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OPEN Non-predictive online spatial coding in the posterior parietal cortex when aiming ahead for catching

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Catching movements must be aimed ahead of the moving ball, which may require predictions of when and where to catch. Here, using repetitive Transcranial Magnetic Stimulation we show for the first time that the Superior Parietal Occipital Cortex (SPOC) displays non-predictive online spatial coding at the moment the interception movements were already aimed at the predicted final target position. The ability to aim ahead for catching must thus arise downstream within the parietofrontal network for reaching.

The ability to predict future events in the environment is key to success of aspects of life. Some even argue that prediction is the key function of the brain¹. Motor control is thought to rely heavily on prediction, because of sensorimotor delays and the general dynamic nature of the environment²⁻⁴. This is often considered hand-in-hand with movement pre-programming, where the relevant movement features are set in advance of movement execution. Interceptive movements such as catching provide an interesting example: these movements are typically aimed ahead of moving target, at the interception location (thus accounting for any target displacement during movement execution)⁵. Some have argued this involves preprogrammed movements based on predictions of where to intercept the object^{6,7}. Previous modelling work, however, has shown that aiming ahead at the future interception location may also emerge from online control mechanisms not relying on explicit spatial predictions of this location8. Fig. 1 illustrates predictive and non-predictive spatial control schemes that could result in aiming ahead of a moving target. To distinguish between these predictive and non-predictive schemes, it is imperative to examine the neural basis of the spatial control of interception. Surprisingly, this has not been done extensively before in the neuroscience literature.

Our key question is how and where within the brain the movement is planned to be aimed ahead of the target. This can be studied among others by examining whether the spatial coding of target and/or hand movement parameters reflects the continuously changing target position (which we will call non-predictive coding) or its final position at interception (which we will call predictive coding). Importantly, defined in this way, predictive coding does not include predictive motion extrapolation to account for sensorimotor delays (e.g., 100-200 ms ahead in time). Given the schemes illustrated in Fig. 1, information is needed concerning the spatial coding around the time the movement is aimed at the interception position (typically directly at movement initiation). This motivates the use of online repetitive Transcranial Magnetic Stimulation (rTMS) around movement onset, aimed at pertinent parts of the posterior parietal cortex (PPC), which is heavily involved in the online visual control of reaching⁹⁻¹¹. Within the PPC, the Superior Parietal Occipital Cortex (SPOC) and medial Intraparietal Sulcus (mIPS) purportedly code the retinotopic reach goal position 12,13 and the hand-goal vector 12,14,15 for reaches to stationary targets. This spatial coding remains to be examined for moving targets, where the visual target position and visual reach goal position are initially not the same. The retinotopic nature of the spatial coding was used to dissociate effects that depend on the target position during stimulation and on the target position at interception. This required target trajectories that cross visual fields, for which the target moved in a different visual hemifield during stimulation than during interception (Fig. 2). This paradigm thus provided separate evaluation of the evidence for predictive and non-predictive coding.

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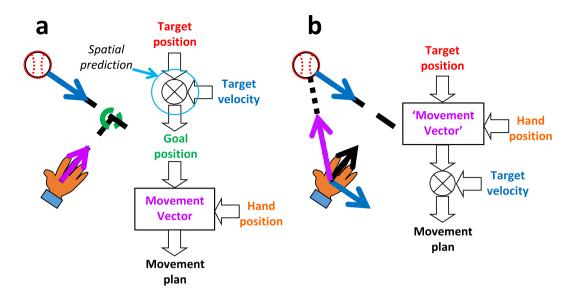


Figure 1. Two possible schemes for planning interceptive hand movements ahead of the moving target, at the final interception location. (a) Predictive scheme. Target position and motion information is used to determine a future interception point. This serves as the goal position of the reach, which is thus compared to hand position to determine the movement vector. (b) One possible non-predictive scheme. Target and hand position are compared 'prior' to integrating information about target motion. The 'movement vector' in this scheme is aimed at the continuously changing target position.

Results

In our experiment, participants reached to intercept a target moving down or up on a screen from either side to either side of the screen. Although the initial movement direction was biased towards the initial target zone, movements were clearly planned ahead and aimed towards the final target zone (see Fig. 3a). The key question is how this behaviour emerges from the cortical online movement planning network (roughly illustrated in Fig. 1). To answer this question, we evaluated how these movements were affected by rTMS to SPOC and mIPS (in comparison to the NoTMS and Cz conditions). Based on findings for reaches to stationary targets, we anticipated rTMS to yield an increase in movement variability, specifically of the initial movement direction for mIPS and horizontal interception error for SPOC. No evidence was found for these specific predictions. In fact, rTMS to mIPS failed to elicit any effects in our study. However, rTMS to SPOC did have a clear effect on the variability of initial movement direction, but only when applied to the hemisphere that would code the retinotopic target position during stimulation $(t(23) = 3.45; p = 0.0011; d' = 0.70, \alpha = 0.00625; \text{see Fig. 3b})$. This demonstrates non-predictive spatial coding for manual interception in SPOC. The much smaller and non-significant effect for the spatial variability at interception (Supplementary Fig. 1) suggest that the rTMS effect was instantaneous and transient – disappearing after the rTMS train ended. In support, we found that the rTMS effect was present only for participants with an early initiation (Fig. 4a). With the exception of a single participant, the rTMS effect was only shown if initiation occurred >100 ms before the last TMS pulse, that is, if the initial movement direction was determined within the rTMS window (Fig. 4b). Of the early initiators, only two clearly showed combined Non-predictive and Predictive effects (Fig. 4c), which may reflect effects of current visual target position in combination with cross-hemispheric predictive gain modulation¹⁶.

