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A deep learning model for prediction of lysine crotonylation sites by fusing multi-features based on multi-head self-attention mechanism

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Lysine crotonylation (Kcr) is an important post-translational modification, which is present in both histone and non-histone proteins, and plays a key role in a variety of biological processes such as metabolism and cell differentiation. Therefore, rapid and accurate identification of this modification has become a key task to study its biological effects. In the past few years, some calculation methods have been developed, but there is room for improvement in prediction performance. In this paper, we propose an effective model named DeepMM-Kcr, which is based on multiple features and an innovative deep learning framework. Multiple features are extracted from natural language processing features and hand-crafted features, where natural language processing features include token embedding and positional embedding encoded by transformer, and hand-crafted features include one-hot, amino acid index and position-weighted amino acid composition, and encoded by bidirectional long short-term memory network. Then natural language processing features and hand-crafted features are fusing by multi-head self-attention mechanism. Finally, a deep learning framework is constructed based on convolutional neural network, bidirectional gated recurrent unit and multilayer perceptron for robust prediction of Kcr sites. On the independent test set, the accuracy of DeepMM-Kcr is highest among the existing models. The experimental results show that our model has very good performance in predicting Kcr sites. The source datasets and codes (in Python) are publicly available at https://github.c om/yunyunliang88/DeepMM-Kcr.

Keywords Lysine crotonylation sites, Natural Language processing, Hand-crafted features, Multi-head self-attention mechanism, Convolutional neural network, Bidirectional gated recurrent unit

Protein post-translational modifications (PTMs) alter the properties of proteins by proteolytic cleavage and the addition of modification groups. Any protein in the proteome can be modified during or after translations^{1,2}. PTMs play an important role in many biological processes such as DNA replication, cell differentiation, embryonic development, gene activation and gene regulation^{3–5}. These PTMs can regulate protein stability and biological activity by affecting protein structure. With the upgrading and development of mass spectrometry detection technology, more and more PTMs have been identified, including a series of short-chain lysine acylation modifications, such as butyrylation, propionylation, succinylation, malonylation, crotonylation and benzovlation⁶.

Lysine crotonylation (Kcr) is a crucial post-translational modification (PTM), where "K" represents lysine, "cr" represents crotonylation, that is, Kcr represents lysine crotonylation. In 2011, Tan et al. defined Kcr using mass spectro proteomics in human cells and mouse germ cells⁷. This modification is widespread in both histone and non-histone proteins, particularly in chromatin regions associated with active transcription. Kcr plays significant roles in regulating gene expression, maintaining chromatin structure, and controlling reproductive processes. Additionally, research has shown that Kcr is involved in various physiological and pathological processes, such as tissue injury, inflammatory responses, and cancer development. It also plays important roles in neuropsychiatric disorders, telomere maintenance, and HIV latency^{8–12}. With the advancement of

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proteomics technologies, including high-performance liquid chromatography-tandem mass spectrometry, stable isotope labeling, and specific antibody techniques, scientists have been able to comprehensively detect Kcr sites¹³. Traditional high-throughput experimental methods are time consuming and expensive, so computational predictors based on machine learning algorithms are becoming mainstream solutions. Moreover, the development of machine learning, especially deep learning techniques, has allowed for accurate prediction of Kcr sites on large-scale datasets. These technological advancements not only enhance our understanding of Kcr, but also provide powerful tools for studying the dynamic regulation of proteins in various cellular contexts. Research into Kcr has revealed its multifaceted functions in gene transcription, cell cycle regulation, tissue repair, and more, offering new possibilities for the diagnosis and treatment of related diseases.

In recent years, several traditional machine learning-based tools have been developed for predicting Kcr sites. The earliest is CroPred, which is designed by using a discrete hidden Markov model (DHMM) based on amino acid sequence data to predict Kcr sites in histones¹⁴. Subsequently, the models of Qiu et al. ¹⁵, CKSAAP-CrotSite¹⁶, iKcr-PseEns¹⁷, iCrotoK-PseAAC¹⁸, LightGBM-CroSite¹⁹, Wang et al. ²⁰ and predML-Site²¹ are successively proposed.

With the widespread application of deep learning in bioinformatics, some prediction tools based on deep learning have been proposed one after another. In 2020, lv et al. developed the prediction tool named Deep-Kcr based on convolutional neural network (CNN)²². In 2021, Chen et al. developed a novel deep learning-based computational framework termed as CNNrgb for Kcr sites prediction on nonhistone proteins by integrating different types of features, and implemented an online server called nhKcr²³. In 2022, Qiao et al. proposed a computational method called BERT-Kcr, which extracted features from the BERT model and placed them into the bidirectional long short-term memory network (BiLSTM)-based classifier for Kcr sites prediction²⁴. Later, Khanal et al. proposed a model named DeepCap-Kcr by using a capsule network (CapsNet) based on CNN and LSTM²⁵. Also in 2022, Li et al. proposed a new deep learning model called Adapt-Kcr, which utilized adaptive embedding based on CNN as well as BiLSTM and attention mechanism²⁶. Meanwhile, in 2022, Dou et al. developed a CNN-based model framework called iKcr_CNN, which applied the focal loss function instead of the standard cross-entropy as the indicator to overcome the imbalance issue²⁷. In 2023, Khanal et al. developed a new model based on capsule network CapsNh-KCR, particularly focusing on non-histone proteins, which more effectively improves the experimental efficiency²⁸.

