Neural Plasticity Following Surgical Correction of Strabismus in Monkeys

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METHODS. Single cell responses were collected from cells in the oculomotor and abducens nuclei before and after two monkeys (M1, M2) with exotropia (divergent strabismus) underwent a strabismus correction surgery that involved weakening of the lateral rectus (LR) and strengthening of the medial rectus (MR) muscle of one eye. Eye movement and neuronal data were collected for up to 10 months after surgery during a monocular viewing smoothpursuit task. These data were fit with a first-order equation and resulting coefficients were used to estimate the population neuronal drive (ND) to each EOM of both eyes.

RESULTS. Surgery resulted in a \sim 70% reduction in strabismus angle in both animals that reverted toward presurgical misalignment by approximately 6 months after treatment. In the first month after surgery, the ND to the treated MR reduced in one animal and ND to the LR increased in the other animal, both indicating active neural plasticity that reduced the effectiveness of the treatment. Adaptive changes in ND to the untreated eye were also identified.

Conclusions. Active neural and muscle plasticity corresponding to both the treated and the untreated eye determines longitudinal success following surgical correction of strabismus. Outcome of surgical treatment could be improved by identifying ways to enhance "positive" adaptation and limit "negative" adaptation.

Keywords: strabismus, resection, recession, eye movements, nonhuman primate

S trabismus is a developmental disorder that affects ${\sim}4\%$ of children worldwide. $^{1\text{-}3}$ In addition to ocular misalignment and sometimes visual acuity deficits (strabismic amblyopia), problems with binocular vision and oculomotor control such as deficits in processing disparity, poor stereoacuity, disconjugate and cross-axis eye movements, and nystagmus are also observed with strabismus and replicated in the monkey model.⁴⁻⁸ The most common treatment strategy for strabismus is the surgical manipulation of specific extraocular muscles (EOM) to realign the eyes. Although popular and practiced widely, studies have shown that surgical approaches have varying levels of success and permanence, and often the patients tend to regain misalignment leading to multiple surgeries.^{9,10} Ekdawi and colleagues¹¹ suggested that the failure rate of surgical correction in children with intermittent exotropia rises to 84% by 15 years. A more recent study by Chew et al.¹² showed that postoperative success reduces from 75% at 1 week after treatment to 41% by the 5-year follow-up.¹² Other forms of strabismus also have significant and variable failure rates.13,14

Fundamentally, the failure of surgery could be due to adaptive changes that are occurring at the periphery (muscle remodeling) or within central brain areas (central neural adaptation). For instance, when the globe was sutured to the orbit wall at an exotropic position in rhesus monkeys, sarcomere lengths were altered in the EOM, indicating that the muscle length had changed in response to the forced stretching of the sutured muscle.¹⁵ Christiansen et al.¹⁶ studied the effects of resection surgery, a common strabismus correction technique to strengthen an apparently weakly acting muscle, performed on the lateral rectus (LR) in rats, and compensatory hypertrophy, that is, increase in cell size, of the treated LR, and the antagonist medial rectus (MR) was observed.¹⁶ Likewise, resection of rabbit EOM resulted in an increase in satellite cell activation in both the treated muscle and its antagonist muscle along with incorporation of new nuclei inside the myofibers,¹⁷ both thought to be indicators of active muscle remodeling. Antunes-Foschini and colleagues¹⁸ showed that the inferior oblique muscles obtained from strabismic patients contained more activated satellite cells than normal controls.

Studies have shown that disruption of binocular visual experience during the critical period of development affects normal development of binocular vision and causes deficits such as strabismus and amblyopia.^{19,20} Such sensory manipulation causes disruption of binocular properties in visual cortical areas V1 and V2 and likely causes a cascade of events along the visual-oculomotor pathway. There is substantial

evidence of neural correlates to strabismus within brainstem oculomotor structures, and it is likely that the motor aspect of misalignment lies within these areas. Previous investigations from our lab in monkey models for strabismus showed that innervation from the oculomotor nucleus to the EOM accounts for the state of strabismus and also cross-axis A/V patterns in animals that have not undergone any surgical manipulation.² Walton and colleagues²² studied the responses of neurons within the abducens nuclei in untreated strabismic monkeys and reported lower baseline firing rates than normal. Neurons within the supraoculomotor area, which encodes vergence responses in normal animals, were found to encode horizontal misalignment in strabismic monkeys.²³ More recent studies showed that electrical stimulation of the rostral superior colliculus causes a change in strabismus angle.^{24,25} Given the weight of evidence supporting a neural substrate for maintenance of strabismus, it is likely that neural plasticity following surgical manipulation of the EOM also contributes to the final strabismic state achieved after surgery.

