Role of Optimal Features Selection with Machine Learning Algorithms for Chest X-ray Image Analysis

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Abstract

Introduction: The objective of the present study is to classify chest X-ray (CXR) images into COVID-positive and normal categories with the optimal number of features extracted from the images. The successful optimal feature selection algorithm that can represent images and the classification algorithm with good classification ability has been determined as the result of experiments. **Materials and Methods:** This study presented a framework for the automatic detection of COVID-19 from the CXR images. To enhance small details, textures, and contrast of the images, contrast limited adaptive histogram equalization was used. Features were extracted from the first-order statistics, Gray-Level Co-occurrence Matrix, Gray-Level Run Length Matrix, local binary pattern, Law's Texture Energy Measures, Discrete Wavelet Transform, and Zernikes' Moments using an image feature extraction tool "pyFeats. For the feature selection, three nature-inspired optimization algorithms, Grey Wolf Optimization, Particle Swarm Optimization (PSO), and Genetic Algorithm, were used. For classification, Random Forest classifier, K-Nearest Neighbour classifier, support vector machine (SVM) classifier gives the most accurate and precise result compared to other classification models. Furthermore, in feature selection methods, PSO gives the best result as compared to other methods for feature selection. Using the combination of the SVM classifier with the PSO method, it was observed that the accuracy, precision, recall, and F1-score were 100%. **Conclusion:** The result of the study indicates that with optimal features with the best choice of the classifier algorithm, the most accurate computer-aided diagnosis of CXR can be achieved. The approach presented in this study with optimal features may be utilized as a complementary tool to assist the radiologist in the early diagnosis of disease and making a more accurate decision.

Keywords: Artificial intelligence, chest X-ray, feature selection, image classification, machine learning

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INTRODUCTION

Coronavirus disease (COVID-19), caused by the SARS-CoV-2 virus, is one of the deadliest and most contagious diseases of this decade.^[1] The COVID-19 pandemic can be considered severe due to the high rate of transmission and lethality.^[2] Lack of any prior knowledge about this disease overwhelmed hospitals with shortages of detection tools and medical supplies, making the battle against COVID-19 onerous.^[3] Most infected people experience mild-to-moderate respiratory symptoms.^[4] Effective screening of the infected people was a critical step. Many techniques, such as real-time polymerase chain reaction, Truenat screening, cartridge-based nucleic acid amplification test, rapid antibody, and rapid antigen test techniques, were used for the detection of COVID-19.^[5,6]

The chest X-ray (CXR) is a useful, noninvasive clinical adjunct that aids in the initial diagnosis of a variety of pulmonary

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disorders.^[7] In the early diagnosis of COVID-19 disease, a vital role was played by the imaging techniques like CXR imaging. Some studies revealed distinct visual characteristics such as ground-glass opacities and patchy reticular opacities.^[8] Ground-glass opacities, patchy reticular opacities, can be detected on CXR images but not precisely as much in computed tomography (CT) images. CT is a more precise approach for imaging the chest, but it has not replaced CXR as the major imaging test due to the additional time, cost, and radiation exposure involved with CT. Less ionizing radiation, quick data collection, accessibility in intensive care units, and mobility

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are a few of the advantages that CXR has over CT. However, it is difficult and requires subject expert knowledge to manually identify these minor visual characteristics on CXR images.^[9]

With the development in technology, computer-aided diagnosis systems are growing in popularity since they reduce the cost of setting up a medical laboratory, hence expanding access to quality health care.^[10] Artificial intelligence has offered a new glimmer of hope for assisting clinicians in making more accurate imaging diagnoses and decreasing their workload.^[11,12]

Identifying the most significant risk factor associated with an illness is crucial in medical diagnosis. Quantitative data values or pixel intensities that provide rich, meaningful information about the pixels of an image in terms of local and/or global variation constitute an image's features.^[13] Image features can be handcraft features and nonhandcraft features or learned features.^[14] Handcraft features are manually engineered features and learning features are the features that are automatically extracted by the algorithm, like in deep learning.

