ORIGINAL RESEARCH

Tree-Based Machine Learning to Identify and Understand Major Determinants for Stroke at the Neighborhood Level

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BACKGROUND: Stroke is a major cardiovascular disease that causes significant health and economic burden in the United States. Neighborhood community-based interventions have been shown to be both effective and cost-effective in preventing cardiovascular disease. There is a dearth of robust studies identifying the key determinants of cardiovascular disease and the underlying effect mechanisms at the neighborhood level. We aim to contribute to the evidence base for neighborhood cardiovascular health research.

METHODS AND RESULTS: We created a new neighborhood health data set at the census tract level by integrating 4 types of potential predictors, including unhealthy behaviors, prevention measures, sociodemographic factors, and environmental measures from multiple data sources. We used 4 tree-based machine learning techniques to identify the most critical neighborhood-level factors in predicting the neighborhood-level prevalence of stroke, and compared their predictive performance for variable selection. We further quantified the effects of the identified determinants on stroke prevalence using a Bayesian linear regression model. Of the 5 most important predictors identified by our method, higher prevalence of low physical activity, larger share of older adults, higher percentage of non-Hispanic Black people, and higher ozone levels were associated with higher prevalence of stroke at the neighborhood level. Higher median household income was linked to lower prevalence. The most important interaction term showed an exacerbated adverse effect of aging and low physical activity on the neighborhood-level prevalence of stroke.

CONCLUSIONS: Tree-based machine learning provides insights into underlying drivers of neighborhood cardiovascular health by discovering the most important determinants from a wide range of factors in an agnostic, data-driven, and reproducible way. The identified major determinants and the interactive mechanism can be used to prioritize and allocate resources to optimize community-level interventions for stroke prevention.

Key Words: cardiovascular health
neighborhood
prevention
tree-based machine learning
variable selection

Stroke is a major chronic disease costing the US healthcare system billions of dollars a year.¹ Identifying modifiable risk factors for stroke is important for developing effective prevention strategies. Existing epidemiological studies on stroke primarily focused on individual-level risk factors, such as demographic factors (eg, age, race/ethnicity), socio-economic factors (eg, income, education), and health behaviors (eg, diet, physical activity).^{2–5} Air pollution exposures have also been shown to adversely affect

the cardiovascular system and increase stroke-related healthcare use.^{2,6} These individual-level factors have been incorporated into intervention programs to prevent and control stroke.^{7–9}

In addition to individual-based interventions, targeted neighborhood-level interventions have been shown to be more cost-effective in preventing stroke.¹⁰ However, little attention has been paid to neighborhood-level factors that may be associated with stroke, despite the fact that growing evidence supports that

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CLINICAL PERSPECTIVE

What Is New?

- A new large-scale neighborhood health data set at the census tract level was created from multiple sources; principled variable selection algorithms exploiting tree-based machine learning techniques were used to identify key neighborhood-level predictors for the neighborhood-level prevalence of stroke.
- Our approach identified a parsimonious set of most important predictors without much loss of prediction accuracy.
- Higher prevalence of low physical activity, larger share of older adults, higher percentage of non-Hispanic Black people, and higher ozone levels were associated with higher prevalence of stroke at the neighborhood level; higher median household income was linked to lower prevalence.

What Are the Clinical Implications?

• The identified major determinants can help prioritize and allocate resources for communitylevel stroke interventions.

Nonstandard Abbreviations and Acronyms

BART	Bayesian additive regression trees					
gbm	gradient boosting machines					
LR	linear regression					
OOB	out-of-bag					
RF	random forests					
RMSE	root mean squared error					
VIPs	variable inclusion proportions					
XGBoost	extreme gradient boosting					

the condition of a neighborhood significantly affects the inhabitants' health.^{11,12} Consequently, there is a lack of understanding of the underlying mechanisms between neighborhood characteristics and the prevalence of stroke at the neighborhood level.

