience, *Ann. N.Y. Acad. Sci.* 1464 (1) (2020) 5–29.
- [57] N. Naseer, K.S. Hong, fNIRS-based brain-computer interfaces: A review, *Front. Hum. Neurosci.* 9 (2015) 3.
- [58] J. Zhang, X. Lin, G. Fu, et al., Mapping the small-world properties of brain networks in deception with functional near-infrared spectroscopy, *Sci. Rep.* 6 (1) (2016) 25297.
- [59] S. Coyle, T. Ward, C. Markham, et al., On the suitability of near-infrared (NIR) systems for next-generation brain-computer interfaces, *Physiol. Meas.* 25 (4) (2004) 815–822.
- [60] A. Abdalmalak, D. Milej, L.C.M. Yip, et al., Assessing time-resolved fNIRS for brain-computer interface applications of mental communication, *Front. Neurosci.* 14 (2020) 105.
- [61] V.V. Lychagov, V.V. Tuchin, M.A. Vilenky, et al., Experimental study of NIR transmittance of the human skull, *Proceedings SPIE*, (2006). doi:10.1117/12.650116.
- [62] G. Gratton, C.R. Brumback, B.A. Gordon, et al., Effects of measurement method, wavelength, and source-detector distance on the fast optical signal, *Neuroimage* 32 (4) (2006) 1576–1590.
- [63] S. Duschek, R. Schandry, Functional transcranial Doppler sonography as a tool in psychophysiological research, *Psychophysiology* 40 (3) (2003) 436–454.
- [64] M. Deppe, E.B. Ringelstein, S. Knecht, The investigation of functional brain lateralization by transcranial Doppler sonography, *Neuroimage* 21 (3) (2004) 1124–1146.
- [65] G.F. Meyer, A. Spray, J.E. Fairlie, et al., Inferring common cognitive mechanisms from brain blood-flow lateralization data: A new methodology for fTCD analysis, *Front. Psychol.* 5 (2014) 552.
- [66] A. Khalaf, E. Sejdic, M. Akcakaya, Hybrid EEG–fTCD Brain-computer interfaces, in: *Neuroergonomics*, Springer, 2020, pp. 295–314.
- [67] N.K. Logothetis, What we can do and what we cannot do with fMRI, *Nature* 453 (7197) (2008) 869–878.
- [68] N. Weiskopf, Real-time fMRI and its application to neurofeedback, *Neuroimage* 62 (2) (2012) 682–692.
- [69] M.S. Cohen, Real-time functional magnetic resonance imaging, *Methods* 25 (2) (2001) 201–220.
- [70] R.W. Cox, A. Jesmanowicz, J.S. Hyde, Real-time functional magnetic resonance imaging, *Magn. Reson. Med.* 33 (2) (1995) 230–236.
- [71] A.B. Bruhl, Making sense of real-time functional magnetic resonance imaging (rtfMRI) and rtfMRI neurofeedback, *Int. J. Neuropsychopharmacol.* 18 (6) (2015).
- [72] A. von Luhmann, H. Wabnitz, T. Sander, et al., M3BA: A mobile, modular, multi-modal biosignal acquisition architecture for miniaturized EEG-NIRS-based hybrid BCI and monitoring, *IEEE Trans. Biomed. Eng.* 64 (6) (2017) 1199–1210.
- [73] S. Ahn, S.C. Jun, Multi-modal integration of EEG-fNIRS for brain-computer interfaces - current limitations and future directions, *Front. Hum. Neurosci.* 11 (2017) 503.
- [74] M.U. Khan, M.A.H. Hasan, Hybrid EEG-fNIRS BCI fusion using multi-resolution singular value decomposition (MSVD), *Front. Hum. Neurosci.* 14 (2020) 599802.
- [75] A. Khalaf, M. Sybdon, E. Sejdic, et al., An EEG and fTCD based BCI for control, in: 2016 50th Asilomar Conference On Signals, Systems and Computers, IEEE, (2016). <https://ieeexplore.ieee.org/document/7869581>.
- [76] E. Dagois, A. Khalaf, E. Sejdic, et al., Transfer learning for a multimodal hybrid EEG-fTCD brain-computer interface, *IEEE Sens. Lett.* 3 (1) (2019) 1–4.
- [77] A. Faress, T. Chau, Towards a multimodal brain-computer interface: Combining fNIRS and fTCD measurements to enable higher classification accuracy, *Neuroimage* 77 (2013) 186–194.
- [78] S. Ruiz, M. Rana, K. Sass, et al., Brain network connectivity and behaviour enhancement: A fMRI-BCI study, 17th Annual Meeting of the Organization for Human Brain Mapping, 2011.
- [79] S.S. Yoo, T. Fairney, N.K. Chen, et al., Brain-computer interface using fMRI: Spatial navigation by thoughts, *Neuroreport* 15 (10) (2004) 1591–1595.
