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2	real-time			
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4	Abbreviated title: Personalized real-time brain state-dependent TMS			
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29				

30 Abstract

31 BACKGROUND: Transcranial magnetic stimulation (TMS) interventions could feasibly treat

32 stroke-related motor impairments, but their effects are highly variable. Brain state-dependent

TMS approaches are a promising solution to this problem, but inter-individual variation in lesion

34 location and oscillatory dynamics can make translating them to the poststroke brain challenging.

35 Personalized brain state-dependent approaches specifically designed to address these

36 challenges are therefore needed.

37

38 METHODS: As a first step towards this goal, we tested a novel machine learning-based EEG-

39 TMS system that identifies personalized brain activity patterns reflecting strong and weak

40 corticospinal tract (CST) output (strong and weak CST states) in healthy adults in real-time.

41 Participants completed a single-session study that included the acquisition of a TMS-EEG-EMG

42 training dataset, personalized classifier training, and real-time EEG-informed single pulse TMS

43 during classifier-predicted personalized CST states.

44

45 RESULTS: MEP amplitudes elicited in real-time during personalized strong CST states were

significantly larger than those elicited during personalized weak and random CST states. MEP

47 amplitudes elicited in real-time during personalized strong CST states were also significantly

48 less variable than those elicited during personalized weak CST states. Personalized CST states

49 lasted for ~1-2 seconds at a time and ~1 second elapsed between consecutive similar states.

50 Individual participants exhibited unique differences in spectro-spatial EEG patterns between

51 personalized strong and weak CST states.

52

CONCLUSION: Our results show for the first time that personalized whole-brain EEG activity
 patterns predict CST activation in real-time in healthy humans. These findings represent a
 pivotal step towards using personalized brain state-dependent TMS interventions to promote
 poststroke CST function.

57

58 **Keywords:** motor cortex, brain stimulation, transcranial magnetic stimulation,

59 electroencephalography, machine learning

61 Introduction

62 Transcranial magnetic stimulation (TMS) is a noninvasive brain stimulation technique that could 63 feasibly treat a variety of psychiatric and neurological disorders, including depression (George et al., 1995, 2010) obsessive-compulsive disorder (Mantovani et al., 2006; Tendler et al., 2021), 64 memory deficits (Freedberg et al., 2022; Solé-Padullés et al., 2006; Wang et al., 2014), 65 cognitive decline (Luber & Lisanby, 2014), and motor impairments caused by neurological 66 damage (Bunday & Perez, 2012; Di Lazzaro et al., 2008; Du et al., 2016; Jo & Perez, 2020). 67 Early studies showed that TMS interventions delivered to the sensorimotor cortex can alter 68 69 corticospinal tract (CST) transmission (Huang et al., 2005; Pascual-Leone et al., 1995, Chen et al., 1998). Given the mechanistic role of the CST in voluntary upper extremity movement 70 (Lemon, 2008) and the prognostic utility of CST integrity in predicting poststroke upper extremity 71 motor recovery (Stinear et al., 2007). TMS interventions that upregulate CST transmission could 72 feasibly improve voluntary motor function in individuals with stroke-related disruption of the 73 74 CST. However, it has recently become apparent that the effects of TMS interventions on CST transmission are highly variable both within and between individuals (Hamada et al., 2013; 75 López-Alonso et al., 2014), such that conventional TMS interventions do not reliably upregulate 76 77 CST transmission even in healthy adults.

78

79 TMS applied over the sensorimotor cortex trans-synaptically activates CST neurons (Di Lazzaro 80 & Ziemann, 2013; Hoogendam et al., 2010; Mills et al., 1992), resulting in a peripheral muscle 81 response termed a motor-evoked potential (MEP). The peak-to-peak amplitude of an MEP 82 reflects the magnitude of CST activation at the precise moment of TMS delivery. Yet, MEP amplitudes dynamically fluctuate over time, even when keeping other parameters such as 83 stimulation location and intensity constant (Jung et al., 2010; Kiers et al., 1993). Such dynamic 84 fluctuations can be attributed in part to variability in subthreshold depolarization of CST neurons 85 and cortical interneurons synapsing onto them (Di Lazzaro & Ziemann, 2013; Ziemann et al., 86 1996). Consistent with this notion, accumulating evidence has shown that CST activation 87 depends on ongoing sensorimotor oscillatory activity at the time of stimulation (Berger et al., 88 2014; Bergmann et al., 2019; Hussain et al., 2019; Ozdemir et al., 2022; Suresh & Hussain, 89 90 2023; Wischnewski et al., 2022; Zrenner et al., 2018), including sensorimotor rhythm phase (Bergmann et al., 2019; Wischnewski et al., 2022; Zrenner et al., 2018), sensorimotor rhythm 91 power (Hussain et al., 2022; Madsen et al., 2019), and interactions between them (Hussain et 92 93 al., 2019b; Ozdemir et al., 2022; Suresh & Hussain, 2023). For example, TMS more strongly 94 activates the CST during sensorimotor mu rhythm trough than peak phases (Bergmann et al.,

