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5 Chronic recording of brain activity in awake toads

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32 ABSTRACT

33 Background

34 Amphibians represent an important evolutionary transition from aquatic to terrestrial
35 environments and they display a large variety of complex behaviors despite a relatively simple
36 brain. However, their brain activity is not as well characterized as that of many other
37 vertebrates, partially due to physiological traits that have made electrophysiology recordings
38 difficult to perform in awake and moving animals.

39 New method

40 We implanted flexible mesh electronics in the cane toad (*Rhinella marina*) and performed
41 extracellular recordings in the telencephalon of anesthetized toads and partially restrained,
42 awake toads over multiple days.

43 Results

44 We recorded brain activity over five consecutive days in awake toads and over a 15 week
45 period in a toad that was anesthetized during recordings. We were able to perform spike sorting
46 and identified single- and multi-unit activity in all toads.

47 Comparison with existing methods

48 To our knowledge, this is the first report of a modern method to perform electrophysiology in
49 non-paralyzed toads over multiple days, though there are historical references to short term
50 recordings in the past.

51 Conclusions

52 Implementing flexible mesh electronics in amphibian species will allow for advanced studies of
53 the neural basis of amphibian behaviors.

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56 1. INTRODUCTION

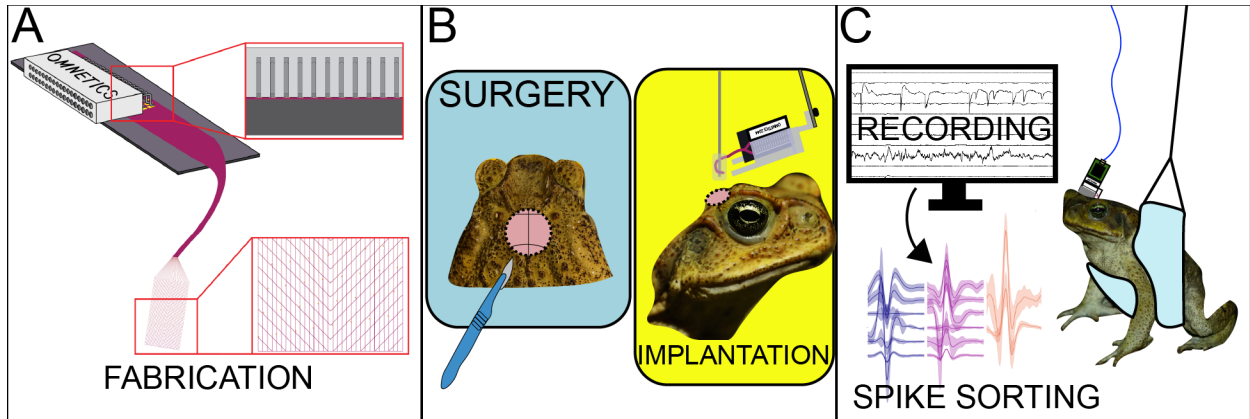
57 Since the discovery of “animal electricity” in amphibians more than 200 years ago
58 (Piccolino, 1997), neural electrophysiology has greatly contributed to our modern understanding
59 of brain function across animal life. Both intracellular and extracellular recordings, *in vivo* and *in*
60 *vitro*, have allowed for biophysical characterization of neuronal activity, descriptions of brain
61 responses to sensory stimuli, and examination of neural circuits underlying complex behavior
62 (Cavanagh, 2019). Even as other methods for the live visualization of neuronal activity are
63 popularized and new methods are developed (such as calcium imaging and opto-acoustic
64 visualizations), much neuroscience research relies on traditional recording methodologies that
65 may incorporate new technologies and genetic tools.

66 Advances of *in vivo* electrophysiology methods have led to recordings being
67 implemented in increasingly difficult environmental situations, such as the wireless recording of
68 brain recording in freely swimming fish (Vinepinsky et al., 2017) and very small *Drosophilid* flies
69 (Swale et al., 2018). Yet, despite the initial discoveries leading to electrophysiology
70 methodology taking place in frogs (Piccolino, 1997), limited modern neural electrophysiology
71 work has characterized brain function in amphibians. This mostly includes measuring neural
72 responses to sensory information, including visual processing in the retina or optic tectum
73 (Buxbaum-Conradi and Ewert, 1995; Ewert et al., 1990; Finkenstädt and Ewert, 1983; Kühn and
74 Gollisch, 2019) and auditory processing in the midbrain (Alluri et al., 2016; Hanson et al., 2016;
75 Taylor et al., 2019; Wilczynski and Ryan, 2010). Historically, recordings from the amphibian
76 telencephalon have been used to measure responses to sensory stimuli (Karamian et al., 1966;
77 Kicliter and Ebbesson, 1976; Liege and Galand, 1972), but pallial brain regions are not
78 commonly recorded from, likely due to low cell density and movement of the brain within the
79 skull. This creates a large gap in our knowledge of amphibian brain function, as the forebrain is
80 responsible for many aspects of cognition, including reward learning and spatial processing

81 (Bingman and Muzio, 2017; Muzio et al., 1994; Papini et al., 2008; Sotelo et al., 2024). In
82 addition, there has been no implementation of chronic recording in amphibians, and limited
83 recordings in awake and moving animals, as amphibians are commonly paralyzed during
84 recordings to reduce brain movement. What is needed to advance amphibian neuroscience
85 research is the ability to (a) record from the amphibian telencephalon, (b) record from awake
86 and moving animals, and (c) long term recordings that last more than a few hours.