- [80] N. Weiskopf, K. Mathiak, S.W. Bock, et al., Principles of a brain-computer interface (BCI) based on real-time functional magnetic resonance imaging (fMRI), *IEEE Trans. Biomed. Eng.* 51 (6) (2004) 966–970.
- [81] K. Yuan, C. Chen, X. Wang, et al., BCI training effects on chronic stroke correlate with functional reorganization in motor-related regions: A concurrent EEG and fMRI Study, *Brain Sci.* 11 (1) (2021) 56.
- [82] W.-T. Wang, B. Xu, J.A. Butman, Improved SNR for combined TMS-fMRI: A support device for commercially available body array coil, *J. Neurosci. Methods* 289 (2017) 1–7.
- [83] J.W. Hole, *Human Anatomy and Physiology*, McGraw-Hill Science, Engineering & Mathematics, 1987. <https://lcn.loc.gov/80065515>.
- [84] Y. Sun, A. Shen, J. Sun, et al., Minimally invasive local-skull electrophysiological modification with piezoelectric drill, *IEEE Trans. Neural Syst. Rehabil. Eng.* 30 (2022) 2042–2051.

- [85] Y. Sun, A. Shen, C. Du, et al., A real-time non-implantation bi-directional brain-computer interface solution without stimulation artifacts, *IEEE Trans. Neural Syst. Rehabil. Eng.* (2023). <https://ieeexplore.ieee.org/document/10238732>.
- [86] Y. Li, S. Zeng, J. Hao, Non-invasive optical guided tumor metastasis/vessel imaging by using lanthanide nanoprobe with enhanced down-shifting emission beyond 1500nm, *ACS Nano* 13 (1) (2019) 248–259.
- [87] S. Zeng, H. Wang, W. Lu, et al., Dual-modal upconversion fluorescent/X-ray imaging using ligand-free hexagonal phase NaLuF₄:gd/Yb/Er nanorods for blood vessel visualization, *Biomaterials* 35 (9) (2014) 2934–2941.
- [88] S.J. Zeng, Z.G. Yi, W. Lu, et al., Simultaneous realization of phase/size manipulation, upconversion luminescence enhancement, and blood vessel imaging in multifunctional nanoprobes through transition metal Mn²⁺ doping, *Adv. Funct. Mater.* 24 (26) (2014) 4051–4059.
- [89] N. Hardy, A. Habib, T. Ivanov, et al., Neuro-SWARM(3): System-on-a-nanoparticle for wireless recording of brain activity, *IEEE Photon. Technol. Lett.* 33 (16) (2021) 900–903.
- [90] N. Hardy, A. Habib, T. Ivanov, et al., Electro-plasmonic nanoantennas for in vivo neural sensing, *CLEO: Applications and Technology*, Optica Publishing Group, 2022. <https://opg.optica.org/abstract.cfm?uri=CLEO-AT-2022-ATu4K.2>.
- [91] I. Posadas, S. Monteagudo, V. Cena, Nanoparticles for brain-specific drug and genetic material delivery, imaging and diagnosis, *Nanomedicine (Lond)* 11 (7) (2016) 833–849.
- [92] J.J. Norton, D.S. Lee, J.W. Lee, et al., Soft, curved electrode systems capable of integration on the auricle as a persistent brain-computer interface, *Proc. Natl. Acad. Sci. U.S.A.* 112 (13) (2015) 3920–3925.
- [93] S.L. Kappel, M.L. Rank, H.O. Toft, et al., Dry-contact electrode ear-EEG, *IEEE Trans. Biomed. Eng.* 66 (1) (2019) 150–158.
- [94] J.W. Ahn, Y. Ku, D.Y. Kim, et al., Wearable in-the-ear EEG system for SSVEP-based brain-computer interface, *Electron Lett.* 54 (7) (2018) 413–414.
- [95] C. Athavipach, S. Pan-Ngum, P. Israsena, A wearable in-ear EEG device for emotion monitoring, *Sensors (Basel)* 19 (18) (2019) 4014.
- [96] R. Kaveh, J. Doong, A. Zhou, et al., Wireless user-generic ear EEG, *IEEE Trans. Biomed. Circuits Syst.* 14 (4) (2020) 727–737.
- [97] D.H. Jeong, J. Jeong, In-Ear EEG based attention state classification using echo state network, *Brain Sci.* 10 (6) (2020) 321.
- [98] T.J. Oxley, N.L. Opie, S.E. John, et al., Minimally invasive endovascular stent-electrode array for high-fidelity, chronic recordings of cortical neural activity, *Nat. Biotechnol.* 34 (3) (2016) 320–327.
- [99] N. Opie, in: *The Stentrode TM Neural Interface System*, in *Brain-Computer Interface Research*, Springer, 2021, pp. 127–132.