To fill these research gaps, this study aims to identify a crucial set of risk factors that have important effects on the neighborhood-level prevalence of stroke with methodological rigor. We implemented several stateof-the-art tree-based machine learning techniques on new neighborhood-level health data combining information from multiple sources. We modeled the relationship between neighborhood-level predictors and the neighborhood-level prevalence of stroke, treating each census tract as the unit of analysis. We considered 24 factors that have been linked to cardiovascular health outcomes at the individual patient level from 4 major domains, unhealthy behaviors, prevention measures, sociodemographic indicators, and environmental measures.^{3-5,13} We then used principled variable selection algorithms based on our machine learning model outputs to identify most important predictors and compared the relative importance of selected predictors in an agonistic way. We further compared the predictive performance of the tree-based methods considered and demonstrated their operating characteristics for variable selection. Finally, we quantified how the identified major predictors may have influenced the prevalence of stroke at the neighborhood level. Results from this study will provide insights into developing tailored community-based stroke-prevention strategies.

METHODS

Data Source

We generated a large neighborhood health data by integrating public domain information at the census tract level from the Centers for Disease Control and Prevention, the Census Bureau, and the Environmental Protection Agency in the United States. We used census tract as a proxy of neighborhood. The first data set included the prevalence of health outcomes, prevention, and health behavior measures from the Centers for Disease Control and Prevention's 500 Cities Data for 28 004 census tracts.¹⁴ This data set is publicly available on its website, https://chronicdata. cdc.gov/browse?category=500+Cities. The second data set focused on sociodemographic measures using the 2011-2015 American Community Survey,^{15,16} publicly available at https://www.census. gov/data/developers/data-sets/acs-5year.html. We also included environmental exposure data from the Environmental Protection Agency's 2015-2016 Environmental Justice Screening database,¹⁷ publicly available at https://www.epa.gov/ejscreen/downl oad-ejscreen-data. This study used publicly available ecological data and is not considered a human subject study; therefore, the study was exempted from obtaining approval of the institutional review board for ethics committee and individual informed consent. The analysis codes that support the findings of this study are available from the corresponding author upon reasonable request.

We included 24 potential predictors from 4 domains: (1) unhealthy behaviors (eg, no leisure-time physical activity, obesity), (2) prevention measures (eg, lack of health insurance), (3) sociodemographic indicators (eg, race/ethnicity, income level), and (4) environmental measures (eg, ambient air pollution). Both stroke and predictors were measured at the neighborhood level (no person-level data were used). Table 1 details all 24 variables, their data sources and their descriptive distributions. We excluded 1307 census tracts with no information on key variables. Among the 1307 census tracts, 137 had missing data on sociodemographic variables, 875 did not have health measures, and 295 had no environmental information. Our final analysis data set included 26 697 census tracts.

Tree-Based Machine Learning Methods

We considered 4 tree-based machine learning methods, Bayesian additive regression trees (BART),¹⁸ gradient boosting machines (gbm),¹⁹ extreme gradient boosting (XGBoost)²⁰ and random forests (RFs).²¹ We compared their performance in predicting the neighborhood-level prevalence of stroke, implemented variable selection using each of the 4 methods, and provided insights into the key determinants selected by each method. We briefly introduce each method considered.

Bayesian Additive Regression Trees

BART is a nonparametric Bayesian approach using regression trees. A regression tree T approximates the covariate-outcome relationship by recursive binary partitioning of the predictor space based on the importance of each predictor to the outcome. The tree T consists of the tree structure and all the decision rules sending a variable either left or right and leading down to a bottom node. Each of the bottom nodes represents the mean response of the subgroup of observations that fall in that node. The tree T can then be used as a prediction model. Treebased regression models are adept at fitting interactions and nonlinearities. An ensemble of regression trees have heightened modeling flexibility and better prediction accuracy.²² BART is a "sum-of-trees" ensemble, relying on a fully Bayesian probabilistic model. A regularization prior is placed to 3 components of each tree-the tree structure itself, the tree parameters given the tree structure, and the error variance-so that each tree is constrained to contribute only a small part to the "sum-of-trees" model, which is remarkably stable and avoids overfitting. An iterative Bayesian back-fitting Markov chain Monte Carlo algorithm generates samples from the posterior of each of the 3 components, which can then be used for prediction. Recently, BART has gained popularity in the statistical machine learning community for its superior predictive performance against several competing machine learning methods, including RFs, boosted models, and neural nets, in a variety of study settings.18,23,24

