Research Article

A Novel Multispace Image Reconstruction Method for Pathological Image Classification Based on Structural Information

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Pathological image classifcation is of great importance in various biomedical applications, such as for lesion detection, cancer subtype identifcation, and pathological grading. To this end, this paper proposed a novel classifcation framework using the multispace image reconstruction inputs and the transfer learning technology. Specifcally, a multispace image reconstruction method was frst developed to generate a new image containing three channels composed of gradient, gray level cooccurrence matrix (GLCM) and local binary pattern (LBP) spaces, respectively. Then, the pretrained VGG-16 net was utilized to extract the high-level semantic features of original images (RGB) and reconstructed images. Subsequently, the long short-term memory (LSTM) layer was used for feature selection and refnement while increasing its discrimination capability. Finally, the classifcation task was performed via the sofmax classifer. Our framework was evaluated on a publicly available microscopy image dataset of IICBU malignant lymphoma. Experimental results demonstrated the performance advantages of our proposed classifcation framework by comparing with the related works.

1. Introduction

Pathological image classifcation is important in various biomedical applications, such as for lesion detection [\[1\]](#page-7-0), cancer subtype identifcation [\[2\]](#page-7-1), and pathological grading [\[3\]](#page-7-2). However, it is difficult for human eyes to recognize subtle diferences in the tissue; there are thus diferent interpretations among medical experts. Moreover, pathologists generally perform the pathological image classifcation by the microscopic examination, which is time-consuming, operator intensive and subjective. Therefore, computer-aided diagnosis (CAD) is indispensable for pathological image analysis.

Traditionally, machine learning (ML) techniques have been widely used for diferent medical image processing tasks, including image detection [\[4\]](#page-7-3), segmentation [\[5\]](#page-7-4), and recognition [\[6\]](#page-7-5). Specifcally, many researchers applied them to the feld of pathological image analysis, which has achieved a great performance. For example, an automated system [\[7](#page-7-6)]

was used to extract a set of texture features by multiwavelets, Gabor-flters, gray level cooccurrence matrix (GLCM), and fractal dimensions (FD) for grading pathological images of prostatic carcinoma. Experimental results showed that FDbased features set had very good performance and provided useful information for pathological image classifcation. If FD-based features were included in the feature set and optimized, the classifcation accuracy can be increased to 95.6%. Jia et al. [\[8](#page-7-7)] proposed an unsupervised network for image segmentation by learning the nonlinear distribution of medical data without prior knowledge. Experimental results demonstrated that the unsupervised one-class support vector machine (SVM) had better segmentation results than a supervised two-class SVM. To sum up, conventional machine learning methods are generally performed based on discriminative hand-craft features from manual features, but the abstract level of the manual features is relatively low, which brings difficulties for subsequent experiments.

Recently, several CAD models based on deep learning (DL) strategies have been developed for pathological image processing, which achieve the automatic extraction of features and improve the accuracy of classifcation. Hence, CAD using deep learning signifcantly reduces the subjective misjudgment of doctors. For instance, Sirinukunwattana et al. [\[9](#page-7-8)] explored the efect of the convolutional network depth on its accuracy in the localization and classifcation track respectively. Xu et al. [\[10\]](#page-7-9) employed a deep convolutional neural network (CNN) to learn the high-level representations of histopathology images based on the transfer learning technology. In other words, initial weights of the model were determined using the optimal parameters pretrained on ImageNet. Lei et al. [\[11\]](#page-7-10) accomplished a work with respect to a weakly supervised classifcation and disease localization using pretrained deep convolutional network. Gu et al. [\[12](#page-7-11)] employed the classical AlexNet to analyze the corresponding classification problems. The classification accuracy obtained by the proposed model can achieve to 69.9% in the task of cancer classification. Magaña-Tellez et al. [\[13](#page-7-12)] proposed a spatially constrained convolutional neural network (SC-CNN) to perform nucleus detection and develop a novel neighboring ensemble predictor for classifcation of nuclei. Mercan et al. [\[14\]](#page-7-13) proposed a deep learning method, which used multiple processing layers to learn representations of data through multiple levels of abstraction. Compared to traditional ML methods, DL can learn low-level features as well as high-level semantic information. Moreover, the extracted features have a stronger generalization performance than the specifc settings and can be applied to multiple felds.

