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Obstructive respiratory disease simulation device

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ABSTRACT

Respiratory disease is a major contributor to healthcare costs, as well as increasing morbidity and early mortality. The device presented is used to simulate the effects of Chronic Obstructive Pulmonary Disease (COPD) in healthy people. The intended use is to provide data equivalent to COPD data measured from those who are ill for initial validation of respiratory mechanics models. It would thus eliminate the need to test unhealthy and/or fragile subjects, or the need for invasive or costly equipment based test methods. The device is used in conjunction with an open-access venturi-based flow sensor, to measure pressure, flow, and breath tidal volume. The device simulates the pressure and flow profiles of a person who has COPD including the non-linear increased resistance to end-exhalation and gas trapping. To achieve this non-linearity, a combination of high and low resistance outlets is used. Thus, the simulator allows the collection of patient-specific COPD-like breathing data in a non-invasive manner from healthy subjects. The device is low-cost with the majority of the parts 3D printed using a Prusa mini 3D printer and PLA filament.

Specifications table

Hardware name	Obstructive Respiratory Disease Simulation Module
Subject area	Engineering and materials science
Hardware type	Measuring physical properties and in-lab sensors
Closest commercial analog	No commercial analog is available.
Open source license	Creative Commons Attribution-ShareAlike license
Cost of hardware	\sim \$60 NZD
	\sim \$350 NZD for the data recording device (shutter not required)
Source file repository	https://doi.org/10.17632/kk6hktdydg.3
	Used in conjunction with components of a data recording device [1]
OSHWA certification UID (OPTIONAL)	NZ000003

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Hardware in context

Respiratory disease is a large contributor to healthcare costs in New Zealand, costing ~ 6.68 billion dollars in 2017, and accounts for 6.3 % of total health loss in New Zealand [2]. COPD is one of the largest contributors to this total health loss at 3.7 % followed by asthma at 1.6 % [3]. The COPD simulation device presented is designed to avoid having to test unhealthy and/or fragile subjects, while minimising the need for invasive or equipment-specific tests, which usually come at a far higher time and economic cost. It is designed to be used in conjunction with an open-access venturi-based flow sensor [1,4], to measure pressure, flow, and breath tidal volume, which can then be used to replicate COPD pressure-flow loops from healthy subjects with much lower cost and risk.

More specifically, the validation of respiratory models for COPD currently requires clinical testing on unhealthy people with the disease and the potential use of invasive or difficult to perform maneuvers and methods. The development of a system or device to simulate respiratory disease in healthy individuals would reduce the need for these methods and unhealthy test subjects, reducing risk and cost. Respiratory models have the potential to be used to determine patient-specific mechanical ventilation settings are traditionally determined by the clinician [8,9], so accurate predictive respiratory models have the potential to assist clinicians to make this decision and provide better patient-specific care [6,10–13].

There are two current categories of respiratory disease simulation devices on the market. The first category are devices that simulate the symptoms of respiratory disease in healthy people. The second category are artificial lung devices that simulate pressure, flow, and volume profiles of respiratory disease. Devices in both categories are high cost (typically > US \$850) and are not useful in the validation of respiratory models. In particular, devices that simulate the symptoms of respiratory disease in healthy people are not specific to COPD. The devices on the market in the first category predominantly focus on simulating the symptoms and feeling of having generalised respiratory distress rather than the specific dysfunctions present in diseases like COPD. Additionally, these devices do not generate the characteristic pressure, flow, and volume profiles that result from COPD. Thus, they are not helpful in the validation of respiratory models in the way the proposed devices intend. The devices in the second category produce the pressure and flow profiles required, but are not patient-specific meaning they cannot mimic inter- and intra- patient variabilities seen in clinical practice, where the device presented does provide these variabilities as they are obtained from individuals every breath. The device outlined in this article combines the benefits of both categories to result in a low-cost, non-invasive device that generates patient-specific pressure, flow, and volume profiles associated with COPD. The majority of the designed device is 3D printed and it is easily customisable to suit the required disease state. COPD is classified by the level of gas trapping and flow limitation [14]. The level of flow limitation in this device is determined by the high resistance outlet and the gas trapping by the free volume. Thus different disease states are able to be simulated by changing the free volume or high resistance outlet sizes. In this case severe COPD has been simulated with a high resistance outlet and large free volume but trial and error with changing these would allow a multitude of different disease states to be simulated.

