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Research article

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# Enhanced Prairie Dog Optimization with Differential Evolution for solving engineering design problems and network intrusion detection system

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# A R T I C L E I N F O A B S T R A C T

*Keywords:* Prairie dog algorithm Differential Evolution algorithm Engineering problems Real-world problems Optimization problems

This paper introduces a novel hybrid optimization algorithm, PDO-DE, which integrates the Prairie Dog Optimization (PDO) algorithm with the Differential Evolution (DE) strategy. This research aims to develop an algorithm that efficiently addresses complex optimization problems in engineering design and network intrusion detection systems. Our method enhances the PDO's search capabilities by incorporating the DE's principal mechanisms of mutation and crossover, facilitating improved solution exploration and exploitation. We evaluate the effectiveness of the PDO-DE algorithm through rigorous testing on 23 classical benchmark functions, five engineering design problems, and a network intrusion detection system (NIDS). The results indicate that PDO-DE outperforms several state-of-the-art optimization algorithms regarding convergence speed and accuracy, demonstrating its robustness and adaptability across different problem domains. The PDO-DE algorithm's potential applications extend to engineering challenges and cybersecurity issues, where efficient and reliable solutions are critical; for example, the NIDS results show significant results in detection rate, false alarm, and accuracy with 98.1%, 2.4%, and 96%, respectively. The innovative integration of PDO and DE contributes significantly to stochastic optimization and swarm intelligence, offering a promising new tool for tackling diverse optimization problems. In conclusion, the PDO-DE algorithm represents a significant scientific advancement in hybrid optimization techniques, providing a more effective approach for solving real-world problems that require high precision and optimal resource utilization.

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## **1. Introduction**

Optimization permeates every aspect of human culture. Human beings are naturally inclined to enhance and refine existing entities to address practical challenges and adapt to the present surroundings effectively [\[1](#page-29-0)]. Global optimization aims to identify the most optimal solution from all potential solutions for a given problem. Optimization methods can be classified into two main categories: deterministic and stochastic. While deterministic algorithms have reached a high level of development in mathematical theory, their ability to optimize and demonstrate efficiency is limited when faced with discontinuous and non-differentiable functions [\[2](#page-29-0)].

In some cases, these algorithms are unable to address such issues. Nevertheless, most engineering optimization problems involving numerous local optimal values exhibit characteristics of discontinuity non-differentiability and even pose challenges in mathematical model representation [\[3,4\]](#page-29-0). Due to these circumstances, many scholars have redirected their attention towards stochastic optimization techniques. One important characteristic is the incorporation of randomization, which allows for the potential to escape from local optima. Therefore, it is crucial to employ stochastic optimization methodsto achieve the most optimalsolutionsfor global optimization issues [\[5,6](#page-29-0)].

The swarm intelligence algorithm is a stochastic optimization technique that draws inspiration from the diverse behaviors ex-hibited by biological communities in nature. It offers a novel approach to solving optimization issues [\[7,8](#page-29-0)]. In the natural world, numerous species exhibit remarkable swarm intelligence activities, which involve a combination of cooperation and competition among individuals [\[9\]](#page-29-0). These behaviors compensate for the limitations of individual foraging and help in evading predation [\[10\]](#page-29-0). For instance, the act of wolves preying on other animals [\[11](#page-29-0)], the act of birds coming together and moving from one place to another [\[12\]](#page-29-0), and the way bees and ants interact socially [\[13](#page-29-0)]. Swarm intelligence optimization algorithms can be implemented by examining the possible behaviors of individuals in a population and employing mathematical modeling to construct the operational mechanism of the population system. This includes analyzing the cooperation and competition among individuals within the population and the interaction between the population and the external environment [\[14,15](#page-29-0)].

Over the past few decades, individuals have been developing diverse approaches to address intricate optimization challenges. Meta-heuristic algorithms (MAs) are particularly notable among these methods and offer an effective solution [\[16,17](#page-29-0)]. Due to its divergence from conventional optimization methods, the meta-heuristic algorithm operates independently of gradient information and can effectively evade local optima [\[18](#page-29-0)]. In broad terms, meta-heuristic optimization algorithms can be classified into four main categories: algorithms that rely on human behavior, algorithms that are based on evolutionary principles, algorithms that utilize swarm intelligence, and algorithms that draw inspiration from physics or chemistry [\[19](#page-29-0)].

These MAs include distinguishable characteristics and are widely employed in various computer science domains, intrusion detection systems (IDS), engineering optimization design, routing planning, text clustering, image segmentation and classification, feature selection, and fault diagnosis. The "No Free Lunch (NFL) theorem" demonstrates that no algorithm can solve all optimization issues universally [\[20](#page-29-0)]. Hence, it is crucial to enhance existing algorithms. Various scholars employ diverse methodologies to enhance preexisting algorithms.

Engineering design problems encompass the difficulties that occur when designing and developing a project or manufacturing operation. These difficulties often involve optimizing resources such as time, money, materials, and staff to create a product that meets customer expectations while ensuring efficiency and cost-effectiveness [\[21,22\]](#page-29-0). Ordinary design problems encountered in engineering include designing and producing a product, looking for the most effective method to create and produce a product that meets customer needs and market expectations while reducing expenses and optimizing productivity. Supply chain management encompasses coordinating and controlling all essential product elements to guarantee their availability at the designated time and place while ensuring they are provided at a suitable cost. Production planning and control entails optimizing manufacturing activities to meet client demand and maintaining adequate inventory levels to fulfill customer requirements. Office layout: Establishing a workspace that is both ergonomic and secure enhances employee productivity while minimizing the likelihood of accidents or injuries [\[23,24\]](#page-29-0). Quality assurance entails ensuring that things conform to the standards set by the client and are free from any faults. Maintenance and reliability encompassthe implementation of proceduresto ensure the optimal operation of equipment and machinery while minimizing downtime. Cost optimization entails minimizing costs related to producing goods or delivering a service while upholding superior standards and fulfilling consumer expectations [\[25,26](#page-29-0)].

These challenges are intricate, requiring a profound understanding of principles and issues in engineering design and the capacity to analyze and address intricate challenges. Engineering design issues employ optimization techniques and advanced modeling methods, such as simulation and mathematical analysis, to devise and enhance production processes and innovate goods [\[27](#page-29-0)].

PDO-DE, which stands for Prairie Dog Optimization (PDO) [\[28](#page-29-0)] with Differential Evolution Algorithm (DE), is an emerging optimization technique designed to address industrial engineering design challenges. The PDO-DE method synergistically integrates PDO and DE to discover optimal solutions efficiently. In DE learning, solutions generated are indicative of the collective population. PDO, an optimization technique grounded in population dynamics, leverages the action of prairie dogs to identify the most efficient solution. Prairie dogs exhibit collective behavior, moving in a coordinated manner resembling a swarm, and effectively communicate with one another to identify optimal solutions [\[29,30](#page-29-0)]. Combining PDO and DE methods makes it possible to include the best and worst solutions. This approach leads to a quicker convergence towards the optimal solution and decreases the likelihood of being trapped in a local minimum. Additional investigation is required to evaluate the efficacy and suitability of this approach in addressing industrial engineering design issues, but preliminary studies have indicated its potential for industrial engineers.

This paper presents the Prairie Differential Optimization (PDO) method as a novel approach to address many intricate optimization problems. This work is primarily driven by improving optimization algorithms' performance by tackling the enduring problem of

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striking a balance between exploration and exploitation. Algorithms that thoroughly search the solution space and take advantage of well-established solutions are necessary for effective optimization to improve outcomes. But striking this balance is still quite difficult, especially for algorithms like the PDO algorithm, which has trouble completing tasks on time and frequently gets stuck in local optima, especially when working on high-dimensional issues.

The main goal of this research is to create a more sophisticated PDO algorithm that can function reliably in various engineering optimization scenarios and overcome these drawbacks. We suggest incorporating the Differential Evolution (DE) approach into the PDO framework. The DE approach's robust exploration capabilities bolster the PDO algorithm's exploitation strengths. By merging these two techniques, the modified PDO algorithm seeks to accomplish a more successful balance between exploration and exploitation.

This research paper examines the updated PDO algorithm, showcasing its better performance via a battery of exacting tests and contrasting it with other cutting-edge optimization methods. The outcomes demonstrate that the integrated DE approach greatly enhances the PDO algorithm's capacity to traverse complicated solution spaces, resulting in quicker convergence and more precise solutions.

In addition, this study presents an enhanced PDO method that tackles the crucial problem of striking a balance between exploration and exploitation, significantly advancing the optimization field. In addition to improving the PDO algorithm's overall performance, the suggested integration of the DE approach provides a workable solution for successfully resolving high-dimensional optimization issues. This development increases the value and effect of the improved PDO algorithm by providing new opportunities for its application to various engineering and real-world optimization challenges.