The Non-predictive contrast for the average initial movement direction showed a similar pattern as its variability, being more inward due to the rTMS to SPOC ($\chi^2(1) = 8.78$, p = 0.0031, $\alpha = 0.00625$), but the difference between SPOC and Cz did not reach significance (p = 0.11; SPOC vs. NoTMS: $\chi^2(1) = 12.77$, p = 0.00035, $\alpha = 0.00313$; Supplementary Table 2). One could argue that our paradigm is valid without a control site – we essentially compare within target sites - but since rTMS to Cz was part of our design from the start we do not wish to draw definitive conclusions about this effect. None of the other spatial biases (initial movement direction and horizontal interception error) were influenced by rTMS to SPOC or mIPS, irrespective of the type of contrast considered (Supplementary Fig. 1). None of the rTMS effects on spatial movement features differed significantly between vertical target motion directions (all p > 0.10), nor between hemispheres receiving rTMS (all p > 0.20; see Supplementary Tables 1 and 2). Interestingly, the rTMS effects on spatial movement features were significant only for diagonal target trajectories that crossed visual hemifields; rTMS did not significantly affect movements towards targets that stayed within the same visual field (i.e., straight down or straight up) (all p > 0.022; see Supplementary Table 3; Supplementary Fig. 2). Indeed, for such same-field trajectories the contrast between SPOC and NoTMS/Cz appeared to be smaller than the Non-predictive contrast for diagonal trajectories (t(23) = 2.95; p = 0.0072; d' = 0.60). Finally, no effects of rTMS to either SPOC or mIPS were observed on the temporal movement parameters (moment of initiation and movement time) (Supplementary Figs. 1 and 2; Supplementary Tables 4 and 5).

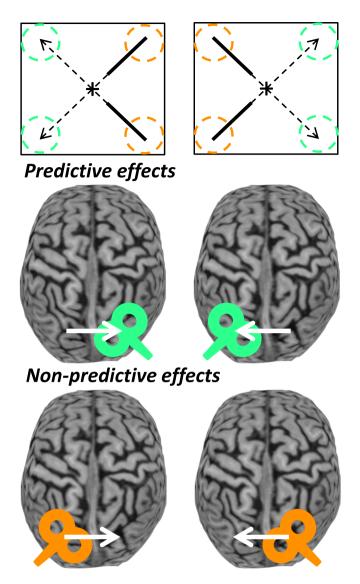
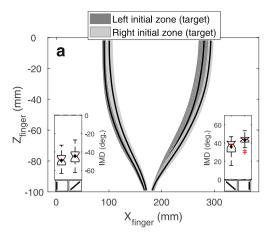


Figure 2. The rTMS paradigm for this study. Predictive and Non-predictive retinotopic coding - concerning the final (green circles) and initial target position (orange circles), respectively - were tested using target trajectories crossing between visual hemifields (top; dashed for occluded part). Given central fixation (cross) and retinotopic coding in the PPC, effects are expected for rTMS to the hemisphere contralateral to the coded initial (orange TMS coils) or final position (green TMS coils). The white arrows point from the hemisphere coding the initial to that coding the final retinotopic target position.

Discussion

This study aimed to establish the nature of the spatial coding within the PPC of target and/or hand movement parameters for manual interception. This was motivated by the overarching question whether humans employ explicit spatial predictions to achieve interception, or whether an alternative non-predictive style of control is used. An online rTMS paradigm was devised in which targets moved from one visual hemifield to the other, such that rTMS applied from target appearance could be used to dissociate predictive and non-predictive spatial coding (Fig. 2).

The observed effect of rTMS – increased variability of initial movement direction when SPOC was stimulated in the hemisphere coding the target position during stimulation – clearly demonstrates that SPOC used non-predictive spatial coding in our interception task. The instantaneous and transient nature of these effects underscores PPC's key role in online visual control of reaching^{9–11}. Whereas studies involving stationary targets suggest SPOC codes the visual reach goal position^{12,13} – the final target position in our task – this does not generalize to manual interception of moving targets. Thus, even if the brain forms an internal model of target motion⁵, SPOC does not simply read out a future target position from such a model to determine the reach goal when aiming ahead for manual interception. If anything, the transient nature of the rTMS effect may suggest that SPOC relays the instantaneous position of the target, inferred elsewhere in the brain, such that the rTMS effect is automatically corrected for once it seizes.