95 2019; Wischnewski et al., 2022; Zrenner et al., 2018), and this effect is strongest during periods 96 of high mu rhythm power (Hussain et al., 2019; Ozdemir et al., 2022; Suresh & Hussain, 2023). 97 These studies raise the possibility that delivering TMS interventions during mu trough phases could enhance their efficacy. Indeed, EEG-triggered repetitive TMS interventions delivered 98 during sensorimotor rhythm mu trough phases increase CST transmission, while identical 99 interventions delivered during mu peak phases weakly depress it (Baur et al., 2020; Zrenner et 100 101 al., 2018). Thus, coupling TMS interventions to brain activity patterns (i.e., brain states) 102 reflecting strong CST activation could potentiate their therapeutic effects in individuals with 103 poststroke motor impairments.

104

105 Although several studies have shown that TMS more strongly activates the CST during 106 sensorimotor mu rhythm trough than peak phases, the magnitude of this effect varies across studies (Bergmann et al., 2019; Hussain et al., 2019b; Madsen et al., 2019b; Wischnewski et al., 107 108 2022; Zrenner et al., 2018), suggesting that mu phase-dependent variation in CST activation exhibits substantial inter-individual variability even in healthy adults. Furthermore, translating 109 real-time, mu phase-dependent TMS approaches from the healthy to the poststroke brain can 110 111 be challenging (Hussain et al., 2020). Because stroke survivors are a highly heterogeneous 112 population, each stroke survivor has a unique pattern of motor impairment and recovery-related 113 adaptive plasticity (Delvaux et al., 2003; Grefkes & Ward, 2014; Jones, 2017; Lotze et al., 2012; 114 Luft et al., 2004; C. Stinear, 2010) that could alter sensorimotor rhythm characteristics and their 115 relationship to CST activation. Lesion-related volumetric brain loss in each stroke survivor is 116 also unique, such that the mapping of brain activity to EEG scalp signals varies across stroke survivors (Lopez-Larraz et al., 2017; Park et al., 2016). Personalized brain state-dependent 117 TMS approaches specifically designed to address these issues are therefore needed. 118

119

120 Consistent with this need, we developed and tested a novel machine learning-based EEG-

121 triggered TMS system that identifies and targets personalized whole-brain activity patterns

reflecting time windows when TMS either strongly or weakly activates the CST (i.e.,

123 personalized strong or weak CST states) in healthy adults. We first acquired a single training

124 dataset for each participant which included EEG and EMG recorded during single-pulse motor

125 cortex (M1) TMS. We then used this dataset to build a personalized classifier that discriminates

between EEG activity patterns during which TMS elicited either a large or small MEP. Finally,

- 127 we tested this personalized classifier by evaluating MEP amplitudes during real-time, EEG-
- 128 triggered TMS targeting personalized strong, weak, and random CST states. Our results show

- 129 that this system can accurately identify and target personalized whole-brain EEG activity
- 130 patterns corresponding to strong and weak CST activation in real-time. These findings represent
- a key step towards using personalized, machine learning-driven brain state-dependent TMS
- 132 interventions to promote poststroke CST function and motor recovery.
- 133

134 Methods

- 135 Data acquisition
- 136 Participants. 21 healthy adults participated in this single-session study, which involved single-
- 137 pulse transcranial magnetic stimulation (TMS) during 62-channel electroencephalography
- 138 (EEG) and bipolar EMG recordings from the left first dorsal interosseous (L. FDI) and left
- abductor pollicis brevis (L. APB) muscles. Of these participants, one was excluded due to EMG
- signal corruption, and one was excluded due to excessively noisy EEG signals. Thus, our final
- sample size was N=19 (15 F, 4 M, age = 20.8 ± 0.7 [standard error of the mean; SEM] years).
- 142 This study was approved by the Institutional Review Board at the University of Texas at Austin,
- and all participants provided their written informed consent prior to participation.
- 144