Although many models have been used to identify Kcr sites, the prediction accuracy of existing methods still needs to be improved, and better integration of hand-crafted features and natural language processing (NLP) features is needed. In this paper, a novel model named DeepMM-Kcr for Kcr sites prediction by fusing multifeatures based on multi-head self-attention mechanism. The multi-head self-attention maps NLP deep features and hand-crafted features to the same space through independent attention heads, avoiding conflicts caused by differences in feature types, each head can adaptively learn the importance of different features. First, multifeatures are extracted based on NLP technology using word embedding combined with transformer encoder. Hand-crafted features are extracted using one-hot, amino acid index (AAindex) and position-weighted amino acid composition (PWAA), which are concatenated with BiLSTM for encoding. Then, NLP features are pointwise added with hand-crafted features, and multi-head self-attention mechanism is adopted for features fusing. Finally, prediction is performed by integrating CNN, bidirectional gated recurrent unit (BiGRU) and multilayer perceptron (MLP) based on K-fold cross-validation and independent test. The prediction accuracy has reached 85.86% for independent test set, and improved 0.4% than that of best model called Adapt-Kcr²⁶.

Materials and methods Datasets

Datasets play an important role in establishment of the model. The datasets used in this paper are the same as those used by lv et al.²², which are originally constructed by Yu et al. in 2020^{13} from HeLa cell data, comprising 14,311 Kcr sites across 3734 proteins. After removing redundant sequences using CD-HIT²⁹ with 30% identity, 9964 non-redundant Kcr sites are retained as positive samples. To balance the dataset, 9964 non-redundant normal lysine sites are randomly selected as negative samples also from HeLa cells. Each sequence is truncated into 31 amino acids with lysine centrally located. If the center K of the segment with 31 amino acids is crotonylation, it is defined as a positive sample (Kcr), otherwise it is defined as a negative sample (non-Kcr). Then, the non-redundant dataset is divided into the benchmark set and the test set with a ratio of 7:3. The benchmark set includes 6975 positive samples and 6975 negative samples for cross-validation, and the test set includes 2989 positive samples and 2989 negative samples for independent test. More details of the datasets are shown in Table 1.

Dataset	Positive	Negative	Total
Benchmark set	6975	6975	13,950
Independent test set	2989	2989	5978

Table 1. Details of the datasets.

Transformer-based natural Language processing

Word embedding

Word embedding (WE) is a key technique in natural language processing, which transforms words in natural language into dense vectors, where similar words are represented by similar vectors. This transformation facilitates the exploration of features between words and sentences in text^{30,31}.

The Token embedding is a technique that converts text into a series of numbers, Token can be understood as the smallest unit used to segment and encode input text, which can be word, subword or character. Token embedding includes two parts: segmentation and encoding. Segmentation divides text into individual words or characters, while encoding assigns each word or character a unique numerical identifier. In this paper, each character represents an amino acid residue in an amino acid sequence, called a "token". This technique helps computer models capture the relationship and similarity between different unit in a sequence. In token embedding, we obtain the representation vector for each amino acid through a table lookup. Words need to be encoded according to different word segmentation methods and the words must exist in the vocabulary.

Positional embedding is a technique that helps a model understand the relative positions of elements in a sequence. Its core purpose is to solve the problem that the model cannot directly perceive the order of elements in the analysis of biological sequences such as DNA, RNA or proteins. It was originally derived from the work of Vaswani et al.³². They tested two approaches, one adaptive position embedding that can be learned and the other fixed position encoding. We choose to use fixed position encoding, using the sine and cosine functions to compute fixed representation vectors. The sequence length is N, and the positional embedding vector (PE) formula is shown as following:

$$\begin{cases}
PE_{(k,2i)} = \sin\left(\frac{k}{b^{2i/d}}\right) \\
PE_{(k,2i+1)} = \cos\left(\frac{k}{b^{2i/d}}\right)
\end{cases}$$
(1)

where k represents the position of each residue in the sequence $(0 \le k \le N-1)$, where N is the length of the sequence. d represents the dimension of positional embedding and must match the dimension of the token embedding. 2i represents even dimensions, 2i+1 represents odd dimensions, $0 \le i < d/2$, meaning only half of the embedding dimensions are used for the sine and cosine calculations. The constants b and d are predefined, d must match the dimension of the token embeddings. In this study, the values of b and d are set to 1000 and 128, respectively.