87 In recent years, the development of new electrophysiological probes (including
88 Neuropixels, NeuroGrid, and various electrode arrays) have improved the ability to record brain
89 activity by upgrading spatial integration, temporal stability, and functional integration (Hong and
90 Lieber, 2019). One class of novel devices are flexible mesh electronics (Dai et al., 2018; Fu et
91 al., 2017, 2016; Hong et al., 2018; Lee et al., 2019; Woods et al., 2020), which are recording
92 units designed to be more physically similar to neural tissue compared to rigid probes, allowing
93 for longer recordings and reduced immune response. In rodents, flexible mesh electronics have
94 allowed for chronic implantation that yielded recordings of local field potentials and single unit
95 activity over the course of 8 months without probe repositioning (Fu et al., 2016).

96 We hypothesized that the tissue-like properties of flexible mesh electronics may help
97 overcome issues of brain movement associated with recording neural activity in the amphibian
98 telencephalon. Here, we demonstrate the use of a novel recording technology which allows us
99 to record brain activity over multiple days in the telencephalon of the cane toad, *Rhinella marina*
100 (Figure 1). Additionally, we demonstrate it is possible to record neural activity for up to 15
101 weeks. This methodology will allow for the more fine-scale study of behavior-related brain
102 activity in amphibians, with the longer term goal of filling the taxonomic gap regarding amphibian
103 brain function in vertebrate neural evolution.



104

105 **Figure 1 Project Overview. (A)** Fabrication and preparation of flexible mesh electronic neural
106 probes. **(B)** Cane toad surgery and implantation of mesh. **(C)** Chronic recordings in awake
107 toads.

108 2. METHODS

109 2.1. Animals

110 All experimental subjects were sexually mature *Rhinella marina* collected in Oahu,
111 Hawaii. Until surgery, toads were group-housed in glass terraria in a temperature and humidity
112 controlled animal facility. Terraria were maintained at 20-25 °C and 80-100% humidity. Toads
113 were fed gut-loaded crickets 3 times a week and had water dishes where they could rehydrate
114 at any time.

115 2.2. Mesh Preparation

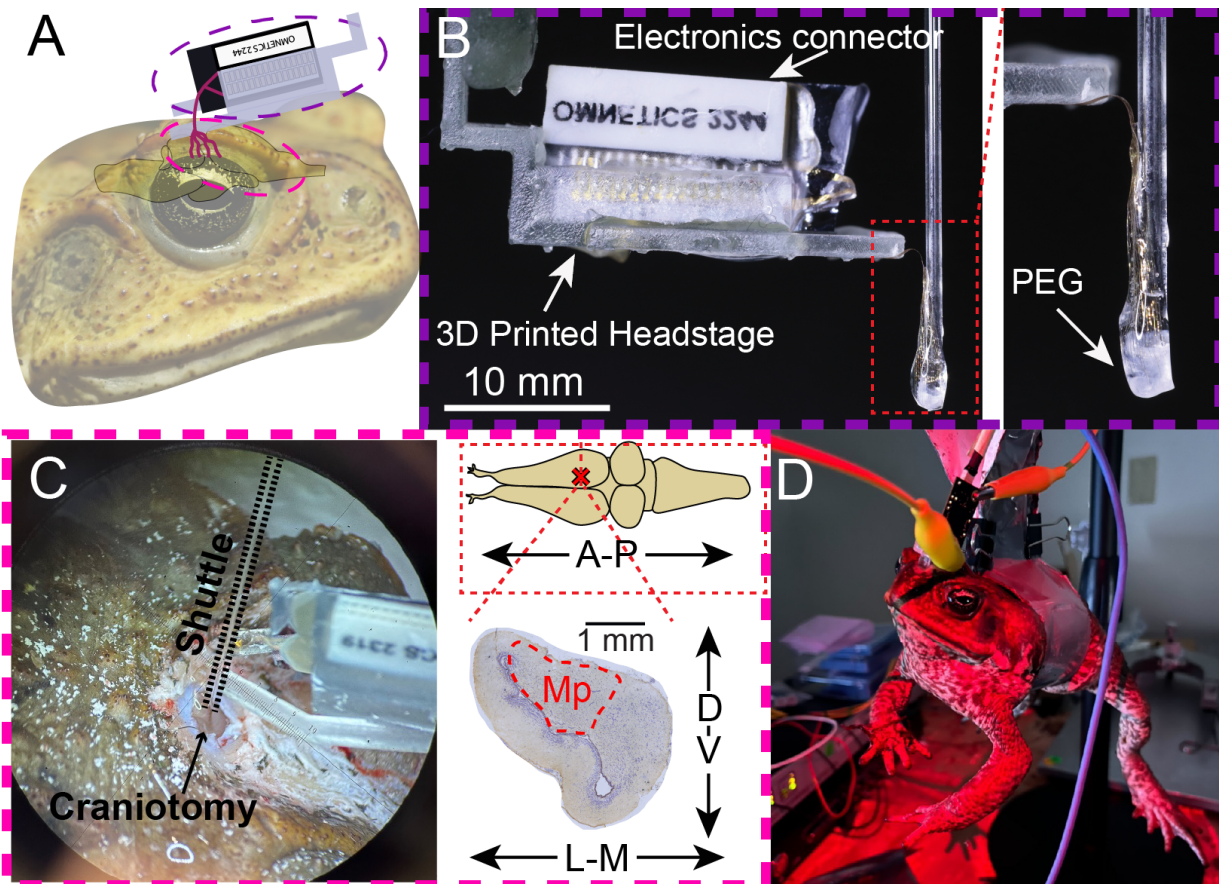
116 On-chip flexible mesh electronics were fabricated by the Hong Lab in Stanford University
117 facilities as described in Woods (2023). Mesh devices were made up of 32 electrodes that had a
118 lateral span of 2 mm. The fabricated device lies on a silicon substrate. Platinum electrodes are
119 exposed on the end of passivated metal lines coated in SU-8, a photoresist polymer. All
120 platinum electrodes are individually connected to Input/Output (I/O) pads at the other end of the

121 mesh through gold interconnects. Each recording electrode is 20 μm in diameter (Woods,
122 2023).