In this study, we investigated neuronal plasticity by comparing responses from motoneurons projecting to the horizontal recti before and after a typical MR resect and LR recess surgery to correct exotropia. One scenario is that there are no changes in the population motoneuron responses, which would mean that any longitudinal change in strabismus angle after surgery (e.g., a failure to retain postsurgical strabismus angle) is fundamentally due to change in muscle properties. On the other hand, if there is a change in the population motoneuron response along with a postsurgical longitudinal change in ocular misalignment, it would indicate that neuronal plasticity that occurs as a consequence of surgery plays a role in setting the final state of ocular alignment. Note that in theory these plastic changes in the motoneuron responses could serve to either counter or facilitate the effects of modified muscle forces due to surgery. When surgery fails in exotropia, for example, the postsurgical neural plastic changes may take the form of a reduced drive to a resected muscle or an increased drive to a recessed muscle. Our data indeed show evidence for significant neuronal plasticity that acts to reverse the intent of surgery, with larger changes observed to the resected MR muscle compared to the recessed LR muscle in one animal and the reverse in the other. Some of these data have been presented before in abstract form (Pullela M, et al. IOVS 2015;56:ARVO E-Abstract 5221) (Agaoglu MN, et al. IOVS 2015;56:ARVO E-Abstract 5222).

MATERIALS AND METHODS

Subjects and Rearing Paradigms

All procedures in this study were performed according to National Institutes of Health guidelines and the ARVO Statement for the Use of Animals in Ophthalmic and Vision Research, and the protocols were reviewed and approved by the Institutional Animal Care and Use Committee (IACUC) at the University of Houston. The study consisted of two juvenile rhesus monkeys, M1 and M2 (Macaca mulatta) (~6 years of age, 9-10 kg). Strabismus was induced in infancy using an optical prism-rearing method. In this method, the infant monkeys wore a lightweight helmet fitted with a horizontally oriented Fresnel prism in front of one eye and a vertically oriented prism (20 PD each) in front of the other eye. Prism viewing started within 48 hours of birth and continued until they were ~ 4 months of age, after which they were allowed unrestricted vision. Disruption of binocular vision (due to binocular decorrelation as a consequence of prism viewing) during the critical period is successful in inducing misalign-



FIGURE 1. Schematic illustrating the surgical approach used to treat misalignment and the organization of motor nuclei projecting to each EOM. In strabismus surgery to correct exotropia, the "weak" medial rectus (MR) is strengthened by shortening the muscle length via a resection procedure while the "strong" lateral rectus (LR) is weakened by changing the point of insertion toward a more posterior location on the globe via a recession procedure. M1 underwent treatment on his left eye and M2 underwent surgery on his right eye. In this study, neuronal recordings were carried out within both oculomotor (OMN) and abducens (ABD) nuclei.

ment and other eye movement abnormalities associated with strabismus.^{7,8,19,26,27}

Surgical Preparations and Treatment of Strabismus

When the monkeys were approximately 4 to 5 years of age, they underwent an aseptic surgical procedure while anesthetized with isoflurane (1.25%-2.5%) to implant a titanium head stabilization post²⁸ to prevent head movements during experiments. In a second surgery, a scleral search coil was implanted in one eye using the technique of Judge and colleagues²⁹ to measure eye movements. In this same surgery, we also implanted a 21-mm-diameter cylindrical titanium neural recording chamber centered at a stereotaxic location 1 mm anterior, 1 mm medial, and 8 mm dorsal to stereotaxic zero for M1, and 3 mm anterior, 1 mm lateral, and 8 mm dorsal to stereotaxic zero for M2. In both animals, the chambers were also tilted 20° dorsolateral to ventromedial in the coronal plane. This chamber location allowed access to both abducens and both oculomotor nuclei from within the same chamber. In a subsequent surgery, the fellow eye was also implanted with a search coil for binocular eye movement recording.

After initial behavioral training on standard oculomotor tasks and neurophysiological recording from each of the four motor nuclei to acquire pretreatment data, the monkeys underwent a standard clinical resect-recess surgery (to correct the strabismus) that was performed by an expert strabismus surgeon and also one of the study authors (Fig. 1). Muscle resection involves removing a section of muscle and therefore "strengthens" the muscle due to its reduced length. Muscle recession involves repositioning the muscle insertion to a more posterior location and therefore "weakens" the muscle because the muscle is less effective in transmitting torque to the globe. Since both monkeys were exotropic (exotropia or divergent strabismus is frequently attributed to weak MR muscles and strong LR muscles), the MR muscle of one eye was strengthened by resection, and the LR muscle of the same eye was weakened by recession. By design, surgical treatment was performed on only one eye (M1 left eye, M2 right eye) so that the fellow eye, including its EOM and corresponding motor nuclei, could serve as a control (Fig. 1).

Data Acquisition and Experimental Procedures

Binocular eye position was measured using the scleral search coil technique (Primelec Industries, Regensdorf, Switzerland). Calibration was performed as the monkey monocularly fixated within a $\pm 2^{\circ}$ window surrounding an optotype target that was back projected onto a tangent screen at a distance of 57 cm. Visual targets were generated using a BITS# stimulus generation system (Cambridge Research Systems, Rochester, UK) and presented using a DepthQ LCD projector (Lightspeed Design, Inc., Bellevue, WA, USA). Monocular viewing was enforced by occluding one of the eyes using liquid crystal shutter goggles (Citizen Fine Devices, Nagano, Japan) under computer control. Binocular eye position, target, and neuronal data were collected as the monkeys performed a smooth-pursuit task $(0.3 \text{ Hz}, \pm 15^{\circ})$ during monocular viewing with either the left or right eye. Eye and target position signals were passed through antialiasing filters at 400 Hz before digitization at 2.79 kHz with 12-bit precision (AlphaLab SNR system; Alpha-Omega Engineering, Nazareth, Israel). Raw spike data were collected at a sampling rate of 44 kHz and sorted offline to generate time stamps of spiking activity (Spike 2 software, Cambridge Electronic Design, Milton, Cambridge, UK). During further analysis using custom software developed in MATLAB (Mathworks, Natick, MA, USA), spike time stamps were convolved with a 15-ms standard deviation Gaussian to obtain a continuous spike density function of firing rate. Since the frequency of smooth-pursuit stimulation was low, target and eve movement data were further filtered using a finite impulse response (FIR) low-pass filter with a cutoff of 20 Hz or 50 Hz.