Unfortunately, sometimes, deep learning models may suffer from overfitting problems, cause high bias because they extract unknown and abstract features, and need high-dimensional datasets to obtain higher performance.^[15-17] To overcome such problems, some researchers used pretrained transfer learning models to take advantage of the potential of deep learning techniques.^[18] For a specific problem, more meaningful and more known features designed can be extracted manually using handcrafted features. Furthermore, such techniques do not require a lot of data.^[19,20]

Multiple features-based classifications have the advantage of achieving good classification accuracy. With the selection of the most effective image features, all noise, redundant, and interrelated features can be removed.^[21] However, if too many features are derived from a limited training dataset, then due to overfitting, the robustness of the classification model will decrease on data other than the data used for training the model.^[22] Hence, the selection of a limited number of features is necessary to balance the accuracy and robust classification efficiency of the model. There are several methods available for feature selection like forward selection, backward elimination, recursive feature elimination (RFE), linear discriminant analysis, etc.^[23-25] Chandra et al. used 8196 features from the CXRs, which are eight first-order statistical features (FOSF), 88 Gray-Level Co-Occurrence Matrix (GLCM), and 8100 histograms of oriented gradients and they selected the features Using Binary Gray wolf optimization.^[26] Öztürk et al. used GLCM, local binary GLCM, Gray-level run length matrix (GLRLM), and segmentation-based fractal texture analysis features and to identify the most prominent features principal component analysis (PCA) was used.^[27] Bhargava et al. presented a comparative study that compared the classification performance of four machine learning models, i.e., PCA, K-Nearest Neighbour (KNN), Sparse Representation Classifier, artificial neural network (ANN), and SVM, for the different features extracted from the segmented CT and CXR images.^[28] Kumar *et al.* proposed the notion of Pearson Correlation Coefficient along with variance thresholding to optimally reduce the feature space of extracted features from the conventional deep learning architectures from the CXR images and used these features to classify the images into different categories.^[29] Sethy *et al.* presented a 2-class study using the SVM algorithm with the features obtained from 11 different well-known convolutional neural network (CNN) models with a very little data set. In their second study, they performed a 3-class study with increased data and determined the classification performance with SVM using the feature maps obtained from 13 CNN models.^[30]

The objective of the present study is to classify the CXR images into a COVID-positive and normal categories with the optimal number of features extracted from the images. The successful optimal feature selection algorithm that can represent images and the classification algorithm with good classification ability has been determined as the result of experiments.

MATERIALS AND METHODS

Dataset used

The presented work used publicly available data, the COVID-QU-Ex dataset from the Kaggle database, which was compiled by researchers from Qatar University.^[31-35] In the present study, out of 33,920 images, 400 CXR images were randomly selected with their ground truth to study only the lung part. All images were in portable network graphics format. The ability to segment lungs from surrounding structures significantly reduces the execution time and boosts the effectiveness of nodule identification.^[36] The given lungs-only masks from the database were used to segment the lungs from the X-ray images.

Data preprocessing

The objective of the data pre-processing stage is to prepare the data for use in the prediction model. Typically, data are disorganized and derived from various sources with varying sizes and resolutions. To reduce the complexity and increase the accuracy of the prediction model, cleaning up the data is crucial. In the first step, all the images were resized to 256×256 . After that, to enhance small details, textures, and contrast of the images, contrast limited adaptive histogram equalization, which is an adaptive contrast histogram equalization method, was used.^[37]

Features extraction

In any pattern classification system, feature extraction is a crucial step. Features were extracted from the first-order statistics (FoS), GLCM, GLRLM, local binary pattern (LBP), Law's Texture Energy Measures (LTEM), Discrete Wavelet Transform (DWT), and Zernikes' Moments (ZM) using an image feature extraction tool "pyFeats."^[38-46]

First-order statistical features

These features were extracted from the histogram of the image. These features included mean, median, skewness, kurtosis, etc.

Gray-level co-occurrence matrix

It is a second-order statistical feature that provides information about texture. GLCM examines the spatial relationship among pixels and defines the frequency of a combination of pixels in a given direction and distance. For texture analysis, several features like angular second moment, contrast, entropy, correlation, etc., can be calculated from the GLCM.