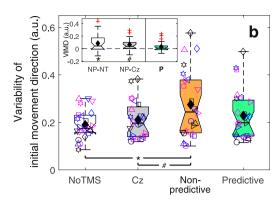


Figure 3. Main results. (a) Top view of a representative participant's fingertip paths for conditions without TMS, averaged across vertical target motion directions (surface width represents the average s.d. across repetitions). The insets illustrate that across participants the initial movement direction (IMD) was in the direction of the final target zone; nevertheless, significant biases towards the initial target zone were also present (Left final zone: $\chi^2(1) = 17.27$, $p = 3.2 \cdot 10^{-5}$, Right final zone: $\chi^2(1) = 23.68$, $p = 1.1 \cdot 10^{-6}$; circular likelihood ratio test³²; $\alpha = 0.025$). For this illustration and these tests, IMD was defined as positive in rightward direction. (b) Standard boxplot for the variability of the initial movement direction (VIMD) for rTMS to SPOC. The inset depicts the Non-predictive (NP) difference to the NoTMS (NT) and Cz conditions and the Predictive contrast (P = P - (NT + Cz)/2). Individual data is depicted using unique symbol/colour/jitter combinations. Means are indicated by black diamonds; outliers are red crosses. *t(23) = 3.08, p = 0.0026, d' = 0.63, $\alpha = 0.00625$; *t(23) = 3.26, p = 0.0017, d' = 0.67, $\alpha = 0.00313$; one-tailed paired-samples t-tests. Validity of results (p-values) was confirmed using 1,000,000 bootstraps.

Non-predictive online spatial coding within the PPC does not refute the use of predictive spatial control of manual interception. It does show that the ability to aim ahead of moving targets, at the final interception point in our task (Fig. 3a), must arise downstream from SPOC in the parietofrontal network. Our results also do not show SPOC does not use short-range predictions, to overcome sensorimotor delays, nor that SPOC uses non-predictive coding during target occlusion. Although the rTMS effects at first sight might suggest SPOC codes current retinal target position, it must be noted that we unexpectedly did not find any rTMS effects for targets remaining within the same visual field. The significantly larger effect for targets crossing the vertical visual meridian (Fig. 3a, Supplementary Fig. 2) argues against SPOC solely coding retinal target position and may suggest a target motion-dependence of the effect. It has indeed been observed that SPOC's homologue in non-human primates (V6A) contains (non-predictive) spatially selective motion sensitive cells¹⁷. If SPOC's activity effectively reflects target position and motion, future target positions may be decoded from its output. The predominant rTMS effect for diagonal target motion might suggest rTMS uniquely affected interhemispheric communication. Indirect support for this possibility comes from rTMS-induced disruptions of interhemispheric balance in PPC^{18,19}. A movement vector^{14,15} based on the decoded predicted target position would be coded in the same hemisphere as the current target position (in SPOC) for non-diagonal target motion and in the opposite hemisphere for cross-meridian target motion (Supplementary Fig. 3). Whether the interception position is actually explicitly decoded and represented (Fig. 1a), or implicitly within the computation of the movement vector remains to be determined.

This study also aimed to assess the nature of movement vector coding; we applied rTMS to mIPS, which is known to code the movement vector for reaches to stationary targets ^{12,14,20}. Surprisingly, no rTMS effects were observed for this brain area. This means our data does not provide ultimate support for the aforementioned interpretation, which would predict Predictive rTMS effects within mIPS. Several aspects may have contributed to the lack of rTMS effects for mIPS in our study. First and most evidently, mIPS may not be involved in manual interception. Relatedly, we may not have provided rTMS to the correct part of the mIPS. Our specific mIPS coordinates were taken from previous studies ^{14,15} involving a task that used wrist displacement to control cursor movements to static targets, which also is rather different than typical human reaching. While another study ¹² also reported effects of mIPS stimulation for actual reaching movements, their mIPS was considerably posterior to ours. Finally, our rTMS paradigm (Fig. 2) would not work for mIPS if it does not employ retinotopic coding for interception. It is known that the reference frames employed in PPC are task-dependent ²¹ and interception without seeing the hand might have promoted non-retinotopic coding within mIPS. However, while this would explain the non-significant contrasts, it would unlikely result in the complete absence of rTMS effects as we observed. Future studies, including more exploratory brain scanning as well as rTMS, should examine the important outstanding question concerning the movement vector coding during manual interception (Fig. 1).

It is informative to consider our results in a wider context of sensorimotor control. Our study was motivated from the longstanding question whether manual interception involves a priori spatial predictions of the interception location. Such spatial predictions had been forwarded in the context of motor programming theories, although technically the use of predictions does not necessitate preprogramming of the entire movement. The