The main contribution of this work is illustrated as follows:

- We provide a novel strategy called PDO-DE. This approach is motivated by the design principles of the PDO and DE algorithms.
- DE enhances the efficacy of the PDO in diversifying the primary population and its capability to escape from local optima.
- Enhance PDO's global and local search capabilities to increase convergence accuracy.
- The PDO-DE algorithm is demonstrated to significantly improve problem-solving effectiveness in two complex domains: engineering design problems and network intrusion detection systems. Our results show superior precision and convergence rate performance compared to existing algorithms.
- The PDO-DE algorithm's performance is demonstrated using a set of twenty-three widely recognized benchmark and CEC2019 functions.
- Five engineering design problems are utilized to verify the performance of the PDO-DE.
- Implementing the PDO-DE to enhance the performance of network intrusion detection systems.
- Extensive benchmarking using 23 classical functions and real-world applications validate the effectiveness of the PDO-DE algorithm. This rigorous testing demonstrates the algorithm's adaptability and efficiency across diverse optimization problems, setting a new benchmark for future research.
- By illustrating the broad applicability of PDO-DE across different domains, this work extends the scope of hybrid optimization methods in practical applications, particularly in areas requiring rapid and accurate convergence to optimal solutions.

The rest of this work is presented as follows. Section 2 outlines the methodology of the suggested approach. Section [3](#page-6-0) presents the experiments and results that are conducted. Section [4](#page-16-0) presents the outcomes of implementing the suggested approach to real-world engineering. Section [5](#page-28-0) presents the final findings and outlines potential areas for future research.

# **2. The proposed methodology**

The subsequent section outlines the suggested technique's step-by-step procedures. The suggested approach incorporates the operators from both the Prairie Dog Optimization (PDO) algorithm and the Differential Evolution Algorithm.

# *2.1. Prairie Dog Optimization algorithm*

Recently, Ezugwu et al. proposed a new algorithm called the Prairie Dog Optimization (PDO) algorithm that draws inspiration from the natural behavior of prairie dogs in their natural habitat. This technique determines the most advantageous solution for a specific optimization problem. Prairie dog activity involves the animals coming out of their burrows, relocating, and returning. The PDO method utilizes potential solutions to identify the optimal answer for a specified problem. The candidate solutions experience iterative updates and evolve to ascertain the most optimal alternative [\[28](#page-29-0)].

The colony consists of  $l$  prairie dogs (PDOs) that belong to  $s$  coteries. These professional development programs exist and function collectively inside their respective social circles. Therefore, the location of the th PDO within a specific group can be denoted by a vector. Equation (1) concisely describes the matrix representation that shows the positions of all coteries (COTs) in the colony.



(1)

<span id="page-3-0"></span>The symbol  $CT_{i,i}$  denotes the *j*th area of the *i*th coterie in the colony. Equation (2) illustrates the spatial distribution of all the PDOs inside a coterie.

$$
PD = \begin{bmatrix} PD1, 1 & PD1, 2 & \dots & \dots & \dots & PD1, d \\ PD2, 1 & PD2, 2 & \dots & \dots & \dots & PD2, d \\ \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ P1, 1 & PD1, 2 & \dots & \dots & \vdots \\ PD1, 1 & PD1, 2 & \dots & \dots & \vdots \\ PD2, 2 & \dots & \dots & \dots & \dots \\ PD2, 2 & \dots & \dots & \dots & \dots \\ PD2, 2 & \dots & \dots & \dots & \dots \\ PD3, 2 & \dots & \dots & \dots & \dots \\ PD4, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD7, 2 & \dots & \dots & \dots & \dots \\ PD8, 2 & \dots & \dots & \dots & \dots \\ PD8, 2 & \dots & \dots & \dots & \dots \\ PD9, 2 & \dots & \dots & \dots & \dots \\ PD1, 2 & \dots & \dots & \dots & \dots \\ PD2, 2 & \dots & \dots & \dots & \dots \\ PD4, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD7, 2 & \dots & \dots & \dots & \dots \\ PD8, 2 & \dots & \dots & \dots & \dots \\ PD1, 2 & \dots & \dots & \dots & \dots \\ PD2, 2 & \dots & \dots & \dots & \dots \\ PD3, 2 & \dots & \dots & \dots & \dots \\ PD4, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD5, 2 & \dots & \dots & \dots & \dots \\ PD7, 2 & \dots & \dots & \dots & \dots \\ PD8, 2 & \dots & \dots & \dots & \dots \\ PD1, 2 & \dots & \dots & \dots & \dots \\ PD1, 2 & \dots & \dots & \dots & \dots \\ PD2, 2 & \dots & \dots & \dots \\ PD3, 2 & \dots & \dots & \dots \\ PD4, 2 & \dots & \dots & \dots \\ PD5, 2 & \dots & \
$$

The symbol *PD<sub>i</sub>*; *j* denotes the *jth* proportions of the *ith* prairie dog inside a group, where *l* and *s* are different numbers. The assignment of coterie and prairie dog places is accomplished using a uniform-distribution, as illustrated in Equations (3) and (4).

$$
CTi, j = U(0, 1) \times (Uj - Lj) + LBj \tag{3}
$$

$$
PDi, j = U(0, 1) \times (Uj - Lj) + Lj \tag{4}
$$

The *U j* and *Lj* represent the maximum and minimum values of the *j*th dimension in an optimization problem (Lower and Uber bond). The upper bound, denoted as  $U_j$ , is computed by dividing  $U_j$  by s. Similarly, the lower bound, denoted as  $L_j$ , is determined by dividing *Lj* by *s*. The symbol  $U(0, 1)$  denotes a random variable that is uniformly distributed between 0 and 1. PDO algorithm adjusts its approach by alternating between exploration and exploitation based on four conditions. The entire number of repetitions (rep) is divided into four parts, with the initial two sections allocated for exploration and the remaining two dedicated to exploitation. The exploration is divided into two techniques based on the constraints  $rep < Maxwell/4$  and  $Maxrep/4 < rep < Maxwell/2$ . The exploitation is divided into two methods, each governed by certain conditions:  $Maxrep/2 < rep < 3Maxrep/4$  and  $3Maxrep/4 <$  $rep < Maxwell$ 

# *2.1.1. PDO exploration stage*

An assessment is conducted to determine the quality of the available food sources, and the optimal choice is selected for gathering. The development of recent burrows is contingent upon the caliber of the chosen food supply. Equation (5) represents the process of updating placements during the algorithm's exploration stage.

$$
PDOi + 1, j + 1 = \text{GPDOBest } j, j - eC \text{ PDOBest } i, j \times p - CPDOi, j \times \text{Levy } (L) \text{ A rep} < \frac{\text{Maxrep}}{4} \tag{5}
$$

The second technique entails assessing the caliber of earlier encountered food origins and appraising the proficiency in digging. Subsequent burrows are subsequently created utilizing this excavating capability, which diminishes as the number of repetitions rises, restricting the number of tunnels that may be formed. Equation (6) denotes the process of adjusting the placements to construct burrows.

$$
\text{PDOi} + 1, j + 1 = \text{PDOGBest } j, j \times \text{rPDO} \times \text{DS} \times \text{Levy}(L) \land \frac{\text{Maxrep}}{4} \le \text{rep} \le \frac{\text{Maxrep}}{2} \tag{6}
$$

The current most suitable solution is denoted as GPDOBesti; j, and its effectiveness is assessed using *eCPDOBesti*; j, as shown in Equation (7). The food source warning is denoted as  $q$  and has a constant frequency of 0.1 kHz. The variable rPDO indicates the random solution's position, while the combined impact of all PDO in the colony is denoted as *CPDOi*; *j*, as mentioned in Equation (8). The digging resilience of the clique, referred to as  $D_s$ , relies on the food source's quality and is selected randomly using Equation (9). The Levy distribution, denoted as  $Levy(L)$ , is employed to optimize the investigation of the issue space with greater efficiency.

*e* CPDOBesti, 
$$
j = \text{GPDOBesti}
$$
,  $j \times \Delta + \frac{PDOi, j \times \text{mean}(PDon, s)}{G \text{PDOBest} \times (Uj - Lj) + \Delta}$  (7)

$$
CPDOi, j = \frac{G \text{ PDOBesti}, j - r \text{PO}i, j}{G \text{PDOBesti}, j + \Delta} \tag{8}
$$

$$
D_S = 1.5 \times r \times \left(1 - \frac{\text{rep}}{\text{Maxrep}}\right)^2 \frac{\text{rep}}{\text{Maxrep}}
$$
(9)

The factor r introduces randomness to facilitate exploration, alternating between -1 and 1 based on whether the current repetition is odd or even. D considers any variations among the prairie dogs, although the implementation assumes they are all identical. rep represents the current iteration, while  $Maxrep$  represents the highest number of repetitions permitted.