Gray-level run length matrix

It is a 2-D matrix of the component in which each component provides information about the total number of occurrences of the run having a length n of the grey level in a given direction. In GLRLM, the run length, or the number of the neighboring grey levels in a particular direction, is the frequency of the particular run in the image. Features such as short-run emphasis, long-run emphasis, run percentage, low gray level run emphasis, high gray level run emphasis, etc., can be calculated from GLRLM.

Local binary pattern

It is a texture descriptor that describes the local texture pattern of the image and is used for the property of high discriminative power. It assigns a binary number to the pixel by comparing the gray level with the neighboring after labeling. Energy and entropy of the LBP image, constructed over different scales, are used as feature descriptors.

Law's texture energy measures

A texture-energy-based approach developed by Law, measures the amount of variation within a fixed-size window. It uses a set of convolutional kernels to compute the texture energy. Features such as texture energy from different kernels, etc., can be calculated from the resulting image.

Discrete wavelet transform

DWT provides information on the time and frequency of the signal simultaneously. The different information of the main signal, such as high-frequency or low-frequency segments, can be extracted with the help of wavelet decomposition. By the application of DWT, the image is divided into four sub-bands, i.e., low-frequency components in horizontal and vertical directions (cA), the low-frequency component in the horizontal, and high-frequency component in the horizontal and low-frequency component in the vertical direction (cV), the high-frequency component in the vertical direction (cH) and high-frequency components in horizontal and vertical directions (cD). cA, cV, cH, and cD can also be represented as LL, LH, HL, and HH, respectively.

Zernikes' moments

In image shape description and content-based image retrieval, the moments, such as geometric moments, centric moments, and orthogonal invariance moments, have been used. The most commonly used technique in image shape feature extraction and description, i.e., Zernike moment, which is one kind of the orthogonal invariance moment and its kernel is a set of Zernike complete orthogonal polynomials defined over the interior of the unit disc in the polar coordinates space. An image moment is a certain particular weighted average of the image pixels' intensities in image processing, computer vision, and related fields or a function of such moments, usually chosen to have some attractive property or interpretation.

Features selection

The features extracted differed in their range, so to make them on the same scale, standardization was performed.^[47] To reduce the computation times and to take up less storage space, dimensionality reduction and feature selection can be so helpful. With the help of feature selection methods, we can remove noisy, redundant data and optimize the efficiency of the classification model simultaneously.^[48]

For the feature selection, three nature-inspired optimization algorithms were used. These nature-inspired algorithms were Grey Wolf Optimization (GWO) algorithm, Particle Swarm Optimization (PSO) algorithm, and Genetic Algorithm (GA).^[49-51] For feature selection using the GWO, PSO, and GA python library Zoofs was used.^[52]

Grey wolf optimization

It is a population-based meta-heuristic algorithm. It stimulates the leadership and predation behavior of the grey wolves. For simulating the leadership hierarchy, four types of grey wolves such as alpha, beta, gamma, and omega are employed. The three main steps of hunting, searching for prey (exploration), encircling prey, and attacking prey, are implemented in this algorithm. In the present study, the value of the parameters, i.e., size of the population and number of iterations used for GWO, were 40 and 20, respectively.

Particle swarm optimization

It is another metaheuristic optimization algorithm. It is inspired by swarm behavior such as a school of fish or a swarm of birds. It is one of the bio-inspired algorithms and differs from other optimization algorithms as it is not dependent on the gradient or any differential form of the objective. Due to the easy encoding of features, global search facility, being reasonable computationally, fewer parameters, and easier implementation, PSO is a suitable algorithm for feature selection. In the present study, the parameters used for PSO were the size of the population, number of the iteration, first acceleration coefficient of the particle swarm, second acceleration coefficient of the particle swarm, and weight parameter. The values of the above parameters used in the present study were 40, 20, 2, 2, and 0.9, respectively.

Genetic algorithm

It is an adaptive heuristic search algorithm based on the principles of genetics and natural selection. In GAs, there is a population or pool of possible solutions to the given problem. These solutions are then subjected to recombination and mutation (similar to natural genetics), resulting in the birth of new offspring, and the process is repeated for multiple generations. Each individual (or candidate solution) is assigned a fitness value, and the fitter people are given a greater opportunity to mate and produce more "fit" individuals. It optimizes both continuous and discrete functions and also multi-objective problems. It is very useful when the search space is very large and there are a large number of parameters involved. In the present study, the parameters used for GA were the size of the population, number of the iteration, selective pressure, elitism, and mutation rate. The values of the above parameters used in the present study were 40, 20, 2, 2, and 0.05, respectively.