The combination of token embedding and positional embedding can improve the performance of the model more effectively²⁶. Hence, token embedding and positional embedding are point-wise addition (Add) as word embedding, which is expressed as follows:

word embedding = token embedding + positional embedding.
$$(2)$$

Encoder with transformer

The transformer, introduced by Vaswani et al.³², has gained widespread attention and popularity in the field of natural language processing (NLP)³³. It is structured around an encoder-decoder framework. In this paper, we use the transformer's encoder block to process the input word embedding. The encoder block structure of transformer is composed of multi-head self-attention mechanism (MHA), feed forward neural network (FFN), residual connection (Add) and layer normalization (Norm).

The self-attention mechanism, enables transformer to capture remote dependencies between sequence elements, and the core is to update the representation of each element in the input sequence by calculating its relationship to the other elements in the sequence. To achieve this, the self-attention mechanism introduces three matrixes: Query (Q), Key (K) and Value (V). These three vectors are generated from the representation of the input matrix X by linear transformation:

$$Q = XW^Q, K = XW^K, V = XW^V, \tag{3}$$

 W^Q, W^K and W^V are the weight matrix. We can calculate the output of self-attention by the following formula:

$$Z = \text{Attention}(Q, K, V) = \operatorname{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V,$$
 (4)

where the inner product of each row vector of the matrix Q and K is calculated by QK^T , which represents correlation score for each input word. To improve the stability of training and prevent gradient explosion, correlation score is normalized by dividing by the square root of d_k , d_k is the dimension of K. The score vector between each word is converted into a probability distribution between [0,1] using the softmax function. The softmax matrix can be multiplied by V to get the final output Z. The multi-head self-attention is formed by concatenating the input for multiple self-attention.

The encoder block structure of transformer is expressed as follows:

$$X_{MHA} = \text{LayerNorm}(X + \text{MHA}(X)),$$
 (5)

$$X_{out} = \text{LayerNorm}(\text{FFN}(X_{MHA}) + X_{MHA}), \tag{6}$$

where $FFN(X_{MHA}) + X_{MHA}$ and $FFN(X_{MHA}) + X_{MHA}$ stands for residual connection commonly used to solve the problem of multi-layer network training, allowing the network to focus only on the part that is currently different. Norm refers to layer normalization and is commonly used in RNN structure, where layer normalization converts the inputs to each layer of neurons to have the same mean and variance, which speeds up convergence. The feed forward neural network is a two-layer fully connected layer, the first layer uses the Relu activation function, the second layer does not use the activation function, the formula is as follows:

$$FFN(X_{MHA}) = Relu(X_{MHA}W_1 + b_1)W_2 + b_2, \tag{7}$$

where W_1 and b_1 are the weight matrixes and bias vectors of the first layer in the FFN. W_2 and b_2 are the weight matrixes and bias vectors of the second layer in the FNN.

Hand-crafted features

Hand-crafted (HF) features refer to the extraction of representative features from the original data, which is generally used in data analysis, modeling and prediction. Feature extraction is a very important step in machine learning. In this paper, we use one-hot, AAindex and PWAA for extracting hard-crafted features.

One-hot

One-hot (OH) coding 34,35 , also known as one-bit effective encoding, mainly uses N-bit status registers to encode N states, each state is composed of its own independent register bits, and only one bit is valid at any time. One-hot encoding is a representation of categorical variables as binary vectors. This first requires mapping class values to integer values. Each integer value is then represented as a binary vector that is zero except for the index of the integer, which is labeled 1. The one-hot coding solves the problem that the classifier is not good at processing attribute data, and plays a role in expanding the feature to a certain extent. Its values are only 0 and 1, and the different types are stored in vertical space. Finally, the dimension of the OH-based feature vector is 620.

AAindex

The amino acid index (AAindex) is a widely used database that contains indices based on multiple physicochemical and biochemical properties of amino acids³⁶. The AAindex database is used to extract major physicochemical properties based on the amino acid index to characterize protein fragments (31 residue long fragments in this study). For such fragments, the amino acids at each location are represented as 12 values based on their physicochemical and biochemical properties. These 12 values represent the following properties: net charge; normalized frequency of alpha-helix; alpha helix propensity of position 44 in T4 lysozyme; composition of amino acids (AA) in intracellular proteins; AA composition of membrane of multi-spanning proteins; the volume of crystallographic water; information value for accessibility; transfer energy, organic solvent/water; AA composition of membrane proteins; entropy of formation; conformational preference for all beta-strands and optimized relative partition energies²². Thus, for each fragment of 31 residues, the amino acids at each position are described by these 12 properties, resulting in a 372-dimensional feature vector. Such feature vector can comprehensively characterize various physicochemical and biochemical properties of protein fragments, and provide rich information for further bioinformatics analysis.