Hardware description

The designed COPD simulation device is low-cost, non-invasive, and customisable. The intended use of this device is to simulate COPD in conjunction with measurements of airway pressure, flow, and volume using either a y-split flow sensor system [1], or a simpler venturi design approach and only exhaling through the device [4,15]. The assembly is designed to be used with or without a constant positive airway pressure (CPAP) device to provide additional positive end-expiratory pressure (PEEP), a common form of treatment therapy for COPD [16–18]. To simulate both the symptoms and characteristic flow profiles of COPD the device uses a combination of high and low resistance outlets. The device is attached to the exhalation side of the flow sensor y-split. Attaching the device to only the exhalation side allows inhalation to remain unchanged. COPD only effects exhalation a key feature other devices on the market don't include. During exhalation air first enters the low resistance free volume chamber, as pressure increases in the chamber the air is diverted out the high resistance outlet. This diversion creates a non-linearity in resistance, characteristic of COPD, with an increased resistance to end-exhalation. The non-linearity is a key difference of this device from those currently available, as it creates the required flow profiles, rather than just simulating an obstruction. Equally, it does so based on a subject-specific breath.

As this device is 3D printed, it is easily customisable in almost all design aspects. This project demonstrates three different free volume chamber sizes (200 mL, 250 mL, and 300 mL), but is generalisable to a very wide range and resolution. Additionally, the resistance of the high resistance outlet can be changed by changing the size of the hole, and is again generalisable and controls, in part, how fast the free volume fills. Customising this device has the potential to mimic multiple different disease states (modes and progressions).

Table 1

Design file summary.

Design file name	File type	Open source license	Location of the file
COPD_CoverLid	CAD (SLDPRT) and STL files	CC BY 4.0	3D Printed Hardware
CODP_Cover_300mL_20-02-23	CAD (SLDPRT) and STL files	CC BY 4.0	3D Printed Hardware
CODP_Cover_250mL_20-02-23	CAD (SLDPRT) and STL files	CC BY 4.0	3D Printed Hardware
CODP_Cover_200mL_20-02-23	CAD (SLDPRT) and STL files	CC BY 4.0	3D Printed Hardware
COPD_LowResPathAdaptor_Female	CAD (SLDPRT) and STL files	CC BY 4.0	3D Printed Hardware
COPD_HighResPathCap_2mm	CAD (SLDPRT) and STL files	CC BY 4.0	3D Printed Hardware
COPD_ExpiratoryYJunction	CAD (SLDPRT) and STL files	CC BY 4.0	3D Printed Hardware

Table 2 Design file bill of materials (cost in NZD).

Designator	Component	Number	Cost per Unit	Total Cost	Source of Materials	Material Type
COPD_CoverLid	1.75 mm PLA + 3D Filament	3 (216.75 g)	\$27.00/ 1kg	\$17.51	https://www.wondershop.nz/i/100000-100016.html	Polymer
COPD_Cover_300mL_20-02-23	1.75 mm PLA + 3D Filament	1	\$27.00/ 1kg	\$7.39	https://www.wondershop.nz/i/100000-100016.html	Polymer
COPD_Cover_250mL_20-02-23	1.75 mm PLA + 3D Filament	1	\$27.00/ 1kg	\$7.05	https://www.wondershop.nz/i/100000-100016.html	Polymer
COPD_Cover_200mL_20-02-23	1.75 mm PLA + 3D Filament	1	\$27.00/ 1kg	\$6.74	https://www.wondershop.nz/i/100000-100016.html	Polymer
COPD_LowResPathAdapter_Female	1.75 mm PLA + 3D Filament	1	\$27.00/ 1kg	\$6.54	https://www.wondershop.nz/i/100000-100016.html	Polymer
COPD_HighResPathCap_2mm	1.75 mm PLA + 3D Filament	1	\$27.00/ 1kg	\$5.56	https://www.wondershop.nz/i/100000-100016.html	Polymer
COPD_ExpiratoryYJunction	1.75 mm PLA + 3D Filament	1	\$27.00/ 1kg	\$6.13	https://www.wondershop.nz/i/100000-100016.html	Polymer
M4 Nut	M4 Hex Nut	6	\$0.14	\$0.84	https://www.aliexpress.com/item/1005003780212966.html?spm = a2g0o.productlist.main.1.2d1bc76fUnhMi4&algo_pvid = 04364139-248a-4a51-9e53-14042b72e459&aem_p4p_detail = 20230222161124450514919800698000355055&algo_exp_id = 04364139-248a-4a51-9e53-14042b72e459-0&pdp_ext_f= %7B%22sku_id%22 %3A%2212000027143164251 %22 %7D&pdp_npi = 3 %40dis%21NZD%212.34 %211.67 %21 %21 % 21 %21 %4021227e5116771110847754832d06bf%2112000027143164251 %21sea%21NZ%210&curPageLogUid = zLQHnB6yBBRI&ad_pvid = 202302221611244505149198006980003550505_1&ad_pvid = 202302221611244505149198006980003550505 1	Metal
M4 x 10	10 mm M4 Screw	6	\$0.20	\$1.20	https://www.aliexpress.com/item/1005002364189187.html?spm = a2g0o.productlist. main.1.344bb686QDXACO&algo_pvid = f773682b-8927-4d8f-ae47-4293ef6fbb1f&aem_p4p_detail = 20230222162028640361160391860003405370&algo_exp_id = f773682b-8927-4d8f-ae47-4293ef6fbb1f-0&pdp_ext_f=%7B %22sku_id%22 %3A%2212000020354274959 %22 %7D&pdp_npi = 3 %40dis%21NZD%216.44 %210.02 %21 %21 %2 21 %21 %40211be59e16771116280258377d06f7%2112000020354274959 %21sea%21NZ%210&curPageLogUid = YYZK8uwM3yQf&ad_pvid = 2023022162028640361160391860003405370_1&ad_pvid = 20230222162028640361160391860003405370_1	Metal
Latex Balloon	Microphone Cover/Non- lubricated Condom	1	\$0.90	\$0.90	https://www.ripnroll.com/products/microphone-covers	Latex
Zip Ties	Zip Ties	2	\$0.02	\$0.04	https://www.thewarehouse.co.nz/p/mako-cable-tie-set-400-piece/R2071900.html?&&&&gclsrc = aw.ds&ds_rl = 1268368&ds_rl = 1268368&ds_rl = 1268368&gclid = CjwKCAjwSdqgBhBNEiwA7PryaIQ_OhaG5gSRLlhGlwuqjspGGUht5hfs0s5hjQhaMpOi31j7VpoSYBoCvh4QAvD_BwE&gclsrc = aw.ds	Polymer
Magnets	Counterweight	2	\$3.50	\$7.00	= aw.ds https://www.magnets.co.nz/shop/neodymium/rings-neodymium/10 mm-x-3 mm-x-3 mm-countersunk-neodymium-ring/? keyword_k=&gclid = CjwKCAjw5dqgBhBNEiwA7PryaOGnJmXKzldhj2UNtyhy6ePSA8sXF92vJWML05vm5AYXvwq2GmnQehoCTjwQAvD_BwE	Metal