Generally, DL methods require a large number of training data. However, one challenge is how to deal with the lack of data samples in the feld of medical images. For example, Shang et al. [\[15\]](#page-7-14) proposed a novel algorithm that can preserve geometric structure information based on the feature selection framework of subspace learning and then used the $L_{2,1}$ -norm to ensure the sparsity of the feature array and avoid complicated solutions. However, it was expensive and impossible to train an efective model using a small amount of labeled data. To address this issue, the transfer learning technique had been used in this framework, which improved model performance. Gupta et al. [\[16](#page-7-15)] proposed a heterogeneous transfer learning framework, which extracted textual information to achieve the image classifcation. Experimental results showed that this framework performed better than other methods under the premise of using the less labeled data.

As previously mentioned, features extracted by DL and transfer learning are benefcial for pathological image classifcation. However, diferent features represent diferent image characteristics; there are thus many literatures to obtain more comprehensive information via image feature fusion. For instance, Li et al. [\[17\]](#page-7-16) proposed a multimodal feature fusionbased framework to achieve representations of geographic images by leveraging a low-to-high learning flow for both the deep and shallow modality features. Banerjee et al. [\[18](#page-7-17)] presented deep-learning-based CADs for the diagnosis of subtypes of rhabdomyosarcoma (RMS) by analyzing multiparametric MR images. They achieved creating a comprehensive representation of tumor by a fusion method. Finally, they used a pretrained deep convolutional neural network to perform classifcation of two RMS subtypes, which achieved a fast, efficient, and reproducible diagnosis for RMS subtypes.

In this study, we propose a pathological image classifcation framework based on a multispace image reconstruction method and the transfer learning technology. The contributions of this paper are summarized as follows. First, the reconstructed image is a new generated image containing three channels composed of gradient, gray level cooccurrence matrix (GLCM) and local binary pattern (LBP) spaces. Specifcally, the gradient image is sensitive to the boundaries and GLCM image is sensitive to regions of nuclei. The LBP image mainly highlights the center of each nucleus. Second, high-level semantic features from RGB and pseudocolor images are extracted via the pretrained VGG-16 net and the long short-term memory (LSTM) layer is used to reduce the feature dimension while increasing its discrimination capability. Our framework is evaluated using a publicly available microscopy image dataset of IICBU malignant lymphoma [\[19\]](#page-7-18). Experimental results demonstrate the performance advantages of our proposed classifcation framework by comparing with the related works.

The remainder of this paper is organized as follows. In [Section 2,](#page-1-0) we introduce NHL pathological image dataset and our classifcation framework. [Section 3](#page-4-0) shows the classifcation results and a comprehensive comparison with some other methods. Finally, discussions and conclusions are summarized in Sections [4](#page-5-0) and [5,](#page-6-0) respectively.

2. Materials and Methods

2.1. Dataset Description. The IICBU lymphoma dataset contains 374 hematoxylin and eosin (H&E) stained non-Hodgkin lymphoma (NHL) images, which are divided into three classes: chronic lymphocytic leukemia (CLL), follicular lymphoma (FL), and mantle cell lymphoma (MCL). They are the major types of malignant small B-cell lymphoma [\[19\]](#page-7-18). The dataset sections are captured using the bright field microscopy and each image is 1388×1040 pixels. In our experiments, each image is divided into 336 nonoverlapped patches with 64 \times 64 pixels (21 \times 16); we perform the classifcation tasks in the patch level and image level, and the image classifcation results are determined via the classifcation results of the corresponding patches.

2.2. Pathological Image Classification. As shown in [Figure 1,](#page-2-0) the proposed process of the pathological image classifcation is described, which is summarized as four stages, including multispace image reconstruction, feature extraction, feature selection, and image classifcation. First, a multispace image reconstruction method is developed to generate new color images, which contain the gradient, GLCM, and LBP information adequately. Second, the VGG-16 net pretrained on ImageNet is applied to original images and reconstructed images for feature extraction. Third, the long short-term memory (LSTM) layer is used for feature selection. Finally,

FIGURE 1: The flowchart of the proposed classification process, which has four steps. (1) Multispace image reconstruction; (2) feature extraction; (3) feature selection; and (4) image classifcation.