Data Analysis

A frequently used monocular first-order equation (Equation 1) was used to fit the neuronal firing rates with smooth-pursuit eye movement data and estimate model coefficients, *K*, *R*, and $C^{21,30,31}$:

$$FR(t) = K * E_{pos}(t) + R * E_{vel}(t) + C$$
⁽¹⁾

In this equation FR is firing rate of the neuron being recorded, E_{pos} and E_{vel} are the position and velocity of the eye that is controlled by the muscle to which the neuron projects; K is the position sensitivity of the neuron, R is the velocity sensitivity of the neuron, and C is the baseline firing rate of the cell, that is, firing rate when the eye that this neuron projects to is viewing a straight-ahead target. For example, the firing rate of a cell within the right oculomotor nucleus (OMN) that shows increased burst-tonic activity for leftward movements (LTBT, projecting to the right eve MR) would be modeled (Equation 1) using the eye position and velocity of the right eye leading to estimates of K, R, and C for that cell. Likewise, the activity of a LTBT cell within the left abducens nucleus (projecting to left eye LR) would be fit using the position and velocity information of the left eye. Some studies have suggested that a binocular model using position and velocity terms of both the ipsi- and contralateral eye is a better representation of motoneuron responses.^{30,32,33} Since the main aim of the study was to investigate treatment effects, we decided that the monocular model to fit the neuronal firing and eye data would be the simplest and most interpretable approach. It is likely that a subset of the neurons recorded from the abducens nucleus are abducens interneurons (AIN) that project to the contralateral OMN and not directly to the LR. AINs were not separated from the LR motoneurons in our data because their response properties tend to overlap in the normal and are unknown in the strabismic. Additional rationale and implications of not separating the two subpopulations of abducens cells are provided in the Discussion.

Eye position signals were differentiated using a central difference algorithm, written in MATLAB to obtain eye velocity. Previous studies have shown that position and velocity coefficients estimated during fast eye movements such as saccades are different from those estimated during slow eye movements such as smooth pursuit or fixation.³¹ Therefore the smooth-pursuit data were "de-saccaded" prior to fitting. Saccades were detected using a 40°/s velocity criterion, and eye and corresponding neuronal data during saccades were removed from the analysis. Model fitting was performed such that the eye position, velocity, and neuronal data were resampled with replacement and fitted with the model in Equation 1 and thereafter repeated 500 times. The model coefficients were deemed significant if the 95% confidence intervals for each coefficient did not overlap with zero. Eye movement and corresponding neuronal data from both right eye and left eye viewing conditions were concatenated during model fitting to develop the estimates of K, R, and C.

After model coefficients were calculated, an estimate of the population neuronal drive (ND) to the lateral and MR muscles of the deviated eye during monocular fixation with the fellow eye was calculated using Equation 2:

$$ND = \sum (K * E_{strab} + C)/n \tag{2}$$

where ND stands for neuronal drive, E_{strab} is the mean position of the nonviewing eye (position of deviated eye or strabismus angle) with the viewing eye looking straight ahead (i.e., at zero position), *K* and *C* are coefficients obtained from Equation 1 for each of the cells projecting to the specific muscle in question, and *n* is the number of cells recorded from the corresponding nucleus. Note that the coefficient *R* is not considered in Equation 2 since ND is computed for a fixation condition (i.e., eye velocity is zero). In this framework, ND is equivalent to the average population neuronal activity innervating the EOM (either LR or MR depending on the nucleus) of the eye under the cover during fixation. In a neural sense, these ND are the reason that the eye under cover is deviated.

Neural data were collected longitudinally before and after treatment. For statistical analysis, the estimated measures were lumped and compared at three time intervals: Pre: data recorded before the surgery; P1: data recorded from day 1 to 1 month after treatment; P6: data recorded from 6 to 10 months after treatment. Statistical testing was carried out using a 1-way ANOVA at significance level of 0.05 following by Holm-Sidak method for post hoc testing unless otherwise specified.