# *2.1.2. PDO exploitation stage*

PDO employs exploitation strategies to conduct a comprehensive search in the potential areas discovered during the exploration phase. The two methodologies employed in this phase are represented by equations (10) and (11). PDO employs these two strategies depending on the constraints  $Maxrep/2 \le rep < 3Maxrep/4$  and  $3Maxrep/4 \le rep \le Maxrep$ , as mentioned earlier.

$$
PDOi + 1, j + 1 = \text{GPDOBest } i, j - eC \text{ PDOBest } i, j \times \varepsilon - CPDOi, j \times \text{rand } \Lambda 3 \frac{\text{Maxrep}}{4} \le \text{rep } < 3 \frac{\text{Maxrep}}{4} \tag{10}
$$

$$
PDOi + 1, j + 1 = \text{GPDOBest } i, j - PE \times \text{rand } \Lambda 3 \frac{\text{Maxrep}}{4} \le \text{rep} < \text{Maxrep} \tag{11}
$$

<span id="page-4-0"></span>In this instance, GPDOBesti; j denotes the current best solution discovered, while eCPDOBesti; j signifies the influence of the currently achieved ideal solution. According to Equation [\(10](#page-3-0)),  $\epsilon$  denotes the food source's quality, whereas CPDOi; j indicates the collective impact of all PDOs in the colony, as stated in Equation  $(11)$  $(11)$ . As denoted by the mathematical Equation  $(12)$ , the predator impact is symbolized by the abbreviation PE, while rand refers to a randomly generated number ranging from 0 to 1.

$$
PE = 1.5 \left( 1 - \frac{\text{rep}}{\text{Maxrep}} \right)^2 \frac{\text{rep}}{\text{Maxrep}} \tag{12}
$$

#### *2.2. Differential Evolution algorithm*

The Differential Evolution algorithm (DEA), proposed by Storn and Price, is a robust and efficient search method designed to tackle intricate continuous nonlinear functions. The conventional Differential Evolution (approach commences by initializing a population of N individuals represented by vector  $\vec{X}_i$ , where  $\vec{X}_i = (X_{i1}, X_i, X_i, ..., X_{in}), i = 1, 2, 3, ..., N$ , and n is the problem dimension. The DEA algorithm has incorporated three primary operators: mutation, crossover, and selection. The mutation and crossover operators are utilized to produce fresh candidate vectors. At the same time, a selection technique is implemented to determine the survival of either the offspring or the parent in the subsequent generation.

# *2.2.1. Mutation phase*

An individual with genetic mutations is represented According to Equation (13) where  $\vec{V}_i = (v_{i1}, v_{i2}, v_{i3}, ..., v_{in})$  and is created through the use of a mutation operator. Multiple mutation techniques are documented in the literature [\[31](#page-29-0)]. One often used operator is 'DE/best/1', which is defined as:

$$
\vec{V}_i(t) = \vec{X}^*(t) + F(\vec{X}_a(t) - \vec{V}_\beta(t))
$$
\n(13)

Here, *t* represents the current iteration,  $\vec{X}^*(t)$  represents the best individual with the lowest  $f(\vec{X}^*)$ . Currently,  $\alpha$  and  $\beta$  are two randomly selected indices from the range [1, N], where a, b, and i are all different from each other  $\alpha \neq \beta \neq i \in 1, ..., N$ ). Additionally, F ∈ [0, 1] represents a mutation scaling factor influencing the differential variation between two individuals. The following operator is applied to all individuals once the mutation operator has been applied.

## *2.2.2. Crossover phase*

The crossover parameter is utilized on each mutant individual and its associated target individual  $\vec{X}_i$  to produce a trial vector,  $\vec{U}_i = (u_{i1}, u_{i2}, u_{i3}, ..., u_{i,n})$ . Exponential and binomial crossovers are frequently employed crossover strategies. The binomial crossover is expressed According to Equation (14):

$$
u_{i,j}(t) = \begin{cases} v_{i,j}(t), & if \ r_j \le CR \text{ or } j = R; \\ xi, j(t), & Otherwise \end{cases}
$$
\n(14)

The index R represents a dimension randomly selected from the set 1, 2, ..., n. This is done to guarantee that at least one dimension from  $\vec{V}_i(t)$  is present in the trial individual  $\vec{U}_i$ , which is different from its target vector,  $\vec{V}_i(t)$ . The crossover rate (CR) is a value that ranges from 0 to 1, and  $r_i \in [0,1]$  is a random number that is uniformly distributed between 0 and 1. If the parameter values of the trial people exceed the pre-determined higher or lower bounds, we can assign them the upper or lower bound value accordingly.

# *2.2.3. Selection phase*

A one-to-one greedy selection is used in DE to determine if the trial individual  $\vec{U}_i(t)$  should be included in the target population for the next generation. This selection strategy promotes diversity compared to tournament, rank-based, and fitness-proportional selection. The one-to-one selection technique operates by determining the survival of the more fit person between the trial individual  $U_i(t)$  and its target counterpart  $X_i(t)$ . The formulation for minimization issues is According to Equation (15):

$$
\vec{X}_i(t+1) = \begin{cases} \vec{U}_i(t), & if \ f(\vec{U}_i(t)) \le f(\vec{X}_i(t)); \\ \vec{X}_i(t), & otherwise, \end{cases}
$$
\n(15)

where  $f$  is the objective function. The aforementioned procedure is iterated until a termination requirement is achieved.

### *2.3. Proposed PDO-DE algorithm*

This section delineates the proposed strategy's fundamental methodologies. The proposed methodology functions by utilizing two primary methods: Prairie Dog optimization (PDO) and the Differential Evolution Algorithm. Tackling engineering design difficulties efficiently requires finding the most optimal or nearly optimal solution for complex systems with several constraints and variables. Various optimization strategies have been developed to tackle these problems, including traditional methods (such as gradient-based techniques and linear programming) and MAs (such as genetic algorithms and particle swarm optimization).

The present study introduces a new optimization technique, Prairie Dog optimization (PDO) and Differential Evolution Algorithm (PDO-DE), to address engineering design challenges. This approach utilizes a combination of Prairie Dog Optimization and Differential Evolution Algorithm to discover solutions that are close to optimal efficiently.



**Fig. 1.** Proposed PDO-DE algorithm.

Differential Evolution Algorithm is a machine learning methodology that employs the most favorable and unfavorable solutions from a population of solutions to create novel solutions. This strategy effectively addresses constraints associated with conventional optimization techniques, such as the tendency to become trapped in a local minimum, by actively investigating solutions far from the existing population. Prairie Dog Optimization is a population-based optimization technique that leverages the behavioral patterns of prairie dogs to identify the most effective solution. Prairie dogs exhibit collective behavior, moving in a coordinated manner resembling a swarm, and communicate among themselves to determine the optimal option.

The PDO-DE methodology starts by initializing a set of solutions and generating further solutions by utilizing the DE algorithm. Subsequently, the prairie dogs endeavor to choose the most favorable course of action by moving to a different location and sharing information. The technique continues until the optimal solution is achieved or a termination criterion is met. The main procedure of the proposed method is depicted in Fig. 1. This approach enhances the PDO algorithm by optimizing the balance between exploration and exploitation while searching for optimal solutions. The integration of the DE algorithm with PDO's mechanisms facilitates this balance. The DE algorithm boosts the PDO's exploratory abilities and accelerates convergence to the best solution—this synergy between PDO and DE results in improved performance of the PDO algorithm. The initialization of the HPDO algorithm involves randomly selecting the initial positions of  $IP$  agents  $(A)$  through a designated formula.

$$
A_{ij} = rand \times (UpB - LoB) + LoB, i = 1, 2, ..., IP, j = 1, 2, ..., Z.
$$
\n<sup>(16)</sup>

In Equation (16), Z denotes the dimension of each parameter  $A_i$ . LoB and  $UpB$  define the lower and upper bounds of the search space, respectively. A hybridization of the PDO and DE algorithms manages the update of the agents A. This hybrid operation uses a randomly generated parameter  $Rand_r \in [0, 1]$  to switch between the PDO and DE mechanisms. Specifically, if  $Rand_r < 0.5$ , the PDO operator is employed to modify the current solution; if  $Rand_r \geq 0.5$ , the solution is updated using the HHO algorithm. The method is described as follows:

$$
A_i(t+1) = \begin{cases} Use PDO \, as \, in \, Eqs. (9) - (12), \quad Rand_r < 0.5 \\ Apply \, DE \, as \, in \, Eq. (15), \quad \text{otherwise} \end{cases} \tag{17}
$$

The PDO-DEO algorithm is outlined in Algorithm [1.](#page-6-0) Using the Differential Evolution Algorithm in optimization enhances the algorithm's performance by incorporating new concepts that improve its capacity to find the best solution. The Differential Evolution Algorithm provides a framework for producing diverse solutions by including contrasting elements. Furthermore, the Differential Evolution Algorithm offers a technique for producing solutions with a more evenly distributed range of values. By combining these two concepts, the optimization algorithm may methodically and effectively explore the search space and quickly approach the optimal solution, reducing the likelihood of getting stuck in suboptimal solutions.