Boosting (gbm and XGBoost)

Boosting is an ensemble approach to improve the predictive performance of a single regression tree T.19,25 Boosting grows the trees slowly and sequentially each time taking into account information from previously constructed trees. In this process, boosting boosts a weak learner into a strong learner. Friedman et al²⁵ connected boosting to a forward stagewise additive model that minimizes a loss function. This new statistical perspective brought forth a highly adaptable algorithm, gradient boosting machines. Friedman further incorporated the bagging technique²¹ to form "stochastic gradient boosting," The key steps of a gradient boosting algorithm are as follows: (1) Initialize the algorithm with the best quess of the response, for example, observed response proportion; (2) compute the residual, or gradient, and fit a tree model to the residuals to minimize the exponential loss; (3) add the current tree model to the previous one; and (4) iterate steps (2) and (3) for a prespecified number of times. This technique is commonly referred to as gbm. Boosting has 3 tuning parameters, the number of trees, the shrinkage parameter, and the number of splits in each tree. XGBoost is further developed to optimize the boosting trees algorithms.²⁰ The underlying algorithm of XGBoost extends the classic gbm algorithm. By employing multithreads and imposing regularization, XGBoost is able to use more computational power and generate more accurate prediction.

Random Forests

The RF model is another ensemble technique to improve the predictive accuracy of a single regression tree T. The key ideas of the RF approach are bagging-short for bootstrap aggregation-and randomly selecting a smaller set of predictors to be considered for each split.²¹ Bagging uses bootstrapping together with the single decision tree algorithm to build an ensemble. Because of the bootstrap resampling technique, bagging supplies out-of-bag (OOB) error for measuring predictive accuracy of the bagged model. At each iteration of bootstrapping, certain samples are left out and not used for fitting the tree model in that iteration. These samples are called OOB samples and can be used to evaluate the predictive performance of the tree model in that iteration. In this way, we can record B performance measures from the B bootstrapped samples. Averaging the B measures over the entire ensemble yields the OOB error. Bagging generates a distribution of trees that may share common structures, which induces tree correlations and consequently prohibits a bagged model from ideally reducing