ω



Fig. 1. COPD simulator assembly.



Fig. 2. Free volume chamber adaptor 3D printed with supports.

Overall, the device is able to simulate COPD for the use of preliminary development and respiratory model validation by using a combination of fixed high and low resistance outlets. The device can be useful as an initial tool as the data collected allows comparison of healthy data and simulated COPD from the same subject. The simulation and data collection is also, non-invasive, does not burden unhealthy people, can be modified to suit multiple applications by changing either the high resistance outlet or free volume chamber size.



Fig. 3. Assembly of M4 nuts in Free Volume Chamber.

- Non-invasive, low-cost, patient specific COPD simulation
- Respiratory model validation
- Non-invasive data collection
- 3D printed and customisable

Design files summary

Table 1 outlines the design files for the simulation device, the type of file is indicated in the table. The categories of files are: 3D Printed Hardware (both CAD and STL file). Both the CAD and STL files are provided for the 3D printed components to allow modifications and ability to use for multiple applications. The data collection used code was taken from the flow sensor design [1].

Bill of materials summary

Table 2 outlines the bill of materials required to build the COPD simulation device with component name, number or amount required, cost per unit (NZD), total cost (NZD), source of materials, and material type.

Build instructions

The expiratory port splitter, free volume chamber adaptor, free volume chamber, free volume lid, and high resistance outlet, Fig. 1, were 3D printed with 1.75 mm PLA using a Prusa mini 3D printer (Prusa Mini+, Prusa Research, Prague, Czech Republic). The 3D printer settings were set at 0.10 mm detail with 40 % infill. The only component printed with support was the free volume chamber adaptor, it was printed with supports on the base plate, Fig. 2. The remaining components were 3D printed without supports.

The support material was removed from the free volume chamber adaptor using pliers. The latex balloons were rolled out 11 cm and zip tied (Fig. 3) to the free volume adaptor, the magnets were attached 4 cm from the end to act as a counterweight, Fig. 4.

Attach the free volume adaptor and balloon assembly to the free volume chamber using 6x M4 10 screws and place the lid on the end of the free volume chamber, Fig. 5.

The high resistance outlet and low resistance free volume assembly were press fit onto either side of the expiratory port, Fig. 1, to complete the COPD simulator assembly. Once assembled, the device was used in conjunction with a venturi-based flow sensor with y-split tubing. The device was attached to the expiratory side of the device to collect respiratory data for the validation of pulmonary



Fig. 4. Free volume adaptor and latex balloon assembly.