FIGURE 2: The process of multispace image reconstruction. (a) Original image. (b) Grayscale image. (c) Gradient image. (d) GLCM. (e) LBP. (f) Our reconstructed image.

the sofmax classifer is utilized to perform the classifcation task.

2.2.1. Multispace Image Reconstruction. Generally, H&E images vary signifcantly in color, because of many factors, including specimen preparation and staining protocol inconsistencies (e.g., temperature of solutions); variations in fxation characteristics and interpatient variation and the scanner are used to digitize the slides. The classification performance could be hampered by color and intensity variations. Many classifcation tasks implemented by DL strategies not only considered RGB inputs but also took the advantage of other spaces' inputs, such as HSV, Lab, and YUV [\[20\]](#page-7-19). Inspired by these works, we first use the white balance method to alleviate color infuence and then convert RGB images into grayscale images. Besides, in order to consider more benefcial information, we propose a novel multispace reconstruction method to generate a new image which is composed of the gradient, GLCM and LBP spaces' images. In other words, the R, G, and B channels of a reconstructed image are represented as the gradient, GLCM, and LBP spaces' images, respectively. [Figure 2](#page-2-1) presents the generative

process of a reconstructed image. [Figure 2\(a\)](#page-2-2) is an original H&E pathological image. Figures [2\(b\)–](#page-2-3)[2\(e\)](#page-2-4) represent the grayscale, gradient, GLCM, and LBP images. [Figure 2\(f\)](#page-2-5) is the generated reconstructed image. Visually, the gradient image is sensitive to boundaries and the GLCM image is sensitive to the regions of nuclei. The LBP image mainly emphasizes the center of each nucleus. The following experiments demonstrate that these three kinds of information are efective for the pathological image classifcation.

2.2.2. Feature Extraction via VGG-16 Net. As is well known, the effective classification greatly depends on the discriminative representations of samples. Some literatures [\[21](#page-7-20)] treated the feature extraction and classifer design as two separated processes; they could not work together to maximally extract and retain the most discriminative information. Recently, deep learning strategies are widely applied to the feature extraction on diferent image classifcation tasks. Particularly, conventional convolutional neural network (CNN) [\[22\]](#page-7-21) is consisted of alternating convolution and subsampling operations. Flatten operation was used on the feature maps of the last convolution layer to obtain the feature vectors. The next

Layer	Filter number	Kernel size	Dimension
Input		$\overline{}$	$64 \times 64 \times 3$
Convl	64	3×3	$64 \times 64 \times 64$
Conv ₂	64	3×3	$64 \times 64 \times 64$
Max-Pool1	$\overline{}$	2×2	$32 \times 32 \times 64$
Conv ₃	128	3×3	$32 \times 32 \times 128$
Conv ₄	128	3×3	$32 \times 32 \times 128$
Max-Pool2	$\overline{}$	2×2	$16 \times 16 \times 128$
Conv ₅	256	3×3	$16 \times 16 \times 256$
Conv ₆	256	3×3	$16 \times 16 \times 256$
Conv7	256	3×3	$16 \times 16 \times 256$
Max-Pool3	$\overline{}$	2×2	$8 \times 8 \times 256$
Conv ₈	512	3×3	$8 \times 8 \times 512$
Conv9	512	3×3	$8 \times 8 \times 512$
Conv10	512	3×3	$8 \times 8 \times 256$
Max-Pool4	$\overline{}$	2×2	$4 \times 4 \times 256$
Conv11	512	3×3	$4 \times 4 \times 512$
Conv12	512	3×3	$4 \times 4 \times 512$
Conv13	512	3×3	$4 \times 4 \times 512$
Max-Pool5		2×2	$2 \times 2 \times 512$

TABLE 1: The network structure for our classification task.

several fully connected layers were applied one by one on the feature vectors. These series of operations were regarded as a process of feature extraction. In addition, the transfer learning in [\[23\]](#page-7-22) used the parameters of trained models (via natural images) to extract medical images' features or initialized the parameters of a particular model. Motivated by [\[24](#page-7-23)], our strategy uses the pretrained VGG-16 [\[25\]](#page-7-24) (Visual Geometry Group) net for performing the feature extraction on lymphoma patches. VGG-16 is a simple and common deep convolutional neural network and can obtain the competitive performances with other networks. The proposed

feature extraction process using VGG-16 net is described in [Figure 3.](#page-3-0) The network is trained on the entire ImageNet [\[26](#page-7-25)] dataset and our input images are all resized to 64×64 pixels. The corresponding outputs are 2048-dimensional features. The specific network structure for our classification task is presented in [Table 1.](#page-3-1) Note that the pretrained VGG-16 net is used for the feature extraction on RGB images and the reconstructed patches simultaneously.