Domain	Variable Name	Definition	(Min, Max)	Median (Q1–Q3)	Mean (SD)	Data Source
Health outcomes	STROKE	Stroke among adults aged ≥18 y	(0.30, 18.80)	2.80 (2.20–3.60)	3.11 (1.43)	CDC 500 Cities Data
Unhealthy	SMOKING	Current smoking among adults aged ≥18 y	(2.00, 48.70)	18.30 (14.30–23.10)	19.10 (6.42)	CDC 500 Cities
behaviors	NO_PA	No leisure-time physical activity among adults aged ≥18 y	(7.90, 61.30)	24.20 (18.30–31.60)	25.30 (8.62)	Data*
	OBESITY	Obesity among adults aged ≥18 y	(8.70, 58.50)	28.60 (23.70-34.90)	29.76 (8.06)	
	INSUF_SLEEP	Sleeping <7 h among adults aged ≥18 y	(18.50, 59.80)	36.30 (32.50-41.20)	37.10 (6.42)	
Prevention	LACK_INSURANCE	Current lack of health insurance among adults aged 18-64 y	(2.50, 70.80)	18.00 (11.70–27.40)	20.58 (11.27)	CDC 500 Cities Data
	DENTAL	Visits to dentist or dental clinic among adults aged ≥18 y	(18.90, 87.10)	61.30 (49.80–70.50)	59.82 (13.16)	
	COLON_SCREEN	Fecal occult blood test, sigmoidoscopy, or colonoscopy among adults aged 50-75 y	(23.40, 81.50)	60.60 (52.60–66.60)	59.29 (9.38)	
	CORE_PREV_M	Older adults aged ≥65 y who are up to date on a core set of clinical preventive services (men: flu shot past year, pneumococcal polysaccharides vaccine [PPV] shot ever, colorectal cancer screening)	(13.10, 52.20)	29.90 (24.80–34.60)	29.88 (6.50)	
	CORE_PREV_W	Older adults aged ≥65 y who are up to date on a core set of clinical preventive services (women: same as above and mammogram past 2 y)	(9.60, 53.80)	28.60 (23.00–33.90)	28.64 (7.32)	
Sociodemographic	AGE65_OVER	Population aged ≥65	(0.00, 100.00)	14.81 (10.61–19.79)	15.81 (8.02)	ACS [†]
status	AGE18_34	Population aged between 18 and 34	(0.00, 100.00)	33.68 (27.28-40.74)	35.01 (12.63)	
	COLLEGE_HIGHER	Bachelor's degree or higher	(0.00, 100.00)	23.71 (12.27–40.33)	28.28 (19.62)	
	HS_COLLEGE	High school graduate or higher	(0.00, 100.00)	85.51 (75.78–91.66)	82.44 (11.87)	
	FEMALE	Female	(0.00, 100.00)	51.19 (48.82–53.60)	51.04 (4.99)	
	NON_HIS_ASIAN	Not Hispanic or Latino-Asian alone	(0.00, 91.32)	3.08 (0.72–8.50)	7.26 (11.36)	
	NON_HIS_BLACK	Not Hispanic or Latino—Black or African American alone	(0.00, 100.00)	7.37 (2.19–24.43)	19.73 (26.69)	
	NON_HIS_OTHER	Not Hispanic or Latino – Other	(0.00, 119.45)	4.61 (2.07–8.06)	6.02 (6.44)	
	NON_HIS_WHITE	Not Hispanic or Latino—White alone	(0.00, 100.00)	48.02 (17.24–72.15)	45.65 (29.55)	
	POVERTY	Below poverty level; estimate; families	(0.00, 100.00)	12.10 (5.1 0–24.00)	16.09 (13.91)	
	MED_INCOME [‡]	Median household income in the past 12 mo (in thousands)	(4.17, 250.00)	49.58 (34.10–70.43)	55.49 (29.17)	
Environmental	HOUSE_PRE1960 [‡]	Pre-1960 housing (lead paint indicator) (in thousands)	(0.00, 8.13)	0.48 (0.10–0.92)	0.59 (0.56)	
factors	TRAFFIC [‡]	Traffic proximity and volume (average number of vehicles/distance)	(0.00, 62.11)	0.39 (0.12–1.10)	1.17 (2.75)	
	OZONE [‡]	Ozone level in air (ppb)	(27.63, 73.67)	48.74 (44.40–52.81)	48.04 (8.13)	EPA-EJSCREEN [§]
	PM25 [‡]	$PM_{2.5}^{2}$ level in air ($\mu g/m^{3}$)	(4.97, 13.32)	9.89 (8.54–10.66)	9.71 (1.53)	
Measures are in perc	sentages for all variables ex	cept those marked with a double dagger. PM indicates particulate matter; Q	l indicates first quant	ile; and Q3, third quantile.		

Distribution of 24 Potential Neighborhood-Level Predictors and Prevalence of Stroke Across 26 697 Census Tracts in 500 Maior US Cities Table 1. Census tract level 500 Cities Data from the Centers for Disease Control and Prevention (CDC), which were modeled based on population-based survey data from the Behavioral Risk Factor Surveillance System. Census tract level data from the 2011–2015 American Community Survey 5-Year Estimates provided by the Census Bureau. [‡]Indicates variables with absolute measurements as opposed to percentages.