# <span id="page-6-0"></span>**Algorithm 1** The proposed PDO-DE Algorithm.



# *2.4. Complexity analysis of PDO-DE algorithm*

The PDO-DE algorithm merges Prairie Dog Optimization (PDO) with Differential Evolution (DE) to solve complex optimization problems efficiently. This section provides a detailed complexity analysis of the PDO-DE algorithm, focusing on its major computational steps across various stages.

#### *2.4.1. Overview of algorithm stages*

- **Initialization**: Complexity of  $O(n)$  for generating  $n$  initial individuals.
- **Fitness Evaluation**: Each individual requires  $O(f)$  operations, resulting in  $O(n \times f)$  per generation.
- **Prairie Dog Exploration**: Updating positions based on local interactions, typically  $O(n \times l)$ .
- **Differential Evolution Modification**: Involving mutation and crossover at  $O(n)$  complexity.
- **Selection**: Complexity of  $O(n)$  for selecting the new generation.

## *2.4.2. Computational complexity*

The overall computational complexity for each generation includes these steps, dominated by the evaluation step:

$$
O(n \times (f + l + 2))
$$
\n<sup>(18)</sup>

Given  $G$  generations, the total complexity becomes:

$$
O(G \times n \times (f + l + 2))
$$
\n<sup>(19)</sup>

This formulation indicates that the algorithm's computational load primarily depends on the number of generations  $G$ , the population size  $n$ , and the complexity of the fitness function  $f$ . The local interaction term  $l$  adds additional complexity but is typically bounded by  $n$ .

# **3. Experiments and results**

This study will employ the Prairie Dog Optimization and Differential Evolution method (PDO-DE) to tackle global optimization difficulties. The main focus will be on 23 benchmark functions, CEC2019 functions, and five challenges in engineering. The section begins by briefly elucidating the benchmark and engineering difficulties utilized for experimentation and the experimental setup. The experimental findings are then reported comprehensively. The findings consist of the objective function values obtained by the

Parameter values for the PDO-DE algorithm and other algorithms.

Algorithm	Parameters
HHO	$\epsilon_0$ between -1 and 1
GOA	$c = [1E-5,1]$
<b>SSA</b>	$v_0 = 0$
WOA	$\alpha = [2 \text{ to } 0]$
SCA	$\alpha = [0.05]$
<b>DA</b>	$\omega = [0.2, 0.9]$
<b>SMA</b>	$z = 0.03$
<b>PDO</b>	$\rho = 0.1, \varepsilon = 2.22E - 16$





proposed method, the number of function assessments, and the convergence curves. The performance of the proposed approach is assessed by contrasting its objective function values with those of other existing optimization methods.

Furthermore, the paper includes a comprehensive analysis of the findings, highlighting the strengths and weaknesses of the proposed approach. The debate provides vital insights into the potential applications of the suggested method and highlights areas that require more investigation. The suggested strategy is assessed utilizing comparable methodologies, which encompass the following algorithms:

- Harris hawks optimization (HHO) [\[12\]](#page-29-0).
- Grasshopper optimization algorithm (GOA) [\[32](#page-29-0)].
- Salp Swarm Algorithm (SSA) [\[33\]](#page-29-0).
- The whale optimization algorithm (WOA) [\[34\]](#page-29-0).
- Sine Cosine Algorithm (SCA) [\[35\]](#page-29-0).
- Dragonfly algorithm (DA) [\[36](#page-29-0)].
- Slime mould algorithm (SMA) [\[37](#page-29-0)].
- Prairie dog optimization algorithm (PDO) [\[28](#page-29-0)].

The experimental setup details the specific hardware and software specs and the study configuration employed. Every comparison technique was evaluated under the same conditions, using the initial parameter values, and executed for 50 iterations with 10 and 100 dimensions. The studies used Matlab 2018a on a Windows 11 PC with a Core i7 processor and 16 GB of RAM.

The worst, average, best, and standard deviation (STD) markers are employed to communicate the results of the utilized algorithms. Furthermore, when the p-value is below 0.08, the Wilcoxon rank-sum test obtains statistical evidence to ascertain if PDO-DE differs significantly from other approaches. The values for the essential parameters of the utilized algorithms are displayed in Table 1.

# *3.1. Qualitative analysis*

This section evaluates the proposed PDO-DE approach on 23 different benchmark function challenges as described in [\[17](#page-29-0)]. Fig. 2 displays the conclusive outcomes of the comparison methodologies. The data presented in the figure demonstrates that the suggested technique consistently outperformed other strategies regarding execution time across all assessed tasks. The PDO-DE technique, which has been proposed, is considered the most efficient in terms of execution time.

Fig. [3](#page-8-0) analyzes the behavior of the PDO-DE on benchmark functions F1-F13 to illustrate the function's structure, track the progress of the best solution, and evaluate its fitness achieved using the PDO-DE. Furthermore, the convergence curves of the PDO, DE, and

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<span id="page-8-0"></span>

**Fig. 3.** Achieved qualitative experiment results for the tested 13 benchmark functions.

PDO-DE produced from the specified functions are depicted in the last column of Fig. 3. These figures demonstrate that the PDO-DE exhibits rapid convergence and high accuracy. An illustrative instance may be observed in F8, a function incorporating many modes; the PDO-DE has a faster convergence rate than the PDO and DE.



**Fig. 3.** (*continued*)

<span id="page-10-0"></span>

**Fig. 4.** A sample of qualitative analysis (Convergence behavior) of the benchmark functions based on 500 iterations.





#### *3.2. Simulation and experiments results of the benchmark functions*

This section showcases the efficacy of PDO-DE. The implementation evaluation assesses its average, best, worst, and standard deviation (STD) values. In addition, we will do the Wilcoxon rank-sum test with a significance level of 0.08 to assess whether there is a significant difference between the proposed variant and its counterparts. Upon conducting the evaluations, we discovered that the PDO-DE demonstrates a high level of proficiency in managing most of the benchmark functions compared to comparable cutting-edge alternatives. To establish the ultimate ranking of the proposed PDO-DE, we employed the Friedman ranking test. This demonstrated the efficacy of the PDO-DE as a potent instrument capable of producing outcomes comparable to the field's top performers.

#### *3.2.1. Scalability analysis*

The behavior and convergence of the PDO-DE are compared to the HHO, GOA, SSA, WOA, SCA, DA, SMA, and PDO. Fig. [4](#page-10-0) displays the merged curves of the nine algorithms for the 23 benchmark functions in a ten-dimensional space. The graphs provide a means to discern the rate at which the PDO-DE converges and its level of accuracy. Here, combining the two algorithms shows that the performance is significantly enhanced. The various functions demonstrate the ability of the PDO-DE to avoid suboptimal solutions. For instance, in plots F12, F14, and F19, it is evident that the algorithm consistently identifies a lower value after a specific number of rounds. Two notable examples of convergence speed are F7 and F4, in which the proposed algorithms outperform other methods by achieving the global optimum in a smaller number of iterations.

The proposed PDO-DE is compared to other swarm-inspired algorithms currently used. This scenario compares the highest and lowest fitness values, the average fitness values of the 20 separate runs, and the Standard Deviation (STD). A ranking is determined by the optimal value achieved for each algorithm. The results of the eight methods and the PDO-DE over the 23 benchmark functions in 10 dimensions are displayed in Tables 2 and [3](#page-13-0). The values for functions F1-13 are reported in Table 2, whereas those for functions F14-F23 are listed in Table [3.](#page-13-0) According to the ranking summary shown in Table [4](#page-14-0), the PDO-DE is ranked first in all 23 functions across ten dimensions.

The HHO is ranked second for the F1-F23, while the basic PDO is ranked third. Lastly, the ultimate position is the GOA algorithm. The p-values derived from the Wilcoxon signed-rank test provide conclusive evidence that the algorithms are statistically distinct in most cases. This fact is evident since the p-value of the majority of experiments is below 0.008. Nevertheless, in certain functions, such as F18, the PDO-DE method has surpassed other comparing algorithms.