145 Experimental design. After experimental setup was complete, the TMS stimulation location and 146 intensity were empirically determined for each participant (see TMS). Then, participants 147 completed a 5-minute EEG recording while resting guietly with their eves open. After resting 148 EEG, 6 blocks of 100 single brain state-independent TMS pulses at 120% of resting motor 149 threshold (RMT) were delivered to the scalp motor hotspot for the L. FDI muscle while EEG and 150 EMG were recorded. Resulting EEG and EMG data were used to build a personalized classifier 151 that could discriminate between whole-brain EEG activity patterns during which TMS strongly 152 activated the CST (i.e., strong CST states) or weakly activated it (i.e., weak CST states), as measured via L. FDI motor-evoked potential (MEP) amplitudes. Afterward, this classifier was 153 154 used to deliver real-time, single-pulse brain state-dependent TMS to the scalp hotspot for the L. 155 FDI during strong and weak CST states at two different stimulation intensities (120% and 110% RMT). For comparison, single-pulse brain state-independent TMS was also applied to the scalp 156 hotspot for the L. FDI at these same intensities (i.e., random CST states). Throughout the 157 158 experimental session, MEPs were recorded from both the L. FDI and L. APB muscles. See 159 Figure 1A for a visual depiction of the experimental timeline.



160

161

Figure 1. Experimental timeline and machine learning analysis pipeline. A) Experimental

timeline. All procedures were completed within a single session. B) Personalized machinelearning classifier analysis pipeline.

165

166 EEG and EMG acquisition. 62-channel EEG signals were recorded at 5 kHz (low-pass hardware

- 167 filtering cutoff frequency: 1250 Hz, 0.001 μV resolution) using TMS-compatible amplifiers
- 168 (NeurOne Tesla, Bittium Biosignals, Finland). EEG impedances were maintained below 10 k Ω .
- 169 Bipolar EMG signals were also recorded from the L. FDI and L. APB muscles at 5 kHz (low-
- pass hardware filtering cutoff frequency: 1250 Hz, 0.001 µV resolution) using Ag-AgCl adhesive
- 171 electrodes arranged in a belly-tendon montage.
- 172
- 173 <u>TMS.</u> The scalp hotspot was identified over the hand representation area of the right motor
- 174 cortex as the site at which suprathreshold single-pulse TMS elicited the largest MEPs within the
- 175 L. FDI as well as a focal muscle twitch. Then, the RMT was determined using a threshold-
- tracking software tool (MTAT 2.0; Awiszus, 2011). RMT was on average 66 ± 2.3% (range = 51
- 177 84) of maximum stimulator output. To maximize trans-synaptic activation of corticospinal tract

(CST) neurons, TMS was delivered using a figure-of-eight coil held at ~45 degrees relative to
the mid-sagittal line (Mills et al., 1992); Deymed Diagnostic, XT100, biphasic pulse shape). Coil
position accuracy was monitored online using frameless neuronavigation (BrainSight, Rogue
Research, Inc.).

182

Personalized offline machine learning classification. We acquired a single TMS-EEG-EMG 183 training dataset from each participant by delivering 6 blocks of 100 single TMS pulses to the 184 scalp hotspot for the L. FDI muscle at 120% RMT during EEG and EMG recordings (inter-185 186 stimulus interval = 3 s + random jitter). Participants rested quietly with their eyes open during 187 TMS delivery and were provided with short rest breaks between blocks. After acquiring this 188 training dataset, participants rested while a personalized machine learning classifier was built. 189 The purpose of this classifier was to discriminate between whole-brain EEG activity patterns during which TMS either strongly or weakly activated the CST, indexed by L. FDI MEP 190 191 amplitudes. EEG and L. FDI EMG data were preprocessed using custom-written scripts utilizing 192 the FieldTrip toolbox (Oostenveld et al., 2011) while machine learning classification was performed using custom-written scripts utilizing the MVPA-Light toolbox (Treder, 2020). Both 193 194 toolboxes operated in the MATLAB environment.