RESULTS

Prior to treatment, monkey M1 had a mean exotropia of $\sim 15^{\circ}$ with the left eye viewing (LEV) and $\sim 30^{\circ}$ with the right eye viewing (REV) while M2 showed an exotropia of $\sim 20^{\circ}$ during REV and $\sim 35^{\circ}$ during LEV. On the first day following a resectrecess surgery on one eye, eye misalignment reduced by $\sim 70\%$ of presurgical values in both M1 and M2 when viewing with the treated eye. Figure 2 shows the longitudinal progression of strabismus angle in M1 and M2 before and after surgical correction. The data show that by the end of the P6 recording period, both monkeys showed large-angle exotropia once again. Additional details of the longitudinal change in alignment and dynamics of eye movements can be found in our previous publication.³⁴ Note that the data points on the plot shown here are chronologically arranged based on days when neural recording yielded cells. Frequently, more than one cell was recorded on a specific day. Note that the presurgery data point in Figure 2 is based on an average of 81 points in M1 and 93 points in M2 collected over a period of ~1 year,



FIGURE 2. Longitudinal changes in horizontal strabismus angle (*top*: M1; *bottom*: M2). The *x*-axis indicates the time after surgery in days. The data points before the 0 on the *x*-axis (presurgery data) represent the average misalignment recorded over \sim 1 year before the surgery. The negative strabismus angle indicates exotropic misalignment. *Blue* and *red* correspond to the strabismus angle when viewing with the left eye (LEV) and right eye (REV), respectively. The *symbols* after the surgery represent average strabismus angle on a single day, and the *lines* indicate the best-fitting exponential decay function (decay constants: M1, 24.3 days—LEV, 7.7 days—REV; M2, 30.8 days—LEV, 22.3 days—REV). *Error bars* represent ±SD around the mean.

whereas the alignment data reported in the behavioral study published earlier reported presurgical strabismus angle values from the days immediately before the surgical treatment. Alignment data were also recorded on days that did not yield successful neuronal recording, but these are not shown in the plot.

In total, data from 530 burst-tonic motoneurons were collected in the two awake-behaving animals across different time intervals and in the four motor nuclei. The Table shows the distribution of cells collected from each nucleus and at each time interval.

Changes in K, R, and C Following Surgery

Most studies investigating motoneuron responses have used a first-order model (Equation 1) to characterize response properties. Figure 3 shows two representative cells recorded from the left abducens of monkey M1 (left burst-tonic MNs), one recorded before and the other 1 day after surgical

TABLE. A Summary of the Number of Cells Recorded From Each Oculomotor (OMN) and Abducens Nucleus in M1 and M2 Across Each Time Point

Subject	Right OMN	Left OMN	Left Abducens	Right Abducens
M1				
Pre	9	13	28	36
P1	20	16	19	23
P6	15	19	28	18
M2				
Pre	24	24	42	25
P1	22	25	16	21
Р6	26	24	17	20

treatment. The monkey was able to perform the smoothpursuit task with normal-looking eye movements even the day after surgery, and neuronal responses from both these cells are well fit using the first-order model with goodness of fit of 0.89 and 0.97, respectively. Average R^2 values at each time interval were 0.87 \pm 0.12 at Pre; 0.88 \pm 0.1 at P1, and 0.86 \pm 0.14 at P6, suggesting that the first-order model was an adequate representation of neuronal responses both before and after surgical treatment of strabismus.

Figure 4 shows a summary of the average position sensitivity coefficient (K), velocity sensitivity coefficient (R), and baseline firing (C) calculated from Equation 1 at each time interval for the four motor nuclei (left and right OMN, left and right abducens). As described earlier, Equation 1 employs the position and velocity of the eye controlled by the muscle to which the neuron projects and smooth-pursuit data from both right eye and left eye viewing conditions were concatenated prior to fitting. Neuronal sensitivity coefficients of neurons projecting to the muscles of the treated eye are shown in Figures 4A, 4C, and 4E, and the coefficients of neurons projecting to the muscles of the untreated eve are shown in Figures 4B, 4D, and 4F. Fundamentally, the changes in each of the coefficients over the different time intervals were complex and variable across the two monkeys. Overall trends for coefficients, with some exceptions, were to change at P1 but return close to presurgical values by P6.

The position coefficient *K* obtained from model fitting of the firing rates of medial rectus motoneurons projecting to the treated (left) eye in M1, that is, RTBT MRMN within left OMN, increased significantly (P=0.01) after surgery (at P1) while the position coefficient (*K*) associated with the lateral rectus motoneurons (LTBT LRMN within left abducens) projecting to the treated eye showed no significant changes (P = 0.64). In M2, the *K* values associated with MRMN or LRMN projecting to the treated right eye (LTBT MRMN within right OMN and RTBT LRMN within right abducens) at P1 showed no significant changes compared to presurgical values. *K* values at P6 for both animals were similar to presurgical values except for the M2 abducens cells.

The R coefficient is related to the velocity of eye movements and is likely to reflect disruption in eye movement dynamics rather than static misalignment. In the treated (left) eye of monkey M1, R values decreased for LTBT abducens cells and increased for RTBT OMN cells at P1, but reverted to presurgical values at P6 for the OMN cells but not the abducens cells. In the treated (right) eye of M2, R values of LTBT OMN cells showed no significant changes at P1 or P6 while R values of abducens cells increased after surgical treatment at P1 and P6. In our previously published study describing the eye movement data from these same animals before and after surgical treatment, eye alignment changes were large and obvious but eye velocity changes (i.e., saccade peak velocity, and smooth-pursuit gains) were small, idiosyncratic, and inconsistent across the animals and directions of eye movement.³⁴ Correlating the dynamic changes in eye movements with the changes in the R coefficient was therefore challenging and not pursued in detail.