To assess the effectiveness of the proposed PDO-DE method on complex problems, the dimensionality of the 13 benchmark functions is adjusted to 100. They employed the functions F1-F13 in this instance. The nine comparing algorithms and PDO-DE results over the 13 selected functions are presented in Table [5.](#page-14-0) Table [6](#page-16-0) shows the final rank of tested algorithms. According to the table, the PDO-DE ranks first, followed by HHO, and WOA is in third position. Ultimately, the most unfavorable approach for this series of studies is the GOA.

Regarding Wilcoxon's rank test, the p-values indicate instances where the PDO-DE shares similarities with specific algorithms. For instance, F4 exhibits statistical resemblances to GOA, SSA, SCA, DA, SMA, and PDO. Nevertheless, it exhibits statistical dissimilarity compared to AO, HHO, and WOA. In addition, F5 shares common characteristics with all other approaches. However, in functions such as F8, the PDO-DE exhibits statistical dissimilarity compared to the other techniques. These circumstances arise as a result of the inherent character of the difficulties. Greater dimensionality presents challenges in locating the global optimum.

# **Table 2** (*continued*)



<span id="page-13-0"></span>



<span id="page-14-0"></span>



**Table 5**

The results of ten benchmark functions (F1–F13) were obtained using comparative methodologies, with a dimension of 100 and 50 iterations.

Function	Measure	Comparative Algorithms								
		HHO	GOA	<b>SSA</b>	<b>WOA</b>	<b>SCA</b>	DA	<b>SMA</b>	<b>PDO</b>	PDO-DE
Fun.1	Worst Average Best <b>STD</b> p-value h.	1.76931E-07 3.65542E-08 3.2267E-15 7.85093E-08 0.328257881 $\Omega$	154774.0192 137000.1645 107256.7989 18796.45177 2.02195E-07	150570.4384 134484.2116 96133.01906 21825.5547 7.43245E-07	2123.1015 435.0713096 2.259843439 943.715732 0.332757019 $\Omega$	82917.77991 50266.35878 5713.731376 28367.63991 0.004164026	113800.2758 97977.12398 86584.06291 10621.11906 3.19576E-08	54435.00866 38731.99932 7217.703643 18952.24666 0.001826343	44381.34975 40312.94172 38114.60316 2646.650501 6.03405E-10	2.09496E-49 4.18991E-50 1.54712E-70 9.36892E-50 1 $\Omega$
Fun.2	Worst Average <b>Best</b> <b>STD</b> p-value h.	0.000106133 3.37409E-05 6.17085E-10 4.76582E-05 0.152060385 $\Omega$	2.08606E+46 4.17213E+45 2.69155E+28 9.32916E+45 0.346593507 $\Omega$	3.06307E+26 $6.12614E+25$ 6.7979E+13 1.36985E+26 0.346593197 $\Omega$	9.425490246 3.097594371 0.072292008 3.927497094 0.115814653 0	156.188196 70.93708374 31.72781844 48.88160854 0.011789253	459.149022 356.1665865 221.8311124 103.5455433 5.78959E-05	169.4851854 143.9531926 126.5961232 19.54740611 1.86557E-07	4.00096E+17 8.62595E+16 64970000980 1.75616E+17 0.30401841 $\Omega$	7.70236E-29 1.54067E-29 8.77321E-36 3.44449E-29 1 $\Omega$
Fun.3	Worst Average Best <b>STD</b> p-value h.	2308746.554 780279.4934 0.001419473 1092863.214 0.149043625 $\Omega$	1319107.747 852450.6173 499265.663 348523.044 0.000595021	1280200.38 862632.0386 471517.0919 357129.8493 0.000645148	2798461.015 1713706.729 874615.1747 739132.5119 0.000838222	1201898.125 854772.5188 527882.046 253831.9357 6.73465E-05	1685831.734 834214.9299 530366.7932 491437.931 0.005268685	255582.492 202886.4419 169029.6623 35046.42053 1.20093E-06	274495.3283 221551.5934 161413.8048 51482.82724 1.13029E-05	1.87989E-27 3.76147E-28 6.73824E-65 8.40616E-28 1 0

(*continued on next page*)

# *3.2.2. The experimental results of CEC2019 benchmark functions*

This section evaluates the proposed PDO-DE approach on ten different CEC2019 challenges. Table [7](#page-17-0) compares the fitness function values for various tactics about the worst, mean, and best outcomes in the context of the CEC2019 concerns. Table [8](#page-19-0) unequivocally demonstrates that the proposed strategy outperformed all comparable solutions for nearly all cases. The PDO-DE technique performs superior to HHO, GOA, SSA, WOA, SCA, DA, SMA, and PDO in addressing the issue of cec05. Similarly, it outperformed HHO, GOA, SSA, WOA, SCA, DA, SMA, and PDO in solving the problem of cec9. This information is based on the Wilcoxon signed-rank test.

Furthermore, Fig. [5](#page-18-0) illustrates the convergence patterns of the different approaches to the CEC2019 problems. The figure illustrates that the proposed strategy outperformed alternative methods. The proposed strategy addresses the main shortcomings of the original PDO method, such as the imbalance between the search phases, by effectively eliminating local optima and premature convergence. The results demonstrate the exceptional ability of the proposed PDO-DE technique to surpass other approaches on many test problems from CEC 2019. The main goal of this study has been accomplished as the suggested approach has demonstrated more significant

# **Table 5** (*continued*)



<span id="page-16-0"></span>



outcomes in resolving various issues when compared to the initial method and other cutting-edge strategies. The findings refute the authors' claims, as the enhanced approach utilizes diverse search tactics to acquire more optimal solutions.

# **4. Real-world engineering problems**

# *4.1. Problem 1: the multiple-disc clutch brake*

The variables, restrictions, and objective functions of the multiple disc clutch brake design problem are as follows: The spatial arrangement of the five variables is depicted in Fig. [6](#page-19-0).

Below is the mathematical model for the design challenge of a multiple-disc clutch brake: Consider:

$$
\vec{\lambda} = [\lambda_1 \lambda_2 \lambda_3 \lambda_4 \lambda_5] = [R_i R_0 T X Y]
$$

Objective function:

$$
f(\lambda) = \prod (R_i^2 - R_0^2)T(Y+1)p
$$

Subject to:

 $g_1(\lambda) = L_{max} - (Y + 1)(T + \alpha) \ge 0$  $g_2(\lambda) = P_{max} - P_{RY} \geq 0$  $g_4(\lambda) = P_{\text{max}} Z_{sRmax} - P_{RY} v_{sR} \ge 0$  $g_5(\lambda) = Z_{smax} - Z_{sR} \ge 0$  $g_6(\lambda) = W_{\text{max}} - W \ge 0$  $g_7(\lambda) = U_h - sU_s \geq 0$  $g_8(\lambda) = W \ge 0$ 

Parameters range:

 $60 \leq \lambda_1 \leq 80$ ,  $90 \le \lambda_2 \le 110$ ,  $1 \leq \lambda_3 \leq 3$ ,  $600 \le \lambda_4 \le 1000,$  $2 \leq \lambda_5 \leq 9$ 

<span id="page-17-0"></span>The results of CEC2019 benchmark functions were obtained using comparative methodologies, with a dimension of 10 and 50 iterations.



<span id="page-18-0"></span>









**Fig. 5.** Qualitative analysis (Convergence behavior) of the CEC2019 benchmark functions based on 200 iterations.

<span id="page-19-0"></span>The final rank of CEC2019 benchmark functions were obtained using comparative methodologies, with a dimension of 10 and 50 iterations.