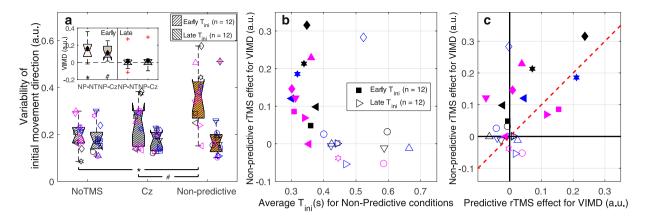


Figure 4. Group and individual differences in the non-predictive rTMS effects for SPOC on the variability of initial movement direction (VIMD). (a) Standard boxplot showing the effect broken down for two subsets of our sample, defined based on the moment of initiation (T_{ini}). The inset depicts the differences between the Non-Predictive (NP) conditions and the NoTMS (NT) and Cz conditions for both groups. Individual data is depicted using unique symbol/colour/jitter combinations. Means are indicated by filled diamonds; outliers are red crosses. *t(11) = 4.22; p = 0.00072; d' = 0.86, $\alpha = 0.003125$; *t(11) = 5.04; p = 0.00019; d' = 1.03, $\alpha = 0.00156$. Indeed, the Non-predictive contrast appeared to be larger for the early than for the late initiators: t(22) = 3.39; p = 0.0027; d' = 1.38 (two-tailed independent-samples t-test). No significant differences were found for late initiators: NP-NT: t(11) = 0.37; p = 0.36; d' = 0.076; NP-Cz: t(11) = 0.65; p = 0.26; d' = 0.13. Validity of these one-tailed paired-samples t-tests (p-values) was confirmed using 1,000,000 bootstraps. (\mathbf{b}) Individual Nonpredictive rTMS effects (i.e., NP-(NT-Cz)/2) for SPOC on VIMD, as a function of the average T_{ini} in the Nonpredictive conditions. With the exception of a single participant (open diamond), the rTMS effect was shown by participants initiating within 0.4s of target appearance. (c) Individual Non-predictive rTMS effects for SPOC on VIMD as a function of individual Predictive rTMS effects (i.e., P-(NT-Cz)/2) for SPOC on VIMD. The red dashed unity line indicates equal Predictive and Non-predictive effects. For most early initiators the rTMS effect predominantly occurred in the Non-predictive conditions; only two participants also showed considerable Predictive effects.

alternative is feedback-based online movement control, in which the location of interception emerges during execution rather than being explicitly set as a goal position. This distinction, however, only pertains to the spatial aspects of trajectory formation. The actual implementation of planned trajectories occurs within a larger scheme of sensorimotor control, involving direct and indirect influences of sensory information. The latter for instance pertains to history-dependent sensory effects or prediction of action consequences based on motor commands (i.e., forward models). The PPC has been linked to these processes^{22–26} (although forward models are also linked to the cerebellum⁴). Forward models have been argued to be essential to account for sensorimotor delays^{3,4} and thus seem particularly relevant for movements with a spatial as well as a temporal constraint, such as ball catching. We defined predictive coding in terms of the interception location, not as predictive short-range extrapolation. Indeed, our observation of non-predictive coding within SPOC in our view does not preclude the use of prediction in the context of forward models.

To conclude, we reported an empirical rTMS-based test of predictive and non-predictive coding for manual interception within the PPC. We only found evidence for online non-predictive coding within SPOC at the same time the hand movement already displayed predictive features, that is, was aimed ahead of the target at the final interception point. This planning ahead must thus arise elsewhere, likely downstream of SPOC, within the parietofrontal sensorimotor network. Future studies thus must answer exactly where and how within the brain interception movements become aimed ahead of the moving target. Findings like these improve the understanding of PPC's movement-related activity during time-constrained reaching movements and may prove seminal to creating effective neural prostheses that use PPC signals as input.

Methods

Subjects. Twenty-five participants took part in this experiment (mean age = 29, age range = 19–54, 13 females, 12 males). All had normal or corrected-to-normal vision and were right-handed (average laterality quotients: 92, range: 75–100²⁷). Participants were recruited through social media advertisements and word of mouth. Participants completed two screening forms for contra-indications to MRI and TMS before participation was deemed safe. Participants also completed a fixation test to ensure they could comply with the fixation requirements of our task. In total, we recruited 44 participants; 19 participants were excluded because they failed the fixation pre-test. One participant only completed the SPOC session, while another participant's data was excluded from the SPOC analyses due to an error in the TMS stimulator settings (5 instead of 6 pulses provided). As a result, 24 participants were included in both the SPOC and mIPS analyses, with 23 completing both sessions. Note that the exclusion of the participant from the SPOC analyses broke the perfect counterbalancing of rTMS conditions. Participants provided written informed consent before each session and completed an acute screening form before rTMS each session²⁸.

