ORIGINAL RESEARCH

A New Accurate, Simple and Less Radiation Exposure Device for Distal Locking of Femoral Intramedullary Nails

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Tel +86-10-63138753 Fax +86-10-63138353 Email drwg87@163.com; docbjwang@126.com **Background:** Due to the metal elasticity of intramedullary nails (IMs) and irregularities of the long bone marrow cavity and other reasons, one of the greatest challenges for surgeons is to position the distal locking screw. Therefore, a novel laser guiding navigation device was designed for the distal locking of femoral IMs. The purpose of this study was to compare the effectiveness of the novel device and freehand technique for distal locking of IMs in the femoral model.

Methods: The laser guiding navigation device (laser group) and freehand technique (freehand group) were used in the distal locking of the IMs in the femoral model. All operations were performed by surgeons of the same level. The differences between the two groups were compared in terms of operative time, radiation exposure time, first success rate, deviation angle between ideal trajectory and actual trajectory, and learning curve.

Results: The distal locking of the IMs in the femoral model was performed 40 times in each group. The results showed that the laser group was better than the freehand group in terms of operative time (345 ± 165 VS 212 ± 105 seconds, t=4.27, P<0.001), radiation exposure time (164 ± 57 VS 41 ± 15 seconds, t=13.15, P<0.001) and first successrate ($\chi^2=21.36$, P<0.001). Compared with the freehand group, the actual trajectory of the laser group was closer to the ideal trajectory in coronal and horizontal planes. Furthermore, the learning curve time of the laser group was shorter.

Conclusion: Compared with traditional freehand technique, the novel laser guiding navigation device can shorten the operative time and reduce radiation exposure invitro. In addition, it is easy to master with more accuracy and a higher first success rate in vitro.

Keywords: femur, intramedullary nails, laser guiding navigation device, freehand technique

Introduction

Minimally invasive treatment is the development trend of trauma and orthopedics¹. Intramedullary nail is one of the key "weapons" for minimally invasive treatment. However, due to the metal elasticity of IMs and irregularities of the long bone marrow cavity², positioning the distal locking screw is one of the greatest challenges for surgeons³, which results in a long operation and radiation exposure time.

In response to this problem, many novel technologies to localize distal locking holes, have been invented, such as electromagnetic navigation technology⁴, computer-aided navigation technology⁵, orthopedic robots⁶ and so on. However, these technologies (including traditional freehand technique⁷) still have some limitations,

© 2021 Gao et al. This work is published and licensed by Dove Medical Press Limited. The full terms of this license are available at https://www.dovepress.com/terms.php you hereby accept the firms. Non-commercial uses of the work are permitted without any further permission from Dove Medical Press Limited, provided the work is properly attributed. For permission for commercial use of this work, please see paragraphs 4.2 and 5 of our Terms (http://www.dovepress.com/terms.php). such as inaccurate positioning, low first success rate, high demand for expensive equipment, long learning curve of surgeons. $^{6-13}$

Based on the above problems, our team designed a laser guiding navigation device based on G-arm and a matching positioning technique by taking advantage of the characteristics of the accuracy and stability of laser. The device has the advantages of easy installation, accurate positioning, no radiation exposure during operation, and is easy to master. This study focused on the application of the new device in the distal locking of IMs in the femoral model, and compared the effectiveness with the traditional freehand technique¹⁴.

Materials and Methods

The femoral model (SAWBONES, Left Femur, Foam Cortical, 16 mm Canal, 47cm length) was firmly fixed in the blind box, and it was ensured that the blind box and the femoral model could not be moved during the operation. The distal locking of the IMs (WASTON, Professional X Series, diameter 9.5mm, length 380 mm) in the femoral model was performed 40 times in each group. 40 operations of each group were performed in 4 sequences and one sequence (10 operations) was performed per day. Each time we first used the laser guiding navigation device in 10 operations, then freehand technique in 10 operations. All operations were performed by two senior residents who finished three years of specialized training. They received the same amount of time training for freehand technique, and their skill levels were very close.

