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OPEN Electric-field-induced alignment of electrically neutral disk-like particles: modelling and calculation

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This work reveals a torque from electric field to electrically neutral flakes that are suspended in a higher electrical conductive matrix. The torque tends to rotate the particles toward an orientation with its long axis parallel to the electric current flow. The alignment enables the anisotropic properties of tiny particles to integrate together and generate desirable macroscale anisotropic properties. The torque was obtained from thermodynamic calculation of electric current free energy at various microstructure configurations. It is significant even when the electrical potential gradient becomes as low as 100 v/m. The changes of electrical, electroplastic and thermal properties during particles alignment were discussed.

Alignment of anisotropic particles toward desirable orientation has been a hot research topic for many decades¹⁻⁹. This has two levels of implementations: The first is to align the particles to generate static anisotropic structural or functional properties. Another is to align the particles dynamically so that the anisotropic microstructure and properties can be switched promptly. A giant torque is required for achieving both fast switch and the effective fabrication.

It is known that tiny particles have their outside morphology inherited from their crystal anisotropic nature¹. The anisotropic shape particles possess favourable anisotropic properties². Randomly packed anisotropic particles, however, would wipe out the desirable anisotropic functionalities due to the statistical average. Aligned microstructures are able to integrate the microscopic anisotropy into useful macroscopic anisotropic properties. The later has many advanced engineering applications^{3, 4}. For examples, aligned carbon nanotubes are being considered in nerve repairing and tissue regeneration⁵. Aligned nanostructures are desirable in electro-optical switching and memory electronics^{6,7}. Alignable graphene have been pursued for display devices^{4,8,9}.

There are three ways to align anisotropic particles, namely the mechanical stress, electric fields and magnetic fields. Mechanical alignment is a general method that is applicable to most situations 10, 11. But it has disadvantages including the operation complexity and possible damage to the targeted particles. The electric field and magnetic field methods are easier to manipulate than the mechanical one^{4, 12}. Magnetic method makes use of the particles magnetic properties caused by magnetic response of orbit electrons. High magnetic fields are usually required in the alignment processing 13, 14. Application of electric field to manipulate electrically neutral particles has been investigated since 1950s. Kolin pointed out that the particles with different electrical conductivities can be separated using an electric field plus an additional cross magnetic field¹⁵. This has been developed into a major technology for separation of different types of biological cells in blood, and has wide applications in separation of materials according to their electrical properties¹⁶. The mechanism is called electromagnetophoresis. Pohl proved that a non-uniform electric field could be implemented to manipulate dielectric particles¹⁷. The mechanism is called electrophoresis and has been used intensively in biomedical applications such as to processing bacteria and target cells¹⁸. It is found that direct current electric field drives multiwall carbon nanotubes move toward negative electrode and alternating current electric field can align the nanotubes in liquid solutions¹². Our previous researches shown that electric field can drive spherical particles to move toward a wall from the inner position in liquid metal¹⁹ and can drive graphene nanoflakes to move toward the negative electrode²⁰. It is also demonstrated recently that electric field can help to breakup droplets into fine particles²¹ and rotate crystals' orientation²². The aim of the present work was to find out a mechanism to use electric field to align disc-like particles. This is to be proved in a way completely different from that of dielectrophoresis. Electric current has percolation effect, which means that electric current flows along a lowest resistance route. The hypothesis of the present work concerns a

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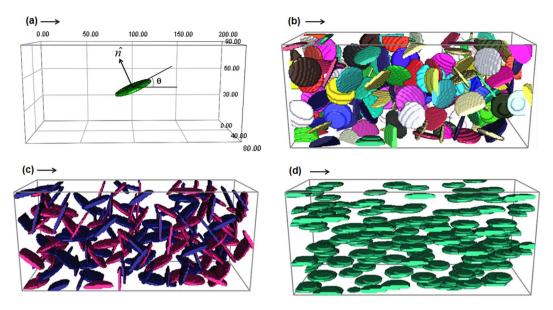


Figure 1. Ellipsoidal particles suspended in the matrix of dimension $200 \times 90 \times 80$ grids. An arrow in each figure represents the direction of applied electric field. The eccentricity for all ellipsoidal particles is 0.1. (a) Only one particle submerged in the matrix with angle of inclination θ to electric field direction and the normal vector \hat{n} ; (b) 173 ellipsoidal particles with random orientation; (c) 173 particles with some extents of preferred orientation toward vertical direction; (d) 173 aligned particles along current flow direction.

reciprocal question, i.e. can electric current help to change the microstructure and to generate a lowest resistivity route in a multiphase material?

