

CORRECTION

Correction: Adaptive Robotic Control Driven by a Versatile Spiking Cerebellar Network

The *PLOS ONE* Staff

The URL that links to the computational models is incorrect in both the Data Availability statement and in the Methods section. The correct link to access the data is: <http://senselab.med.yale.edu/modeldb/ShowModel.asp?model=167414>.

Reference

1. Casellato C, Antonietti A, Garrido JA, Carrillo RR, Luque NR, et al. (2014) Adaptive Robotic Control Driven by a Versatile Spiking Cerebellar Network. *PLoS ONE* 9(11): e112265. doi: [10.1371/journal.pone.0112265](https://doi.org/10.1371/journal.pone.0112265) PMID: [25390365](https://pubmed.ncbi.nlm.nih.gov/25390365/)



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