123 Mesh were prepared as follows for implantation in *R. marina* (as depicted in Figure 2A).
124 Fabricated mesh neural probes were bonded to Omnetics electronics connectors (A79024-001,
125 Omnetics Connector Corporation, Minneapolis, MN, USA). First, photoresist was washed off
126 from the device with acetone for ~ 1 minute and then the device was rinsed in isopropyl alcohol.
127 Next, using a stencil, Silver Conductive Epoxy Adhesive (MG Chemicals, Burlington, Ontario,
128 Canada) was applied over the I/O pads and visually inspected under a stereoscope to check for
129 shorts. Under stereoscopic guidance, an Omnetics connector was attached to a vacuum and
130 lowered onto the I/O pads on a stereotaxic stage so that the connector legs aligned with the
131 pads. Once the legs were contacting the pads, the epoxy was allowed to cure for roughly 20
132 minutes before the vacuum was lifted away, and the device was allowed to fully cure overnight.

133 The next day, dental cement was applied over the Omnetics legs and I/O pads, and over
134 the lower edge of the Omnetics connector. When the surgery date approached, the mesh was
135 etched from the substrate by suspending the device in etchant (Ferric Chloride 415, MG
136 Chemicals, Ontario, Canada) by taping the substrate to the inner wall of a beaker and filling the
137 beaker with etchant so that it covered the mesh, but did not reach the Omnetics Connector.
138 Once the mesh had etched in ~ 3 -4 hours and could float off of the substrate, the device was
139 removed from the etchant and excess was washed off with deionized (DI) H_2O . The substrate
140 was lightly scored with a diamond scribe below where the mesh was bonded to the Omnetics
141 connector. The device was then fitted into a 3D printed headstage (seen in Figure 2B) and fixed
142 with dental cement (C&B Metabond Quick Adhesive, Parkell, Edgewood, NY, USA). The mesh
143 was floated off from the substrate in water and the substrate was snapped along the scoring
144 lines. After the substrate was dry, dental cement was applied over the cleaved edge to prevent
145 damage to the mesh. The headstage was taped to the wall of a beaker filled with DI H_2O so the
146 mesh floated and the Omnetics remained unsubmerged until the surgery. The day of or the day

147 before the animal surgery, the headstage was screwed on to a shuttle adapter fitted to the arm
148 of a stereotaxic stage. A glass capillary tube (Inner Diameter 0.15 mm, Outer Diameter 0.25
149 mm, Produstrial, Newton, NJ USA) was fitted into a pipette holder in the shuttle adapter and the
150 tip of the shuttle was covered in polyethylene glycol (PEG 4000). Using a drop of water held on
151 the end of a transfer pipette, the suspended mesh was attached to the shuttle via the PEG, and
152 an additional drop of PEG was added to cover the mesh (Figure 2B).



153

154 **Figure 2 Implementation of flexible mesh electronics in cane toads.** (A) Schematic of mesh
155 implanted in toad brain. Colored ovals correspond to panels B and C. (B) Mesh bonded to the
156 Omnetics connector and adhered into a 3D printed headstage. Inset shows mesh attached to
157 glass shuttle with polyethylene glycol (PEG). (C) Implantation of mesh in a cane toad.
158 Photograph taken through stereoscope of mesh on shuttle being lowered into toad
159 telencephalon. Inset shows the position of implantation on the toad brain and a coronal section
160 depicting the medial pallium (Mp). (D) Recording from an awake animal in a sling with implanted
161 mesh connected to Intan RHX Data Acquisition system through the Omnetics connector.

162 2.3. Craniotomy and Implantation

163 At the beginning of the surgical procedure, the toad was placed into an MS-222
164 anesthetic bath (1.4 g/L) for about 20 minutes, or until the animal was unresponsive and did not
165 respond to a toe pinch. The animal was removed from the bath and 4% Lidocaine was rubbed
166 onto its skull and washed off with 1x phosphate buffered saline (PBS) after 3 minutes. A
167 sterilized scalpel was used to remove all the skin from the snout to the back of the skull. Enamel
168 etchant was applied to the exposed skull for 3 minutes and washed off with 1x PBS.

169 Prior to implanting the mesh, a craniotomy was performed in the middle of the skull in a
170 line transecting the tympanum. A dental drill (Marathon-III, Saeyang Microtech, Daegu, Korea)
171 with drill bits starting from 5/64" and transitioned to smaller sizes were used to drill through the
172 skull. Surgical scissors and knives were used to cut through the dura over the brain. Once the
173 brain was exposed, we visually confirmed that the telencephalon was visible. Once the
174 craniotomy was complete, the toad was placed in the stereotaxic stage and the bonded mesh
175 device, with the mesh attached to the shuttle, was loaded onto the stereotaxic arm. The shuttle
176 was positioned over the medial pallium and lowered into the craniotomy opening until the end of
177 the shuttle had penetrated 3 mm of brain tissue (Figure 2C). The shuttle was left in the brain for
178 ~10 minutes while the PEG dissolved. During this time, with the exception of toad M01, toads
179 then had approximately 2 mm of 40 G stainless steel wire inserted into the telencephalon in the
180 hemisphere opposite the mesh to serve as a physiological ground. After the mesh was fully
181 released from the shuttle, the printed headstage was unscrewed from the shuttle adapter, the
182 shuttle was retracted, and the headstage was attached to the skull with dental cement. Once the
183 dental cement had set, any gaps and the exterior border were filled with Vetbond (3M, St. Paul,
184 MN, USA). The section of the headstage that had attached the device to the shuttle adapter was
185 broken off to prevent animals from using it to pry off the implant.

186 Following surgery, the toad was monitored until it had recovered from anesthesia and
187 was fully mobile. It was housed alone in a glass terraria with automatic misting turned off and

188 hydration provided through manual misting and a shallow glass dish with water. For 3 days
189 post-surgery, the toad was subcutaneously injected with Meloxicam solution (OstiLox, VetOne,
190 Boise, Idaho, USA) dosed at 0.4 mg/kg as an analgesic. Toads were monitored on a daily basis
191 until recordings began. Following surgery, toads had a 2 week recovery period before any
192 recordings were performed.