[§]To match the geospatial unit of census tract available in the other 2 data sources, we aggregated the census block group level environmental measures to the census tract level by taking the means for PM_{2.8} and O₃, and the sum for the housing data, and the sum of block-group-level population weighted traffic proximity data. PM_{2.5} concentrations are annual average of the daily ambient average, and ozone concentrations are average of daily maximum 8-hour level for the summer season. Both PM_{2.5} and ozone were from a space-time downscaling fusion model based on monitoring data and modeled data. Traffic data reflect annual average daily traffic count of vehicles, that is, count of vehicle at major roads within 500 meters divided by distance in meters, and was calculated based on traffic data from the US Department of Transportation. Pre-1960 housing data were based on the American Community Survey from the US Census. variance of predicted outcomes. To reduce correlation among bootstrapped trees and consequently improve the predictive performance of the ensemble, the RF technique considers a random subset of predictors for each split in the tree-building process on each bootstrap sample. A typical RF's tuning parameters are the number of randomly selected predictors and the number of trees.

Variable Selection Using Tree-Based Methods

BART-Machine

We implemented a variable selection procedure, BART-Machine, developed in Bleich et al²⁶ to uncover a parsimonious set of most critical predictors for the prevalence of stroke at the neighborhood level. This method performs favorably compared with variable selection using importance scores of RF. BART-Machine uses the variable inclusion proportions (VIPs), that is, the proportion of times each variable is selected as a splitting rule divided by the total number of splitting rules in building the model, as the measure of variable importance, and then compares the VIPs on the basis of the observed data to the distributions of VIPs computed from 100 permutated data sets to decide whether a variable has a large enough VIP and should be regarded as important. This procedure identifies variables that have real important effects on the response rather than appear to be important by chance alone. We described the BART-Machine algorithm in Figure 1.

Following the selection of major predictors, we examined interaction effects with a BART model. Variables were considered to interact in a tree only if they appeared together in a contiguous downward path from the top to the bottom of the tree. We computed the total number of interactions for each pair of



Figure 1. Variable selection algorithm using BART-Machine. BART indicates Bayesian Additive Regression Trees; and VIP, variable inclusion proportions.

predictors by summing across trees and Markov chain Monte Carlo iterations, from which relative importance of each interaction was evaluated.

Boosting and RFs

Both boosting (gbm and XGBoost) and RFs provide the variable importance scores. For RFs, we measured the importance magnitude of a predictor by recording the improvement in the Gini index each time the predictor in a nonterminal node is selected for splitting. Then these individual improvement records for each predictor were averaged over the OOB samples of all the trees in the forest to quantify the overall relative importance of the predictors. For boosting, the important scores were calculated in a similar fashion and were scaled and referred to as relative influence scores. We used the variable importance score supplied by the RF algorithm and implemented an iterative procedure described in Jiang et al.²⁷ Dietrich et al.²⁸ and Hu et al.²⁹ for variable selection. Briefly, (1) compute an RF or boosting model using all of the 24 candidate predictors; (2) rank the predictors by variable importance and remove the predictor with the least importance score from the data; (3) compute a new RF or boosting model with the remaining data; (4) repeat steps (2) and (3) until only 1 predictor remains; and (5) choose the set of predictors with the smallest prediction error rate (OOB error for RF, cross-validation error for gbm and XGBoost).

Assessing Advantages of Machine Learning for Variable Selection

We first compared the predictive performance of the 4 tree-based methods using repeated 5-fold cross validation on the basis of root mean squared error (RMSE).³⁰ We then applied these machine learning methods for variable selection and further compared them with 2 alternative methods frequently used in public health research: main effects linear regression (LR) including all predictors, termed as LR-AllVar, and stepwise LR variable selection, referred to as LR-StepWise.^{31,32} LR-StepWise starts with all predictors in the model and removed predictors based on P values until all remaining variables are statistically significant in the model; the best final model is chosen with the smallest Akaike Information Criterion. For a fair comparison of the methods based only on their capability to identify most important predictors, we included variables (both individual variables and interaction terms) selected by tree-based methods in a LR model, and computed RMSE and RMSE reduction per predictor for each method. Thus, the difference in the performance metrics will be attributable to only the selected variables and not confounded by the predictive performance of different models. RMSE reduction per predictor is defined as $(RMSE_{null}-RMSE_{method})/Number$ of Predictors_{method}, where $RMSE_{null}$ is the RMSE from the null model (ie, intercept only model), and $RMSE_{method}$ corresponds to the RMSE of each specific method. This performance metric answers the question of how much gain do we get for adding each predictor variable suggested by a variable selection approach. Methods that give larger RMSE reduction per predictor variable are preferred.²⁶

Finally, to increase the interpretability, we quantified the associations between the identified major predictors and interaction terms and stroke prevalence using a Bayesian linear regression model.³³ All statistical analysis were performed using the R software version 3.6.1.