Results

The resistance of a material containing anisotropic particles is dependent on the orientation of particles if the resistivity of particles is different from that of the matrix. The classic linear law of mixture for materials resistivity does not suitable for the anisotropic microstructure. This work is to consider the disc-like particles suspended in a matrix. We use thin and round ellipsoidal particles to represent the disc-like particles. The system is illustrated in Fig. 1. Figure 1(a) contains only one particle, which is inclined by θ degrees from the current flow direction. \hat{n} is the normal direction of the disc. The particle is perpendicular to the current flow direction when $\theta = 90^{\circ}$ and is parallel when $\theta = 0^{\circ}$. To prove that electric current tends to rotate the disc-like particles from $\theta = 90^{\circ}$ to $\theta = 0^{\circ}$, one needs to illustrate that the rotation reduces system free energy. In the present case, a pure rotation does not change the volume fraction of particles or matrix. The chemical free energy remains the same during rotation. The total system surface energy is also not changed due to nonexistence of coalesce and breakup. Hence the change of system free energy during particle rotation contains only the change of electric current free energy (G_e). The second law of thermodynamics for Fig. 1(a) is hence expressed as

$$\frac{\delta G_e}{\delta \theta} \le 0$$
 (1)

where G_e is the electric current free energy, which takes following expression in a static state approximation²⁴.

$$G_e = -\frac{1}{8\pi} \iint \frac{\mu(r)\vec{j}_{\theta}(r') \cdot \vec{j}_{\theta}(r)}{|r - r'|} dr dr'$$
(2)

where $\mu(r)$ is the local magnetic permeability at a position r. $\vec{j_{\theta}}(r)$ is the local electric current density when the particle incline angle is θ . Denoting the electrical conductivity and magnetic permeability of particle by σ_p and μ_p and that of matrix by σ_m and μ_m respectively, the different values of θ cause different spatial distributions of electrical and magnetic properties in the system. This will again cause different electric current density distributions in the system, which leads to different values of electric current free energy according to Eq. (2).

The analytical solution for current density distribution in Fig. 1 is not possible to obtain by solving Maxwell equations. Numerical calculations have been carried out instead. A logistic frame with $200 \times 90 \times 80$ cubic lattice has been implemented in the present work. In construction of microstructure, an nucleus was introduced in the centre of the logistic frame and then to grow with a velocity $\vec{v} = \hat{v}_x + 0.1\hat{v}_y + \hat{v}_z$. The anisotropic growth rate enables the introduced ellipsoidal geometry with eccentricity of 0.1. The dimension of velocity was 1 lattice distance per time step. The growth in Fig. 1(a) was stopped when the volume of ellipsoidal particle reaches 4500 grids. This gives the volume fraction of particle around 0.3%. A 3×3 Euler angles rotation matrix is then applied to the particle so that the desirable value θ is generated.

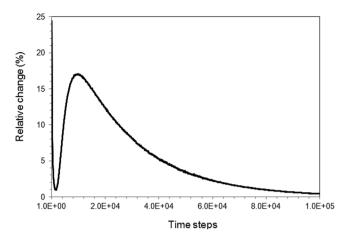


Figure 2. The convergence of relaxation method in the calculation of current density distribution.

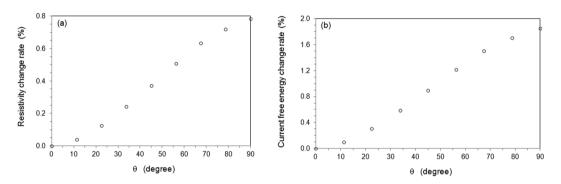


Figure 3. Property changes during the rotation of ellipsoidal particle. (a) Change of apparent electrical resistivity of system; (b) Change of apparent electric current free energy.