- [100] K. Xu, T. Yu, Y. Yuan, et al., Current status of the application of intracranial venous sinus stenting, *Int. J. Med. Sci.* 12 (10) (2015) 780–789.
- [101] B.D. Elder, C.R. Goodwin, T.A. Kosztowski, et al., Venous sinus stenting is a valuable treatment for fulminant idiopathic intracranial hypertension, *J. Clin. Neurosci.* 22 (4) (2015) 685–689.
- [102] M.S. Teleg, M.E. Czep, M.A. Lazzaro, et al., Idiopathic intracranial hypertension. A systematic analysis of transverse sinus stenting, *Interv. Neurol.* 2 (3) (2013) 132–143.
- [103] N.L. Opie, N.R. van der Nagel, S.E. John, et al., Micro-CT and histological evaluation of an neural interface implanted within a blood vessel, *IEEE Trans. Biomed. Eng.* 64 (4) (2017) 928–934.
- [104] V.S. Polikov, P.A. Tresco, W.M. Reichert, Response of brain tissue to chronically implanted neural electrodes, *J. Neurosci. Methods* 148 (1) (2005) 1–18.
- [105] S.E. John, N.L. Opie, Y.T. Wong, et al., Signal quality of simultaneously recorded endovascular, subdural and epidural signals are comparable, *Sci. Rep.* 8 (1) (2018) 8427.
- [106] I.A. Forsyth, M. Dunston, G. Lombardi, et al., Evaluation of a minimally invasive endovascular neural interface for decoding motor activity, 2019 9th International IEEE/EMBS Conference on Neural Engineering (NER), IEEE, (2019). <https://ieeexplore.ieee.org/document/8717000>.
- [107] L. Leishangthem, P. SirDeshpande, D. Dua, et al., Dural venous sinus stenting for idiopathic intracranial hypertension: An updated review, *J. Neuroradiol.* 46 (2) (2019) 148–154.
- [108] S. Majidi, A. Fry, N. Harel, et al., LB009 Motor neuroprosthesis to restore motor control for the command of digital devices: An early feasibility study of safety in subjects with severe quadriplegia, *Br. Med. J. Publishing Group* (2022). doi:10.1136/neurintsurg-2022-SNIS.406.
- [109] G. Montaldo, A. Urban, E. Mace, Functional ultrasound neuroimaging, *Annu. Rev. Neurosci.* 45 (2022) 491–513.
- [110] E. Mace, G. Montaldo, I. Cohen, et al., Functional ultrasound imaging of the brain, *Nat. Methods* 8 (8) (2011) 662–664.
- [111] C. Rabut, S. Yoo, R.C. Hurt, et al., Ultrasound technologies for imaging and modulating neural Activity, *Neuron* 108 (1) (2020) 93–110.
- [112] T. Deffieux, C. Demene, M. Pernot, et al., Functional ultrasound neuroimaging: A review of the preclinical and clinical state of the art, *Curr. Opin. Neurobiol.* 50 (2018) 128–135.
- [113] B.J. Edelman, E. Mace, Functional ultrasound brain imaging: Bridging networks, neurons, and behavior, *Curr. Opin. Biomed. Eng.* 18 (2021) 100286.
- [114] S.L. Norman, D. Maresca, V.N. Christopoulos, et al., Single-trial decoding of movement intentions using functional ultrasound neuroimaging, *Neuron* 109 (9) (2021) 1554–1566 e1554.
- [115] A. Urban, C. Dussaux, G. Martel, et al., Real-time imaging of brain activity in freely moving rats using functional ultrasound, *Nat. Methods* 12 (9) (2015) 873–878.
- [116] P.F. Viana, J. Duun-Henriksen, M. Glasstetter, et al., 230 days of ultra long-term subcutaneous EEG: Seizure cycle analysis and comparison to patient diary, *Ann. Clin. Transl. Neurol.* 8 (1) (2021) 288–293.
- [117] J. Duun-Henriksen, T.W. Kjaer, D. Looney, et al., EEG signal quality of a subcutaneous recording system compared to standard surface electrodes, *J. Sens.* 2015 (2015) 1–9.
- [118] S. Weisdorf, S.W. Gangstad, J. Duun-Henriksen, et al., High similarity between EEG from subcutaneous and proximate scalp electrodes in patients with temporal lobe epilepsy, *J. Neurophysiol.* 120 (3) (2018) 1451–1460.
- [119] P.F. Viana, L.S. Remvig, J. Duun-Henriksen, et al., Signal quality and power spectrum analysis of remote ultra long-term subcutaneous EEG, *Epilepsia* 62 (8) (2021) 1820–1828.
- [120] W. Penfield, H. Jasper, *Epilepsy and the functional anatomy of the human brain*, in: *Neurology*, 4(6), Little, Brown & Company, 1954, p. 483.