193 Implants occurred in 9 toads as described above. Three toads were recorded from over
194 multiple days, as reported below. Two additional toads were recorded for 1 day and their
195 implants fell out during the recording, after which the animals were euthanized. An additional 4
196 animals were implanted with mesh and their implants fell out prior to the 2 week recovery period
197 being reached, after which the animals were euthanized.

198 2.4. Recordings

199 Toads were allowed to recover for 14 days post surgery before recordings began.
200 Recordings were performed with the Intan RHD Recording System and Intan RHX Data
201 Acquisition Software (Intan Technologies, Los Angeles, California, USA).

202 Recordings happened under two different regimes. Toad M01, a pilot toad with no
203 physiological ground used to test mesh recordings prior to attempting them in awake toads, was
204 recorded nine times over a period of 15 weeks, with recordings occurring once a week or once
205 every two weeks. Prior to each recording, M01 was lightly anesthetized in a MS-222 bath (1.4
206 g/L). When anesthetized, a stainless steel wire was inserted into the edge of the toad's beak to
207 serve as physiological ground for the recording. This wire was connected to an alligator clip
208 cable, the other end of which was clipped to a 2.54 mm mounting hole on the corner of the
209 acquisition headstage. The Intan RHD 32 Channel Headstage, connected to the RHD Data
210 Acquisition system by a 12-pin Omnetics cable, was plugged into the Omnetics connector of the
211 implant. The recording happened as the animal was beginning to wake up, as evidenced by

212 increased respiration and muscle tone, to increase the likelihood of capturing activity, as MS-
213 222 is a sodium channel blocker that attenuates action potentials.

214 The remaining toads for which data is reported, F02 and F03, were recorded without
215 anesthesia over the course of six recording sessions. Toads were put into a simple sling that
216 held them around their midsection and were suspended from a desk-top stand. The Intan
217 Headstage (wired to the RHD Data acquisition system) was plugged into the Omnetics
218 connector of the implant. An alligator clip cable was used to connect the stainless steel
219 physiological ground wire implanted in the toad to the 2.54 mm mounting hole on the corner of
220 the headstage. Toads were recorded for ~5 minutes every day. F02 was recorded for 5
221 consecutive days, and then a 6th day following a one day break. F03 was recorded for 6
222 consecutive days. However, as noise levels increased on the sixth days of recording, we did not
223 consider the last days in our analysis.

224 2.5 Data Analysis

225 All raw recording data and filtered traces were plotted in Matlab for visual inspection to
226 identify recordings with large movement artifacts or the presence of high noise levels. The
227 recording files were then spike sorted using Kilosort4 (<https://github.com/MouseLand/Kilosort>)
228 (Pachitariu et al., 2024) with manual curation in phy (<https://github.com/cortex-lab/phy>)(Rossant
229 et al., 2016) to identify channels with single- and multi-unit activity. The bandpass frequency in
230 Kilosort4 was set at 250 Hz. As Kilosort4 and phy are designed and optimized for dense
231 electrode arrays with many contacts, we also used custom codes in our analysis. After
232 identifying active channels and the amplitudes of the spikes, we used custom Matlab (v R2022b,
233 MathWorks, Natick, MA, USA) code to visualize waveforms and interspike interval histograms to
234 validate whether activity was likely to be single or multi-unit. A custom python script turned the
235 sorted data from Kilosort4 and phy into a csv datasheet. R Studio (v 2023.09.1+494, Posit

236 Software, PBC, Sunnyvale, CA) running R (v 4.3.1, R Foundation for Statistical Computing,
237 Vienna, Austria) was used to create summaries of the results presented below.

238 2.6 Ethics Statement

239 All procedures were approved by the Institutional Animal Care and Use Committee of
240 Stanford University (Protocol #33530). Toads were collected under the State of Hawaii,
241 Department of Land and Natural Resources, Division of Forestry and Wildlife Protected Species
242 (Permit No. WL21-16).