Position-weighted amino acid composition

Position-weighted amino acid composition (PWAA) is a method to encode sequence information based on the weight of the position of amino acids in a protein sequence³⁷. It takes into account the relative positions of amino acid residues in the sequence and reflects the position information by calculating weights. It takes the center of the sequence as the observation point and calculates the position weight of each amino acid residue relative to the center point. The size of the weight depends on the distance between the residue and the center point, usually the closer the distance, the greater the weight.

The specific steps are as follows: (1) Define a sequence fragment P of length 2L+1 (L is the number of upstream or downstream residues). (2) For each amino acid residue, and calculate its position weight C_i ($i=1,2,\ldots,20$) in sequence fragment P. (3) The calculation of position weights is usually based on a predefined function or rule that considers the position of the residue relative to the center point. (4) Finally, the dimension of the feature vector based on PWAA is 20 (corresponding to 20 amino acids), and the value of each dimension represents the sum of the position weights of the corresponding amino acids in the whole sequence²². The formula is as follows:

$$C_{i} = \frac{1}{L(L+1)} \sum_{i=-L}^{L} x_{i,j} (j + \frac{|j|}{L}) \quad (j = -L, ., 0, ., L),$$
(8)

where L indicates the number of upstream residues or downstream residues from the central site in the protein sequence fragment P, if the jth positional residue is a_i in protein sequence fragment P, $x_{i,j} = 1$, otherwise $x_{i,j} = 0$. Finally, the dimension of the PWAA-based feature vector is 20.

Encoder with BiLSTM

LSTM is an improved RNN model³⁸. Traditional RNN is prone to gradient disappearance or gradient explosion when dealing with long sequences, while LSTM solves these problems by introducing gating mechanisms (input gate, forget gate, output gate) to control the flow of information, thus better capturing long-term dependencies. The calculation formula is as follows:

$$\begin{cases}
f_t = \sigma(W_{fh}h_{t-1} + W_{fx}x_t + b_f) \\
i_t = \sigma(W_{ih}h_{t-1} + W_{ix}x_t + b_i) \\
\tilde{C}_t = \tanh(W_{Ch}h_{t-1} + W_{Cx}x_t + b_C) \\
C_t = f_t \odot C_{t-1} + i_t \odot \tilde{C}_t \\
o_t = \sigma(W_{oh}h_{t-1} + W_{ox}x_t + b_o) \\
h_t = o_t \odot \tanh(C_t)
\end{cases} \tag{9}$$

where $f_t, x_t, i_t, o_t, h_t, C_t$ and \tilde{C}_t represent forget gate, input data, update gate, output gate, cell state, memory cell and candidate state, respectively. W and W represent weight matrix and bias, respectively. W represents pointwise multiplication.

A one-way LSTM processes sequence data in only a single direction, usually from left to right of the sequence, and cannot combine the dependencies of sequence information. Therefore, it is a better way to choose BiLSTM for feature extraction. BiLSTM is essentially two LSTMs, one to process the sequence forward and one to process the sequence backward, and after processing, the output of the two LSTMs is concatenated. BiLSTM captures both forward and backward information of the sequence, which can greatly improve the effect of the model. The forward LSTM processes the sequence from beginning to end, generating a feature vector represented as $h_L = [h_{L,0}, h_{L,1}, \ldots, h_{L,T}]$. Meanwhile, the backward LSTM analyzes the sequence in reverse, producing a feature vector $h_R = [h_{R,0}, h_{R,1}, \ldots, h_{R,T}]$. To form the final output, the corresponding elements from these two vectors are combined, resulting in $h = [h_{L,0}, h_{R,T}, h_{L,1}, h_{R,T-1}, \ldots, h_{L,T}, h_{R,0}]$. This approach ensures that each feature at position incorporates both past and future context. Generally, BiLSTM outperforms standard LSTM when handling context-sensitive data. One-hot, AAindex and PWAA are concatenated (Concat) and encoded with BiLSTM, which can integrate the temporal context information of various features, enrich the feature representation, and further optimize the feature extraction effect.

Deep learning framework

Attention fusion layer

The multi-head self-attention is formed by the combination of multiple self-attention³⁹. In this paper, word embedding with transformer coding (NLP features) is combined with hand-crafted features with BiLSTM coding by point-wise addition as follows:

$$X = WE + HF \tag{10}$$

where *X* represents multiple features, which are fused by multi-head self-attention mechanism.

The multi-head self-attention enables effective feature fusion by: (1) Capturing heterogeneous feature interactions via independently learned attention patterns across heads; (2) Implementing dynamic feature re-weighting to enhance discriminative elements; (3) Enriching representation spaces through decomposed attention subspaces without significant parameter overhead.

CNN layer

CNN refers to convolutional neural networks, a deep learning model that is widely used in computer vision fields such as image classification, object detection, and image segmentation⁴⁰. The main feature of CNN is the use of convolutional layers to automatically extract image features, and filters (or convolution cores) slide over the image to capture local patterns, which are then used to identify image content. In this paper, one-dimensional convolution (Conv1d) is used, which efficiently extracts local features of input data through local perception and parameter sharing mechanisms. The batch normalization layer, used to normalize input features to zero mean and unit variance, helps speed up the training process and improve model performance. Dropout layer can prevent overfitting, which randomly drops a certain percentage of the neuronal output in the network during training. ReLU activation function is used to increase the nonlinearity of the network. It sets all negative values to zero and keeps all positive values. The one-dimensional maximum pooling layer (MaxPool1d) is used to reduce the dimension (height) of the feature map.