195

196 Continuous bipolar EMG data for the L. FDI muscle were divided into segments (-0.100 to 197 +0.400 s relative to each TMS pulse). We then calculated the root-mean-square (RMS) value 198 for each L. FDI EMG pre-stimulus EMG segment (-0.100 to -0.025 s relative to each TMS 199 pulse). Trials contaminated by voluntary muscle activation were identified as those for which 200 pre-stimulus RMS values exceeded a participant-specific threshold, defined as the mean of prestimulus L. FDI EMG RMS values + 2 * the standard deviation of pre-stimulus L. FDI EMG RMS 201 202 values. On average, $2.3 \pm 0.4\%$ of all trials (range = 0.2 - 6.8%) were contaminated by voluntary muscle activation per participant. Then, each L. FDI EMG segment was used to 203 calculate peak-to-peak L. FDI MEP amplitudes. To ensure that our classification approach 204 captured trial-by-trial variability in L. FDI MEP amplitudes rather than slow fluctuations in CST 205 activation that can occur with repeated application of single-pulse TMS (Pellicciari et al., 2016), 206 207 the resulting time course of L. FDI MEP amplitudes was demeaned and linearly detrended, z-208 transformed, and then rescaled to range between 0 and 1. These steps were performed 209 separately for all L. FDI MEPs not contaminated by voluntary muscle activation per block. 210 Transformed L. FDI MEPs were then combined across blocks and dichotomized into categories 211 that reflected strong activation of the CST (i.e., L. FDI MEPs with amplitudes larger than or

equal to the median L. FDI MEP amplitude) or weak activation of the CST (i.e., L. FDI MEPs
with amplitudes smaller than the median L. FDI MEP amplitude). These categories were used
as class labels during subsequent offline classification.

215

216 Continuous 62-channel EEG data were divided into segments (-[0.500 + x] to -[0 + x] ms beforeeach TMS pulse, where x reflects the technical delay of the real-time EEG streaming and 217 218 analysis system; see Real-time EEG analysis and personalized brain state-dependent TMS). To 219 ensure accurate real-time performance, the technical delay was calculated at the beginning of 220 each experimental session and individually adjusted per session. Technical delays were on 221 average 43.6 ± 1.3 (range = 39 - 59) ms. Segmented EEG data were re-referenced to the 222 common average reference, demeaned, linearly detrended, and downsampled to 1 kHz. 223 For personalized machine learning classification, we used Linear Discriminant Analysis (LDA) 224 225 with 5-fold stratified cross-validation. As applied here, LDA is a supervised machine learning algorithm that identifies the hyperplane which best separates whole-brain EEG brain activity 226

227 patterns during which TMS either strongly or weakly activated the CST (i.e., strong or weak CST

states, respectively), as indexed by L. FDI MEP amplitudes. We applied a modified version of

our previously published personalized classification approach (Hussain et al., 2022) to

230 preprocessed EEG data and L. FDI MEP amplitude class labels.

231

232 Trials were randomly divided into folds. For each fold, classifiers were trained on the training 233 dataset (80% of trials) and tested on the testing dataset (20% of trials). We first applied common spatial filter analysis (CSP; Blankertz et al., 2008) to the preprocessed EEG timeseries data. 234 CSP is a signal processing approach that improves the discriminability of two classes of EEG 235 236 signals by maximizing the variance of EEG data corresponding to one class and minimizing the 237 variance of EEG data corresponding to the other class. CSP as applied here generates 238 subcomponents that reflect spatially filtered EEG timeseries data corresponding to each class. 239 For each fold, CSP spatial filters were calculated using the training dataset and then applied to 240 the testing dataset to avoid information leakage that could bias classification results. All 62 241 subcomponents generated by CSP were retained and spectrally decomposed using Welch's 242 method (4-35 Hz with 0.25 Hz resolution). Power spectra obtained for each CSP subcomponent 243 were then summarized by calculating mean spectral power values for each of five canonical 244 frequency bands, including theta (4-8 Hz), alpha1 (8-10 Hz), alpha2 (10-13 Hz), beta1 (13-20 245 Hz) and beta2 (20-35 Hz). Overall, this approach generated five power spectral features for

each of the 62 CSP subcomponents, resulting in a total of 310 power spectral features perparticipant.