The coefficient *C* represents the firing rate of the cell when the animal is fixating straight ahead. In general, prior to surgery, the *C* values of MRMN in both the treated and the untreated eyes in our exotropic monkeys were higher than the *C* values obtained from the LRMN and also higher than reported values in normal monkeys of ~80-100 spikes (spks)/ s.^{35,36} One interpretation of the difference in *C* value between normal and exotropic monkeys is that muscle length adaptation changes the set point of the eye toward a more abducted location when compared to the normal animal and therefore viewing straight ahead would involve a relaxation of the LR and



FIGURE 3. Representative left burst-tonic cells recorded from the left abducens nucleus of M1 before and after surgery. The *top row* shows the average horizontal eye movement traces from multiple cycles of smooth pursuit. Positive numbers represent rightward eye position and negative numbers represent leftward eye position. Left eye position is shown in *blue* and right eye position is in *red*. The *bottom row* shows the corresponding neural responses (spike density function of firing rates). (A, B, E, F) Presurgery data (K = -2.09 spks/s per degree, R = -1.23 spks/s per °/s, C = 51.4 spks/s, $r^2 = 0.89$); (C, D, G, H) data from a cell recorded 1 day after surgical treatment (K = -5.14 spks/s per degree, R = -1.25 spks/s per r^2 , S = 0.97).

contraction of the MR from this new set point, resulting in an increase in *C* values of the MRMN and reduction in *C* values of the LRMN compared to the normal animal.

In the treated eye in M1, changes in *C* values were not significant at the various time points. In M2, at P1 there was a reduction in *C* values of MRMN (P = 0.02) and increase in *C* values of LRMN (P = 0.002), and these values reverted toward presurgical values by P6.

In general, changes in coefficients of cells projecting to muscles of the untreated eye showed similar complex changes. In some cases, the trends were similar to those seen in cells of the treated eye muscles (e.g., lower C values from the left and right abducens MN at P6 compared to P1 in M2) while in other cases, the trends were different (e.g., the significant decrease in the *C* value of the MRMNs within the right OMN compared to no changes in the *C* value of the MRMN within the left OMN of M2).

Changes in Neuronal Drive Following Surgery

Our goal was to estimate the longitudinal change in neural signals that are driving the covered eye to be deviated at preand posttreatment time points. Therefore, to get a handle on the total neural activity that is determining the position of the deviated eye during fixation (state of strabismus), we calculated a ND to each EOM of the deviated eye (estimated from the population activity within each of the OMN and abducens nuclei, Equation 2). If there were no changes in ND across the time intervals, then the longitudinal changes in strabismus angle could be attributed to muscle remodeling factors only. On the other hand, central neural adaptation would manifest as changes in ND to EOM across the different time points.

Figure 5 shows the estimated average NDs over each time interval to each of the EOMs of the deviated eye while the fellow eye is fixating straight ahead. Figures 5A and 5C show ND estimates to muscles of the treated eye when the untreated eye is viewing. In general, the NDs from OMN (purple bars) are lower than the abducens NDs (green bars), which could be an

indication of the neural basis for exotropia in these monkeys. For comparison, the ND to the MR in normal monkeys when looking straight ahead, as derived from the literature, is ~ 83 spks/s, 35,37 and the ND to the LR of normal monkeys is ~ 77 spks/s.^{31,38} In monkey M1, in the immediate time period after surgery (at P1, Fig. 5A), the ND to the MR was reduced significantly (Holm-Sidak post hoc comparison, P = 0.004) compared to presurgical ND while the LR ND remained the same (P = 0.11). Such an overall reduction in ND to only the MR would result in the eye being pushed toward a more exotropic state. The postsurgical eye alignment in M1 at P1 when the untreated eye is viewing is therefore the consequence of beneficial EOM treatment (MR resection and LR recession) plus an adaptive neuronal change to MR drive that is effectively attempting to negate the effect of surgery. By P6, NDs to the treated MR had reverted to presurgical values and LR drive remained unchanged. Such a combination should ideally result in an overall reduction of exotropia by P6, but the recurrence of large exotropia suggests a possible role of EOM remodeling over the long term negating the effects of treatment.

The result in M2 at time P1 was different. The treated eye of M2 received an increased ND to the treated LR (P < 0.001) compared to presurgery while the ND to the treated MR was unchanged (P = 0.43). An increase to the LR drive is detrimental in that its effect would be to increase exotropia. Therefore, in M2, the postsurgical strabismus angle at P1 observed when viewing with the untreated eye is a result of the benefits of altered muscle contractility due to surgery and a "negative" adaptive neuronal change to the LR. By P6, the NDs to the treated LR reverted to presurgical values while the ND to the treated MR remained unchanged. Similar to M1, the recurrence of large-angle exotropia suggests a possible role of EOM remodeling.