One applies V = 20 volts electrical potential along the longest dimension of cuboid logistic frame. Without losing generality but for the convenience of experimental validation, one uses $\sigma_m = 9.17 \times 10^6 \, \text{S} \cdot \text{m}^{-1}$ and $\mu_m = 300 \,\mu_0$, where $\mu_0 = 1.26 \times 10^{-6} \, \text{N} \cdot \text{A}^{-2}$ is the vacuum permeability²⁵⁻²⁸. These parameters are taken from the corresponding properties of ferrite iron. The properties of ellipsoidal particle are assumed to be $\sigma_p = 1.22 \times 10^6 \, \text{S} \cdot \text{m}^{-1}$ and $\mu_p = 30 \, \mu_0^{25-28}$. These are selected after the references of Fe₃C cementite particles. The electrical resistivity of interface is assumed to have the average value between that of the adjacent phases. This is equivalent to a Stephan sharp interface approximation so that the resistance is equivalent to that of the serial connection between two resistors. The distribution of electric current density is calculated using Kirchhoff's circuit laws. In the calculation, non-dimensionalization was performed to the parameters using $\widetilde{j}=j/j_0=j[\Delta x_0/(V_0\sigma_0)], \widetilde{\sigma}=\sigma/\sigma_0, \widetilde{x}=x/x_0, \widetilde{V}=V/V_0 \text{ and } \widetilde{T}=T/T_0=T[\Delta x^2\rho c/V_0^2\sigma_0\Delta t], \text{ where } \Delta x_0 \text{ is the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } \rho \text{ and } c \text{ are the grid distance of logistic frame, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric current load duration, } V_0=1 volt, \sigma_0=10^7 \text{ S} \cdot m^{-1}, \Delta t \text{ is the electric curren$ mass density and specific heat of local phase, respectively. A relaxation method has been applied to calculate the current density distribution. The initial condition was set as $\widetilde{V}=20$ at the left boundary of frame and $\widetilde{V}_{iik}=0$ at all the rest grids with grid coordinates (i, j, k) in three-dimensional system. The direction of the applied electric field is illustrated in Fig. 1. During calculation, the values of relativity change was calculated by $(\sum_{ijk} \widetilde{V}_{ijk}^{t+1} - \sum_{ijk} \widetilde{V}_{ijk}^{t})/\sum_{ijk} \widetilde{V}_{ijk}^{t} \cdot 100\%$. Its value has been recorded, as shown in Fig. 2 as a typical trend. The steady state distribution of electric current is considered to be achieved when the relativity change of electrical potential across the logistic frame is less than $10^{-5\%}$. The electric current free energy was calculated according to the steady state electric current. One thing to be pointed out is that all the calculations are based on static approximation. The non-equilibrium effect, such as skin effect has not been taken into account.

The numerical calculation is able to provide electrical resistance of the system for various microstructural configurations. Figure 3(a) shows the θ -dependent resistance for Fig. 1(a). When the decline angle of particle changes from 0 to 90°, the apparent resistivity $(\widetilde{R}_{\theta} - \widetilde{R}_{\theta=0})/\widetilde{R}_{\theta=0} = (\widetilde{\rho}_{\theta} - \widetilde{\rho}_{\theta=0})/\widetilde{\rho}_{\theta=0})$ increases by 0.8%. where $\widetilde{\rho}_{\theta}$ is the average resistivity for θ . Giving the volume fraction of particle is 0.3 only, the change of electrical resistivity during the rotation of the anisotropic particle is significant. An anisotropic particle with higher eccentricity ratio will contribute even more. The result shows that the orientation of suspended particles to the electrical properties is considerable. This is different from the classic linear law of mixture²³. In fact, the orientation of anisotropic particles affects many other properties such as flow permeability²⁹, optical³⁰, and others^{31,32}.

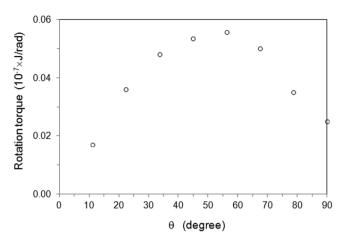


Figure 4. The electric-current-induced torque is dependent on the incline angle.

Figure 3(b) shows the change of apparent electric current free energy $(\widetilde{G}_e^{\theta} - G_e^{\theta=0})/\widetilde{G}_e^{\theta=0}$ when the incline angle reduces from 90° to 0°. It shows that the electric current free energy decreases monotonically when the ellipsoid particle rotates toward the alignment along electric current direction. Eq. (1) is satisfied for the rotation. The disc-like particle will be aligned toward the direction parallel to that of the electric current in order to reduce electric current free energy.

As is known, the reduction of free energy can be used to do work. It has $-G_e = \tau \theta$ for rotation, where τ is torque. The electric-current-induced torque for rotation has been calculated according to change of electric current free energy during particle rotation. The results for $\Delta x = 10^{-8} \, m$ are plotted in Fig. 4. The value of torque is in a magnitude of 10^{-9} J/rad. To illustrate the contribution of this torque to the rotation of a disc-like particle, one uses the density of cementite of $d = 7730.14 \, kg/m^3$ and get the moment of inertia as $I = \sum_i m_i r_i^2 = 2.88 \times 10^{-31} \, kg \cdot m^2$. This gives an angular acceleration without consideration of viscosity in a magnitude of $10^{21} \, \text{rad/s}^2$, which is very large. The angular acceleration is proportional to the square of voltage potential gradient. Even if the electrical potential reduces from the present value of $10^7 \, v/m$ to $100 \, v/m$, the torque can still generate an angular acceleration of $10^{11} \, \text{rad/s}^2$, which is still significantly large. This is in agreement with experimental observations³³.

It should be pointed out that rotating a disc-like particle to a direction parallel to the current flow direction does not mean the normal direction (see in Figure 1(a)) of all particles to point toward the same direction. In order to align the normal direction of plates to desirable direction, subsequent electric current processes are required. For example, rotating the sample around a vertical axis by 90° and then subjected to the electric potential would help to further align the particles' normal direction and to achieve a state of Fig. 1(d).