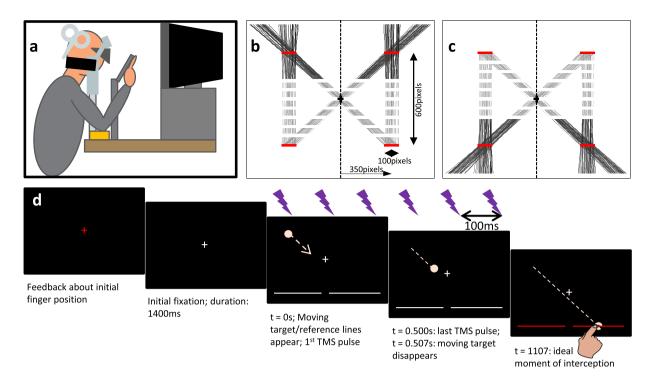


Figure 5. Experimental set-up and paradigm. (a) Schematic side-view of the physical set-up. (b and c) Exemplary target paths used during the experiment for downward and upward target motion, respectively. Panels (b) and (c) represent the full screen at 1280×1024 pixels. The visible part of each path is shown as a solid red line; the occluded part is a grey dashed line. The initial and final target zones are displayed as thick horizontal red lines (not shown to participants). Note that the calibration involved pointing movements towards targets presented at the screen centre (black cross-sign) and the 8 outer positions of the initial and final target zones. Also note that the initial zone constrained target positions midway through its visible window. (d) Trial sequence. First, colour of the central fixation cross represents whether the fingertip is within (green) or outside (red) the initial finger zone. After the finger remained within the zone for 250 ms, the white fixation cross is shown for 1400 ms. Subsequently, the target appears (on TMS trials) in sync with the onset of the rTMS train (0–500 ms, 6 pulses at 10 Hz); two horizontal reference lines appear. After 38 frames (507 ms) the target disappears, but it supposed to continue to keep moving until 600 ms later (dashed circle), when the target reaches one of the reference lines, now turned red to signal the ideal moment of interception.

Experimental Set-up. Participants were seated in a height-adjustable chair behind a table on which a chinrest (with forehead support) and computer screen were mounted ~35 cm in front of the eyes (see Fig. 5a). Their head was fixed comfortably in the padded chinrest with a thick Velcro strap stretching across the back of the head to restrict excessive head movement. The experiment took place in a dark room; the only light sources were the stimuli presented on a 19 inch Dell CRT screen (1280 × 1024 pixels, 75 Hz refresh rate), a dim glow from the neuronavigation feedback screen and a small lamp that was switched on between blocks of trials. The light output of the CRT screen was reduced by two layers of darkening film (Defender Auto Window Film, Car Accessories Ltd., Buckingham, UK). Stimulus presentation was controlled through Matlab (The Mathworks, Nattick, MA, USA) by Version 3 of the Psychophysics Toolbox²⁹. Movement of the right index finger was recorded with an NDI 3D Investigator system (Northern Digital Inc., Waterloo, ON, Canada) at 250 Hz using six markers placed on an aluminium base taped to the distal part of the right index finger (partly covering the nail). This system was calibrated before each session such that the positive x-axis was rightward, the positive y-axis downward and the positive z-axis was into the screen (all from the participant's perspective), with the origin in the left top corner of the screen. Binocular eye movements were recorded at 60 Hz by SMI Eyetracking Glasses 2 w Analysis Pro (SensoMotoric Instruments GmbH, Germany.

Neuronavigation. To adequately position the TMS coil for each participant, we used a frameless stereotaxic neuronavigation system (Brainsight 2; Rogue Research, Montreal, Quebec, Canada). To this end, before the TMS sessions an MRI scan was obtained for each participant using a Siemens $1.5\,\mathrm{T}$ scanner at NorthernMRI, Belfast (voxel size $1.0\times1.0156\times1.0156\,\mathrm{mm}$). We used six fiducial points (nasion, inion, right and left pre-auricular notch, right and left deepest point on the skull on the outside of the eye sockets) to align the MRIs with the recorded head position based on standard BrainSight methods. We deemed the alignment to be acceptable if the relative position of the fiducial points matches the positions obtained from the MRI with an error $<2\,\mathrm{mm}$ (typically $\sim0.1-1\,\mathrm{mm}$).

We applied rTMS to the medial Intraparietal Sulcus (mIPS) and Superior Parietal Occipital Cortex (SPOC). mIPS was defined as a region located over the medial portion of the IPS, near the caudal part of the angular

		Left Hemisphere			Right Hemisphere		
	N	X	Y	Z	X	Y	Z
mIPS							
This Study	24	-38.3 ± 4.7	-49.9 ± 4.7	47.0 ± 3.9	37.5 ± 3.5	-47.5 ± 5.4	50.1 ± 4.5
Davare et al.15	6	-33	-47	48	31	-45	53
Davare et al.14	9	-32 ± 5	-49 ± 6	46±9	33±5	-46 ± 7	49±10
Vesia et al.12*	6	-22.4	-68.9	41.9	24.0	-66.2	41.3
SPOC							
This Study	24	-10.0 ± 3.4	-80.8 ± 4.6	38.3 ± 5.3	10.2 ± 2.6	-79.0 ± 4.5	40.4 ± 6.0
Dessing et al.30*	7	-6.5 ± 1.4	-81.0 ± 2.2	31.3 ± 7.0			
Vesia et al.12*	6	-10.4	-84.7	41.5	9.6	-85.3	43.6

Table 1. MNI coordinates of SPOC and mIPS in current and previous studies. Note: mIPS = medial Intraparietal Sulcus; SPOC = Superior Parietal Occipital Cortex. Data provided as mean \pm SD. *MNI coordinates estimated from reported Talairach coordinates (using *tal2mni.m*, see https://osf.io/n4yjr/).

gyrus, in an attempt to match the sites used previously 14,15 (see Table 1). SPOC was located on the superior part of the anterior bank of the parieto-occipital sulcus 12,30 , (Table 1). A control site, Cz, was included to account for non-specific effects of rTMS and was defined as a point on the skull midway between the inion and nasion and equidistant from the left and right pre-auricular notches. The corresponding coil position was determined during practice stimulation at the start of the first session and used for neuronavigation during the session. During the experiment, feedback about the quality of neuronavigation was provided on a 15 inch Dell LCD screen coated with several layers of the darkened film and with a carton cover on non-essential parts of the screen (to minimize the amount of light coming from this screen). Coil position was deemed acceptable if the distance from the optimal position on the skull (between the identified target spot and hotspot vector) was <1 mm (typically 0.0-0.6 mm).