2.2.3. Feature Selection by LSTM. Due to the great diferences between natural images and pathological images, the features

Index	Classes	RGB	Reconstruction	Combination
ACC.	Overall	(0.5317 ± 0.016)	(0.4423 ± 0.016)	(0.6667 ± 0.008)
SEN	CLL	(0.5205 ± 0.011)	(0.4214 ± 0.010)	(0.6414 ± 0.010)
	FL	(0.5179 ± 0.010)	(0.4187 ± 0.013)	(0.6396 ± 0.018)
	MCL	(0.5224 ± 0.009)	(0.4226 ± 0.009)	(0.6428 ± 0.009)
SPE	CLL	(0.5515 ± 0.008)	(0.4602 ± 0.004)	(0.6806 ± 0.005)
	FL	(0.5469 ± 0.012)	(0.4584 ± 0.011)	(0.6789 ± 0.007)
	MCL	(0.5524 ± 0.011)	(0.4628 ± 0.014)	(0.6833 ± 0.009)

Table 2: Diferent classifcation results using RGB (2048-dimension), reconstruction (2048-dimension), and combination features (4096 dimension).

extracted by pretrained VGG-16 net may not obtain the satisfactory classifcation results. A common method for addressing this issue is to initialize the model's parameters using the pretrained net and then train our images to adjust the parameters. However, there is no essential diference compared with training own data directly, and it also could lead to the overftting. To this end, we propose a "feature selection strategy" to fnd the discriminative features and remove the redundant features using the long short-term memory (LSTM) layer. The LSTM [\[27](#page-7-26)] is an efficient network for text classifcation tasks, which considers the relationship between the text and time information. For our case, the relationship between original RGB images and corresponding reconstructed images is similar to temporal text data. Specifically, redundant features are removed via the forget gate, then benefcial features are added to the input gate and the optimal feature vector is obtained by the output gate. [Figure 1](#page-2-0) shows the feature selection process using the LSTM layer. The VGG-16 features of RGB images are regarded as the original content information (text information in LSTM), while the VGG-16 features of the corresponding reconstructed images are considered as the auxiliary information (temporal information in LSTM). There are 32-dimension features selected via the LSTM layer. Aferwards, we cascade the 32-dimension features of RGB images and the reconstructed images into a 64-dimension feature vector. Finally, the sofmax classifer is used to perform the pathological image classifcation task. Note that the integral loss function is defned as follows in $(1)-(3).$ $(1)-(3).$

$$
Loss = Loss_{original} + Loss_{reconstruction}
$$
 (1)

$$
Loss_{original} = -\sum_{i} y_i \log a_i \tag{2}
$$

$$
Loss_{reconstruction} = -\sum_{i} y_i \log b_i \tag{3}
$$

where y_i represents the label of each sample. a_i and b_i are the output probabilities obtained via the sofmax function $e^{z_i}/\sum_{k} e^{z_k}$, $z_i = \sum_{j} w_{ij} x_{ij} + b$ is the output of the neuron, x_{ii} represents the feature vectors of the RGB and reconstructed inputs, respectively, and w_{ii} and b are the corresponding weights and bias. We can observe that if one loss function $(Loss_{original}$ or $Loss_{reconstruction}$) leads to the vanishing gradient, the feedback information from another loss function can also train the LSTM layer. In order to remove redundant information in the features, the LSTM layer for text classifcation tasks is used in this paper by analyzing each row of the feature matrix recursively, and it has produced good results.