243 3. RESULTS

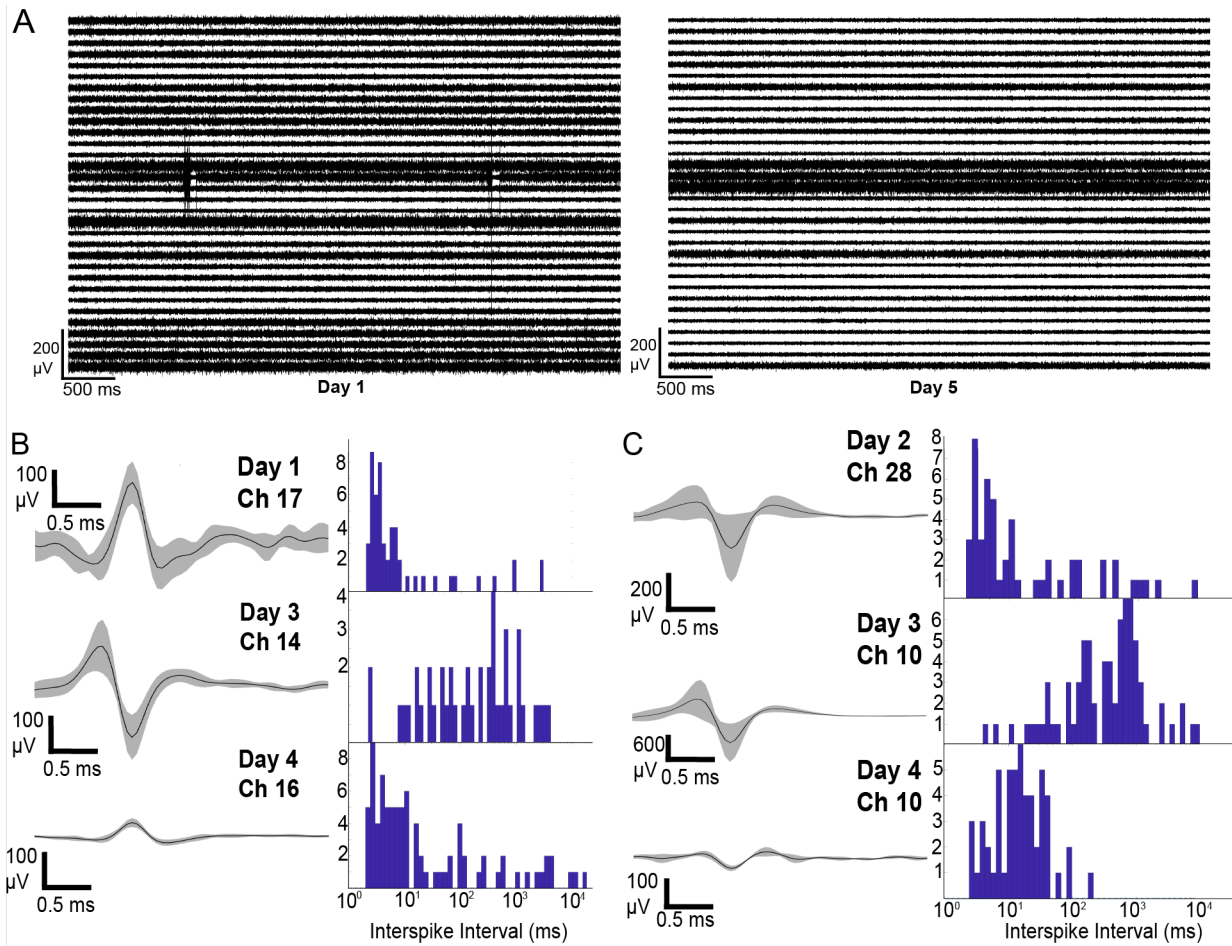
244 3.1 Recording from awake animals

245 We recorded two toads (F02 and F03) over five consecutive days while they were awake
246 (not paralyzed and not anesthetized) (Figure 3). To assess our ability to measure single neuron
247 activity over five consecutive days, we visually inspected raw recording data, performed spike
248 sorting with Kilosort4 and phy to identify channels with single and multi-unit activity, and
249 performed additional visualizations in Matlab.

250 For toad F02, we recorded 0-3 single units per day across all channels (mean 1.4) and
251 4-11 multi-unit signals per day for all channels (mean 6.4). The daily average amplitude of
252 single units estimated by Kilosort4 ranged from 140-384 μV ($231 \pm 110 \mu\text{V}$), which reflects the
253 waveforms plotted by our Matlab spikesorter (Figure 3B). Amplitudes of multi-unit activity
254 ranged from 187-533 μV ($276 \pm 146 \mu\text{V}$).

255 For toad F03, we recorded 0-4 single units per day across all channels (mean 1.8) and
256 2-8 signals per day (mean 5.6) indicating multi-unit activity. The daily average amplitude of
257 single units estimated by Kilosort4 ranged from 99-880 μV ($472 \pm 384 \mu\text{V}$), also reflecting the

258 waveforms plotted by our Matlab spikesorter (Figure 3C). Amplitudes of multi-unit activity
259 ranged from 74-514 μ V ($236 \pm 196 \mu$ V).



260

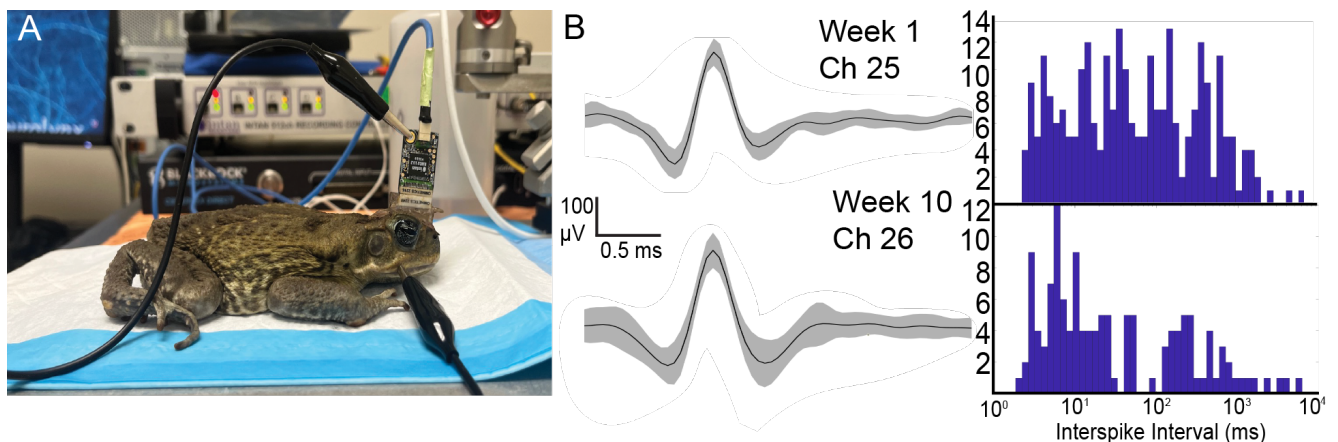
261 **Figure 3 Chronic recordings in awake, partially restrained toads show single-unit activity.**
262 **(A)** Five seconds of high pass filtered (250-6000 Hz) traces from toad F02 taken on the first
263 (left) and fifth (right) days of recordings. **(B-C)** Representative waveforms of single unit activity
264 across recording days in (B) F02 and (C) F03, and interspike interval histograms for
265 represented units. Lines represent mean waveforms and shading represents standard deviation
266 of waveforms for single minutes of recording. Interspike interval histograms were generated
267 from the same recordings.

