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Simulation of liquid fow OPEN with a combination artifcial intelligence fow feld andAdams–Bashforth method

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Direct numerical simulation (DNS) of particle hydrodynamics in the multiphase industrial process enables us to fully learn the process and optimize it on the industrial scale. However, using highresolution computational calculations for particle movement and the interaction between the solid phase and other phases in fne timestep is limited to excellent computational resources. Solving the Eulerian fow feld as a source of solid particle movement can be very time-consuming. However, by the revolution of the fast and accurate learning process, the Eulerian domain can be computed by smart modeling in a very short computational time. In this work, using the machine learning method, the fow feld in the square shape cavity is trained, and then the Eulerian framework is replaced with a machine learning method to generate the artifcial intelligence (AI) fow feld. Then the Lagrangian framework is coupled with this AI fow feld, and we simulate particle motion through the fully AI framework. The Adams–Bashforth fnite element method is used as a conventional CFD method (Eulerian framework) to simulate the fow feld in the cavity. After simulating fuid fow, the ANFIS method is used as an AI model to train the Eulerian data-set and represents AI fuid fow (framework). The Lagrangian framework is coupled with the AI method, and the particle freely migrates through this artifcial framework. The results reveal that there is a great agreement between Euler-Lagrangian and AI- Lagrangian in the cavity. We also found that there is an excellent agreement between AI overview with the Adams–Bashforth approach, and the new combination of machine learning and CFD method can accelerate the calculation of the fow feld in the square-shaped cavity. AI model can mimic the vortex structure in the cavity, where there is a zero-velocity structure in the center of the domain and maximum velocity near the moving walls.

Computational methods and mathematical simulations help process engineering tools have their role in two aspects. First, comprehending complex process engineering, which includes potentially rate-limiting transport phenomena. Moreover, the next one refers to designing unit operations, and completing process plants. Multiscale simulations received much attention due to linking with two elements, including phenomena and processes at various time and length scales^{[1](#page-7-0),[2](#page-8-0)}. CFD simulations are extensively used in different industrial processes, such as multiphase flows, and interaction between phases. This numerical tool can provide a new framework to understand the process and calculate some parameters in the fow that are difcult to measure in experimental observations or time consuming^{[3–](#page-8-1)[12](#page-8-2)}. The progress in process modeling has been enhanced by increasing the computational power. CFD approach standing for computational fuid dynamics has a signifcant role in the

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mentioned trend. However, the engineering community is taking advantage of the Adams–Bashforth method to simulate the flow filed in different industrial scales $1,13$.

The Adams-Bashforth method refers to an approach that is conventional CFD modeling. In classical process engineering, continuum models are mostly preferable rather than using 'particle' based models. However, a large number of transport phenomena textbooks that comment on kinetic gas theory deal with how chaotic molecular movements are at the basis of phenomenological transport coefficients. This model, which is a capable and numerical one, is based on molecular motion information. It is also able to simulate fuid fow in the complex geometry, and in particular, in reactors, while solid particles are linked with the fluid flow solver $^{\rm l}$.

Fluid–particle fows are ofen encountered in diferent industrially signifcant reactors, so the gas-fuidized bed is an essential instance for this use. Fluidized beds are mostly used due to their appropriate heat and mass transfer characteristics. Tis interaction between solid phase and liquid phase can be seen in other applications, such as nanofluid matter¹⁴. But the problem of staying with them is that their complex hydrodynamics is not fully understood, leading to severe difficulties in the scale-up of these solid–gas interactions^{[15](#page-8-5)[–17](#page-8-6)}.