When the treated eye is forced to view the straight-ahead target (Figs. 5B, 5D), ND to the muscles of the same treated eye must change in comparison to the presurgical state to compensate for its altered muscle properties. Therefore ND to certain muscles of the deviated untreated eye will also



FIGURE 4. (**A**, **C**, **E**) The mean (\pm standard error) of the position coefficient (*K*), velocity coefficient (*R*), and baseline firing (*C*) at each time interval (Pre: before undergoing surgical correction; P1: through 1 month after correction; P6: through 6 to 10 months after correction) from motoneurons projecting to muscles in the treated eye in M1 and M2; parameters obtained from cells projecting to muscles in the untreated eye are summarized in (**B**, **D**, **F**). The parameters associated with oculomotor neurons are shown in *purple* and parameters associated with abducens neurons are in *green*. *Solid lines* are data associated with monkey M1, and *dotted lines* are data associated with monkey M2. The *symbols* represent statistical significance for M1 data while the *circles* represent statistical significance for M2 data.

automatically change due to the anatomic connections between the treated eye abducens nucleus and contralateral (untreated eye) OMN.³⁹ This sort of change should not be considered an adaptive response. In M1, the untreated eye received an increase in ND to the MR (P = 0.008) and a decrease in ND to the LR (P = 0.039) at time P1. While the increase in MR ND may be due to an accompanying change within the abducens of the fellow eye (not an adaptive response), the decrease in ND to the LR is evidence of neuronal adaptation of the untreated eye. The same result was observed in monkey M2 also at time P1. The combined effect results in a smaller strabismus angle after treatment when viewing with the treated eye. Both LR and MR drives reverted toward presurgical values by P6.

Predicted Changes in Muscle Contractility

In addition to the central innervation remodeling, it is likely that some of the final alignment is due to changes in muscle properties. Indirect evidence for muscle remodeling can be gained from the fact that, at P6, strabismus angle and NDs were similar to presurgical values although the muscles had been substantially modified by the surgical procedure. Adaptive changes in muscle following EOM surgery or binocular vision disruption have been suggested in other studies also.^{15,40} Although we did not directly measure contractility in this study, we are able to quantitatively estimate the changes in contractility using a simple Hooke's-law based modeling method that uses the eye alignment measures (ϕ) and the recorded ND.

According to Hooke's law, the force (ND) needed to extend a spring (EOM) scales linearly with distance (eye position) and is determined by its spring constant (measure of EOM contractility). The equations in Figure 6 describe the Hooke's law relationship between the ND, EOM spring constants (k1, k2, k3, k4), and the eye positions of the viewing and deviated eyes during either treated eye viewing or untreated eye viewing. The NDs to the muscles of the deviated eye are available from Equation 2 and Figure 4. NDs to the muscles of the viewing eye (ND1, ND2 during treated eye viewing and ND3, ND4 during untreated eye viewing condition) are simply the *C* term from Equation 1. Since the position of the deviated eye (φ^{TEV} and φ^{UEV}) is basically the strabismus angle and is also a measured quantity, we are able to estimate the contractility coefficients k1 through k4.

The contractility coefficients were obtained using a bootstrapping technique in which 10,000 data sets were generated using resampling with replacement. The mean contractility coefficients along with standard errors obtained using this bootstrapping method are shown in Figure 7. A 1-way ANOVA



FIGURE 5. (A, B) The mean and standard error of the population neuronal drives (ND) to the EOM of the treated (A) and untreated eye (B) for M1. (C, D) ND to the treated eye and the untreated eye, respectively, for M2. Drives to the lateral rectus from the abducens nucleus are in *green* and drives to medial rectus from the oculomotor nucleus are in *purple* for each time point. The *asterisks* represent statistical significance when compared to the preceding time point while an *asterisk* on the Pre time point represents a significant difference when compared to the P6 time point.

was used to detect statistical difference among groups, and Holm-Sidak post hoc testing was used for multiple comparisons.

The contractility of the treated LR decreased at P1 with an accompanying increase in the contractility of the treated MR in both M1 and M2. This is to be expected of a LR recess and MR resect surgery. However an improper adaptive response

occurred in treated eye muscles by P6, more pronounced in M2. In both animals, contractility of LR increased and MR decreased compared to P1, indicative of muscle remodeling that contributed to the recurrence of exotropia at P6.

Adaptive changes were also observed in the untreated eye although only in certain muscles. In M1, the contractility of the



FIGURE 6. Schematic model for determining muscle contractility. *Left* part of figure develops equations for treated eye viewing conditions (TEV) and *right* part develops equations for untreated eye viewing (UEV) conditions. ϕ^{TEV} and ϕ^{UEV} are the positions of the deviated eye during treated eye viewing and untreated eye viewing, respectively, basically the strabismus angle. ND represents the neuronal drive from each nucleus. k1 through k4 represent muscle contractility coefficients and are the parameters to be estimated.



FIGURE 7. Mean and standard deviation of muscle contractility estimated via the analytical method described in Figure 6. (\mathbf{A} , \mathbf{B}) The MR (k2, k3) and LR (k1, k4) contractility in M1 treated and untreated eye, respectively; (\mathbf{C} , \mathbf{D}) the MR and LR contractility in M2 treated and untreated eye, respectively. The *asterisks* represent statistical significance with the same convention as in Figure 5.

untreated LR increased significantly at P1 and, although decreased by P6, remained higher than the presurgical values. In M2 the contractility of the untreated MR did not change much at P1 but decreased to below presurgical values by P6. The untreated eye contractility changes in both animals are not beneficial from an alignment perspective as they shift the eye toward exotropia.