268 3.2 Recording from an anesthetized animal

269 We recorded from one toad (M01) over the course of about 15 weeks, where the animal
270 was not freely moving but was anesthetized lightly with MS-222 during recording periods (Figure
271 4A). To assess our ability to measure single neuron activity across nine recordings, we

272 inspected recording data visually, spike sorted in Kilosort4 and phy to identify active channels,
273 and performed visualizations in Matlab.

274 In general, likely due to the less effective grounding in the animal, the activity recorded
275 had a higher noise floor and was of much higher amplitude, and less single-unit and multi-unit
276 activity was detectable in Kilosort4. However, on two days, we were able to record activity that
277 appeared to be distinct, single unit activity (Figure 4B). In Kilosort4, the amplitude of these units
278 was depicted at 1173 μV on the first day of recording and an amplitude of 1532 μV two months
279 later. These amplitudes were likely disrupted by noise in Kilosort4, and appear at around 200 μV
280 and 300 μV , respectively, in our Matlab visualization with thresholds applied. We recorded multi-
281 unit activity on five of the nine recordings over 15 weeks, recording 1-3 signals in these days
282 ranging in amplitude from 341-1345 μV ($802 \pm 368 \mu\text{V}$).



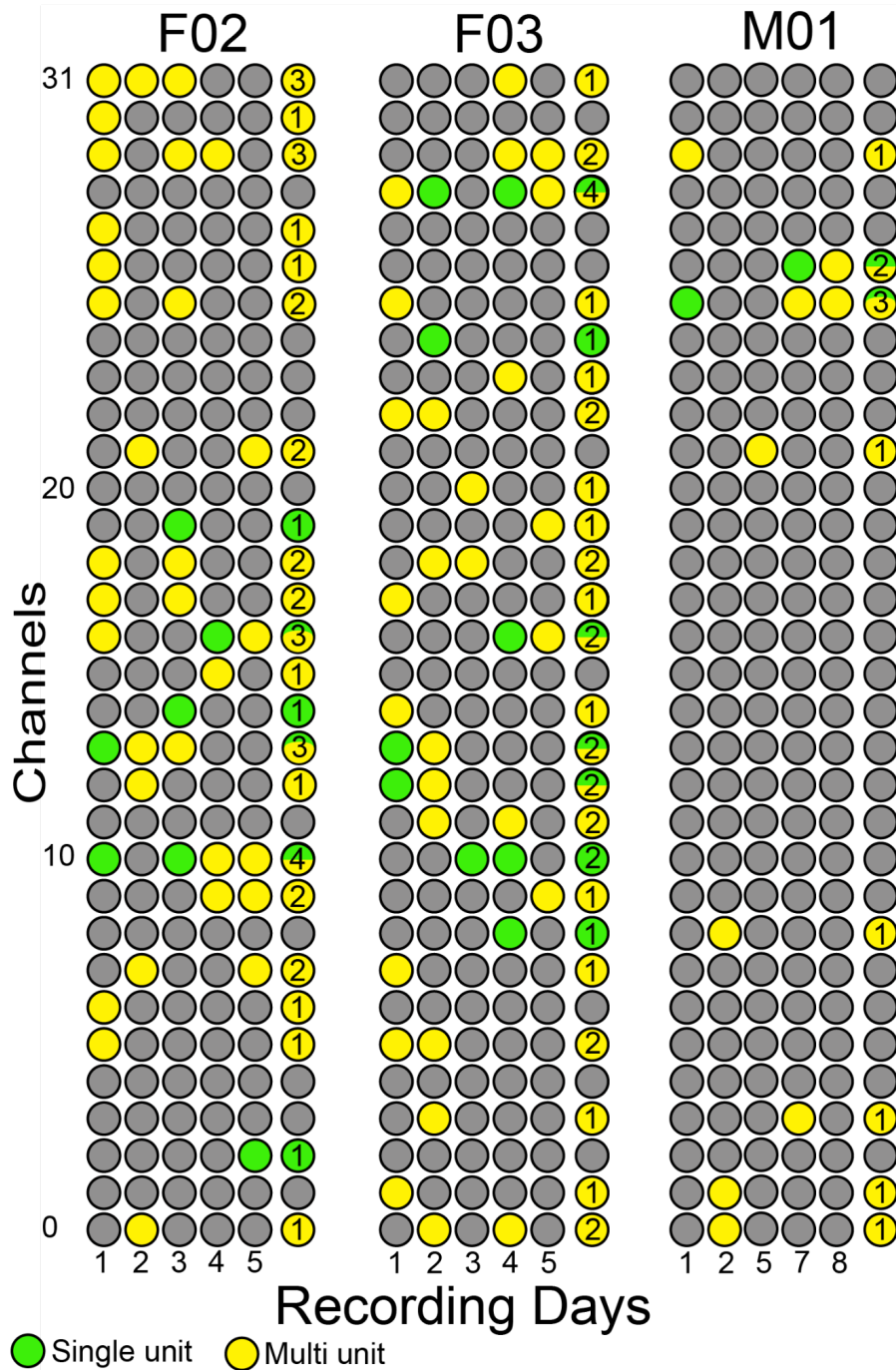
283

284 **Figure 4 Mesh allows recording from an anesthetized toad over 15 weeks. (A)** Toad M01
285 during recording, with Intan headstage connected to mesh and ground wire inserted in beak. **(B)**
286 Representative waveforms of single unit activity in M01, with lines representing mean
287 waveforms and gray shading representing standard deviation of waveforms, with corresponding
288 interspike interval histograms.