BiGRU layer

The bidirectional gated recurrent unit (BiGRU) was proposed in 2014 by Cho et al.⁴¹. It is a recurrent neural network (RNN)^{42,43} that consists of two independent GRU units, one processing data forward in time series and the other processing data backward in time series. Similar to BiLSTM, it combines forward and backward hidden states to capture contextual dependencies in the sequence. Because GRU is simpler than LSTM, the computational efficiency of BiGRU is higher than that of BiLSTM.

The CNN operates as a local feature extractor for short-range spatial patterns, whereas the BiGRU captures long-range temporal dependencies across the entire sequence. This integrated framework by combining CNN with BiGRU enables synergistic spatial-temporal representation learning.

Output layer

MLP is a feedforward neural network that can model complex nonlinear relationships through multilayer linear transformations and nonlinear activation functions. MLP is widely used in a variety of tasks, such as classification, regression, and sequence prediction. Through the steps of forward propagation, loss calculation

and backpropagation, MLP can gradually adjust the parameters and optimize the model performance. In this paper, we use the batch normalization layers and dropout layers, which can improve the robustness of the model.

Detailed structure and parameter settings

In order to present the model structure clearly, more detailed introduction and parameter settings are shown in Table 2.

Model evaluation

In this paper, five-fold cross-validation is applied to the model on the benchmark set, and independent test is used to evaluate the model on the test set 44-46. The five-fold cross-validation is a way to divide the data set into 5 subsets of equal size, usually randomly, and use 4 subsets as the training set in turn, and the remaining subset as the test set for model training and evaluation. The experiment is run five times, ensuring that each subset is used as the test set once. Finally, the results of 5 tests are averaged to get the final performance evaluation of the model. The independent test utilizes a test set, entirely independent from the training set, to evaluate the generalization ability of the trained model. We use five popular statistical measures to assess the model performance, including accuracy (ACC), sensitivity (Sn), specificity (Sp), Matthew's correlation coefficient (MCC) and area under the ROC curve (AUC or auROC)⁴⁷⁻⁵¹. The formulas are as follows:

$$ACC = \frac{TP + TN}{TP + TN + FP + FN},$$

$$Sn \text{ or } Rec = \frac{TP}{TP + FN},$$

$$Sp = \frac{TN}{TN + FP},$$

$$AUC \text{ or } auROC = \frac{\sum_{i}^{n_{pos}} rank_{i} - \frac{n_{pos}(n_{pos} + 1)}{2}}{n_{pos}n_{neg}},$$

$$MCC = \frac{TP \cdot TN - FP \cdot FN}{\sqrt{(TP + FN)(TP + FP)(TN + FP)(TN + FN)}},$$

$$(11)$$

where *TP*, *TN*, *FP* and *FN* denote the numbers of true positive, true negative, false positive and false negative, respectively. In addition, we adopted the receiver operating characteristic (ROC) curve and the precision-recall (PR) curve. The ROC curve is a graphical way to evaluate the performance of a classification model. The closer the AUC (auROC) value is to 1, the better the prediction performance of the model. The PR curve shows the relationship between precision and recall at different thresholds. The area under PR curve (auPRC) can also be used to quantify the performance of a model, but usually more attention is paid to the shape and position of the PRC curve itself.

Module	Network layer	Parameter settings
Attention	Multi-head self-attention	input_dim = 128, k_dim = 32, v_dim = 32, num_heads = 8
	Conv1d	in_channels = 31, out_channels = 64, kernel_size = 3, stride = 1, padding = 0
	BatchNorm1d	num_channels = 64
CNN Dropout		0.2
	ReLU	-
	MaxPool1d	kernel_size = 3, padding = 0, dilation = 1
BiGRU	BiGRU	input_size = 42, hidden_size = 64, num_layers = 2, bidirectional = True, dropout = 0.2
	Flatten	-
Linear		input_dim=8192, hidden_dim=512
MLP-1	BatchNorm1d	hidden_dim = 512
	Dropout	0.2
LeakyReLU		-
	Linear	hidden_dim=512, output_dim=128
	Linear	-
	BatchNorm1d	input_dim = 128, hidden_dim = 64
MLP-2	Dropout	0.2
WILP-2	ReLU	-
	Linear	input_dim = 64, hidden_dim = 2
	Softmax	-

Table 2. Detailed structure and parameter settings of the deep learning model.