Apart from the change of electrical conductivity during the rotation and alignment of anisotropic particles, other properties such as electroplascity, electromigration and Ohm heat distributions change as well. Figure 5(a) and (c) plot the apparent current density distribution for incline angles at 0 and 90°, respectively. The current density inside the particle is lower than that of the matrix due to its high electrical resistivity and is dependent on the orientation of particles. Electroplasticity and electromigration effects are dependent on the local electric current density. Figure 5(b) and (d) are apparent Ohm-heat-induced temperature distribution when the incline angles are 0 and 90°, respectively. The apparent temperature inside the particle is higher than that of the matrix when $\theta = 90^\circ$ but is lower than that of the matrix when $\theta = 90^\circ$. The distribution changes smoothly during the rotation. The scale of temperature is in a dimension of $V_0^2 \sigma_0 \Delta t / (\Delta x^2 \rho c)$.

Discussion

The derivation of the rotation torque in the present work is based on thermodynamic consideration and calculation. This is different from that of deriving electromagnetophoresis¹⁵ and dielectrophoresis¹⁸. Electromagnetophoresis was derived by considering the change of force on a spherical particle when it moves across an electric current and a homogeneous magnetic field which is perpendicular to the electric current ^{15, 16}. The dielectrophoresis was derived by replacing a portion of spherical medium with material of different permittivity, which is equivalent to introduce a dipole moment into an electric field^{17, 18}. Both theories were based on dynamic considerations and have not included the anisotropic particles. This work does not include a magnetic

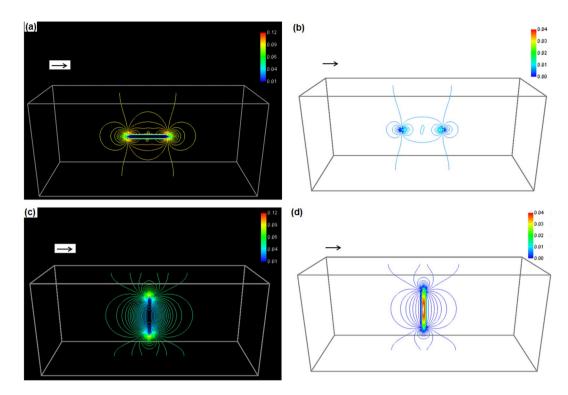


Figure 5. Distribution of apparent electric current density ((**a**) and (**c**)) and apparent Ohm-heat-induced temperature ((**b**) and (**d**)), where (**a**) and (**b**) are with incline angle $\theta = 0^{\circ}$; (**c**) and (**d**) are with incline angle $\theta = 90^{\circ}$. The arrows in the figure represent the applied electric field.

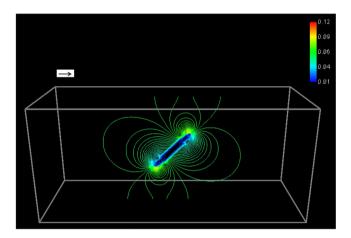


Figure 6. The electric current density distribution when the particle's incline angle is 45°. The arrow represents the direction of applied electric field.

field, and hence is different from electromagnetophoresis. The dipole moment in dielectrophoresis was calculated according to electrostatic field distribution of an infinite large system containing a spherical particle. The derivation of dielectrophoresis of spherical particles in finite system is complex³⁴. The dielectrophoresis of anisotropic particles in a finite system is difficult to derive by the dynamic method.

The electric current distribution pattern illustrated in Fig. 5(a) is similar to that of a dipole moment superimposed to a uniform electric current field. However, the pattern in Fig. 5(c) is more similar to a dipole to present in vertical direction. It is difficult to image that a horizontal uniform electric field could induce polarization of a particle in vertical direction. Figure 6 presents the electric current density distribution of one disc-like particle with incline angle of 45°. The current distribution is sensitive to the particle orientation. The geometry and orientation alter the current distribution significantly, which again affect the electric current free energy. The lowest free energy position is the most stable position, which is a state the longest axis of disc-like particles parallel to the current flow direction.

This work investigated the electric-current-induced alignment of suspended anisotropic particles in fluid medium. In fact, the effect has been observed in many other solid-state experiments in low-carbon automotive steels³⁵ and high silicon electrical steels³⁶. The difference between the alignment in solid and liquid medium is that the former is via reconstruction and the latter is by rotation.

Methods

Software. The three-dimensional visual analysis of the computational data was generated using MatVisual software.

Data availability statement. The datasets generated during and/or analysed during the current study are available from the corresponding author on reasonable request.

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Author Contributions

All the works presented in this article were done by Rongshan Qin.

Additional Information

Competing Interests: The authors declare that they have no competing interests.

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