- [121] W.J. Freeman, L.J. Rogers, M.D. Holmes, et al., Spatial spectral analysis of human electrocorticograms including the alpha and gamma bands, *J. Neurosci. Methods* 95 (2) (2000) 111–121.
- [122] M.W. Slutzky, L.R. Jordan, T. Krieg, et al., Optimal spacing of surface electrode arrays for brain-machine interface applications, *J. Neural Eng.* 7 (2) (2010) 26004.
- [123] T. Ball, M. Kern, I. Mutschler, et al., Signal quality of simultaneously recorded invasive and non-invasive EEG, *Neuroimage* 46 (3) (2009) 708–716.
- [124] W.J. Freeman, M.D. Holmes, B.C. Burke, et al., Spatial spectra of scalp EEG and EMG from awake humans, *Clin. Neurophysiol.* 114 (6) (2003) 1053–1068.
- [125] G. Schalk, E.C. Leuthardt, Brain-computer interfaces using electrocorticographic signals, *IEEE Rev. Biomed. Eng.* 4 (2011) 140–154.
- [126] B. Wittevrongel, E. Khachatryan, M.F. Hnazaee, et al., Decoding steady-state visual evoked potentials from electrocorticography, *Front. Neuroinform.* 12 (2018) 65.
- [127] C. Kapeller, K. Kamada, H. Ogawa, et al., An electrocorticographic BCI using code-based VEP for control in video applications: A single-subject study, *Front. Syst. Neurosci.* 8 (2014) 139.
- [128] P. Brunner, A.L. Ritaccio, J.F. Emrich, et al., Rapid communication with a “P300” matrix speller using electrocorticographic signals (ECoG), *Front. Neurosci.* 5 (2011) 5.
- [129] W. Wang, A.D. Degenhart, G.P. Sudre, et al., Decoding semantic information from human electrocorticographic (ECoG) signals, 2011 Annual International Conference of the IEEE Engineering in Medicine and Biology Society, IEEE, 2011. <https://ieeexplore.ieee.org/document/6091553>.
- [130] Q. Rabbani, G. Milsap, N.E. Crone, The potential for a speech brain-computer interface using chronic electrocorticography, *Neurotherapeutics* 16 (1) (2019) 144–165.
- [131] M.C. Schaeffer, T. Aksenova, Switching Markov decoders for asynchronous trajectory reconstruction from ECoG signals in monkeys for BCI applications, *J. Physiol. Paris* 110 (4 Pt A) (2016) 348–360.
- [132] G.K. Anumanchipalli, J. Chartier, E.F. Chang, Speech synthesis from neural decoding of spoken sentences, *Nature* 568 (7753) (2019) 493–498.
- [133] D. Manahan-Vaughan, *Handbook of in Vivo Neural Plasticity Techniques: A Systems Neuroscience Approach to the Neural Basis of Memory and Cognition*, Academic Press, 2018.
- [134] J. Vogel, S. Haddadin, J.D. Simeral, et al., Continuous control of the dlr light-weight robot iii by a human with tetraplegia using the braingate2 neural interface system, *Experimental Robotics*, Springer, 2014. https://link.springer.com/chapter/10.1007/978-3-642-28572-1_9.
- [135] E. Musk, Neuralink, An integrated brain-machine interface platform with thousands of channels, *J. Med. Internet Res.* 21 (10) (2019) e16194.
- [136] D. Seo, J.M. Carmena, J.M. Rabaey, et al., Neural dust: An ultrasonic, low power solution for chronic brain-machine interfaces. *arXiv preprint arXiv:1307.2196*. (2013). <https://doi.org/10.48550/arXiv.1307.2196>.
- [137] D. Seo, Neural Dust: Ultrasonic Biological Interface, UC Berkeley, 2016.
- [138] D. Seo, J.M. Carmena, J.M. Rabaey, et al., Model validation of untethered, ultrasonic neural dust motes for cortical recording, *J. Neurosci. Methods* 244 (2015) 114–122.
- [139] R.M. Neely, D.K. Piech, S.R. Santacruz, et al., Recent advances in neural dust: Towards a neural interface platform, *Curr. Opin. Neurobiol.* 50 (2018) 64–71.
- [140] D. Seo, R.M. Neely, K. Shen, et al., Wireless recording in the peripheral nervous system with ultrasonic neural dust, *Neuron* 91 (3) (2016) 529–539.
- [141] E.M. Maynard, C.T. Nordhausen, R.A. Normann, The Utah intracortical Electrode Array: A recording structure for potential brain-computer interfaces, *Electroencephalogr. Clin. Neurophysiol.* 102 (3) (1997) 228–239.
- [142] R.J. Vetter, J.C. Williams, J.F. Hetke, et al., Chronic neural recording using silicon-substrate microelectrode arrays implanted in cerebral cortex, *IEEE Trans. Biomed. Eng.* 51 (6) (2004) 896–904.