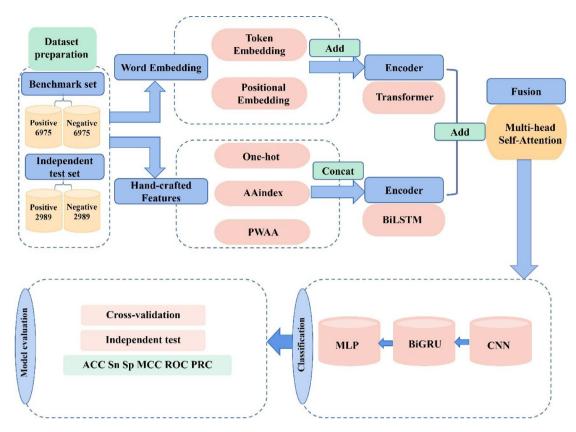


Fig. 1. The flowchart of the DeepMM-Kcr model.

Dataset	Evaluation	ACC(%)	Sn(%)	Sp(%)	MCC	AUC	
	Five-fold CV						
Benchmark set	1	83.10	86.04	80.32	0.6638	0.9042	
	2	82.21	83.18	81.25	0.6444	0.8933	
	3	81.49	85.19	77.68	0.6309	0.8950	
	4	82.01	83.15	80.83	0.6401	0.8903	
	5	81.36	83.96	78.73	0.6278	0.8822	
	Mean	82.03 ± 0.62	84.30 ± 1.14	79.76±1.35	0.6414±0.0127	0.8930 ± 0.0071	
Independent test set	Independent	85.56	87.59	83.54	0.7119	0.9310	

Table 3. The performance of the DeepMM-Kcr model on the benchmark set and independent test set.

Results and discussion

Experimental settings and runtime

In this paper, we train the DeepMM-Kcr model under the Python PyTorch framework (https://pytorch.org/). The hardware environment is 11th Gen Intel(R) Core(TM) is 1135G7 CPU @ 2.40 GHz 2.42 GHz with 16.0 GB of RAM. The cross-entropy is used as the loss function, and the weight parameters are optimized by the Adam algorithm. The batch size is 64, the learning rate is 0.0001 for our training model, and the iteration epoch number is 50. The average training time and independent test time for each epoch are 115 s and 10 s, respectively.

Prediction performance of our model

In this paper, a new model named DeepMM-Kcr is proposed, the workflow of the model is shown in Fig. 1. The mean values and standard deviation of five-fold and values of each fold for ACC, Sn, Sp, MCC and AUC are calculated by the five-fold cross-validation on the benchmark set, as well as the values of ACC, Sn, Sp, MCC and AUC are calculated by the independent test on the test set, and the results are shown in Table 3. As can be seen from Table 3, the ACC of the benchmark set and the independent test set reaches 82.03% and 85.56%, respectively. Sn, Sp, MCC and AUC also obtained satisfactory results. The results of five-fold cross-validation show that our model has strong stability, and independent test results show that our model has good generalization ability.

Dataset	Features	ACC(%)	Sn (%)	Sp (%)	MCC
Benchmark set	One-hot + BiLSTM	70.49	76.59	64.36	0.4130
	AAindex + BiLSTM	67.71	75.87	59.57	0.3601
	PWAA + BiLSTM	52.09	53.56	50.05	0.0388
	HF + BiLSTM	70.21	71.79	68.60	0.4046
	WE+transformer	78.51	83.22	73.79	0.5739
	Add	78.33	78.73	77.92	0.5669
Independent test set	One-hot + BiLSTM	68.94	71.03	66.85	0.3791
	AAindex + BiLSTM	63.80	73.84	53.76	0.2817
	PWAA + BiLSTM	50.32	53.86	46.77	0.0064
	HF + BiLSTM	72.88	75.98	69.79	0.4586
	WE+transformer	79.24	85.78	72.70	0.5899
	Add	79.58	78.92	80.23	0.5916

Table 4. Performance comparison for ablation experiment on feature groups.

Dataset	Method	ACC(%)	Sn (%)	Sp (%)	MCC
	Self-attention	81.07	83.39	78.75	0.6222
Benchmark set	4-head self-attention	81.45	84.64	78.27	0.6306
	8-head self-attention	82.03	84.30	79.76	0.6414
Independent test set	Self-attention	80.91	84.21	77.62	0.6196
	4-head self-attention	82.79	84.98	80.60	0.6564
	8-head self-attention	85.56	87.59	83.54	0.7119

Table 5. Performance comparison for ablation experiments on attention methods.

Ablation experiments

Feature ablation

Features extraction plays an important role in the prediction performance of the model. To validate the impact of feature representation methods on model performance, ablation experiments are performed. We construct the different feature groups, including One-hot+BiLSTM, AAindex+BiLSTM, PWAA+BiLSTM, HF+BiLSTM, WE+transformer and Add, which are all without multi-head self-attention. One-hot+BiLSTM refers to One-hot features encoded by BiLSTM, AAindex+BiLSTM and PWAA+BiLSTM are similar to One-hot+BiLSTM. HF+BiLSTM refers to hand-crafted features derived from the concatenation of features One-hot, AAindex and PWAA encoded by BiLSTM. WE+transformer refers to word embedding encoded by transformer. Add refers to the features that combine the features of WE+transformer and HF+BiLSTM by point-wise addition. The ablation experimental results on the benchmark set and independent test set are shown in Table 4.