Image classification

For the classification of the images using the reduced features from the above-mentioned algorithms, different machine-learning models were used. These models were the Random Forest (RF) classifier, KNN classifier, SVM classifier, and light gradient boosting model (LGBM) classifier.^[53-56]

Random forest

It is a supervised machine learning algorithm based on ensemble learning. It is a combination of the large number of the decision each tree in the ensemble is comprised of a bootstrap sample, which is a data sample obtained from a training set with replacement. To make the final decision, it aggregates the output from all decision trees formed on different samples and decides the outcome based on the majority voting. Figure 1 shows the working of RF.

K-nearest neighbour

It is also a nonparametric supervised machine learning algorithm. An input test data point is classified by identifying the K nearest training vectors using a suitable distance metric. The class to which the majority of these K nearest neighbors belong is then allocated to the test input data point. Figure 2 shows the working of KNN.

Support vector machine

It is a supervised machine learning algorithm, and the objective of the SVMC is to find a hyperplane in N-dimensional space that can distinctly classify the data points. The dimension of the hyperplane depends on the number of features. Data points falling on either side of the hyperplane can be attributed to different classes. It chooses the extreme points that help in creating the hyperplane. These extreme cases are called "support vectors." Figure 3 shows the working of SVM.

Light gradient boosting model

It is based on the gradient boosting framework. It uses two types of techniques which are Gradient-based one side sampling (GOSS) and Exclusive Feature bundling (EFB). In contrast to other boosting algorithms, which grow tree level-wise, it selects the leaf with maximum delta loss to grow. Limiting the maximum depth of trees can not only ensure training efficiency but also prevent overfitting. GOSS excludes the significant portion of the data part, which has small gradients and to estimate the overall information gain use the remaining data. For computation on information gain, the data instances which have large gradients play a greater



Figure 1: Working of random forest algorithm



Figure 2: Working of K- nearest neighbour algorithm



Figure 3: Working of support vector algorithm

role. When the value of information gain has a large range, this can lead to a more accurate gain estimation than uniformly random sampling with the same target sampling rate. While working with high dimensional data, there are many features that are mutually exclusive, with the EFB technique, LGBM can safely bundle such exclusive features into a single feature to reduce the complexity.

Proposed work

In the present study, a total of 400 CXR images were taken. These images were equally divided into COVID-19 and normal classes. This dataset was further divided into training and testing in a ratio of 80:20. Figure 4 depicts the block diagram of the present study.

A total of 98 features were obtained for each image using FoS, GLCM, GLRLM, LBP, LTEM, DWT, and ZM. For optimization of the features, with each optimizing algorithm, the classification algorithm with hyper-tuned parameters was given as an objective function. For the classification models, the hyperparameters used in the study are given in Table 1.

For each classification algorithm, i.e., RF, KNN, SVM, LGBM, different numbers of optimal features were obtained using GWO, PSO, and GA. All steps, which included feature extraction, feature reduction, and classification, were implemented using Python 3.10 on Google Colab. In classification models, for hyperparameter tuning of parameters, GridSearchCV from the sklearn library was used.^[57] The machine learning model is evaluated for a variety of hyperparameter values. This approach seeks for the best set of hyperparameters from a grid of hyperparameters values.

Performance evaluation

The metrics that were used in the evaluation process for the model performance were accuracy, precision, sensitivity, and F1 score. Accuracy is the ratio of the number of correct predictions to the total number of predictions. Precision is the ratio of the number of correct positive class predictions to the total positive class predictions. Sensitivity is the number of correct positive class predictions and the false negative class predictions. The F1 score is the weighted average of precision and sensitivity. F1 score reaches its best value at 1 and worst score at 0. The relative contribution of precision and recall to the F1 score are equal. The accuracy metric computes how many times a model made a correct prediction across the entire dataset. F1-score gives a better measure of the incorrectly classified cases than the accuracy metric.