Chamber Adaptor

Fig. 5. Assembly of free volume chamber.

mechanics models, Figs. 6 and 7.

Different disease states, in terms of severity, were simulated by printing various volumes of the free volume chamber. Testing was carried out for each free volume chamber size. Additionally, the size of the resistance hole can be modified to increase or decrease the resistance, and thus the dynamics of simulated gas trapping in the free volume.

Operation instructions

Connect the COPD simulator into the venturi-based flow sensor expiratory port as per Fig. 6. Connect the computer recording the data to the Arduino nano. To the patient end, attach the filter and mouthpiece, Fig. 7.

If using CPAP to record data with added PEEP, attach the CPAP tube to the inhalation side of the venturi-based flow sensor device, Fig. 7.



Outlet





Fig. 7. COPD simulator assembly with CPAP mouthpiece and filter.

A mouthpiece and nose clip assembly are preferred with this device as the simulator requires a significant exhalation effort. Due to this effort and high pressure this can cause mask leaks if the CPAP is used with a mask attachment. The nose clip is used in conjunction with the mouthpiece to stop the user beathing out their nose, resulting in unobstructed and uncaptured expiratory flow. Using the MATLAB code, set the time to the desired length and record the data. Breathe normally through the device, additional effort may be required on exhalation. Collect the raw overall pressure and atmospheric differential pressure, inhalation pressure differential and exhalation pressure differential sampled at 100 Hz. This data can then be used to separate each breath and determine the pressure, flow, and volume profile of each breath.

Validation and characterization

The device is characterised by:

- Modular free volume attachments of 200, 250, and 350 mL
- A fixed high resistance outlet with a parabolic resistance orifice (166 cmH2O at 0.5L/s) (Equation (1), Fig. 8)

Both of which, are easily customisable by changing the size of the free volume housing, and the size of the hole on the high resistance outlet, respectively.

The data collection system has been validated against a TSI4000 Flow meter (4000 Series Analog and Digital Flow Meter, TSI, Shoreview, MN, USA) [1]. The data collection system used low-cost sensors to measure the pressure differentials of inhalation and exhalation, for further information on the validation of this system refer to [1]. The additional cost of the data collection system was approximately \$350 NZD [1] or previous iterations of this data collection system can be used at a lower cost [4,15].

The fixed parabolic high resistance was characterised using Equation (1), resulting in the plot seen in Fig. 8. The theoretical



Fig. 8. Resistance curve of fixed parabolic high resistance outlet.



Fig. 9. Example of PQ plot using COPD simulation device in comparison to no device and PQ loop from real COPD [20,21].

resistance (Equation (1), Fig. 8) was compared to the pressure and flow curves of known mechanical lung resistors [19].

$$P = \frac{\frac{1}{2}\rho\left(\frac{Q}{1000}\right)^2 \left(\left(\frac{1}{A_2^2}\right)\left(1 - \left(\frac{A_2}{A_1}\right)^2\right)\right)}{98.066} \#$$
(1)

Equation (1) is derived from Bernoulli using pressure in cmH₂0 [1,4,15]. Where P is the Pressure drop [cmH₂0], Q the flow [L/min], ρ is density of the air 1.225 kg/m3, A1 and A2 are the area of the Venturi at the inlet and constriction respectively [1,4,15].

Fig. 9 shows the resulting pressure flow (PQ) curve for one breathing using the 250 mL simulation device compared to the control breath with no device, and real COPD data [20]. Specifically, the expiratory lobe generated by the device in comparison to a normal breath without the device. Where the lobe is generated by the variable resistance free volume before air is solely diverted out the fixed high resistance outlet. In addition, since the data was generated by a healthy subject the control breath on the inspiratory limb matches the blue line when the device is added, where the example COPD data from a clinical study has a different slope, as well as less gas trapping seen in the smaller lobe.

Ethics statements

Ethics approval for this research was granted by the University of Canterbury Human Ethics Research Committee (Ref: HREC2022/26/LR), with amendments accepted on the 17th of February 2023. Test subjects were voluntarily and given a verbal and written description before starting the trial or signing a consent form.

CRediT authorship contribution statement

Jaimey A. Clifton: Conceptualization, Software, Validation, Writing – original draft. Ella F.S. Guy: Conceptualisation, Software, Validation, Supervision, Writing – review & editing. Jennifer L. Knopp: Conceptualization, Supervision, Writing – review & editing. J. Geoffrey Chase: Conceptualisation, Funding Acquisition, Resources, Supervision, Writing – review & editing.

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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