It should be noted that our method to assess muscle contractility is indirect at best. Although we expect that this is a reasonable proxy for changes in muscle properties, the most direct method of studying contractility would be to examine specimens of EOM themselves and study muscle contraction properties.⁴¹⁻⁴³

DISCUSSION

The main aim of this study was to investigate, longitudinally, the neuronal changes that follow a typical strabismus correction surgery in prism-reared strabismic monkeys. Both monkeys in the study showed large-angle exotropia prior to strabismus correction surgery, which decreased by \sim 50% to 70% immediately after surgery. The strabismus angle underwent rapid change toward increasing exotropia in the first month after correction (0- to 30-day blocks in Figs. 2A, 2B) and approached presurgical levels of exotropia by the end of the P6 period. Recurring exotropia after surgical correction of strabismus is also commonly seen in human subjects and is viewed as a significant clinical problem.^{44,45} Here, we discuss the neuronal and muscle changes that could drive the behavioral changes in alignment following surgery.

Changes in the Neuronal Drive From the OMN and Abducens

It is inappropriate to directly correlate changes in sensitivity (coefficients in Equation 1) to change in alignment or eye movements because multiple terms in the first-order equation must be considered together to assess neuronal responses during fixation (static: K and C) or eye movements (dynamic: K, R, and C). Further, interpreting the changes in K, R, and C across the three time intervals is not a direct reflection of the changes occurring at the neuronal level because the sensitivity coefficients convey the combined effect of the motoneurons and the muscle. For example, when the length of a muscle is changed via resection, the calculated position coefficient K of a cell projecting to a muscle of the deviated eye will change even if the muscle receives the same neuronal command from the motoneurons because the eye is at a different position than before resection. The ND derivation (Equation 2) gives a better comparative summary and comprehensive understanding of neural adaptation because it reflects the total output from the brain directed toward a specific EOM and can be calculated unequivocally for each of the time intervals.

In M1, the ND from the left OMN to the treated MR decreased right after surgery, despite the improvement in the strabismus angle. This works against the aim of the correction surgery, as a reduction in ND from the OMN would result in a temporal shift of eye position (toward more exotropia). The ND from the left (treated) abducens did not change at any of the time intervals. This suggests that the immediate improvement in strabismus angle in this monkey is due to the change in effective muscle contractility due to the surgical procedure whose effect was unfortunately partially countered by the reduced ND to the MR. In monkey M2, the ND from the right OMN to the treated MR remained relatively unchanged following surgery. However, there was unfortunately an accompanying increase in the ND to the treated LR, which will tend to pull the eye temporally (increased exotropia). It was interesting that these changes in NDs were largely reversed by P6. It could have been fruitful to be able to monitor changes in population neural drive on a finer time scale (e.g., on a day-to-day basis in the first month after surgery) than what we have reported in the study. Unfortunately, the

single-unit recording method does not yield data from sufficient numbers of cells on a daily basis to be able to make reliable conclusions on changes in neural drive that may be occurring on a day-to-day basis after surgery. Also, the size and location of the oculomotor and abducens nuclei do not make it particularly amenable to array recording techniques.

When the treated eye is fixating, the increase in ND from the untreated OMN to the untreated MR at P1 could, at least partially, be due to an increase in ND within the treated side abducens nucleus because the LR to which the treated abducens projects had been weakened by recession and therefore needs greater innervation (relative to presurgery) when fixating a straight-ahead target. Therefore, this increase qualitatively reflects Hering's law and would not constitute an adaptive response. A postsurgical reduction was also observed in the ND from the abducens to the untreated LR resulting in an improvement in the strabismus while viewing with the treated eye. This is likely to be an adaptive neuronal response whose mechanism is yet unknown. Note, however, that adaptive muscle changes have been previously reported in the untreated eve of rabbits undergoing EOM surgery,⁴⁶ and therefore adaptive neuronal changes to untreated muscle is not entirely unexpected.

In summary, although the misalignment reverted to presurgical values in both M1 and M2, it appears that the sequence of neuronal plasticity driving these changes was different in the two animals. Thus, in M1, surgery was rendered ineffective because of reduced ND to MR ("bad" plasticity) while in M2, surgery was rendered ineffective because of increased ND to LR (also "bad" plasticity). In both monkeys, the neural plasticity appears to commence immediately after treatment and is largely back to presurgical values by 6 months after surgery.

Combined Effects of Neuronal Plasticity and Muscle Remodeling

Our analysis of NDs and muscle contractility allows an overall view of what happens as a consequence of strabismus correction surgery. Although both animals showed longitudinal alignment changes that indicate progressive failure of the strabismus correction procedure, the actual neural and muscle changes showed some similarities and some differences between the animals. In the treated eye of both animals, contractility changes following surgery (at P1) were in the appropriate direction (MR contractility increased and LR contractility decreased). However, a neural de-adaptive response also commenced (reduction in neural drive to MR in M1 and increase in neural drive to LR in M2), partially offsetting the contractility changes. Although the neural deadaptive signals were largely gone by P6 (i.e., NDs returned toward presurgical values), the contractility changes had also unfortunately reversed. Contractility changes in M2 at P6 appeared to be more severe, with a reduction in MR contractility to below presurgical values. It was interesting that adaptive neural and muscle changes were observed in the untreated eye of both animals that help to set the strabismus angle when viewing with the treated eye. Specifically, changes in ND to LR muscles from the abducens (Figs. 5B, 5D) and the change in MR contractility (Fig. 7D) would constitute adaptive responses.