RESULTS

In the present study, the classification performance of the four machine learning algorithms (RF, KNN, SVM, LGBM) with the optimal number of features extracted from the CXR images was studied.

Feature extraction

The details of the features extracted from the Zoofs library are given in the supplementary file, with each feature name as mentioned in the library.

The different number of features extracted from the CXR images are given in Table 2.

Performances of feature selection algorithms

Using the GWO, PSO, and GA feature selection algorithms, the selected optimal number of features was selected. The GWO reduced the features in the range of 81 to 85 from

Table 1: Value of hyperparameters for different classification models

Classification model	Parameters
RF	max_features="log2," n_estimators=40
KNN	n_neighbors=6, weights="distance"
SVM	C=100, gamma=0.001
LGBM	bagging_fraction=0.5, bagging_frequency=5, feature_fraction=0.5, max_depth=10, min_ data_in_leaf=110, num_leaves=1200

RF: Random Forest, KNN: K-Nearest Neighbour, SVM: Support Vector Machine, LGBM: Light Gradient Boosting Model

Table	2:	Different	features	extracted	from	the	chest	X-ray
image	s							

Number of features
16
14
11
8
6
18
25
98

FoS: First-order statistics, GLCM: Gray-Level Co-Occurrence Matrix, GLRLM: Gray-Level Run Length Matrix, LBP: Local Binary Pattern, LTEM: Law's Texture Energy Measures, DWT: Discrete Wavelet Transform, ZM: Zernike's Moments



Figure 4: Block diagram representing the working of present study

a total of 98 features, the PSO reduced the features in the range of 47 to 52 from a total of 98 features and the GA reduced the features in the range of 38 to 53 from total 98 features as given in Table 3. On an average, 83 (84.69%) features out of the total features were selected by GWO, 49 (50.00%) features out of the total features were selected by PSO, and on an average, 44 (45.66%) features of the total features were selected by GA in the optimal feature selection.

Classification algorithm comparison with different feature selection algorithms

Table 4 shows the comparative performance of 3 feature selection algorithms and 4 classification algorithms for the classification of 400 CXR images. For the RF classifier, the feature selection algorithms PSO and GA outperform the GWO. For KNN, SVM, and LGB classifiers, the feature selection algorithms PSO outperform the GWO and GA. The python source code is available on https://github.com/MohiniManav/ Feature-optimization.

Figure 5 demonstrates the classification performance of classification models on test data with different feature selection algorithms.

In order to demonstrate the performance of the proposed framework over the existing state-of-the-art in terms of various evaluation metrics, a comprehensive performance comparison with other similar works in the literature has been performed. Khuzani *et al.* performed a study with spatial (Texture, GLDM, GLCM), frequency (Wavelet and FFT), and statistical measurements. In their study features were reduced using PCA and classified using an Artificial Neural Network (ANN). In their study, the highest overall accuracy and F1-score values were 95% and 94.3%, respectively.^[19]

Singh *et al.* extracted the features from CXR images and relevant features were selected using the Hybrid Social Group Optimization algorithm. With these selected features, a classification accuracy of 99.65% was achieved using the SVM classifier in their study.^[58]

Mostafiz et al. proposed an approach to detect COVID-19 with good accuracy from the CXR image using the hybridization

Table 3: Feature selection for various classification models using feature selection algorithms			
Models used for classification	Methods used for feature reduction	The initial number of features	Selected optimized number of features
RF	GWO	98	83
	PSO	98	48
	GA	98	38
KNN	GWO	98	85
	PSO	98	47
	GA	98	38
SVM	GWO	98	81
	PSO	98	50
	GA	98	53
LGB	GWO	98	83
	PSO	98	52
	GA	98	50

RF: Random Forest, KNN: K-Nearest Neighbour, SVM: Support Vector Machine, GWO: Grey Wolf Optimization, PSO: Particle Swarm Optimization, GA: Genetic Algorithm, LGB: Light Gradient Boosting