RESULTS

Comparison of Predictive Performance of Tree-Based Methods

We used repeated cross validation with 5 folds and 200 replications to compare the prediction accuracy of the 5 tree-based method considered. Figure 2 displays boxplots of the cross-validated RMSEs for the 4 tree-based methods. BART appeared to be the top performer with the lowest RMSE, followed by XGBoost. The RFs had the largest RMSE.

Variable Selection by BART-Machine

As shown in Figure 3, by keeping track of predictor inclusion frequencies, BART-Machine identified, for the prevalence of stroke at the neighborhood level, 5 most important predictors: the proportions of people who do not have leisure-time physical activity, who are >65 years of age, and who are non-Hispanic Black;



Figure 2. Comparison of Cross-validated (CV) root mean squared error (RMSE) for each of 4 tree-based methods. BART indicates Bayesian additive regression trees; gbm, gradient boosting machines; and RF, random forests.



Figure 3. Visualization of the variable selection procedures for stroke.

The blue lines are the threshold levels for variable selection procedure described in Figure 1. The red line represents the cutoff determined by a more stringent rule. Variables passing this threshold are displayed as solid dots. Variables that exceed the blue lines but not the red line are represented as asterisks. We select variables with either an asterisk or a solid dot. Open dots correspond to variables that are not selected.

median household income; and ozone levels in the air. The relative importance of these 5 variables based on the observed data exceeded their respective threshold values (the tips of the blue lines), determined from the "null" distributions for VIPs estimated from the permutated data. The inclusion proportions estimated from the BART model fitted to the observed data suggest the observed relative importance of the predictors. The proportion of residents who do not have leisure-time physical activity appeared to be the most important predictor, as it had the largest VIP, whereas ozone levels had the lowest rank among the 5 selected variables.

To understand the synergistic or antagonistic effects of the chosen predictors, we further investigated the importance of variable interactions. Figure 4 shows the top 10 interaction terms computed from the BART model for the neighborhood-level prevalence of stroke. The relative importance is most distinct for the interaction between the prevalence of leisure-time physical activity and the percentage of adults ≥65 years of age.

Comparing Operating Properties of BART, Boosting, and RFs in Variable Selection

We performed variable selection using the variable importance scores provided by boosting and RFs. Table 2 summarizes the RMSE, RMSE reduction per predictor, number of selected predictors, and the selected predictors for each of the 6 methods considered (4 tree based and 2 LR based), as described in the section Assessing Advantages of Machine Learning for Variable Selection. All 4 tree-based methods had similar RMSEs with their respective selected predictors. BART selected the most parsimonious set of predictors and therefore had the largest RMSE reduction per predictor. The common predictors selected by all methods were the proportion of people who do not have leisure-time physical activity, the share of non-Hispanic Black people, the proportion of adults >65 years of age, median household income and interaction between the proportions of people who do not have leisure-time physical activity and adults ≥65 years of age. Boosting and RFs tended to select more variables, some of which were highly correlated (see Table 2). Ozone was selected by BART-Machine only.

The operating properties of all 6 methods considered are also provided in Figure 5.

Quantifying Exposure-Outcome Associations

As machine learning methods are commonly limited by their "black-box" nature, to strengthen findings from our machine learning models, we further fitted a Bayesian linear regression to evaluate the effects of key predictors and their interactions on the neighborhoodlevel prevalence of stroke. Because BART showed the best predictive performance and best operating properties in variable selection, we used the key determinants identified by BART-Machine. Figure 6 displays the point estimates and 95% credible intervals for each main and interaction effect.