Description of the Novel Device

The laser guiding navigation device consisted of 4 major components: a horizontal green-light laser pointer (in-line, energy 100mW, wavelength 520nm, Senwei Electronic Commerce Co., Ltd), a coronal red-light laser pointer (inline, energy 100mW, wavelength 635nm, Senwei Electronic Commerce Co., Ltd), two laser pointer pedestals, a round strap attached to the G-arm's image intensifier (Figure 1). Before operation, the device was adjusted repeatedly to ensure that the intersection of the two laser lines, X-ray fluoroscopy center and display screen center were completely overlapped (Figure 2). When the device was first installed on the G-arm's image intensifier, it needed to be installed and adjusted. It took no more than 10 minutes. Each G-arm machine needed to be installed and adjusted for the first time and it only needed to be calibrated in the following use. The calibration time was not more than 1 minute every time. This should be done before the operation.

Surgical Procedure

In the group undergoing the freehand technique¹⁵, it was crucial to confirm that the distal nail holes appeared as a perfect circle in the lateral image of the G-arm fluoroscope. Then we kept the direction of the Kirschner wire (Φ =2mm) and gradually drilled and stayed on the same axis under fluoroscopic visualization. After fluoroscopy confirmed that the Kirschner wire passed through the nail hole, we used a drill bit to enlarge the screw channel, measured the length of the channel, and inserted the distal screw.

In the laser group, the same as the freehand technique¹⁵, when the distal nail hole in the lateral image of the G-arm fluoroscope was a perfect circle, adjusted the position of G-arm to ensure that the center of the nail hole was overlapped with the center of the display screen. It meant that the center of the nail hole was overlapped with the intersection of the two laser lines. Ensured that the Kirschner wire (Φ =2mm) was drilled along the red and green laser lines and confirmed that the Kirschner wire passed through the nail hole through fluoroscopy (Figure 3). Then we used a drill bit to enlarge the screw channel, measured the length of the channel, and inserted the distal screw.

Observation Indicators

1. Main indicators: ① Operative time, starting from the positioning of the distal nail hole, including the total time (seconds) of positioning and insertion of the distal screw; ② Radiation exposure time, including the total fluoro-scopy time (seconds) of positioning and insertion of the distal screw.

2. Other indicators: ① Imaging indicators, the Picture Archiving and Communication System (PACS)¹⁶ was used to measure the deviation angle (coronal plane, horizontal plane) between the actual trajectory and the ideal trajectory (Figure 4). The coronal deviation angle was measured according to the long axis of IMs¹⁷. The ideal vertical line through the center of the nail hole was regarded as the ideal trajectory¹⁸, and the Kirschner wire passing through the angle between the two lines was regarded as the track angle of the coronal plane (TAC). The femoral vertical fluoroscopy image was used to measure the horizontal deviation angle¹⁷. The line parallel to the tangent line of the posterior condyle of the femur was regarded as the ideal trajectory, and the Kirschner



Figure I Three-dimensional model drawings of laser pointer and pedestal (A and B) and the physical photos of the novel device (C and D). The blue object represents the laser pointer and the green object represents the corresponding pedestal. The yellow round strap is used to attach to the G-arm's image intensifier (E).

wire was regarded as the actual trajectory. The angle between the two lines was regarded as the track angle of horizontal plane(TAH); ② The success rate of the first positioning; ③ The change of the operator's learning curve.

Sample Size Estimation and Statistical Methods

According to the data obtained in the preliminary test (trauma orthopedics series operation simulator, Melerit Medical TraumaVision^{20,21}), we set the first-class error to 0.025 and the power to be 0.9 through calculation of PASS software based on the 2 main research indicators. The minimum sample size for the study of operative time (seconds) was 14 and 4 for the exposure time (seconds). Considering the actual situation of this study, the sample size of each group was finally determined to be 40.