From Table 4, for the three types of hand-crafted features, the order of feature importance from high to low is One-hot, AAindex and PWAA. Meanwhile, we can also see that WE+transformer has better identification ability than HF+BiLSTM, because it can provide richer and more delicate feature representations. Combining the features of WE+transformer and HF+BiLSTM by point-wise addition, as a whole, better effect is to be generated than that using single type features. In conclusion, WE+transformer contribute most significantly to model performance.

Attention mechanism ablation

Multi-head self-attention is composed of the concatenation of multiple self- attention results. The number of heads is selected by conducting attention mechanism ablation. Self-attention (1-head), 4-head self-attention and 8-head self-attention are listed for ablation experiments. The ablation experimental results on the benchmark set and independent test set are shown in Table 5; Fig. 2. As is shown in Tables 5 and 8-head self-attention obtain the best prediction performance. ROC and PR curves, as well as auROC and auPRC in Fig. 2 intuitively shows that 8-head attention is the best method.

Model structure ablation

In order to fully evaluate and prove the superiority and effectiveness of the constructed deep learning framework, ablation experiments on model structure are performed. We list six model structures, including No-attention-CNN, Attention-CNN, No-attention-BiGRU, Attention-BiGRU, No-attention-CNN-BiGRU and Attention-CNN-BiGRU, these results for ablation experiments on the benchmark set and independent test set are shown in Table 6.

As is shown in Table 6, attention represents multi-head self-attention. CNN, BiGRU and CNN-BiGRU with attention are better than CNN, BiGRU and CNN-BiGRU without attention, respectively. Prediction accuracies

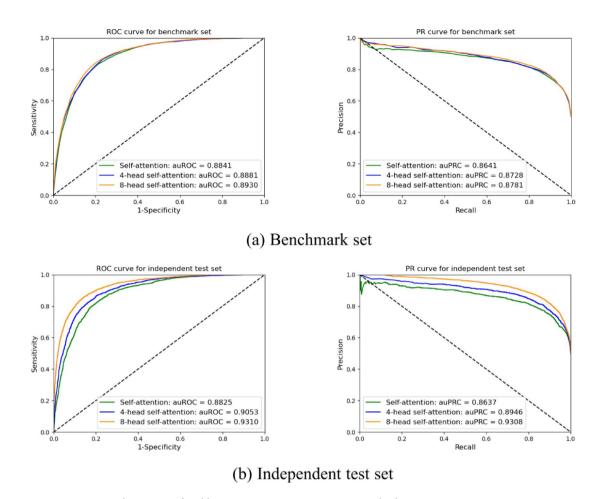


Fig. 2. ROC and PR curves for ablation experiments on attention methods.

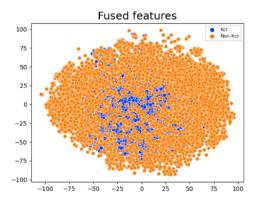
Dataset	Model structure	ACC (%)	Sn (%)	Sp (%)	MCC
	No attention-CNN	79.73	83.19	76.23	0.5963
	Attention-CNN	81.55	87.88	75.18	0.6360
Benchmark set	No attention-BiGRU	76.15	78.35	73.94	0.5237
Benciiniark set	Attention-BiGRU	81.02	82.84	79.21	0.6208
	No attention-CNN-BiGRU	78.33	78.73	77.92	0.5669
	Attention-CNN-BiGRU	82.03	84.30	79.76	0.6414
Independent test set	No attention-CNN	79.76	85.85	73.67	0.5996
	Attention-CNN	81.18	89.13	73.24	0.6316
	No attention-BiGRU	78.10	79.69	76.51	0.5623
	Attention-BiGRU	82.64	84.48	80.80	0.6532
	No attention-CNN-BiGRU	79.58	78.92	80.23	0.5916
	Attention-CNN-BiGRU	85.56	87.59	83.54	0.7119

Table 6. Performance comparison for ablation experiments on model structures.

of all substructures including No-attention-CNN, Attention-CNN, No-attention-BiGRU, Attention-BiGRU, No-attention-CNN-BiGRU are lower than that of our constructed deep learning framework (Attention-CNN-BiGRU). The results for ablation experiments demonstrate the effectiveness of multi-head self-attention, the structure Attention-CNN-BiGRU is the most outstanding. Attention, CNN and BiGRU all make positive contributions for our model.