3. Results and Comparisons

3.1. Experimental Results. In order to verify the efectiveness of the proposed framework, three commonly used evaluative criteria are considered as follows in [\(4\)-](#page-4-3)[\(6\).](#page-4-4)

$$
ACC = \frac{1}{n} \sum_{i=1}^{n} I(f(x_i) = y_i)
$$
 (4)

$$
SEN\left(c_i\right) = \frac{Num\left(PT\left(c_i\right)\right)}{Num\left(GT\left(c_i\right)\right)} \times 100\%
$$
\n⁽⁵⁾

$$
SPE(c_i) = \frac{Num (PT (-c_i))}{Num (GT (-c_i))} \times 100\%
$$
 (6)

where ACC means the overall grading accuracy. $SEN(c_i)$ and SPE(c_i) are sensitive and specificity for each class (c_i). $I(f(x_i) = y_i)$ is the indicative function. It defines that if $f(x_i) = y$, $I(f(x_i) = y_i) = 1$; otherwise $I(f(x_i) = y_i) =$ 0. $-c_i$ denote all the other classes except (c_i) . Num(PT(c_i)) and $Num(GT(c_i))$ denote the number of correctly predicted class (c_i) and the total number of (c_i) in the ground truth, respectively.

In our experiments, frst, we perform the NHL classifcation tasks using the VGG-16 features [\(Section 2.2\)](#page-1-1). Our experiments adopt 10-cross validation method to determine the optimal parameters of each model. [Table 2](#page-4-5) presents the diferent classifcation results with the VGG-16 features extracted on the original and reconstructed images. We can observe that the feature combination (4096-dimension) is benefcial for our classifcation task. It can be also proved that reconstructed images can provide complementary information with respect to RGB images. As is well known, more features could not denote that they can achieve a better result. This is because that there are redundant features which can result in the worse classifcation results. To address this issue, the feature selection strategy is widely used for the more accurate classifcation result while reducing the

Index	Classes	RGB-LSTM	Reconstruction-LSTM	Combination-LSTM
ACC	Overall	(0.8453 ± 0.018)	(0.7637 ± 0.012)	(0.9894 ± 0.011)
SEN	CLL	(0.8243 ± 0.014)	(0.7459 ± 0.019)	(0.9666 ± 0.012)
	FL	(0.8168 ± 0.010)	(0.7321 ± 0.009)	(0.9662 ± 0.011)
	MCL	(0.8251 ± 0.019)	(0.7482 ± 0.015)	(0.9685 ± 0.013)
SPE	CLL	(0.8721 ± 0.014)	(0.7832 ± 0.008)	(0.9931 ± 0.007)
	FL	(0.8659 ± 0.011)	(0.7779 ± 0.007)	(0.9912 ± 0.005)
	MCL	(0.8718 ± 0.012)	(0.7834 ± 0.011)	(0.9938 ± 0.013)

Table 3: Diferent classifcation results using RGB (32-dimension), reconstruction (32-dimension), and combination features selected by the LSTM layer (64-dimension).

FIGURE 4: Accuracy versus iteration times graph.

computational cost. [Table 3](#page-5-1) shows diferent classifcation results using diferent features selected by the LSTM layer. It can be observed that the LSTM layer is efective for feature selection and improving classifcation accuracy. Following these experimental results, our proposed framework for NHL image classifcation is determined. In addition, [Figure 4](#page-5-2) shows the classifcation results according to diferent iteration times and the best time is 250.

3.2. Image-Level Classification. As mentioned before, our objective of this paper is to classify 374 NHL pathological images, which include CLL, FL, and MCL. Our proposed classifcation framework is performed on the image patches with 64×64×3; the image-level classifcation is thus accomplished via the label of each patch inside a whole pathological image. Specifcally, a pathological image is divided into 336 nonoverlapped patches and the label of each patch is obtained via the proposed classifcation framework. We can thus determine the pathological image's label using the majority voting strategy via the number of each category's patches. To visualize the classifcation results of the whole pathological images, [Figure 5](#page-6-1) shows the probability atlases of three examples with diferent classes. Figures [5\(a\)](#page-6-2)[–5\(c\)](#page-6-3) are CLL, FL, and MCL pathological images. Figures [5\(d\)–](#page-6-4)[5\(f\)](#page-6-5) are corresponding probability atlases. The colors in the probability atlases represent the probability that each patch is predicted to be a label of the image categories. The colors

from bottom to top is ranged from [0, 1]. According to the probability atlases, we can see that majority of patches inside a pathological image are correctly classifed as the corresponding image's label.