Continuous variables were presented as mean±standard deviation (SD), and the independent sample *t*-test was used to evaluate differences of quantitative values between two methods, including the operative time, radiation exposure time, TAC and TAH. Categorical variables were presented as frequency and percentage, and the paired chi-square test was used to evaluate differences between two methods, including the first success rate. All statistical analyses were performed using the SPSS Statistics version 22 (IBM Corp., Armonk, NY). Statistical significance was defined as P<0.05.

Results

The average operative time of the freehand group was 345 ± 165 seconds, whereas the time was 212 ± 105 seconds in the laser group. The average radiation exposure time of the freehand group and the laser group was 164 ± 57 seconds



Figure 2 Work principle sketch maps of the new device. Before operation, the device was adjusted repeatedly to ensure that the intersection of the horizontal green-light laser and the coronal red-light laser (A and B), X-ray fluoroscopy center and display screen center were completely overlapped (C).



Figure 3 The femoral model was firmly fixed in the blind box (A). Ensured that the Kirschner wire (Φ =2mm) was drilled along the red and green laser lines and confirmed that the Kirschner wire passed through the nail hole through fluoroscopy (B).

and 41 ± 15 seconds respectively. The average operative time of the laser group was statistically significantly shorter compared to the freehand group (*t*=4.27, *P*<0.001), and the exposure time was significantly reduced in the laser group compared to the freehand group (*t*=13.15, *P*<0.001). (Figure 5).

The TAC of the freehand group and the laser group were $6.7\pm1.1^{\circ}$ and $2.9\pm0.8^{\circ}$ respectively, and the difference was statistically significant (*t*=9.12, *P*<0.001); In

terms of the TAH, the freehand group and the laser group were respectively $8.2\pm0.5^{\circ}$ and $2.8\pm0.5^{\circ}$, and the difference was statistically significant (*t*=22.83, *P*<0.001). (Figure 6)

In the freehand group, there were 7 first positioning errors, while, there were 2 first positioning errors in the laser group. By comparing the failure rates of the two groups were 17.5% (7/40, the freehand) and 5.0% (2/40, the laser group), the difference was statistically significant



Figure 4 The PACS system was used to measure the angle (coronal plane, (**A**) horizontal plane, (**B**)) between the actual trajectory and the ideal trajectory. The red line was the actual trajectory of the laser group. The blue line was the actual trajectory of the freehand group. The orange line was the ideal trajectory. And the upright Image of Femur (**C**).



Figure 5 The box plot showed the operative and radiation exposure time of the laser group was statistically significantly shorter compared to the freehand group.

(χ^2 =21.36, P<0.001), and the first success rate of the laser group was higher.

With the improvement of proficiency, the operative time was gradually shortened. Through the changing trend of learning time, it could be seen that the two groups have a gradual downward trend, but in general, the learning time of the laser group was shorter and more stable (Figure 7).

Discussion

Although there were many solutions to the distal locking of the long bone IMs, including mechanical positioning



Figure 6 The box plot showed the ideal and actual trajectory deviation angle of the laser group was statistically significantly less compared to the freehand group.



Figure 7 The time required for the laser group to master was shorter and more stable compared to the freehand group.

devices²², electromagnetic navigation devices, surgical robots, Intra-medullary endo-transilluminating $(iMET)^{23}$ and so on, there were still problems such as inaccurate

positioning, low first success rate and long learning curve.^{7,24} As the freehand technique was the final solution after all the other methods failed, this study compared the

effectiveness and safety of the laser device with freehand technique.^{7,25}

According to literature, the freehand positioning of the distal locking screw takes about 7–15 minutes¹⁰. It takes more operative and radiation exposure time for novice surgeons. Repeated positioning can lead to lateral cortical defect, reduce the stability of interlocking nail and cortex, which will result in nail withdrawal and affect the surgical effect of internal fixation²⁶. Compared with the freehand method, the laser guiding navigation device could shorten the operative time, increase the first success rate and improve the efficiency of the operation.