Target Trajectories. Target trajectories were varied in terms of vertical direction (upward or downward) and horizontal initial and final zone (see Fig. 5b,c). We thus presented four trajectory types: two approximately vertical trajectories that stayed within the same visual field, and two diagonal trajectories that crossed over from the left to the right visual field (or vice versa). The exact horizontal initial and final positions on a given trial were randomized within 100 pixel wide zones centred on a horizontal eccentricity of ± 350 pixels relative to screen centre horizontal eccentricity ($\sim \pm 16.2$ deg.; range 14.0–18.3 deg.; see Fig. 5b,c). The 'initial' position was specified as the horizontal target position after 253 ms (i.e., \sim midway through the TMS train). In combination with the occlusion time, this method ensured that the target disappeared well before crossing the midline. The vertical position of the zones was ± 300 pixels relative to the middle of the screen (depending on the direction of target motion) ($\sim \pm 13.4$ deg. vertical eccentricity). Target trajectories were straight and of constant velocity.

Procedures. Each session involved a calibration of the eye tracker (using a 3×3 grid spanning ± 2.5 degrees in horizontal and vertical direction). The recorded raw gaze data for the outer eight points specified a zone (polygon) within which the gaze coordinates had to remain from target appearance until finger-screen contact (estimated online as the first time the fingertip came within 10 mm of the screen surface) for the trial to be valid. The gaze data corresponded to the point of regard on the screen, averaged across the eyes; the experimenter could decide to ignore data from one eye if its calibration was deemed inadequate. Next, a calibration of the fingertip locations was performed. Participants reached to touch 9 points (i.e., screen centre and the edges of the horizontal range within which the final target positions could have been selected; see below) three times. The fingertip position relative to the six markers was determined based on the known physical location of the central point relative to these markers, averaged across the three touches. The other eight calibration points were used to reconstruct the 'perfect' final finger position (see Data Analyses).

The trial sequence is shown in Fig. 5d. With their heads fixed in the chin rest, participants positioned their fingertip within a pre-defined starting zone (determined using real-time streamed marker position data) between the eyes and the screen (100 mm in front of and 10 mm below the screen centre; spherical zone with radius of 15 mm). During this phase, the fixation cross, presented at screen centre, was red while the fingertip was outside of the zone and green when it is inside. After the fingertip remained inside the starting zone for 250 ms the fixation cross became white and was shown at the screen centre for 1400 ms before a light pink target (~6 mm diameter) appeared either the top or bottom of the screen, moving at a constant speed to one of two unseen final target zones at the bottom/top of the screen. The full target trajectory took 1107 ms (83 frames), the targets were occluded after 507 ms visibility (38 frames). During the trial, participants moved their index finger from the initial position to reach and touch the invisible target as it reached the white line; to promote correct timing, the white line turned red when the invisible target reached it.

After each trial, gaze data was drift-corrected on each trial based on the median coordinates recorded in the last 300 ms prior to target appearance. Eye tracking artefacts - infrequent sudden jumps (defined as gaze displacement during consecutive samples in opposite direction of at least twice the average amplitude of the saccade from screen centre to the four calibration points along the horizontal or vertical axes) - were removed. Any resulting gaps in the data were filled using linear interpolation. We recycled trials (at a random position in the remainder of the block) if fixation was inadequate (1250 trials, 8.1% of the original total number of non-practice trials), if reach initiation occurred within 200 ms of target appearance (18 trials, 0.1%), if initiation was not detected (defined at

this stage as a >15 mm displacement of the fingertip, relative to the position during the frame prior to the fixation point turning white) (in total 80 trials 0.5%), if fingertip-screen contact was not detected (183 trials, 1.2%), and if any interframe interval of our CRT screen deviated more than 20% from the optimal value (1/75) while the target was visible (113 trials, 0.7%). Since in many trials multiple criteria were met, a total of 1550 trials were rerun (10.1%). After trial parameters were saved, the next trial started.

Each participant completed a fixation test (10 practice trials followed by two blocks of 20 trials [with randomly selected target trajectories, see above]). At the end of this session, which took around 20 minutes to complete, the experimenter checked whether fixation was adequate in at least 30 of the 40 trials. This participant inclusion test ensured we only obtained an MRI scan for and applied rTMS to participants who could adequately perform our task. Included participants were taken to NorthernMRI to obtain their MRI scan and they completed two rTMS sessions, both of which contained blocks with TMS provided to Cz (a control site, included to control for non-specific aspects of the rTMS) and blocks without rTMS (to assess baseline behavioural performance). In one session additional blocks involved rTMS to left and right SPOC, while the other also involved TMS to the left and right mIPS. At the start of each rTMS session we determined the resting motor threshold (rMT) for both hemispheres prior to the eye tracker and fingertip calibrations and experimental blocks. This involved standard electromyography-based procedures (intensity/location for which 3 out of 6 single-pulse trials lead to >50 μ V peak-to-peak motor evoked potential of the first dorsal interrosus muscle). The rTMS sessions were at least 3 days apart.