Table 4: Performance of different feature selection algorithms with different classifiers					
Models used for classification	Methods used for feature reduction	Accuracy	Precision	Recall	F1-score
RF	GWO	88	85	85	85
	PSO	96	94	97	96
	GA	96	94	97	96
KNN	GWO	84	77	88	82
	PSO	93	89	94	91
	GA	90	86	91	89
SVM	GWO	96	92	100	96
	PSO	100	100	100	100
	GA	99	97	100	99
LGB	GWO	93	91	91	91
	PSO	95	92	97	94
	GA	93	89	94	91

RF: Random Forest, KNN: K-Nearest Neighbour, SVM: Support Vector Machine, GWO: Grey Wolf Optimization, PSO: Particle Swarm Optimization, GA: Genetic Algorithm, LGB: Light Gradient Boosting

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Figure 5: Bar graph representing the classification performance of classification models on test data with different feature selection algorithms

of deep CNN and DWT features. They extracted optimum features from these hybridized features through minimum redundancy and maximum relevance along with RFE and achieved an overall accuracy of more than 98.5%.^[59]

Nour et al. conducted a 3-class classification study for the classification of COVID-19-normal-viral Pneumonia. They obtained the features with CNN models and optimized the parameters of the models using the Bayesian optimization algorithm. They used SVM and KNN for classification. In their study, the most efficient results were ensured by the SVM classifier with an accuracy of 98.97%, a sensitivity of 89.39%, a specificity of 99.75%, and an F-score of 96.72%.[60] Sahlol et al. proposed an improved hybrid classification approach for COVID-19 images by combining the strengths of CNNs to extract features and a swarm-based feature selection algorithm (Marine Predators Algorithm) to select the most relevant features from 2 datasets. They achieved 98.7%, 98.2% and 99.6%, 99% of classification accuracy and F-Score for dataset 1 and dataset 2 respectively.^[61] Dias Júnior et al. extracted the features from CXR using a deep features-based approach implemented through the networks VGG19, Inception-v3, and ResNet50 and the classified the CXR images into COVID-19 and Non-COVID-19 groups, using eXtreme Gradient Boosting (XGBoost) optimized by PSO. They achieved an accuracy of 98.71%, a precision of 98.89%, a recall of 99.63%, and an F1-score of 99.25%.[62] Mohammed et al. used Binary PSO to optimize the LBP features extracted from the CXR images. For the classification of CXR into COVID and Non-COVID category, they have used SVM and KNN classifiers. Their experimental results showed an average accuracy of 94.6%, sensitivity of 96.2%, and specificity equal to 93% with the SVM classifier.^[63]

In the present study, for all the feature selection methods, SVM classifier gave the most accurate and precise result as compared to other classification models. Also, in feature selection methods, PSO gave the best result as compared to other methods for feature selection. Using the combination of SVM classifier with the features selected with PSO algorithm, we observed that the accuracy, precision, recall, and F1-score were 100%.

CONCLUSION

The present study used the optimal number of features extracted from the CXR images for classification. Based on these features, CXR images were classified into two categories, i.e., COVID-19 and normal images. For optimal feature selection, three nature-inspired algorithms GWO, PSO, and GA were used. For classification, RF, KNN, SVM, and LGBM classifiers were used. With optimal features obtained with PSO, the SVM classifier achieved the highest accuracy, precision, recall, and F1 score as compared to others. The result of the study indicates that with optimal features and the best choice of the classifier algorithm, the most accurate computer-aided diagnosis of CXR can be achieved.

Since the present study uses publicly available data so the diversity of the databases can simulate the clinical routine, and makes the classification method amenable to comparison. It does not require large quantities of hardware resources, which is one of the biggest problems faced in deep learning-based methods. As it is extremely difficult to manually select a feature from the dataset on which the algorithm can perform better, so understanding the dataset and selecting meaningful features from it prior to feeding data into the machine learning algorithm is necessary. The feature selection impacts the final accuracy of the machine learning models. Contrarily, a deep learning algorithm with a small dataset has a high chance of over-fitting. It also requires high computational power, a large feature set, and resources compared to machine learning models.

However, our method did not propose a new machine-learning model. We used the existing models and demonstrated their effectiveness for feature classification. It is believed that developing a new model or modifying the existing classification architectures will further improve results and can be extended as future work.