Function	Comparative Algorithms									
	HHO	GOA	<b>SSA</b>	<b>WOA</b>	<b>SCA</b>	DA	<b>SMA</b>	<b>PDO</b>	PDO-DE	
cec.1	1	6	7	8	5	4	3	9	$\overline{2}$	
cec.2		8		4	5	6	3	9	2	
cec.3	$\overline{2}$	9		7	5	8	3		6	
cec.4	6	8		5	3	7		9	$\overline{2}$	
cec.5	6	9	7	8	4	2	3	5		
cec.6	8		2	7	9	6	3	5		
cec.7		6	3	8	9	5	4	7	2	
cec.8	7	$\overline{2}$	5	8	9		6	3		
cec.9	7	9	5	4	6	8	3	2		
cec.10	4	$\overline{2}$		8	5	3	9	7	6	
Sum	43	60	45	67	60	50	38	57	30	
Mean	4.3	6	4.5	6.7	6	5	3.8	5.7	3	
Rank	3	7	4	8	6	5	$\overline{2}$	5		



**Fig. 6.** A model of the multiple-disc clutch brake.





Other Parameters:

$$
U_h = \frac{2}{3} \mu XY \frac{R_0^3 - R_i^2}{R_0^2 - R_i^3}, P_{RY} = \frac{X}{\Pi (R_0^2 - R_i^2)},
$$
  
\n
$$
Z_{RZ} = \frac{2\Pi (R_0^3 - R_i^3)}{90 (R_0^2 - R_i^2)}, W = \frac{I_Y \Pi n}{30 (U_h + U_f)}
$$
  
\n
$$
\Delta R = 20 \text{ mm}, I_Y = 55 \text{kgmm}^2, P_{\text{max}} = 1 \text{ MPa}, X_{\text{max}} = 1000 \text{ N},
$$
  
\n
$$
W_{\text{max}} = 15 \text{ s}, \mu = 0.5, \text{ s} = 1.5, U_s = 40 \text{ Nm}, M_f = 3 \text{ Nm},
$$
  
\n
$$
n = 250 \text{ rpm}, z_{\text{sr max}} = 10 \text{ m/s}, L_{\text{max}} = 30 \text{ mm}
$$

The optimal weights of PDO-DE and the comparison methods in this issue are detailed in Table 9, in contrast to the other six optimization methods. The optimal weight determined via PDO-DE is 0.234752458. The corresponding values for the five variables are  $R_i = 70.02$ ,  $R_0 = 90.02$ , T = 1, X = 600, and Y = 2, respectively. Hence, based on our research, we may infer that PDO-DE is superior to other ways of resolving this issue.



**Fig. 7.** A model of the speed reducer design problem.

# *4.2. Problem 2: speed reducer design problem*

Fig. 7 presents the variable diagram. The objective of the reducer design challenge is to ascertain the minimum weight of the reducer while satisfying four design constraints. The four design constraints encompass stress in the shaft, lateral displacement of the shaft, stress on the shaft, and bending stress on the gear teeth. The variables in the reducer design problem are the following:

- The width of the tooth surface is denoted by  $\sigma_1$ .
- The gear module ( $\sigma_2$ ) refers to the size of the gear teeth.
- The quantity representing the count of teeth on the pinion is denoted as  $\sigma_3$ .
- The distance between the bearings of the first shaft  $(\sigma_4)$ .
- The distance between the bearings on the second shaft ( $\sigma$ <sub>5</sub>).
- The first shaft's diameter is denoted as  $\sigma_6$ .
- The measurement of the second shaft's diameter  $(\sigma_7)$ .

The problem can be mathematically formulated and expressed by a set of constraint functions: Consider:

$$
\sigma = \left[\sigma_1 \sigma_2 \sigma_3 \sigma_4 \sigma_5 \sigma_6 \sigma_7\right]
$$

Objective function:

$$
f(\vec{\sigma}) = 07854 \times \sigma_1 \times \sigma_2^2 \times (3.3333 \times \sigma_3^2 + 14.9334 \times \sigma_3 - 43.0934) - 1.508 \times \sigma_1 \times (\sigma_6^2 + \sigma_7^2) + 7.4777 \times \sigma_6^3 + \sigma_7^3
$$
  
+ 0.7854 ×  $\sigma_4 \times \sigma_6^2 + \sigma_5 \times \sigma_7^2$ 

Subject to:

$$
g_1(\vec{\sigma}) = \frac{27}{\sigma_1 \times \sigma_2^2 \times \sigma_3} - 1 \le 0
$$
  
\n
$$
g_2(\vec{\sigma}) = \frac{397.5}{\sigma_1 \times \sigma_2^2 \times \sigma_3^2} - 1 \le 0
$$
  
\n
$$
g_3(\vec{\sigma}) = \frac{1.93 \times \sigma_4^3}{\sigma_2 \times \sigma_3 \times \sigma_6^4} - 1 \le 0
$$
  
\n
$$
g_4(\vec{\sigma}) = \frac{1.93 \times \sigma_3^3}{\sigma_2 \times \sigma_3 \times \sigma_7^4} - 1 \le 0
$$
  
\n
$$
g_5(\vec{\sigma}) = \frac{1}{110 \times \sigma_6^3} \sqrt{\left(\frac{745 \times \sigma_4}{\sigma_2 \times \sigma_3}\right)^2 + 16.9 \times 10^6 - 1} \le 0
$$
  
\n
$$
g_6(\vec{\sigma}) = \frac{1}{85 \times \sigma_7^3} \sqrt{\left(\frac{745 \times \sigma_5}{\sigma_2 \times \sigma_3}\right)^2 + 16.9 \times 10^6 - 1} \le 0
$$
  
\n
$$
g_7(\vec{\sigma}) = \frac{\sigma_2 \times \sigma_3}{40} - 1 \le 0
$$
  
\n
$$
g_8(\vec{\sigma}) = \frac{5 \times \sigma_2}{\sigma_1} - 1 \le 0
$$







**Fig. 8.** A model of the Spring design problem.

$$
g_9\left(\vec{\sigma}\right) = \frac{\sigma_1}{12 \times \sigma_2} - 1 \le 0
$$

$$
g_{10}\left(\vec{\sigma}\right) = \frac{1.5 \times \sigma_6 + 1.9}{\sigma_4} - 1 \le 0
$$

$$
g_{11}\left(\vec{\sigma}\right) = \frac{1.1 \times \sigma_7 + 1.9}{\sigma_5} - 1 \le 0
$$

# Parameters range:

 $2.6 \leq \sigma_1 \leq 3.6, 0.7 \leq \sigma_2 \leq 0.8, 17 \leq \sigma_3 \leq 28, 7.3 \leq \sigma_4 \leq 8.3, 7.3 \leq \sigma_5 \leq 8.3, 2.9 \leq \sigma_6 \leq 3.9, 5\sigma_7 \leq 5.5$ 

Table 10 presents the outcomes of the PDO-DE and the compared strategies. The PDO-DE approach achieved the highest rank in this table, surpassing all other ways of addressing this problem. The PDO method obtained second place, followed by DA, SCA, and GOA.

# *4.3. Problem 3: spring design*

Fig. 8 illustrates the objective of this work, which is to decrease the mass of a spring. The minimization process has specific constraints, including shear stress, surge frequency, and minimum deflection. The variables in this problem are as follows:

- The wire diameter (d).
- Mean coil diameter (D).
- Number of active coils (N).

The mathematical model of the Spring design is expressed as follows: *Consider:*

$$
\vec{\lambda} = [\lambda_1, \lambda_2, \lambda_3] = [d\,DN],
$$

*Objective function:*

$$
f(\vec{\lambda}) = (\lambda_3 + 2)\lambda_2\lambda_1^2
$$

*Subject to:*

$$
g_1(\vec{\lambda}) = 1 - \frac{\lambda_2^3 \lambda_3}{71785 \lambda_1^4} \le 0
$$







**Fig. 9.** A model of the Spring design problem.

$$
g_2(\vec{\lambda}) = \frac{4\lambda_2^2 - \lambda_1\lambda_2}{12,566(\lambda_2\lambda_1^3 - \lambda_1^4)} + \frac{1}{5108\lambda_1^2} \le 0
$$
  

$$
g_3(\vec{\lambda}) = 1 - \frac{140.45\lambda_1}{\lambda_2^2\lambda_3} \le 0
$$
  

$$
g_4(\vec{\lambda}) = \frac{\lambda_1 + \lambda_2}{1.5} - 1 \le 0
$$

# *Variable range:*

 $0.05 \le \lambda_1 \le 2.00$ ,  $0.25 \le \lambda_2 \le 1.30$ , and  $2.00 \le \lambda_3 \le 15.00$ .

The results of all comparison methods and the recommended PDO-DE for addressing the spring design issue are presented in Table 11. The optimal parameter values are presented in Table 11, along with the highest achieved results for all comparison algorithms. The variables with the values  $\lambda = (d = 0.060599, D = 0.316181, N = 10.2101150)$  yield the optimal objective's value:  $F(\lambda) = 0.011670$ . This demonstrates that the suggested PDO-DE method is superior to other state-of-the-art approaches in terms of giving a more reliable solution.

# *4.4. Problem 4: the pressure vessel*

The pressure vessel, which has hemispherical caps and a cylindrical shape (see Fig. 9), must be built with minimal expenses. The construction of the compressed air tank must adhere to the American Society of Mechanical Engineers (ASME) regulations for boilers and pressure vessels [\[38\]](#page-29-0). The tank operates at a pressure of 3,000 pounds per square inch (psi) and has a minimum volume of 750 cubic feet (ft3). The final price is determined by the cumulative costs of welding, material, and forming charges. The optimization factors considered the following:

- The length of the cylindrical segment.
- The inner radius.
- The thickness of the cylinder skin.
- The thickness of the spherical head.
- The inner radius.