- [143] A.K. Vaskov, Z.T. Irwin, S.R. Nason, et al., Cortical decoding of individual finger group motions using ReFIT Kalman filter, *Front. Neurosci.* 12 (2018) 751.
- [144] M. Esghaei, M.R. Daliri, Decoding of visual attention from LFP signals of macaque MT, *PLoS ONE* 9 (6) (2014) e100381.
- [145] J.S. Brumberg, E.J. Wright, D.S. Andreasen, et al., Classification of intended phoneme production from chronic intracortical microelectrode recordings in speech-motor cortex, *Front. Neurosci.* 5 (2011) 65.
- [146] F.R. Willett, D.T. Avansino, L.R. Hochberg, et al., High-performance brain-to-text communication via handwriting, *Nature* 593 (7858) (2021) 249–254.
- [147] S.C.T. Colachis, C.F. Dunlap, N.V. Annetta, et al., Long-term intracortical microelectrode array performance in a human: A 5 year retrospective analysis, *J. Neural Eng.* 18 (4) (2021) 0460d0467.
- [148] T. Milekovic, A.A. Sarma, D. Bacher, et al., Stable long-term BCI-enabled communication in ALS and locked-in syndrome using LFP signals, *J. Neurophysiol.* 120 (7) (2018) 343–360.
- [149] R.A. Andersen, S. Musallam, B. Pesaran, Selecting the signals for a brain-machine interface, *Curr. Opin. Neurobiol.* 14 (6) (2004) 720–726.

- [150] S. Guan, J. Wang, X. Gu, et al., Elastocapillary self-assembled neurotassels for stable neural activity recordings, *Sci. Adv.* 5 (3) (2019) eaav2842.
- [151] Z. Zhao, X. Li, F. He, et al., Parallel, minimally-invasive implantation of ultra-flexible neural electrode arrays, *J. Neural Eng.* 16 (3) (2019) 035001.
- [152] S. Zhao, G. Li, C. Tong, et al., Full activation pattern mapping by simultaneous deep brain stimulation and fMRI with graphene fiber electrodes, *Nat. Commun.* 11 (1) (2020) 1788.
- [153] Y. Zhou, C. Gu, J. Liang, et al., A silk-based self-adaptive flexible opto-electro neural probe, *Microsyst. Nanoeng.* 8 (1) (2022) 118.
- [154] J. Bartels, D. Andreasen, P. Ehirim, et al., Neurotrophic electrode: Method of assembly and implantation into human motor speech cortex, *J. Neurosci. Methods* 174 (2) (2008) 168–176.
- [155] M. Gearing, P. Kennedy, Histological confirmation of myelinated neural filaments within the tip of the Neurotrophic Electrode after a decade of neural recordings, *Front. Hum. Neurosci.* 14 (2020) 111.
- [156] J. Parvizi, S. Kastner, Promises and limitations of human intracranial electroencephalography, *Nat. Neurosci.* 21 (4) (2018) 474–483.
- [157] L. Koessler, T. Cecchin, S. Colnat-Coulbois, et al., Catching the invisible: Mesial temporal source contribution to simultaneous EEG and SEEG recordings, *Brain Topogr.* 28 (1) (2015) 5–20.
- [158] F. Chassoux, V. Navarro, H. Catenioix, et al., Planning and management of SEEG, *Neurophysiol. Clin.* 48 (1) (2018) 25–37.
- [159] A. Granados, V. Vakharia, R. Rodionov, et al., Automatic segmentation of stereo-electroencephalography (SEEG) electrodes post-implantation considering bending, *Int. J. Comput. Assist. Radiol. Surg.* 13 (6) (2018) 935–946.
- [160] K. Meng, D.B. Grayden, M.J. Cook, et al., Identification of discriminative features for decoding overt and imagined speech using stereotactic electroencephalography, 2021. 9th International Winter Conference on Brain-Computer Interface (BCI), IEEE, (2021). <https://ieeexplore.ieee.org/document/9385355>.
- [161] G. Li, S. Jiang, Y. Xu, et al., A preliminary study towards prosthetic hand control using human stereo-electroencephalography (SEEG) signals, 2017 8th International IEEE/EMBS Conference on Neural Engineering (NER), IEEE, (2017). <https://ieeexplore.ieee.org/document/8008368>.
- [162] B. Dutta, A. Andrei, T. Harris, et al., The Neuropixels probe: A CMOS based integrated microsystems platform for neuroscience and brain-computer interfaces, 2019 IEEE International Electron Devices Meeting (IEDM), IEEE, (2019). <https://ieeexplore.ieee.org/document/8993611>.
- [163] N.A. Steinmetz, C. Koch, K.D. Harris, et al., Challenges and opportunities for large-scale electrophysiology with Neuropixels probes, *Curr. Opin. Neurobiol.* 50 (2018) 92–100.