The minimal consumption of data storage, processing time, and hardware is an additional advantage of the optimal feature selection. Thus, the proposed computer-aided diagnosis approach with optimal features may be used as a complementary tool to assist the radiologist in making a more accurate and early diagnosis of disease using CXR images.

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Conflicts of interest

There are no conflicts of interest.

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Supplementary Table 1: Extracted features from X-rays

Feature extracted from	Features extracted (features name given here as mentioned in zoofs python library)
FOS features	"FOS_Mean," "FOS_Variance," "FOS_Median," "FOS_Mode," "FOS_Skewness," "FOS_Kurtosis," "FOS_ Energy," "FOS_Entropy," "FOS_MinimalGrayLevel," "FOS_MaximalGrayLevel," "FOS_CoefficientOfVariation," "FOS_10Percentile," "FOS_25Perce-ntile," "FOS_75Percentile," "FOS_90Percentile," "FOS_HistogramWidth"
GLCM	"GLCM_ASM," "GLCM_Contrast," "GLCM_Correlation," "GLCM_SumOfSquaresVariance," "GLCM_ InverseDifferenceMoment," "GLCM_SumAverage," "GLCM_SumVariance," "GLCM_SumEntropy," "GLCM_Entropy," "GLCM_DifferenceVariance," "GLCM_DifferenceEntropy," "GLCM_Information1," "GLCM_Information2," "GLCM_ MaximalCorrelationCoefficient"
LTE	"LTE_LL_7," "LTE_EE_7," "LTE_SS_7," "LTE_LE_7," "LTE_ES_7," "LTE_LS_7"
GLRLM	"GLRLM_ShortRunEmphasis," "GLRLM_LongRunEmphasis," "GLRLM_GrayLevelNo-Uniformity," "GLRLM_ RunLengthNonUniformity", "GLRLM_RunPercentage", "GLRLM_LowGrayLevelRunEmphasis", "GLRLM_ HighGrayLevelRunEmphasis," "GLRLM_Short owGrayLevelEmphasis," "GLRLM_ShortRunHighGrayLevelEmphasis," "GLRLM_LongRunLowGrayLevelEmphasis," "GLRLM_LongRunHighGrayLevelEmphasis"
LBP	"LBP_R_1_P_8_energy," "LBP_R_1_P_8_entropy," "LBP_R_2_P_16_energy," "LBP_R_2_P_16_entropy," "LBP_R_3_P_24_energy," "LBP_R_3_P_24_entropy"
DWT	"DWT_bior3.3_level_1_da_mean," "DWT_bior3.3_level_1_da_std," "DWT_bior3.3_level_1_dd_mean," "DWT_ bior3.3_level_1_dd_std," "DWT_bior3.3_level_1_ad_mean," "DWT_bior3.3_level_1_ad_std," "DWT_bior3.3_level_2_ da_mean," "DWT_bior3.3_level_2_da_std," "DWT_bior3.3_level_2_dd_mean," "DWT_bior3.3_level_2_dd_std," "DWT_bior3.3_level_2_ad_mean," "DWT_bior3.3_level_2_ad_std," "DWT_bior3.3_level_3_da_mean," "DWT_ bior3.3_level_3_da_std," "DWT_bior3.3_level_3_dd_mean," "DWT_bior3.3_level_3_dd_std," "DWT_bior3.3_level_3_ad_std," "DWT_bior3.3_level_3_dd_std," "DWT_bior3.3_level_3_dd_s
ZM	"zenikes 0," "zenikes 1," "zenikes 2," "zenikes 3," "zenikes 4," "zenikes 5," "zenikes 6," "zenikes 7," "zenikes 8," "zenikes 9," "zenikes 10," "zenikes 11," "zenikes 12," "zenikes 13," "zenikes 14," "zenikes 15," "zenikes 16," "zenikes 17," "zenikes 18," "zenikes 19," "zenikes 20," "zenikes 21," "zenikes 22," "zenikes 23," "zenikes 24"

FOS: First-order statistics, GLCM: Gray-level co-occurrence matrix, GLRLM: Gray-level run length matrix, LBP: Local binary pattern, DWT: Discrete wavelet transform, ZM: Zernike's moments, LTE: Law's Texture Energy