248

After calculating all features for each fold, we next optimized the number of features included in 249 250 each participant's personalized classifier. This was done by first ranking all 310 features in order of the strength of their statistical dependency with L. FDI MEP classes using the chi-square 251 252 method (Hussain et al., 2022). Here, the negative log of the chi-squared test's p-value for each feature was taken as its feature score, with higher scores reflecting features that more strongly 253 covary with L. FDI MEP classes. We then used grid search to optimize two aspects of each 254 participant's classifier: feature number (1 to 310) and regularization rate (100 linearly spaced 255 values from 1×10^{-10} to 1). During grid search, we iteratively trained multiple classifiers using all 256 possible combinations of feature numbers (with features added in order of importance) and 257 regularization rate values. Overall, this grid search approach produced 31,000 trained classifiers 258 259 per fold. For each fold, we applied all classifiers trained on the training dataset to the testing 260 dataset. Here, we identified each classifier's most confident predictions from the testing dataset by calculating the distance of each trial's prediction from the model's hyperplane (i.e., each 261 262 trial's d-value, with larger d-values indicating more confident predictions). A prediction was 263 labeled confident if the absolute value of its d-value was within the top 50% of that class's set of 264 d-values. In contrast, a prediction was labeled under-confident if the absolute value of its d-265 value was in the bottom 50% of that class's set of d-values. Confident strong CST state 266 predictions (predictions of large L. FDI MEP amplitudes) were labeled 2, confident weak CST 267 state predictions (predictions of small L. FDI MEP amplitudes) were labeled 1, and under-268 confident predictions were labeled 0. We then calculated each classifier's prediction performance using the F1 score, focusing only on high confidence predictions. The F1 score is 269 270 the harmonic mean of precision and recall and was chosen to maximize the number of true 271 positives (i.e., accurate weak CST state predictions) and minimize the number of false negatives and false positives (i.e., inaccurate strong or weak CST state predictions). We then 272 273 averaged F1 scores across folds and identified the best performing classifier with the fewest features and highest regularization rate. This resulted in selection of one personalized ensemble 274 275 classifier with 5 LDA models embedded within it (i.e., one per fold). F1 scores were on average 0.68 ± 0.01 when considering only high confidence predictions and 0.63 ± 0.01 when 276 considering all predictions. See Figure 1B for a visual depiction of the personalized classification 277 278 analysis pipeline.

280 <u>Real-time EEG analysis.</u> After identifying each participant's best-performing personalized

ensemble classifier, we used this classifier to identify EEG activity patterns predicting strong

- and weak CST activation in each participant in real-time. To achieve this, continuous 62-
- channel EEG was recorded and streamed to a Dell workstation PC (10 cores, Intel i9 processor,
- 16 GB RAM, 1 TB Solid State Drive) at 1 kHz using LabStreamingLayer
- 285 (https://github.com/sccn/labstreaminglayer; Kothe et al., 2024). This workstation was configured
- to perform real-time EEG analysis in MATLAB version 2020a using a combination of custom-
- 287 written scripts, FieldTrip, and MVPA-Light Toolboxes.
- 288

After being streamed to the workstation PC, EEG data were buffered into overlapping 500 ms windows. Overlap between consecutive windows determined by the technical delay of the real-

- time EEG streaming and analysis system (with overlap equal to [500ms technical delay]).
- 292 Buffered data were downsampled to 1 kHz, re-referenced to common average reference,
- 293 demeaned, and linearly detrended. Preprocessed data were used to obtain 62 CSP
- subcomponents per fold using the same CSP parameters used for that participant's optimized
- 295 ensemble classifier. This approach produced 5 distinct versions of 62 time-resolved CSP
- subcomponents (i.e., one per fold). Then, each fold's CSP subcomponents were used to
- 297 calculate power spectral features for that fold using the same approach implemented during
- 298 offline classification. For each fold, the relevant features were selected and used to classify the
- 299 current EEG segment, resulting in five separate class predictions for each segment. Then, each
- 300 EEG segment's predictions were labeled as confident or under-confident using the same
- 301 procedures applied during offline classification. To obtain a single prediction for each EEG
- 302 segment, all five predictions were combined using majority voting. If all five predictions were
- 303 under-confident or a tie occurred, no prediction was made. The label produced by the majority
- of the five classifiers was chosen as the label for that EEG segment, indicating either a strong
- 305 CST state, a weak CST state, or no prediction. When 10 consecutive confident predictions of
- the desired CST state occurred, TMS was triggered. For some participants, 10 consecutive
- confident strong and/or weak CST states could not be detected in real-time (2 participants for
 strong states at 120% and 110% RMT, 1 participant for weak states at 110% RMT). In these
- 309 scenarios, TMS was triggered upon 10 consecutive confident *or* under-confident predictions of
- the desired CST state.
- 311
- 312 <u>Real-time personalized single-pulse brain state-dependent TMS.</u> TMS was delivered to the L.
- 313 FDI scalp hotspot and MEPs were recorded from the L. FDI and L. APB muscles. 25 pulses