- [164] A.C. Paulk, Y. Kfir, A.R. Khanna, et al., Large-scale neural recordings with single neuron resolution using Neuropixels probes in human cortex, *Nat. Neurosci.* 25 (2) (2022) 252–263.
- [165] T.Z. Luo, A.G. Bondy, D. Gupta, et al., An approach for long-term, multi-probe Neuropixels recordings in unrestrained rats, *Elife* 9 (2020) e59716.
- [166] J.E. Chung, K.K. Sellers, M.K. Leonard, et al., High-density single-unit human cortical recordings using the Neuropixels probe, *Neuron* 110 (15) (2022) 2409–2421 e2403.
- [167] N.A. Steinmetz, C. Aydin, A. Lebedeva, et al., Neuropixels 2.0: A miniaturized high-density probe for stable, long-term brain recordings, *Science* 372 (6539) (2021) eabf4588.
- [168] Y. Chen, G. Zhang, L. Guan, et al., Progress in the development of a fully implantable brain-computer interface: The potential of sensing-enabled neurostimulators, *Natl. Sci. Rev.* 9 (10) (2022) nwac099.
- [169] M.J. Vansteensel, E.G.M. Pels, M.G. Bleichner, et al., Fully implanted brain-computer interface in a locked-in patient with ALS, *N. Engl. J. Med.* 375 (21) (2016) 2060–2066.
- [170] E.G.M. Pels, E.J. Aarnoutse, S. Leinders, et al., Stability of a chronic implanted brain-computer interface in late-stage amyotrophic lateral sclerosis, *Clin. Neurophysiol.* 130 (10) (2019) 1798–1803.
- [171] I. Cajigas, K.C. Davis, B. Meschede-Krasa, et al., Implantable brain-computer interface for neuroprosthetic-enabled volitional hand grasp restoration in spinal cord injury, *Brain Commun.* 3 (4) (2021) fcab248.
- [172] J.A. Herron, M.C. Thompson, T. Brown, et al., Cortical brain-computer interface for closed-loop deep brain stimulation, *IEEE Trans. Neural Syst. Rehabil. Eng.* 25 (11) (2017) 2180–2187.
- [173] S. Palagi, P. Fischer, Bioinspired microrobots, *Nat. Rev. Mater.* 3 (6) (2018) 113–124.
- [174] Y. Zhang, Y. Zhang, Y. Han, et al., Micro/Nanorobots for medical diagnosis and disease treatment, *Micromachines* (Basel) 13 (5) (2022) 648.
- [175] F. Soto, J. Wang, R. Ahmed, et al., Medical micro/nanorobots in precision medicine, *Adv. Sci. (Weinh)* 7 (21) (2020) 2002203.
- [176] W. Xi, A.A. Solovev, A.N. Ananth, et al., Rolled-up magnetic microdrillers: Towards remotely controlled minimally invasive surgery, *Nanoscale* 5 (4) (2013) 1294–1297.
- [177] F. Soto, A. Martin, S. Ibsen, et al., Acoustic microcannons: Toward advanced microballistics, *ACS Nano* 10 (1) (2016) 1522–1528.
- [178] S. Jafari, L.O. Mair, I.N. Weinberg, et al., Magnetic drilling enhances intra-nasal transport of particles into rodent brain, *J. Magn. Magn. Mater.* 469 (2019) 302–305.
- [179] Y. Chen, J. Zhang, X. Liu, et al., *Noninvasive in vivo 3D bioprinting*, *Sci. Adv.* 6 (23) (2020) eaba7406.
- [180] M.J. Rodriguez, J. Brown, J. Giordano, et al., Silk based bioinks for soft tissue reconstruction using 3-dimensional (3D) printing with in vitro and in vivo assessments, *Biomaterials* 117 (2017) 105–115.
- [181] B. Sha, S. Zhao, M. Gu, et al., Doping-induced assembly interface for noninvasive in vivo local and systemic immunomodulation, *Proc. Natl. Acad. Sci.* 120 (49) (2023) e2306777120.
- [182] X. Strakosas, H. Biesmans, T. Abrahamsson, et al., Metabolite-induced in vivo fabrication of substrate-free organic bioelectronics, *Science* 379 (6634) (2023) 795–802.
- [183] J.A. Goding, A.D. Gilmour, U.A. Aregueta-Robles, et al., Living bioelectronics: Strategies for developing an effective long-term implant with functional neural connections, *Adv. Funct. Mater.* 28 (12) (2018) 1702969.
- [184] M.D. Serruya, J.P. Harris, D.O. Adewole, et al., Engineered axonal tracts as “living electrodes” for synaptic-based modulation of neural circuitry, *Adv. Funct. Mater.* 28 (12) (2018) 1701183.
- [185] J. Prox, B. Seicol, H. Qi, et al., Toward living neuroprosthetics: Developing a biological brain pacemaker as a living neuromodulatory implant for improving parkinsonian symptoms, *J. Neural Eng.* 18 (4) (2021) 046081.