Other Considerations

Data from this study support a role for unwanted neuronal and muscle plasticity that together results in reversion of strabismus angle. Fundamentally these studies seem most pertinent to humans with infantile exotropia and likely also esotropia. It is unknown how plasticity might have progressed in other common forms of strabismus such as intermittent exotropia. Although the same type of surgery was performed by the same surgeon on the prism-reared experimental monkeys, the plastic changes following surgery were unique to the two monkeys. The variability of plasticity of the ND and muscle contractility in response to surgery possibly might be the source of the large variability seen in outcomes of strabismus surgery in human patients.⁴⁷ One study reported a success rate of 34% after the initial strabismus correction surgery that rose to 63% after repeated procedures.¹⁴ It is unclear how the brain and the muscles would respond to multiple surgical procedures, and additional primate studies are required to study the effect of multiple procedures on neural and muscle plasticity.

It is also unknown how plasticity might have proceeded if the immediate effect of muscle surgery had been to reduce strabismus angle further than what was currently achieved. It is possible that the nature of plastic changes may have been more helpful if the immediate postsurgical misalignment were small and there was residual binocular vision to "lock" the eyes in an aligned state. Considering the large-angle exotropia in our monkeys, operating on EOM of both eyes might have produced better alignment immediately after surgery. However, we made the decision to operate on muscles of only one eye to be able to distinguish neural drive changes and muscle changes to a treated and an untreated eye.

A concern is whether the use of implanted scleral search coils to measure eye movements (e.g., as opposed to a videobased eye tracker) could have influenced the results and interpretation. The coil system is a widely used measurement method in both normal and strabismic animals and is reliable and precise.⁴⁸ Care is taken during the implantation of the scleral search coils not to disrupt the EOMs and likewise not to disturb the coils when performing the strabismus correction surgery. Finally, since the same system is used at all time points for measurement, the possibility of influence of the coils on interpretation of longitudinal adaptive changes is further minimized.

The consistent change that we have identified across the two animals is that failure of strabismus surgery is driven by adaptive changes from the brain and adaptive changes within the muscle. This is likely to be a consistent finding in all cases of strabismus surgery failure. The timing of the observed changes is also fairly consistent across the two animals. The variability across the two animals (possibly also reflecting the variable response in humans) lies in the magnitude and mechanism of neural adaptation, and these central mechanisms that drive the adaptive changes that are eventually reflected in the motoneuron activity need further investigation. For example, these changes could be driven by proprioceptive feedback mechanisms (although poorly understood at the moment) that are potentially affected by surgery. Alternatively, if adaptation is driven by availability of binocular vision, then cortical binocular areas and oculomotor vergence areas might be involved. Generally, the cerebellum is considered the seat of neural adaptation in the oculomotor system, and it may be that cerebellar circuits are also involved in the postsurgical neural adaptive process.

In making population estimates of LR ND, we have used the data from all of the cells when almost certainly part of the recorded population comprises abducens internuclear neurons (AIN) that project to the contralateral OMN via the medial longitudinal fasciculus.^{39,49} Other studies that have studied abducens populations have used the same approach.^{22,31} Fuchs and colleagues³⁸ used antidromic activation methods to precisely identify LRMN and AIN and suggested that there was a unique threshold-velocity sensitivity relationship for the LRMN population but not for the AIN population. Sylvestre and

Cullen³⁰ used this relationship to construct an upper and lower boundary to classify the population of abducens neurons in their study. Such an approach could not be used in our study due to the horizontal misalignment in our animals. However, it should be noted that these authors also showed that the detected AINs do not always encode the monocular position and velocity of the contralateral eye in isolation. Studies have found that groups of abducens neurons identified as AINs and LRMNs behaved similarly during converging eye movements.^{35,50} A more recent study comparing vergence and conjugate sensitivities of normal monkey abducens neurons reported similar findings, suggesting that the response characteristics of AINs and LRMNS are largely similar.³⁷ It is unknown whether the same framework is applicable for a strabismic model and further in postsurgical conditions when NDs appears to adapt (Agaoglu M, et al. IOVS 2014;55:ARVO E-Abstract 2572). Since we are not unequivocally identifying AIN and LRMN, even if unlikely, the consideration must be left open that postsurgical neuronal plasticity is asymmetric between these neuronal populations.

CONCLUSIONS

In conclusion, we show that both neuronal and muscle plasticity occurs in the aftermath of strabismus correction surgery. Plasticity affects both the treated eye and the untreated eye. Although our sample size was low and therefore inferences must be treated with caution, we suggest that resection is more prone to failure either due to inappropriate neuronal plasticity that drives the eye to exotropia (monkey M1) or due to inappropriate muscle plasticity that counters the goal of increased contractility and therefore drives the eye to exotropia (monkey M2). In any case, most of the neuronal plasticity appears to occur in the immediate aftermath of surgery, and so efforts to improve surgical outcomes could be tuned to developing strategies that prevent "bad" plasticity.

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