Each experimental session started with a block of 10 practice trials without TMS. Per TMS condition (No TMS, Cz, left SPOC/mIPS, right SPOC/mIPS), participants completed two blocks of 42 trials (2 practice trials plus 5 repetitions per trajectory [2 vertical directions x 2 horizontal initial zones x 2 horizontal final zones]), plus any recycled trials (see above). All 4 conditions in each session were presented in blocks, the order of which was fully counterbalanced across participants (except for the additional participant for SPOC); the two blocks per TMS condition were distributed within each session using an A-B-C-D-D-C-B-A design to control for the effects of fatigue. If the left and right rMT differed, the stimulation intensity for one Cz block matched the left SPOC/mIPS value and for the other it matched the right SPOC/mIPS value. In each TMS trial six TMS pulses (10 Hz, 120% rMT) were applied from target appearance, which implied the last pulse occurred just before target disappearance. The inter-trial interval was adjusted for safety reasons such that the time between TMS trains on subsequent trials was at least 6 seconds²⁸. TMS was not provided if movements were initiated prior to the first TMS pulse (i.e., these trials were recycled). Participants were given a 5–10 minute break between TMS blocks; this allowed for cooling of the coil using ice packs and avoided any residual effects of stimulation. Note that during the early sessions some breaks occurred in the midst of blocks when the coil overheated, when fans were used for cooling. In those cases, the remaining trials in the block were completed directly after the coil had cooled down. In addition, the gaze data streaming sometimes malfunctioned, resulting in a short hold up. In all, these mid-block hold ups occurred 76 times during 288 blocks. Whenever deemed necessary, the eye tracker and fingertip calibrations were rerun (e.g., if eye tracking glasses or finger markers were moved on the body). Participants and experimenters wore earplugs throughout blocks of trials to protect from the TMS noises. All procedures were approved by the Queen's University Belfast, School of Psychology Research Ethics Committee (45–2013) before any data was collected; all methods were performed in accordance with the relevant guidelines and regulations.

Note that one participant had a rather high rMT for the right hemisphere, which resulted in the rTMS being rather uncomfortable when its value was used to set the Cz intensity (it sometimes resulted in twitches of the eye muscles). During both sessions we therefore set the Cz position 2 cm posterior and we stimulated Cz at 120% of the rMT of the left hemisphere. Incidentally, a few other instances of discomfort were reported (discomfort under ear, in eye, teeth clattering, left hand twitches, see log on https://osf.io/n4yjr/).

Data analyses. Data analyses were conducted offline using Matlab. Movement initiation was defined as the sample (until the fingertip was displaced 5 mm relative to the position at target appearance) at which the forward fingertip velocity last passed through the threshold on 5% of the maximal forward velocity achieved from target appearance to trial offset. The interception position was defined as the fingertip position at finger-screen contact. Finger-screen contact was determined as the first sample after the fingertip arrived within 10 mm of the screen at which the forward fingertip velocity dipped below the threshold of 10 mm/s. Contact-dependent variables were not calculated if the fingertip position could not be reconstructed (i.e., missing markers) for the sample preceding contact as well as ≥ 9 of the last 50 samples before contact. If this velocity-based definition did not work, contact was defined as the last valid sample (after the fingertip arrived within 10 mm of the screen, but before 250 ms after reaching its maximal forward position) at which the forward fingertip position was less than 1 mm into the screen (n.b., due to soft tissue and bend of the finger, fingertip positions into the screen were possible). Note that these definitions of initiation and contact deviated slightly from the pre-registered definitions (see https://osf.io/n4yjr); minor algorithm adjustments were needed – prior to calculating the dependent variables – due to suboptimal visibility of the finger markers for some participants.

We determined the constant interception error (CE) by subtracting the 'perfect' fingertip position from the interception position. This perfect fingertip position was determined from the fingertip calibration: for each zone we used linear interpolation (based on the pixel coordinates of the exact final target position) between the fingertip positions recorded for the outer edges of the zone (averaged across the three repetitions in the initial calibration; note that a calibration point was excluded if it was further than 20 mm from both other two repetitions). A positive horizontal CE was defined in the direction away from screen centre. Variable interception error (VE_x) was defined as the variance of the horizontal CE across all repetitions for each condition. We applied a 4^{th} root transformation to VE_x to afford parametric statistics³¹. The initial movement direction (IMD) was defined based on the 2D vector (i.e., in a horizontal plane, based on the lateral and forward coordinates) between the fingertip positions at initiation and 100 ms after initiation (being positive away from screen centre). The variability of the

initial movement direction (VIMD) was defined using the length of the within-condition average of the normalized initial movement vectors (R_{av}), which we transformed to a linear scale to afford parametric statistics³², using:

$$VIMD = \sqrt{-2\log_e(R_{av})} \tag{1}$$

Due to marker occlusion and coil overheating, we excluded 71 trials from the CE_X and VE_X calculations (0.46%), 48 trials from the VIMD and IMD calculations (0.31%), and 43 trials from the calculation of the moment of initiation (0.28%), and 106 trials from the calculation of movement time (0.69%).