On average, a higher proportion of older residents and higher percentage of the population who are physically inactive in a neighborhood were associated with a higher prevalence of stroke at the neighborhood level. The neighborhoods with a larger share of non-Hispanic Black people tended to have higher percentage of stroke. An increase of \$100 000 in median household income was on average associated with a reduction of 0.19% in the neighborhood-level prevalence of



Figure 4. The top 10 average interaction counts (termed as *relative importance*) for the neighborhood-level prevalence of stroke, averaged over 25 BART model constructions. The segments atop the bars represent 95% confidence intervals. BART indicates Bayesian additive regression trees.

stroke. Ozone levels had an adverse effect on the prevalence of stroke—every 10 ppb increase in ozone was on average associated with 0.06% higher prevalence of stroke at the neighborhood level. No leisure-time physical activity and age modified each other's effect. The positive sign of the interaction estimate indicates a synergistic effect of combined senior population and prevalence of physical inactivity.

DISCUSSION

This study used the state-of-the-art tree-based machine learning approaches to identify and investigate major factors in predicting the neighborhood-level prevalence of stroke, leveraging a large-scale data set with information on unhealthy behaviors, prevention measures, sociodemographic status, and environmental factors garnered from more than 20 000 census tracts in 500 US major cities.

We identified key predictor variables for the prevalence of stroke at the neighborhood level. The results are consistent with known patient-level risk factors. Neighborhoods with a higher proportion of older residents or physically inactive residents tended to have a higher prevalence of stroke. Ozone level was found to be adversely linked to the prevalence of stroke.

Table 2.	RMSE Reduction	, Number of Sel	ected Predictors	, and Selected	Predictors by	Each of 4	Tree-Based Methods
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Methods	RMSE	RMSE Reduction per Predictor	Number of Predictors	Selected Predictors
BART	0.48	0.15	6	NO_PA, NON_HIS_BLACK, AGE65_OVER, MED_INCOME, OZONE, NO_PA×AGE65_OVER
XGBoost	0.48	0.11	8	NO_PA, NON_HIS_BLACK, AGE65_OVER, MED_INCOME, OBESITY, SMOKING, INSUF_SLEEP, NO_PA×AGE65_OVER
gbm	0.49	0.11	8	NO_PA, NON_HIS_BLACK, AGE65_OVER, MED_INCOME, OBESITY, SMOKING, AGE18_34, NO_PA×AGE65_OVER
RFs	0.47	0.09	11	NO_PA, OBESITY, AGE65_OVER, NON_HIS_BLACK, DENTAL, INSUF_SLEEP, SMOKING, MED_INCOME, COLON_SCREEN, LACK_INSURANCE

The Pearson correlation was –0.9 between DENTAL and LACK_INSURANCE (selected by RFs), 0.75 between SMOKING and INSUF_SLEEP (selected by XGBoost) and 0.84 between OBESITY and SMOKING (selected by gbm). LR-StepWise retained 20 out of 24 predictors. Neither of the two LR methods had the capability to identify interactions. BART indicates Bayesian additive regression trees; gbm, gradient boosting machines; LR, linear regression; RFs, random forests; RMSE, root mean squared error; and XGBoost, Extreme Gradient Boosting.



Figure 5. RMSE, number of predictors and RMSE reduction per predictor for each of 6 methods: BART-Machine, XGBoost, gbm, RF, stepwise LR variable selection and LR with all covariates.

BART indicates Bayesian additive regression trees; gbm, gradient boosting machines; LR, linear regression; RFs, random forests; RMSE, root mean squared error; and XGBoost, Extreme Gradient Boosting.

Wealthier communities tended to have fewer strokes and neighborhoods with more non-Hispanic Black people were associated with higher prevalence of stroke. We also found that older population structure and the lack of leisure-time physical activity of a neighborhood together had a synergistic effect on the neighborhood-level prevalence of stroke. It is worth noting that not all risk factors for stroke at the individual level, such as smoking and obesity, were ranked as having high importance scores in predicting neighborhood-level stroke outcomes. One possible explanation is that different studies considered different candidate sets of predictors. We used wide-ranging information across 4 domains. In addition, tree-based machine learning methods like BART and XGBoost may be less likely to select highly correlated predictors than traditional LR because of their tree boosting modeling process.