Numerical simulation fow in the geometry is connected with solid particles and needs high computational time as well as cautious CFD model implementation in the CFD model. Not long ago, machine learning is smartly applied for combining with CFD results and promote the overall optimization process and therefore produce con-tinuous results^{[18](#page-8-7)}. Moreover, soft computing methods exist, which are neural networks support vector machines, evolutionary algorithms, and adaptive neuro-fuzzy inference system (ANFIS) that have been suggested in other literature for simulating physics in real-life uses^{[19–](#page-8-8)[21](#page-8-9)}. There are several studies about mapping CFD data-set into machine learning methods such as a combination of neural network or ant colony with fuzzy structure system. These mapping strategies have been used in different industrial and scientific processes such as bubbly flow^{[22](#page-8-10),[23](#page-8-11)} and thermal distribution in nanofluid devices^{24,25}. They showed that there is a great agreement between CFD and prediction results and suggested this mapping solution as alternative ways for prediction of process. Tis type of prediction has also proposed a non-discrete prediction methodology. However, there are many studies about the prediction of numerical data set with machine learning methods^{2[,26](#page-8-14)}. As far as the ANFIS method can train complicated relationships, the method becomes widespread and attracted the attention of researchers. The ANFIS method has an intelligent behaviour for the comprehensive as well as complicated algorithm referring to the method²⁰. Moreover, the method has the potentiality to adjust its accuracy in situations whenever making a decision is hard.

In the learning step of this method, we need a suitable selection of training output, which is needed for the accurate development of the ANFIS tool. The ANFIS technique can simulate the fluid flow and temperature distribution in a lid-driven cavity; therefore, researchers, including Azwadi et al. utilized this method for the mentioned purpose²⁷ in which simulation of heat transfer behaviour was carried out in a 2D system, considering different Reynolds numbers. The results of their study revealed that the developed ANFIS model has the potentiality to simulate the temperature and fow felds in a very limited time. Not long ago, the ANFIS was used for simulating flow pattern within a bubble column reactor. Pourtousi et al.^{28,29} are the researchers who applied information about the hydrodynamics of multiphase reactors for the training step. The researchers of the study found that CFD and ANFIS can be used as a perfect tool for estimating BCR behaviour. They reported that the ANFIS algorithm is a suitable method that can be substituted for the CFD method for simulating bubble fow within the BCR. For the case of homogeneous fow regime, the simulation of bubble fow is possible, meaning that the bubbles need to be identical with a spherical shape and velocity in the BCR.

To the best of our knowledge, the combination of machine learning and the CFD method has not been fully used to predict the behaviour of solid materials in the fuid fow, and physical interaction between fuid and solids. In addition, many machine learning methods used CFD results to mimic similar conditions of fow or optimize the process based on CFD results. Still, machine learning methods do not play mathematical or physics-driven rules in the calculation of physics, and everything is based on CFD or experimental calculations. In previous studies, also reported that machine learning methods are assistance tools beside CFD methods for faster optimization of the process or finding some connections between inputs and outputs results¹⁸. However, there is great potential for this framework to predict some parts of the process. For example, the AI framework is an alternative method of the Eulerian method. In this case, one can predict fuid fow with CFD results, and solid material can couple with this framework.

In this study, we used a machine learning method in order to generate the artifcial intelligence (AI) fow feld for particle movement in a square shape cavity. The flow field is simulated with the Adams–Bashforth method, and through the results of the fow feld, the ANFIS method is trained to predict the fow feld without having exact CFD data. The new method of training is used for learning CFD data throughout the domain in which the domain size is classifed for each computing node. Afer the prediction of the fuid fow, the AI fow feld is used instead of the Euler-Euler method, and then we couple the Lagrangian method with the AI method. Afer coupling these two methods, we simulate particle through the meshless AI method.

Method

CFD method. In this study, a second-order Admas-Bashforth method is employed to determine the fuid flow inside a square cavity. The time splitting method is applied to remove the pressure term at the first step, and the time is predicted by using the Adams–Bashforth scheme:

$$
U^* = U^n + 1.5\delta t H^n - 0.5\delta t H^{n-1}
$$
\n(1)

where *H* is the convection term and δt is time step. U^{*} Represents velocity at the first step before determining the pressure field. U^n is the velocity at previous time step. In order to obtain the velocity at time $n+1$, first, we need to solve the pressure Poisson by using U^* . Then, the corrected velocity can be calculated from the below equations:

Table 1. Description of ANFIS layers.

Figure 1. Training error for prediction model of U velocity.