Thickness can only be expressed as discrete numbers integer multiples of 0.0625. The mathematical formulation of this problem can be stated as:







**Fig. 10.** A model of the Welded design problem.

# *Objective function:*

$$
f(\lambda) = 0.6224 \lambda_1 \lambda_3 \lambda_4 + 1.7781 \lambda_2 \lambda_3^2 + 3.1661 \lambda_1^2 \lambda_4 + 19.84 \lambda_1^2 \lambda_3
$$

# *Subject to:*

$$
g_1(\lambda) = -\lambda_1 + 0.0193\lambda_3 \le 0
$$
  
\n
$$
g_2(\lambda) = -\lambda_2 + 0.00954\lambda_3 \le 0
$$
  
\n
$$
g_3(\lambda) = -\pi \lambda_3^2 \lambda_4 - \frac{4}{3}\pi \lambda_3^3 + 1296000 \le 0
$$
  
\n
$$
g_4(\lambda) = \lambda_4 - 240 \le 0
$$

## *where:*

 $1 \times 0.0625 \le \lambda_1, \lambda_2 \le 99 \times 0.0625, 10 \le \lambda_3 \le 200$  and  $10 \le \lambda_4 \le 240$ .

Table 12 illustrates the comparison algorithms and the PDO-DE method used to address the vessel design problem. The optimal parameter values are displayed in Table 12, along with the best results achieved by all the algorithms that were compared. Table 12 demonstrates that the proposed PDO-DE outperforms other state-of-the-art methods by offering a more reliable solution that assigns the optimal variables at  $\lambda = (\lambda_1 = 0.813, \lambda_2 = 0.4281, \lambda_3 = 42.070053, \lambda_4 = 175.625672)$ , resulting in the best objective value of  $f(\lambda) =$ 61*.*5245.

# *4.5. Problem 5: welded beam*

The welded beam design issue is a widely recognized case study used to assess the efficacy of PDO-DE. The concept was initially introduced in [\[39\]](#page-29-0) to reduce the total manufacturing cost of a welded beam by utilizing four finding variables, as depicted in Fig. 10. The variables consist of the following: The weld thickness (h). The length (l) of the joint beam. The height of the beam (t). Thickness (b).

The mathematical formulation of this problem can be stated as:

*Consider*

 $\vec{\chi} = [\chi_1, \chi_2, \chi_3, \chi_4]$ ]  $=[h, l, t, b]$ 





*Minimize*

$$
f\left(\vec{\chi}\right) = 1.10471\chi_1^2\chi_2 + 0.04811\chi_3\chi_4\left(14.0 + \chi_2\right)
$$

# *Subject to*

$$
g1(\vec{\chi}) = \tau(\chi) - \tau_{max} \le 0
$$
  
\n
$$
g2(\vec{\chi}) = \lambda - \lambda_{max} \le 0
$$
  
\n
$$
g3(\vec{\chi}) = \delta - \delta_{max} \le 0
$$
  
\n
$$
g4(\vec{\chi}) = \chi_1 - \chi_4 \le 0 \le 0
$$
  
\n
$$
g5(\vec{\chi}) = P - P_C(\vec{\chi}) \le 0
$$
  
\n
$$
g6(\vec{\chi}) = 0.125 - \chi_1 \le 0
$$
  
\n
$$
g7(\vec{\chi}) = 1.10471 \chi_1^2 + 0.04811 \chi_3 \chi_4 (14 + \chi_2) - 5 \le 0
$$

*Variable range*

 $0.125 \leq \chi_1 \leq 5$ ,  $0.1 \leq \chi_2$ ,  $\chi_3 \leq 10$ , and  $0.1 \leq \chi_4 \leq 5$ .

*where*

$$
\tau(\vec{\chi}) = \sqrt{(\tau')^2 + 2\tau'\tau'' \frac{\chi_2}{2R} + (\tau'')^2}, \tau' = \frac{P}{\sqrt{2\chi_1\chi_2}}, \tau' = \frac{MR}{J}, M = P\left(L + \frac{\chi_2}{2}\right)
$$
  
\n
$$
R = \sqrt{\frac{\chi_1^2}{4} + \left(\frac{\chi_1 + \chi_3}{2}\right)^2}, J = 2\left\{\sqrt{2\chi_1\chi_2} \left[\frac{\chi_2^2}{4} + \left(\frac{\chi_1 + \chi_3}{2}\right)^2\right]\right\},
$$
  
\n
$$
\chi(\vec{\chi}) = \frac{6PL}{E\chi_3^2\chi_4}, \delta(\vec{\chi}) = \frac{6PL^3}{E\chi_3^2\chi_4},
$$
  
\n
$$
P_C(\vec{\chi}) = \frac{4.013E\sqrt{\frac{\chi_3^2\chi_4^6}{36}}}{L^2} \left(1 - \frac{z_3}{2L}\sqrt{\frac{E}{4G}}\right)
$$
  
\n
$$
\lambda_{max} = 3000psi, \delta_{max} = 0.25in, \tau_{max} = 30,000psi.
$$
  
\n
$$
E = 30 \times 10^6psi, G = 12 \times 10^6psi
$$
  
\n
$$
L = 14in, P = 6000lb.
$$

The proposed PDO-DE is implemented to address the problem of the welded beam. The PDO-DE algorithm outperforms compared algorithms and produces consistent results with the optimal variables at  $\chi = (h = 0.26406111, l = 2.0423029, t = 8.47022978,$  $b=0.453219$ ) and the optimal cost at  $f(\chi)=1.915701$ , the results are shown in Table 13. This demonstrates that PDO-DE can effectively address the problem of welded beam design.

# *4.6. Problem 6: network intrusion detection system*

As internet usage continues to expand, so do its vulnerabilities, prompting the implementation of Intrusion Detection Systems (IDS) to safeguard security. IDSs serve as protective measures, identifying external intrusions, unauthorized accesses, and network



malfunctions. By analyzing data such as port scanning and abnormal traffic patterns, IDSs can detect intrusions and alert network administrators. Intrusion detection poses a classification challenge, and identifying optimal features is crucial for classification techniques to be effective. Common classification methods include neural networks, fuzzy logic, data mining techniques, and metaheuristics. The proposed PDO-DE is implemented to enhance the precision of detecting intrusion. It is utilized to select features with support vector machine (SVM) assets for classification.

#### *4.6.1. Support vector machine*

Support Vector Machines (SVM) are a widely used supervised machine learning model known for their effectiveness in classification tasks, including intrusion detection. They excel in linear classification and regression, offering robustness and adaptability even with limited training data. One of their key advantages is their ability to operate without assumptions about the underlying data, instead identifying hyperplanes to separate data points effectively. In Intrusion Detection Systems (IDS), where attack distributions can be imbalanced, SVMs have succeeded due to their ability to generalize well, handle multiple classes efficiently, and operate with low classification times. The SVM classifier is central to SVM-based intrusion detection systems, generating models of the target system and correlating attribute data with classification outcomes [\[40](#page-29-0)].

# *4.6.2. Dataset*

The NSL-KDD dataset is used in this work to show the performance of the PDO-DE for intrusion detection. The KDD CUP 1999 dataset, derived from the DARPA 98 IDS evaluation program by Lincoln Labs, features around five million connection records from a U.S. Air Force military simulation, serving as a standard benchmark for testing intrusion detection algorithms. To overcome issues like duplicate records, skewed distributions, and redundancies in the KDD dataset, the improved NSL-KDD dataset was introduced. It includes 41 attributes categorized into four groups: time-based and host-based traffic, basic, and content attributes, which can be discrete or continuous. This dataset labels deviations from normal network behavior as attacks, categorizing them into 24 types, such as Denial of Service (DoS), Probe, user-to-root (U2R), and remote-to-local (R2L) attacks [\[41\]](#page-29-0).

Each connection record in the dataset has 41 features, which fall into one of three categories:

- Basic Features: These are characteristics like duration, protocol type, service, and flag that are obtained from TCP/IP connections.
- Content Features: These features include counts like the quantity of unsuccessful login attempts and file creation operations obtained from the data contained in a connection.
- Traffic characteristics: This category includes the number of connections to the same host and to the same service. It is obtained from a two-second time window.

The training set consists of about 4.9 million connection records, and the testing set consists of about 311,000 connection records, as shown in Table 14. This large dataset offers a thorough foundation for testing and developing network intrusion detection methods.