289 3.3 Recording stability

290 To test recording stability over time, we compared activity on channels over recording
291 days (Figure 5). We found the channel specific activity varied for all toads over the time spans
292 shared, as active channels changed over the recording periods in all toads. In F02, activity

293 (single- or multi-unit) was recorded on 21 channels over 5 days of recording: 10 channels
294 showed activity on one day, 5 channels showed activity on 2 days, 5 channels showed activity
295 on 3 days, and 1 channel showed recording on 4 days of recordings. In F03, 23 channels
296 showed some activity over the course of the experimental period. Twelve channels showed
297 activity on one day, 10 channels showed activity on 2 days, and 1 channel recorded some
298 activity over 4 days of recording. In M01, we could distinguish activity on 8 channels. Six
299 channels showed activity on one day, 1 channel showed activity on 2 days, and 1 channel
300 showed activity on 3 days.



301

302 **Figure 5 Stability of recording single- and multi-unit activity over recording days.** Vertical
303 axis depicts recording channels and the horizontal axis depicts days of recording for each of the
304 three toads recorded over multiple days. Numbers in the last column for each toad indicate how
305 many days a signal was recorded and the amount of green/yellow coloration depicts the
306 proportion of signals that were single- or multi-unit. Five consecutive days of recording are
307 depicted for F02 and F03; for M01, data shown represents the five recordings in which single- or
308 multi- unit activity was detected, out of nine total recordings that occurred over fifteen weeks.

309 4. DISCUSSION

310 Here we demonstrate a method to record chronic extracellular activity from the
311 amphibian telencephalon in awake, moving toads. This represents a major advancement in the
312 experimental approaches available to study neural activity in amphibians by (a) allowing
313 recording from a brain region that was previously incompatible with electrophysiology
314 experiments, (b) allowing recording across several days, and (c) recording from animals that are
315 not paralyzed. This presents a new opportunity for scientists to probe questions about neural
316 function in amphibians. Further optimization is needed to increase yield of recordings and
317 improve our ability to characterize action potentials. Overall, our results suggest that flexible
318 mesh electronics are a useful tool to expand the possibilities of electrophysiology-based
319 neuroscience research to new species.

320 4.1. Chronic electrophysiology in moving amphibians

321 The vast majority of neural recordings in amphibians occurs in paralyzed animals to
322 overcome challenges in brain movement within the skull. Since at least the 1970's, it has been
323 commonplace to chemically immobilize amphibians with paralytics like pancuronium bromide
324 and succinylcholine chloride (Ewert et al., 1990; Ewert and Hock, 1972; Leary et al., 2008;
325 Womack et al., 2016). Indeed, chemical immobilization prevents the brain from moving,
326 reducing noise during recordings and preventing damage to the brain. However, paralysis also
327 reduces the possibility of what type of neuronal activity can be recorded during experiments, as
328 the animal can only respond to stimuli presented to it and cannot perform behaviors. Thus, to
329 study decision-making in amphibians, such as how they navigate their world or interact with
330 other animals, recordings in freely moving amphibians is needed.

331 There have been many past attempts to perform electrophysiology in moving
332 amphibians. There are records of extracellular recordings made from the optic tectum in freely

333 moving toads using stainless steel electrodes decades ago (Laming et al., 1984; Laming and
334 Ewert, 1983; Schürg-Pfeiffer, 1989). However, these *in vivo* recordings were regularly not
335 stable, as Laming and Ewert (1983) report that recording from seven out of twelve freely moving
336 toads could not be maintained for even 30 minutes in their experiment. More recently, a
337 microdive allowed single recordings from awake Egyptian leopard toads (Mohammed et al.,
338 2013), although we cannot locate additional studies utilizing this method. Overall, recordings
339 from moving or unparalyzed amphibians are not reported in the last decade, where literature
340 searches for “freely moving amphibian electrophysiology”, “mobile toad electrophysiology” and
341 similar queries yield no modern results. Conversely, in other animals, including rodents, birds,
342 and fish, it is commonplace to record activity from awake, moving animals to study neural
343 activity related to mobile behaviors (Cohen et al., 2023; Payne et al., 2021; Yartsev and
344 Ulanovsky, 2013). The ability to perform similar characterizations in amphibians will allow for a
345 better understanding of the evolution of neural function across the vertebrate lineage.

346 Electrophysiological recordings in paralyzed animals generally do not allow for
347 recordings lasting beyond 2 days, as the animals must be re-immobilized and the recording
348 units lowered back into the brain. Implanted units in other vertebrates have already allowed for
349 recordings that take place over days, weeks, and months, with flexible mesh electronics
350 allowing for recordings happening over 8 months (Dai et al., 2018). Chronic recordings allow for
351 the tracking of changes that happen over time and in response to experimental treatments. The
352 ability to perform recordings over multiple days in amphibians may also benefit questions
353 commonly asked in amphibians, such as responses to visual and auditory stimuli. Thus,
354 implementing flexible mesh electronics in these studies may result in novel findings through the
355 longitudinal observation of neural activity.

356 4.2. Recording telencephalic activity in amphibians

357 Most studies of electrophysiology in amphibians have concentrated on relatively few
358 brain regions to characterize responses to sensory stimuli. For example, *in vivo* extracellular
359 and whole cell recordings of the midbrain torus semicircularis, the anuran homolog to the
360 mammalian inferior colliculus, have examined the duration and interval selectivity of neurons
361 responding to sound stimuli (Alluri et al., 2016; Hanson et al., 2016). *In vivo* extracellular
362 recordings from the optic tectum helped characterize how amphibians respond to objects
363 moving in “worm” and “antiworm” orientation (Ewert, 1987; Schürg-Pfeiffer, 1989). However,
364 there is a lack of modern *in vivo* electrophysiology methods for the amphibian telencephalon,
365 even though this large segment of the brain holds regions involved in complex behaviors like
366 reward learning (Muzio et al., 1994, 1993), parental care (Fischer et al., 2019), and spatial
367 navigation (Shaykevich et al., 2024; Sotelo et al., 2022, 2019, 2016).