Figure 2. Training error for prediction model of V velocity.

$$
\nabla \cdot U^* = \delta t \times \nabla^2 P^{n+1} \tag{2}
$$

$$
U^{n+1} = U^* - \delta t \times \delta x^{-1} \times \Delta P^{n+1}
$$
\n⁽³⁾

The fluid flow near the moving walls is maximum, and by approaching the center of the domain, the stagnant point of fow has appeared. In this case, the large vortex structure is generated throughout the domain. All velocity components are used for training the machine learning method to mimic the artifcial vortex structure in the

Figure 3. Schematic fgure transformation of CFD results in the AI domain.

cavity. In several studies, the fnite volume technique is employed for the discretization of complex equations, and with the Eulerian method², they solved the fluid flow domain for two-phase flow.

Tis work studies the behaviour of the particles and their efect on the fuid by employing Eulerian–Lagrangian method under the condition of Re = 470, the kinematic viscosity of the liquid (v) = 0.0372 (kg m⁻¹ s⁻¹) and the wall velocity (U_o) = 0.175 (m s⁻¹). The trajectory of a particle with diameter of 3 mm and specific gravity 1.21 in a grid size of 100×100 was calculated. In the Lagrangian term, the 4th order Runge–Kutta method is employed to solve the particle motions^{[14](#page-8-4)}.

ANFIS algorithm. In this study, we utilize ANFIS, which is a combination of neural networks and fuzzy approaches and consists of fve layers, as shown in Table [1](#page-2-0). We implement 202 ANFIS models to predict the fuid velocities (101 models for U and 101 models for V velocity). It can be mentioned that the structure of all ANFIS models is similar. Each model belongs to a specifc width of the cavity, starting from 0 to 100 (101 in total).

Two variables, which are height in cavity and time, are considered as the inputs of the model, and U and V velocities are separately considered as the outputs of the model. All CFD simulation results are divided into two categories, which are training and test data sets, and every model is trained by training data set for 500 iterations in order to reach an appropriate accuracy and convergency. Afer training, the accuracy of each ANFIS model is evaluated by means of the test data set.

Machine learning validation. For faster computational calculations, we use the individual ANFIS method for each element in x computing directions. Tis computational procedure accelerates the overall computing ability in the learning process. For validation of the ANFIS algorithm in prediction of fow in the square-shaped cavity, we calculate RMSE as a function of the iteration for velocity in x and y directions. Figures [1](#page-2-1) and [2](#page-2-2) show the RMSE for different computational iterations for U and V velocities. The results show that RMSE reduces as the iteration rises. For U and V velocity, we need almost 350 iterations to reach convergence.

Implementation of CFD results in AI framework. For this study, the CFD computing method is employed to simulate the fuid fow in the cavity domain, and each time step is saved into the memory. In the

Figure 4. Plots of membership functions for time (input 1) and Y (input 2) as inputs of U prediction model.

Figure 5. Plots of membership functions for time (input 1) and Y (input 2) as inputs of V prediction model.

next stage of calculation, the steady-state results are used for the training of AI. In this step, the AI method learns the process and provides results for minimal time steps. All results of AI are coupled with Lagrangian calculation to show the movement of particles in the square shape domain. Learning CFD results for two layers of fuid is shown in Fig. [3](#page-3-0). All fow characteristics can be trained in x and y computing directions, and then can be represented in x and y computing AI structure.

Boundary condition and physical problems. In this work, the square shape cavity domain is simulated by the CFD technique. The top wall moves from left to the right side, and other walls are fixed as a no-slip boundary condition. In this condition, a larger vortex is generated in the center of the domain with zero velocity at the center and solid walls, and maximum velocity near the moving walls. All computing nodes at the initial condition contain zero values by running the CFD algorithm, and the interaction between computing nodes, the solution is generated for each local node.

Results

The flow pattern in the square shape cavity is solved by the Adams–Bashforth approach. The evolution of the fluid nodes as a function of time is trained with the ANFIS method as a machine learning approach. Afer training the fow feld, the artifcial fow feld is created by the intelligent algorithm, and solid particles can be coupled into the new field. This new combination of AI and CFD can provide the new framework of modeling that leads to faster computing of particle motion in a fully resolved AI flow field.

In the frst layer of the ANFIS model, four diferent membership functions are implemented by using time and Y values. Figures [4](#page-4-0) and [5](#page-4-1) portray the plots of membership functions in ANFIS models to predict U and V velocities, respectively.