# *4.6.3. Results and discussions on IDS*

The evaluation of the PDO-DE algorithm is based on four metrics: accuracy (ACC), feature count (NoF), false alarm rate (FR), and detection rate (DR). These metrics are calculated using counts of true positives (correctly identified intrusions), false positives (normal activities incorrectly flagged as intrusions), true negatives (normal activities rightly identified), and false negatives (intrusions wrongly classified as normal). The computational methods for these metrics are detailed below:

$$
FR = \frac{\text{FP}}{\text{FP} + \text{TN}}\tag{20}
$$

$$
DR = \frac{True_{positive}}{True_{positive} + False_{Negative}}
$$
 (21)

$$
NoF = Total_{Number\ of\ features} - Nonselected_{Features}
$$
\n
$$
(22)
$$

$$
ACC = \frac{True_{positive} + True_{negative}}{True_{positive} + False_{negative} + True_{negative}}
$$
\n(23)

This section comprehensively evaluates several state-of-the-art algorithms, including the original PDO and DE and the proposed PDO-DE, HHO, GOA, SSA, and WOA. The study assesses the effectiveness of these algorithms in handling the Intrusion Detection System (IDS) problem compared to the suggested technique. Improvements have been made with the suggested PDO-DE to address shortcomings like premature convergence, solution diversity, and slow search speed in the initial PDO algorithm. The impact of varying the number of PDs on optimization, striking a balance between exploration and exploitation searches, is also examined in this section.





**ENPDO-DE ENPDO ENDE ENHHO ENGOA ENSSA EN WOA** 





*Detection rate* The PDO-DE method demonstrates superior performance in detection rates compared to the PDO and DE algorithms, achieving a detection rate of 98.1% against PDO 92% and DE 82%. This marks a significant enhancement in the network intrusion detection capabilities, with results depicted in Fig. 11. Repeated testing confirms the reliability of PDO-DE, noting an increase in system complexity and a maintained high detection rate when integrating DE features.

*False alarm rate* The PDO-DE method also shows a marked improvement in reducing false alarms, with a rate of only 2.4%, in contrast to higher rates observed in other methods: 26% for DE, 8.5% for PDO and between 18%, 25%, 29%, and 19% for HHO, GOA, SSA, and WOA, respectively. This advancement leads to fewer irrelevant alerts from the IDS, enhancing operational efficiency, as detailed in Fig. 12.

*Accuracy* The PDO-DE method's accuracy is outstanding, reaching 96%. This outperforms PDO at 92% and DE at 87% and significantly surpasses HHO, GOA, SSA, and WOA, which range from 80% to 86%. This improvement results from the algorithm's multi-objective function, which prioritizes accuracy and refines the intrusion detection system's precision. The summarized results in Fig. [13](#page-27-0) underscore the method's precision and reliability.

*Number of features* The PDO-DE selects only 9% of features for effective intrusion detection, compared to 16% and 22% by PDO and SMA, respectively. This reduction optimizes the number of relevant characteristics the IDS manages, minimizing system overhead. This efficiency in feature selection underscores the robustness of PDO-DE, as presented in Fig. [14](#page-27-0). The strategic increase in prairie dogs enhances the diversity and selection quality of the features.

The IDS results show that the PDO-DE method significantly outperforms the PDO and DE algorithms in several key areas of network intrusion detection. It achieves a higher detection rate of 98.1%, greatly reducing false alarms with a rate of only 2.4%, and improves accuracy to 96%. Additionally, it selects fewer but more effective features for intrusion detection, only 9% compared to

<span id="page-27-0"></span>









PDO's 16% and DE's 23%. These improvements in detection rate, false alarm rate, accuracy, and feature selection efficiency highlight the PDO-DE method's enhanced capability and operational efficiency in network security environments.

# *4.7. Evaluation of the suggested approach: advantages and disadvantages*

The suggested method integrates two optimization techniques, PDO and DE, to enhance optimization performance and attain superior outcomes. *Advantages:*

- DE algorithm enriches the population's diversity and prevents premature convergence by producing contrasting solutions.
- The purpose of using PDO is to expand the search area and prevent being trapped in local optima. DE aids in achieving a balance between exploration and exploitation by incorporating a stochastic element into the search procedure.
- The technique is assessed using benchmark functions and engineering design optimization challenges. It surpasses certain other cutting-edge optimization algorithms in accuracy and efficiency.

# *Disadvantages*:

- The effectiveness of the suggested method is highly dependent on the parameter settings. If the parameters are not appropriately chosen, it can result in inferior outcomes or slow convergence.
- The method may require a substantial number of function evaluations to get the best solution, which can require a high computational cost for problems with many dimensions.
- The user's text is a bullet point. This approach may not be appropriate for specific targeted optimization issues and may exhibit suboptimal performance on benchmark functions not included in the study.

# <span id="page-28-0"></span>**5. Conclusions**

This paper introduces a new population-based metaheuristic method incorporating Prairie dog optimization (PDO) and the Differential Evolution algorithm to enhance the PDO algorithm's searchability.

The efficacy of the proposed PDO-DE is evaluated by assessing its ability to balance exploration and exploitation through experimentation with classical and CEC2019 benchmark test functions. The findings showcased the efficacy of PDO-DE in identifying the most favorable global solutions and exhibiting more consistent convergence when compared to other widely recognized optimization algorithms documented in the literature. The effectiveness of the proposed PDO-DE is determined using statistical analysis utilizing the Freidman ranking test. The statistical results further validated the resilience of the proposed PDO-DE in effectively conducting both exploration and exploitation.

In addition, the suggested PDO-DE approach is applied to address five practical engineering issues. The outcomes obtained by the PDO-DE algorithm verified its potential to provide superior (almost optimal) solutions compared to various metaheuristic algorithms, such as HHO, WOA, DA, SMA, SCA, GOA, and the basic PDO. PDO-DE demonstrated a significant ability to manage diverse restrictions in optimization situations.

The suggested PDO-DE algorithm effectively addressed single-objective continuous optimization problems. Researchers should explore the possibility of building a binary version of the algorithm. Additionally, it is possible to create a multi-objective version of the PDO. Researchers may also explore the possibility of adjusting and hybridizing the PDO-DE. Extending the PDO-DE to address various discrete or continuous challenges can be a promising effort.

In conclusion, the PDO-DE algorithm represents a significant scientific advancement in hybrid optimization techniques, providing a more effective approach for solving real-world problems that require high precision and optimal resource utilization. Our extensive experiments on 23 benchmark functions and five engineering design problems demonstrate that PDO-DE consistently achieves superior performance metrics. Notably, the algorithm shows an average accuracy improvement of 2.5% over existing state-of-the-art methods. In the context of network intrusion detection, PDO-DE achieved an overall accuracy of 96%, a detection rate of 98.1%, and a false alarm rate of 2.4%. These results underline the algorithm's robustness, reliability, and efficiency.

The significance of these improvements is profound, as they highlight PDO-DE's ability to deliver precise and reliable solutions in complex and dynamic environments. The enhanced convergence speed and reduced computational time further establish its applicability in various domains. Future work will explore the application of PDO-DE to other challenging optimization problems and investigate further enhancements to the algorithm's framework. The promising results achieved in this study suggest that PDO-DE can be a valuable tool in both engineering optimization and cybersecurity, paving the way for more advanced and practical applications in these fields.

Future research will focus on extending the application of PDO-DE to other challenging optimization problems, such as largescale industrial optimization, bioinformatics, and financial modeling. Additionally, exploring the integration of other metaheuristic algorithms could further enhance the performance of PDO-DE. We also plan to investigate adaptive mechanisms within the algorithm to improve its adaptability to different problem landscapes dynamically. Furthermore, real-world implementations and case studies in engineering and cybersecurity will be conducted to validate the practical effectiveness and scalability of PDO-DE in diverse scenarios.

The promising results achieved in this study suggest that PDO-DE can be a valuable tool in both engineering optimization and cybersecurity, paving the way for more advanced and practical applications in these fields.

#### **Ethical approval**

Not applicable.

# **CRediT authorship contribution statement**

**Mohammad Alshinwan:** Formal analysis, Data curation, Conceptualization. **Osama A. Khashan:** Supervision, Project administration, Data curation. **Mohammed Khader:** Formal analysis, Conceptualization. **Omar Tarawneh:** Formal analysis, Data curation, Conceptualization. **Ahmed Shdefat:** Resources, Investigation, Funding acquisition, Data curation. **Nour Mostafa:** Formal analysis, Conceptualization. **Diaa Salama AbdElminaam:** Funding acquisition, Formal analysis, Data curation, Conceptualization.

# **Declaration of competing interest**

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

## **Data availability**

All data are available upon reasonable request from the corresponding author, Diaa Salama AbdElminaam.

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#### <span id="page-29-0"></span>*M. Alshinwan, O.A. Khashan, M. Khader et al.*

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