The criterion for the successful insertion of the distal screw was judged by the smooth passage of the screw through the nail hole. At the same time, the ideal trajectory²⁷ was through the center of the nail hole and perpendicular to the long axis of the intramedullary nail. Due to the necessary redundancy between the screw and the nail hole, there was a certain angle deviation between the ideal trajectory and the actual trajectory, which could reflect the accuracy of positioning. The deviation angle between the ideal and the actual trajectory of the coronal plane (femoral front position) and horizontal position (femoral vertical position) was measured by the PACS system²⁸. The deviation angle of the laser group on the coronal and the horizontal plane was smaller and the accuracy was higher.

All kinds of positioning methods need X-ray fluoroscopy to localize distal locking holes. It takes about 20–40 seconds for a surgeon skilled in freehand method to complete the distal locking of the intramedullary nail under radiation exposure. The average radiation dose to the surgeon was 1.27 mSv during the procedures of intramedullary nailing of femoral and tibial fracture²⁹. It will take more radiation exposure time for a novice surgeon. Considering the safety of operators and patients, radiation exposure should be minimized. In this study, the radiation exposure time of the laser group was about 1/4 of the freehand group, and fluoroscopy was not necessary in the process of inserting the locking screws, which could significantly reduce radiation exposure (especially for the surgeon).

The operators in this study were all senior residents, with limited freehand experience and needed the guidance of superiors. It was difficult to master the freehand technique and a large amount of radiation exposure was unavoidable to gain experience³⁰. The main challenge was to maintain a stable direction when the guide pin was

inserted³¹. The learning curve chart of this study showed it took the laser group less time to be close to a stable level. In other words, this method was easier to master.

There are problems of long radiation exposure time and cortical defects in freehand techniques. After the guide pin was positioned successfully, the direction deviation may still occur during screw insertion. With the help of the laser guiding navigation device, the surgeon only needs to change the guide needle, drill and the distal screw along the laser direction, which can avoid more radiation exposure and insertion direction deviation. Other laser positioning devices previously reported could only perform body surface positioning but could not perform navigation, and were inconvenient to install and disassemble,^{32,33} and have poor compatibility. Other electromagnetic navigation technologies and surgical robot navigation systems were either expensive or complicated to operate, which made it difficult to popularize⁵. The distal locking should be as fast, accurate and low radiation exposure as possible, which can be satisfied by this device.

Strengths and Limitations

According to the results, the advantage of this device was more accurate and effective and was easy to master. But there were some limitations. First of all, this was a study invitro, which may be different from the real clinical setting. Secondly, each G-arm needed to be calibrated and adjusted in advance when it was first used. Thirdly, although the two senior residents have similar experience, there are still slight differences in surgical techniques, which may have a certain impact on the final results. Finally, the secondary damage of the laser to the surgeon's eyes³⁴ should be protected by wearing special protective glasses.

Conclusions

Compared with the freehand method, this device was more accurate and effective in the distal locking of the IMs. In addition, it could reduce the operative and radiation exposure time, and was easy to master. Therefore, the device has the value of popularity.

Abbreviations

TAC, track angle of coronal plane; TAH, track angle of horizontal plane; IM, intramedullary nail.

Data Sharing Statement

Please contact the author for data requests.

Ethics Approval and Consent to Participate

The study was approved by the ethics committee of Beijing Friendship Hospital. This article does not contain any studies with human participants or animals performed by any of the authors. A New Accurate, Simple and Less Radiation Exposure Device for Distal Locking of Femoral Intramedullary Nails

Author Contributions

All authors contributed to data analysis, drafting or revising the article, have agreed on the journal to which the article will be submitted, gave final approval of the version to be published, and agree to be accountable for all aspects of the work.

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Disclosure

The authors declare that they have no competing interests.

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