Figure [6a](#page-5-0) shows the comparison of CFD and AI modeling for simulation of the fow pattern in the cavity at the beginning of CFD simulation, 500-time steps. The liquid flow has maximum velocity near the moving walls, and during the prediction of AI, we also observe the maximum velocity near the moving walls. While near the center of the cavity, one large vortex is generated with zero velocity in the center of the vortex structure. It is also

Figure 6. Flow pattern at iteration number 500 (**a**), 2500 (**b**) and 5000 (**c**).

indicated the evolution of vortex generation in AI and CFD methods. As the velocity of the top wall increases, the fuid layer near the wall migrates to the right, and eventually, other layers of fuid are following the frst layer near the top walls and move to the right side. The velocity from the top to the center of the domain decreases, and therefore, we achieve to stagnation point where the fuid fow has zero velocity. AI structure can accurately

Figure 7. Flow pattern at iteration number 3000 (**a**) and 4000 (**b**).

predict this fluid–structure on the top and center of the domain. The evolution of the vortex structure over time is fully predicted by AI. Figure [6b](#page-5-0),c depict that the AI can follow the movement of the vortex structure that moves to the right side. However, near the walls, the AI cannot fully recognize the wall boundaries, and we need fltration for this boundary condition.

Afer the prediction of fuid fow by the Euler-Euler method, we use a fuid fow data-set to train the ANFIS method, and then as a result of training this method, we can represent artifcial Euler-Euler fuid fow domain. In this case, we couple the Lagrangian framework with the AI method, and we add solid particles through the domain. Afer adding particles in the AI domain, a particle can move near the moving wall, and then it migrates to the center of the domain. Figure [7](#page-6-0) also shows flow patterns for different number of iterations. In this case, the flow pattern changes from 3000 to 4000 iteration, and the center of vortex structure changes. The AI method and CFD method both can show the fow structure near the walls and center of the domain.

For validation of this new framework, we fully simulate particle in CFD, and then we compare results with AI- Lagrangian method (Fig. [8\)](#page-7-1). The results indicate that there is a great agreement between the Euler-Lagrangian and AI-Lagrangian. As this domain is independent of CFD generation mesh and CFD time step, the particle can freely move in the AI space and time. Additionally, in the method of AI-Lagrangian, we can capture more details of particle dynamics as we can provide very fne time step and space.

Movement of solid materials based on AI fuid can explore more details of particle movement, and the interaction between solid and fuid fow, as the AI domain, is not limited to time step and numerical issues and instabilities. Figure [8](#page-7-1) shows that the particle can cover more space in the field because of the very fine timestep of AI simulations. However, in CFD changing time step causes numerical instability or very high computational expenses. Compared to previous works, AI structure plays a computing rule, not optimization of the process based on CFD results. In this case, the AI method can take care of all fow calculations, and use this information for solid material dynamics for movement of particles.

Conclusions

The simulation of the flow inside the cavity by CFD methods can be computationally expensive. In contrast, by the development of AI methods and learning algorithms, CFD methods can transfer their rules to AI and only participate in the learning process. In this study, the Adams–Bashforth approach is used to simulate the fow feld in the cavity, and the ANFIS method learns the information of the flow field in the domain. The new learning process is used to determine the fow feld in which the ANFIS method learns all x computing direction nodes during the training process. The calculated flow field with AI follows the same direction of the CFD method near the moving walls and center of the domain. Tis new combination of CFD and AI has the potential to picture the vortex structure in the middle of the cavity. However, the prediction of the fow behaviour near the solid walls is not similar to the CFD study, and we need to defne these boundary conditions in the AI method separately or filter data near the solid walls. The AI method is used beside the Lagrangian framework to simulate particle movement in the fuid fow. Tis AI- Lagrangian method can predict particle motion in a shorter time step in a meshless environment. The results also show that particle in AI fluid flow has a similar behaviour as Euler framework. This combination of CFD and AI also causes faster computational interactions to predict the flow feld in the cavity. AI model enables us to memorize all fuid fow characteristics in a short computer memory, which is useful for storing many fluid flow characteristics information.

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Author contributions

M.B.: Performing the simulations. I.B.: Data analysis. A.T.N.: Formal analysis and validation. A.M.: Writing and reviewing the draft. S.S.: Supervision, conceptualisation.

Competing interests

The authors declare no competing interests.

Additional information

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