- [186] L. Stratchko, I. Filatova, A. Agarwal, et al., The ventricular system of the brain: Anatomy and normal variations, *Seminars in Ultrasound, CT and MRI*, Elsevier, 2016, doi:10.1053/j.sult.2016.01.004.
- [187] A.M. Tucker, P.J. Madsen, G.G. Heuer, Ventricular shunts for hydrocephalus, in: *Fundamentals of Pediatric Surgery*, Springer, 2022, pp. 805–810.
- [188] S.L. DeVos, T.M. Miller, Direct intraventricular delivery of drugs to the rodent central nervous system, *J. Vis. Exp.* (75) (2013) e50326.
- [189] D.S. Hersh, A.S. Wadajkar, N.B. Roberts, et al., Evolving drug delivery strategies to overcome the blood brain barrier, *Curr. Pharm. Design* 22 (9) (2016) 1177–1193.
- [190] J.J. Shih, D.J. Krusienski, Signals from intraventricular depth electrodes can control a brain-computer interface, *J. Neurosci. Methods* 203 (2) (2012) 311–314.
- [191] S. Shipp, Structure and function of the cerebral cortex, *Curr. Biol.* 17 (12) (2007) R443–R449.
- [192] D.L. Cuesta, A.F.G. Rivera, J.S.M. Borrero, Interfaz BCIE (brain computer interface educational) en Raspberry Pi utilizando sensor neurosky, 2020 15th Iberian Conference On Information Systems and Technologies (CISTI), IEEE, 2020. <https://ieeexplore.ieee.org/document/9141128>.
- [193] B. van de Laar, H. Gurkok, D. Plass-Oude Bos, et al., Experiencing BCI control in a popular computer game, *IEEE Trans. Comput. Intell. AI Games* 5 (2) (2013) 176–184.
- [194] M. Li, F. Li, J. Pan, et al., The MindGomoku: An online P300 BCI game based on bayesian deep learning, *Sensors* (Basel) 21 (5) (2021) 1613.
- [195] H. Serby, E. Yom-Tov, G.F. Inbar, An improved P300-based brain-computer interface, *IEEE Trans. Neural Syst. Rehabil. Eng.* 13 (1) (2005) 89–98.
- [196] K.K. Ang, K.S.G. Chua, K.S. Phua, et al., A randomized controlled trial of EEG-based motor imagery brain-computer interface robotic rehabilitation for stroke, *Clin. EEG Neurosci.* 46 (4) (2015) 310–320.
- [197] P. Trujillo, A. Mastrogiorgio, A. Scano, et al., Quantitative EEG for predicting upper limb motor recovery in chronic stroke robot-assisted rehabilitation, *IEEE Trans. Neural Syst. Rehabil. Eng.* 25 (7) (2017) 1058–1067.
- [198] L.C. Jameson, T.B. Sloan, Using EEG to monitor anesthesia drug effects during surgery, *J. Clin. Monit. Comput.* 20 (2006) 445–472.
- [199] G.A. Dumont, Closed-loop control of anesthesia—a review, *IFAC Proc.* 45 (18) (2012) 373–378.
- [200] L. Besedovsky, H.-V.V. Ngo, S. Dimitrov, et al., Auditory closed-loop stimulation of EEG slow oscillations strengthens sleep and signs of its immune-supportive function, *Nat. Commun.* 8 (1) (2017) 1984.
- [201] M.L. Ferster, C. Lustenberger, W. Karlen, Configurable mobile system for autonomous high-quality sleep monitoring and closed-loop acoustic stimulation, *IEEE Sens. Lett.* 3 (5) (2019) 1–4.
- [202] B.T. Jap, S. Lal, P. Fischer, et al., Using EEG spectral components to assess algorithms for detecting fatigue, *Expert Syst. Appl.* 36 (2) (2009) 2352–2359.
- [203] J. Xu, B. Zhong, Review on portable EEG technology in educational research, *Comput. Hum. Behav.* 81 (2018) 340–349.
- [204] A.A. Fingelkurts, A.A. Fingelkurts, T. Kallio-Tamminen, EEG-guided meditation: A personalized approach, *J. Physiol.-Paris* 109 (4–6) (2015) 180–190.
- [205] D. Monteiro, H.-N. Liang, A. Abel, et al., Evaluating engagement of virtual reality games based on first and third person perspective using EEG and subjective metrics, 2018 IEEE International Conference on Artificial Intelligence and Virtual Reality (AIVR), IEEE, (2018). <https://ieeexplore.ieee.org/document/8613634>.
- [206] J. Heo, G. Yoon, EEG studies on physical discomforts induced by virtual reality gaming, *J. Electr. Eng. Technol.* 15 (2020) 1323–1329.