Visualization of learned features

To reflect the performance of learning features, we visualize the significant relevant model outputs by employing t-distributed stochastic neighbor embedding (t-SNE) to reduce dimensions and visualize the distribution of



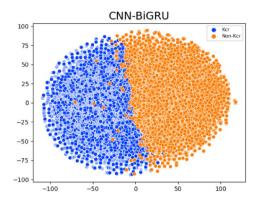


Fig. 3. Visualization of samples on the benchmark set using t-SNE.

Model	ACC	Sn	Sp	MCC	AUC
Position_weight ¹⁵	0.591	0.725	0.458	0.189	0.633
CKSAAP_CrotSite ¹⁶	0.737	0.853	0.621	0.487	0.813
LightGBM-CrotSite19	0.781	0.806	0.757	0.563	0.861
Deep-Kcr ²²	0.751	0.630	0.871	0.516	0.859
BERT-Kcr ²⁴	0.820	0.801	0.838	0.640	0.905
Adapt-Kcr ²⁶	0.852	0.854	0.849	0.706	0.924
DeepMM-Kcr	0.856	0.876	0.835	0.712	0.931

Table 7. Performance comparison of the DeepMM-Kcr and existing models on the independent test set.

positive and negative samples. We extract and visualize fused features by multi-head self-attention from natural language processing features and hand-crafted features, and outputs of the CNN and BiGRU in Fig. 3. It clearly demonstrated that the fused features are disorderly, after CNN and BiGRU, the distribution of learned features tends to be separated as Kcr and non-Kcr. The visualization results using t-SNE tool further illustrate that the DeepMM-Kcr model can effectively capture subtle differences between Kcr and non-Kcr.

Performance comparison with different existing models

To demonstrate the validity and superiority of our model DeepMM-Kcr, we search for existing models for discriminating Kcr sites, including Position_weight¹⁵, CKSAAP_CrotSite¹⁶, Lightbm-crotsite¹⁹, Deep-Kcr²², BERT-Kcr²⁴, Adapt-Kcr²⁶. The measurements of ACC, Sn, Sp, MCC and AUC of the seven models are shown in Table 7.

As can be seen from Table 7, the ACC, Sn, Sp, MCC and AUC of our model DeepMM-Kcr on the independent test set are 0.856, 0.876, 0.835, 0.712 and 0.931, respectively. It is obvious that the performance of our model has improved significantly. The ACC of our model is improved by 0.256 compared with the Position_weight of the earlier model and by 0.004 compared with the better model Adapt-Kcr. We can see that although the Sp of our model is 0.835, which is 0.036 lower than that of the Deep-Kcr model, Sp and Sn have better balance in our model, as well as ACC, Sn, MCC and AUC all achieve the best results. The experimental results show that our model DeepMM-Kcr is superior to the existing model and is a very good calculation tool.

Discussion

The DeepMM-Kcr model use word embedding with transformer encoder, hand-crafted features with BiLSTM encoder, multi-head self-attention, CNN and BiGRU. The transformer encoding based on word embedding directly captures the global context by calculating the correlation weights of all position pairs. Hand-crafted features, which reflect statistical regularities and exhibit robustness to distributional changes. BiLSTM coding with hand-crafted features can better capture bidirectional information in the sequence, better establish long-term dependence relationship. Hand-crafted features can serve as complementary inputs in NLP. The multi-head self-attention fuses multiple features by learning multiple sets of attention weights in parallel. The attention weights of different heads can explain the focus of the model's attention and help understand the decision-making process of the model. The combination of CNN and BiGRU can achieve excellent performance in complex tasks that require both detailed features and contextual understanding through collaborative design of local perception and global modeling.

Although our model has achieved good prediction performance, there are still some limitations, such as potential overfitting and limited data sources. In future work, for potential overfitting, we will use regularization to reduce model complexity and data augmentation methods to further address overfitting issue. Our model is only appropriate for dataset from HeLa cells. For restricted data sources, we will strengthen academic exchanges with peers to obtain richer data.

Kcr plays an important role in gene expression regulation, metabolism, and disease occurrence, and is a key node in the regulation of "metabolism epigenetics". Kcr sites prediction using DeepMM-Kcr model provides a new target for cancer treatment, and in the future, high-resolution detection technology and site-specific editing tools need to be developed to deepen research.

Conclusions

In this paper, we combine the hand-crafted features and natural language processing features, and then use multi-head self-attention mechanism to fuse these features. A deep learning framework is constructed based on CNN, BiGRU and MLP for classification. Our model named DeepMM-Kcr, has better predictive accuracy and more balanced performance than previous tools. Therefore, our model is valid and greatly improved. The accurate identification of Kcr sites will not only contribute to the in-depth understanding of biological mechanisms, promote disease diagnosis and treatment, promote the development of biotechnology and agricultural applications, but also promote scientific research progress and interdisciplinary cooperation.

Data availability

Data is provided within the manuscript.

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Author contributions

Yunyun Liang and Minwei Li wrote the main manuscript text and E.F. prepared Figs. 1, 2 and 3. All authors reviewed the manuscript.

Declarations

Competing interests

The authors declare no competing interests.

Additional information

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