3.3. Comparisons. To further evaluate our proposed classifcation framework with other models, there are three popular methods [\[28](#page-7-27)[–30](#page-8-0)] used for comparison in our experiments. Shamir et al. [\[28](#page-7-27)] developed CAD sofware for biological image analysis. This software worked by first extracting image content descriptors from the raw images, image transforms, and compound image transforms. Then, the most informative features were selected and then used for classifcation and similarity measurement. Meng et al. [\[29\]](#page-8-1) proposed a framework using the novel and robust collateral representative subspace projection modeling (CRSPM) supervised classifcation model for general histology image classifcation. Codella et al. [\[30](#page-8-0)] frst created additional 5 images for each H&E pathological image, which can emphasize unique aspects of the original image, such as dominant staining and staining segmentations. Then a pretrained CNN model was used to extract 4096-dimension visual features. Finally, nonlinear SVMs were utilized to perform the classifcation. Similarly, all methods are performed on NHL dataset and tested using 10-cross validation method. The average comparison results are presented in [Figure 6.](#page-6-6) We can observe that our method performs the best in terms of ACC.

4. Discussions

According to the classifcation results in [Section 3.1](#page-4-6) (Tables [2](#page-4-5) and [3\)](#page-5-1), there are two important characteristics with respect to our proposed classifcation framework. First, besides RGB image information, we also consider the other classes of information via a "multispace image reconstruction" strategy. As [Figure 2](#page-2-1) is shown, the gradient image is sensitive to boundaries and GLCM image is sensitive to regions of nuclei. The LBP image mainly highlights the center of each nucleus. The results indicate that this auxiliary information facilitates the improvement of classifcation accuracy signifcantly. Second, in order to remove redundant features, the pretrained LSTM layer is used to perform a "feature selection" process. Further, our classifcation framework obtains the ACC of 98.94% in patch-level classifcation.

FIGURE 5: The probability atlases of three examples with different classes. (a) A CLL pathological image. (b) A FL pathological image. (c) An MCL pathological image. $(d-f)$ The probability atlas of $(a-c)$, respectively.

FIGURE 6: The average classification accuracy (%) using different methods.

Comparing results from our classifcation framework with other methods, the software proposed in [\[28\]](#page-7-27) only used hand-craft features to perform classification tasks and considered no high-level semantic features (extracted via deep learning model). Our method and [\[29\]](#page-8-1) both converted the image-level classifcation into the patch-level classifcation. A diference from [\[29](#page-8-1)] was that it divided the image into 25 overlapped patches with a larger size. This, however, may lose more subtle local information. Finally, the method in [\[30\]](#page-8-0) utilized a pretrained CNN to extract the visual features from diferent images. Our improvement related to [\[30](#page-8-0)] is that we adopt a feature selection method to increase its

discrimination capability. The results in [Figure 6](#page-6-6) demonstrate the advantages of our proposed classifcation framework.

5. Conclusions

In this paper, we proposed a novel classifcation framework based on a multispace image reconstruction method and the transfer learning technology. The multispace image reconstruction mapping method can convert original RGB images into gradient, gray level cooccurrence matrix (GLCM), and local binary pattern (LBP) spaces. This auxiliary information is beneficial for more accurate classification results. Then, the pretrained VGG-16 net was utilized to extract the highlevel semantic features of RGB and reconstructed images. Subsequently, the LSTM layer was used for feature selection and refnement while increasing its discrimination capability. Experimental results demonstrated the performance advantages of our proposed classifcation framework by comparing with related works. Future work may be considered based on our proposed framework. For feature extraction, we plan to establish a complete feature set, which includes hand-craf features and high-level representations. Another important work will consider the feature extraction on more other spaces' images.

Data Availability

(i) The dataset includes three types of malignant lymphoma. (ii) The data can be accessed from [https://ome.grc.nia.nih](https://ome.grc.nia.nih.gov/iicbu2008/lymphoma/index.html) [.gov/iicbu2008/lymphoma/index.html.](https://ome.grc.nia.nih.gov/iicbu2008/lymphoma/index.html) In addition, there are no restrictions on data access.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

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