- [207] A.L. Benabid, T. Costecalde, A. Eliseyev, et al., An exoskeleton controlled by an epidural wireless brain-machine interface in a tetraplegic patient: A proof-of-concept demonstration, *Lancet Neurol.* 18 (12) (2019) 1112–1122.
- [208] S.Y. Gordleeva, S.A. Lobov, N.A. Grigorev, et al., Real-time EEG-EMG human-machine interface-based control system for a lower-limb exoskeleton, *IEEE Access* 8 (2020) 84070–84081.
- [209] F.A. Al-Nuaimi, R.J. Al-Nuaimi, S.S. Al-Dhaheri, et al., Mind drone chasing using EEG-based brain computer interface, 2020 16th International Conference On Intelligent Environments (IE), IEEE, (2020). <https://ieeexplore.ieee.org/document/9154926>.
- [210] T.W. Shi, H. Wang, C. Zhang, Brain Computer Interface system based on indoor semi-autonomous navigation and motor imagery for Unmanned Aerial Vehicle control, *Expert Syst. Appl.* 42 (9) (2015) 4196–4206.
- [211] M.S. Willsey, S.R. Nason-Tomaszewski, S.R. Ensel, et al., Real-time brain-machine interface in non-human primates achieves high-velocity prosthetic finger movements using a shallow feedforward neural network decoder, *Nat. Commun.* 13 (1) (2022) 6899.
- [212] G.R. Muller-Putz, G. Pfurtscheller, Control of an electrical prosthesis with an SSVEP-based BCI, *IEEE Trans. Biomed. Eng.* 55 (1) (2008) 361–364.
- [213] M.J. Vansteensel, E. Klein, G. van Thiel, et al., Towards clinical application of implantable brain-computer interfaces for people with late-stage ALS: Medical and ethical considerations, *J. Neurol.* 270 (3) (2023) 1323–1336.

- [214] J.R. Wolpaw, D.J. McFarland, T.M. Vaughan, Brain-computer interface research at the Wadsworth Center, *IEEE Trans. Rehab. Eng.* 8 (2) (2000) 222–226.
- [215] S. Leinders, M.J. Vansteensel, M.P. Branco, et al., Dorsolateral prefrontal cortex-based control with an implanted brain–computer interface, *Sci. Rep.* 10 (1) (2020) 15448.
- [216] P. Romanelli, M. Piangerelli, D. Ratel, et al., A novel neural prosthesis providing long-term electrocorticography recording and cortical stimulation for epilepsy and brain-computer interface, *J. Neurosurg.* 130 (4) (2018) 1166–1179.
- [217] M. Arlotti, M. Colombo, A. Bonfanti, et al., A new implantable closed-loop clinical neural interface: First application in Parkinson's disease, *Front. Neurosci.* 15 (2021) 763235.
- [218] X. Zhang, Z. Ma, H. Zheng, et al., The combination of brain-computer interfaces and artificial intelligence: Applications and challenges, *Ann. Transl. Med.* 8 (11) (2020) 712.
- [219] Z. Cao, A review of artificial intelligence for EEG-based brain–computer interfaces and applications, *Brain Sci. Adv.* 6 (3) (2020) 162–170.
- [220] M. Reisert, B.E. Sajonz, T.S. Brugger, et al., Where position matters—deep-learning-driven normalization and coregistration of computed tomography in the postoperative analysis of deep brain stimulation, *Neuromodul.: Technol. Neural Interface* 26 (2) (2023) 302–309.
- [221] T. Martin, M. Peralta, G. Gilmore, et al., Extending convolutional neural networks for localizing the subthalamic nucleus from micro-electrode recordings in Parkinson's disease, *Biomed. Signal. Process Control* 67 (2021) 102529.
- [222] J. Li, K. Lim, H. Yang, et al., AI applications through the whole life cycle of material discovery, *Matter* 3 (2) (2020) 393–432.
- [223] S.R. Kalidindi, Feature engineering of material structure for AI-based materials knowledge systems, *J. Appl. Phys.* 128 (4) (2020) 041103.
- [224] A.V. Singh, D. Rosenkranz, M.H.D. Ansari, et al., Artificial intelligence and machine learning empower advanced biomedical material design to toxicity prediction, *Adv. Intell. Syst.* 2 (12) (2020) 2000084.

Author profile

Yike Sun is a doctorate student at the Department of Biomedical Engineering, Tsinghua University School of Medicine. He is a recipient of the National Scholarship for Chinese Graduate Students.

Xiaogang Chen (BRID: 05793.00.10507) graduated from the Department of Biomedical Engineering of Tsinghua University. He is currently an associate researcher at the Institute of Biomedical Engineering, Chinese Academy of Medical Sciences.

Xiaorong Gao (BRID: 09138.00.59233) is a professor in the School of Medicine at Tsinghua University. He is the main founder of the discipline of neural engineering and brain-computer interface in China.