368 In the past, there was more research done about the function of the amphibian
369 telencephalon. Kicliter and Ebbeson write that, prior to the 1970’s, research in this area either
370 focused on the effects of ablations and stimulation on motor function, or studies using
371 recordings or ablations to examine the role of the telencephalon in sensory discrimination
372 (Kicliter and Ebbesson, 1976). These early recording studies occurred in paralyzed frogs and
373 examined evoked potentials in response to visual and auditory stimuli (Karamian et al., 1966;
374 Liege and Galand, 1972), similarly to the focus on sensory representation in modern amphibian
375 electrophysiology. Outside of *in vivo* recordings, *in vitro* recordings from toad brain preparations
376 have been used to describe the architecture of sensory input in a toad telencephalon (Laberge
377 and Roth, 2007).

378 Past *in vivo* recordings in paralyzed frogs or recordings in slice preparations cannot
379 characterize neural activity directly related to behavior, which is a major challenge in modern
380 behavioral neuroscience in amphibians. However, there are a few reports of recordings in freely
381 moving toads from the 1980’s that showed the promise of behaviorally relevant results with

382 respect to responses to visual stimuli (Laming and Ewert, 1983; Schürg-Pfeiffer, 1989). The
383 recordings from the telencephalon of awake toads demonstrated here open up new possibilities
384 for research in this area. Furthermore, we were successful in recording for more than one day,
385 which would further expand electrophysiology in amphibians by allowing for the study of
386 changes in brain activity over the span of a few days, or even a few months. Our next steps will
387 be to examine behaviorally-relevant neural coding with this methodology.

388

389 4.3 Further optimization of recording protocol

390 The recording protocol reported here needs further optimization before it can be
391 implemented more widely. For example, we report activity recorded from one frog over the
392 course of three months to show that it is possible for the implant to remain in a toad for that
393 period of time. However, likely due to the lack of implanted physiological ground in this surgery
394 (the toad was grounded through the mouth during recordings), the recordings were noisy and it
395 was difficult to distinguish single units. In subsequent surgeries, with successfully implanted
396 ground wires, we overcame this issue. After three months, the dental cement holding toad
397 M01's headstage came off as significant amounts of skin had regenerated under the cement.
398 However, the fact the implant could stay on for that period of time is extremely promising.
399 Implants fell out prematurely in other toads as well, which may be partially attributable to the
400 humid and wet conditions required for amphibian housing. We found that using enamel etchant
401 improved the longevity of our implants, but additional measures, such as using bone screws,
402 may be necessary to ensure these implants have a higher rate of success in the future.

403 The quality of the recordings and channel-specific activity varied from day to day (Figure
404 5). This suggests that, even with the mesh remaining implanted and activity detected from day
405 to day, movement of the brain and shifting of the contacts in between recording periods may

406 significantly alter the signal recorded across channels. Further experiments testing neuronal
407 responses to stimuli and neuronal firing related to behavior are needed to test the feasibility of
408 the chronic recordings in studying various types of neuronal activity.

409 We successfully managed to record from two toads over the course of 5 days with lower
410 noise levels and a better ability to sort out activity (we stopped these experiments after 6 days of
411 recordings, and the implants did not fall out in these two toads). Given that the device has 32
412 channels, we only ever saw partial yield of total recording capacity on any given day, seeing a
413 maximum of 13 units on a day of recording. Low yield could be due to the low density of cells in
414 the medial pallium and contacts not being near enough to neurons to pick up activity. Low yield
415 could also be a result of poor bonding of the mesh with silver epoxy to the Omnetics connector,
416 and better control of this manual step could lead to higher yield. Similarly, redesigning some
417 aspects of the mesh fabrication to test more compact or more spread out distribution of contacts
418 may result in a mesh better suited for recording from the toad telencephalon.

419 4.4 Expanding use of flexible mesh electronics

420 Flexible mesh electronics are an exciting technological development that has been
421 implemented in neuroscience studies using rodent electrophysiology (Dai et al., 2018; Fu et al.,
422 2016; Hong et al., 2018; Lee et al., 2019). Our results expand the utility of mesh electronics to a
423 non-mammalian research organism. Our study shows that these recording units can not only be
424 used in other species, but can potentially solve problems that prevented recordings from being
425 achieved in the first place, such as sparse cells and large brain movements. Increasing the
426 implementation of mesh in more model species will allow for greater optimization and further
427 refinement of electrode architecture for different recording scenarios.

428 5. CONCLUSION

429 We demonstrated an extracellular recording protocol that allows for chronic recordings in
430 awake toads with the use of flexible mesh electronics. This advancement will allow for a greater
431 breadth of neuroscience in amphibians and provide methodology that can be used to study the
432 neural activity underlying behaviors and responses to environmental stimuli. We hope to see
433 this protocol adopted by other groups so that we can continue optimizations and broaden the
434 understanding of neuroethology in frogs and other amphibians.

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443

444 7. DATA AVAILABILITY

445 Matlab scripts for spike sorting and visualizations have been uploaded as supplementary
446 materials. Authors can provide raw recording files upon request.

447 8. AUTHOR CONTRIBUTIONS

448 Conceptualization: D.A.S., L.A.O, G.H.; Methodology: D.A.S., G.A.W., G.H.; Formal

449 analysis: D.A.S., G.A.W.; Investigation: D.A.S., G.A.W.; Resources: L.A.O., G.H.; Data

450 curation: D.A.S., G.A.W.; Writing – original draft: D.A.S.; Writing – reviewing and editing:
451 L.A.O., G.H., G.A.W.; Visualization: D.A.S., G.A.W. ; Supervision: L.A.O., G.H.; Project
452 administration: L.A.O., G.H.; Funding acquisition: D.A.S., L.A.O., G.H.

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458 10. COMPETING INTERESTS

459 The authors declare no competing or financial interests.

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