Fig. 2a illustrates our hypothesis tests, which follow from the retinotopic coding in mIPS and SPOC. Evidence for predictive and non-predictive coding was quantified using upward and downward diagonal target trajectories with stimulation to SPOC/mIPS in the hemisphere coding the visual hemifield of the final and initial target position, respectively. Dependent variables were averaged across these conditions; for Cz and NoTMS this did not require distinguishing between hemispheres. It should be noted that the hypothesis tests require that natural interception movements are planned ahead and not aimed at the current target position; this was visually confirmed (i.e., effects large enough not to require statistics); any additional (smaller) effects of the initial target zone on IMD was statistically tested separately for the two final target zones (circular likelihood ratio test for unknown concentration parameter on initial zone effect³², alpha = 0.025). Note that for this particular test a positive value denoted a rightward IMD (as opposed to the rTMS tests, where positive was in the direction of the final target zone).

For both PPC sites, we performed the comparisons based on a predicted increase in movement variability due to rTMS in comparison to both no TMS and Cz stimulation. Based on the literature, we anticipated effects for SPOC on VEx³⁰ and for mIPS on VIMD^{14,15}, which we thus preregistered prior to data collection (https://osf.io/n4yjr). In the preregistered methods, we treated the sessions (SPOC and mIPS) as separate experiments; starting at a Bonferroni-corrected alpha-level of 0.025 (i.e., 2 tests, referred to as 'Predictive' and 'Non-predictive' hereafter), we applied a further Holm-Bonferroni step-down correction for the comparisons with NoTMS and Cz.

We always anticipated further exploration of our data. Firstly, since we assumed rTMS would affect the movement from initiation to interception, the aforementioned tests should also show the effects on VIMD for SPOC stimulation and on VE_x for mIPS stimulation. A more conservative alpha-level was used for these tests; taking the exploration as part of testing rTMS effects for two hypotheses for two brain sites using two dependent variables, we started with an alpha-level of 0.05/8 = 0.00625. This alpha-level was applied to contrasts of predictive/non-predictive effects compared to the average of the NoTMS and Cz effects; only significant effects were followed up by separate comparisons with the NoTMS and Cz conditions with associated Holm-Sidak corrections as described above. Importantly, since we only expected rTMS-induced *increases* in movement variability all comparisons referred to above involved one-tailed paired-samples *t*-tests (with Cohen's *d* reported for effect size).

The data was further explored using other dependent variables. We used the aforementioned statistical procedure to explore the effects for both PPC sites on IMD (in degrees) and the horizontal constant interception error (CE_x in mm); since we did not have a unique prediction about the direction of the effects these involved two-tailed paired-samples *t*-tests (n.b. a circular likelihood ratio test for unknown dispersion was used for IMD³²). Although the present investigation focused on spatial control, for completeness we also tested whether rTMS affected the moment of initiation (relative to target appearance) and movement time, both expressed in seconds.

For all tests, we explored whether there were any asymmetries in the rTMS effects between hemispheres and vertical target motion directions. We compared the size of the Predictive/Non-predictive contrasts (relative to the average of NoTMS and Cz) between vertical directions and between hemispheres (the same procedure for correcting alpha levels was used, except that no break-down for NoTMS and Cz was planned to avoid inflating the number of tests). We also evaluated the rTMS effects for non-diagonal trajectories for all dependent variables: we took the difference between the effects of target motion coded in the stimulated and non-stimulated hemisphere and contrasted this with the same differences for NoTMS and Cz (averaged across these two control conditions).

Based on one of the effects observed for rTMS to SPOC on VIMD, specific follow-up tests were designed. We compared the size of the Non-predictive contrast (relative to the average of NoTMS and Cz) to the same contrast for straight trajectories (coded within the stimulated hemisphere). We explored individual differences in the size of the Non-predictive and Predictive contrasts, to ascertain whether there was any indication of combined predictive and non-predictive effects¹⁶. Finally, we tested for Non-predictive coding separately for two groups, which differed in how soon they initiated their movements after target appearance. To this end, median-splitting based on the overall average moment of initiation for the Non-predictive conditions for SPOC was used to create groups. The Non-predictive contrasts were also compared between these groups using two-tailed independent-samples t-tests. Validity of all statistical tests was confirmed using bootstrapped p-values (n = 1,000,000, see Supplementary Tables 1–5).

Data availability. All data and analysis code for this study are available for download through https://osf. io/n4yjr.

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Author Contributions

S.A.R. carried out all experiments, being accompanied by J.C.D. during the first 10 TMS sessions. S.A.R. and J.C.D. designed the study and J.C.D. implemented the experimental paradigm. J.C.D. and S.A.R. conducted the data analyses and wrote the manuscript.

Additional Information

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