Our study has several important implications related to public health and policy. Identifying important predictors of and how they jointly exert influence on neighborhood cardiovascular health would allow public health researchers and policymakers to have a deeper understanding of the drivers of neighborhood population health. Prevention measures such as lack of leisure-time physical activity and environmental measures such as ozone level can provide important avenues for potential community-level interventions. For example, community-level interventions to engage residents in exercising, to improve air quality, and to build exercise-friendly neighborhoods (eg, increasing walkability through parks and trails) may lead to fewer incidences of stroke in the communities. In addition, as the lack of physical activity exacerbated the effect of older age on stroke, indicated by the positive interaction effect, community-based exercise promotion interventions that are aging friendly or with older adults in mind may alleviate overall prevalence of stroke.

Discovering the subset of predictors that are most influential on the outcomes is challenging, especially when the number of relevant predictors is sparse relative to the total number of available predictors and the fundamental relationships are nonlinear. Existing studies that have attempted to assess the relationships between neighborhood characteristics and cardiovascular health outcomes (often at the individual level) are limited in the scope of data source and analysis approaches.³⁴



Figure 6. Effect estimates and 95% credible intervals for 5 key predictors and 1 most important interaction.

Effect estimates represent average changes in percent of stroke per 10% increase in AGE65_OVER, NO_PA or NON_HIS_BLACK, and per \$100 000 increase in MED_INCOME and per 100 ppb (for the sake of legibility of the effect) increase in OZONE. AGE65_OVER indicates proportion of people who were ≥65 years old; MED_INCOME, Median household income in the past 12 months (in thousands); NO_PA, proportion of adults who had no leisure-time physical activity; NON_HIS_BLACK, proportion of non-Hispanic Black people; and OZONE, ozone level in air (ppb).

Predictors are often restricted to a specific type (eg, behaviors) and selected a priori, risking "cherry picking." As a result, these studies may overlook important determinants affecting cardiovascular health.

We considered a wide range of potential predictor variables from multiple sources for the neighborhood-level prevalence of stroke, and compared the predictive performance of 4 tree-based machine learning techniques and evaluated their abilities in variable selection. The predictors selected were largely consistent among the 4 methods. Moreover, BART-Machine identified an additional important environmental predictor based on a principled permutation-based inferential approach. The feature of "upblackboxing" interactions supplied by the machine learning algorithm provided us with an opportunity to gain insights into the effects of the major predictor variables, which are often ignored in studies using machine learning algorithms. We compared tree-based approaches to linear regression with all predictors and with stepwise variable selection. The tree-based approach, particularly BART-Machine, distinguished a subset of most influential variables and top interactions, whereas the LR-based procedure kept most variables (dropped only 4 variables) and was susceptible to selecting highly correlated variables. Coupled with the ranking of variable importance, our method can provide valuable guidance for targeted community-based interventions. Finally, we complemented the machine learning modeling by conducting a Bayesian linear regression to quantify the effects of each major predictor and interaction on the neighborhood-level prevalence of stroke.

The study has several limitations. First, behavioral measures available in the 500 Cities Data were small area estimations with their own uncertainties. Also, the prevalence of stroke only reflects the proportion of population who are alive and have a history of stroke, which may not accurately and completely reflect stroke incidence and severity of the disease and are subject to survivor bias.³⁵ However, the estimates provide the best available data for these small areas, and the approach has been well validated.³⁶ Second, given the nature of the cross-sectional data and ecological design, the results do not bear causal interpretations.³⁷ The identified neighborhood-level factors of neighborhood-level stroke prevalence can be potentially used to stimulate future research on causal relationships. Finally, while we included 24 predictors from 4 domains based on existing literature, the list is not exhaustive. Nonetheless, the study demonstrated the utility of a novel machine learning approach in identifying and understanding major determinants for stroke at the neighborhood level. Our results also have important implications in policymaking and designing intervention programs to improve population health.

ARTICLE INFORMATION

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Disclosures

None.

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