314 were applied per CST state (strong or weak) and stimulus intensity (110% and 120% RMT) in a 315 blocked manner (minimum interstimulus interval = 3 s + random jitter). In practice, interstimulus 316 intervals were on average 10.0 ± 0.9 and 7.0 ± 0.6 s for strong and weak CST states. respectively. For comparison, we also delivered conventional brain state-independent TMS 317 (i.e., during random CST states) at the same two intensities (interstimulus interval = 3 s + 318 random jitter). Overall, we obtained personalized brain state-dependent MEP amplitudes from 6 319 320 blocks of single-pulse TMS for each participant. The order of targeted CST states was counterbalanced across participants. However, stimulation intensities were always tested in the 321 322 same order, with 120% RMT followed by 110% RMT.

323

324 Data analysis

Evaluation of CST state targeting accuracy. After data acquisition was complete, we evaluated 325 the ability of our EEG-triggered TMS system to accurately identify and deliver TMS during pre-326 327 defined CST states in real-time. To achieve this, we first divided EEG data obtained during realtime personalized single-pulse brain state-dependent TMS into segments (-[0.500 + x] to -[0 + x])328 ms before each TMS pulse, where x reflects the session-specific technical delay of the real-time 329 330 EEG streaming and analysis system). We then applied the same EEG preprocessing, CSP, 331 spectral decomposition, and classification procedures used when performing real-time EEG 332 analysis to these segments, thus mimicking our real-time CST state prediction analysis 333 procedure in an offline analysis environment. For each participant, this approach resulted in a 334 series of predictions made by the offline application of each participant's personalized ensemble 335 classifier per CST state and stimulation intensity. Then, EEG segments for which the prediction 336 made by the real-time and offline application of each participant's personalized ensemble 337 classifier were identical were labeled as accurate. For each participant, the percentage of 338 accurate CST states targeted per state and intensity was calculated.

339

Analysis of MEP amplitudes and variability. Continuous L. FDI and L. APB EMG data obtained 340 during real-time, personalized single-pulse brain state-dependent TMS were divided into 341 segments (-0.100 to +0.400 s relative to each TMS pulse). Pre-stimulus EMG data (-0.100 to -342 343 0.025 relative to each TMS pulse) obtained from each muscle were demeaned and linearly 344 detrended. Then, a discrete Fourier transform-based filter was used to attenuate line noise and its harmonics within these pre-stimulus signals. For each muscle, the RMS value for each trial's 345 346 processed pre-stimulus EMG signal was calculated. Then, peak-to-peak MEP amplitudes were 347 calculated for each muscle. Trials for which peak-to-peak MEP amplitudes could not be reliably

calculated were excluded from analysis (average = $7.2 \pm 3.3\%$ of all trials, range = 0 - 43.3%). For each participant, trial-by-trial MEP amplitudes were normalized to the mean of all MEP amplitudes elicited from that muscle at that stimulation intensity. We also evaluated MEP amplitude variability by calculating the coefficient of variation of all remaining MEP amplitudes per CST state, intensity, and muscle for each participant.

353

354 Characterization of CST state duration. To characterize the mean duration of personalized strong and weak CST states, we applied each participant's personalized ensemble classifier to 355 their resting EEG data obtained at the beginning of the experimental session. We selected the 356 357 first 3 minutes of each participant's resting EEG data and divided these data into consecutive. 500 ms overlapping segments (overlap = 50 ms). EEG segments were then analyzed using the 358 359 same preprocessing, CSP, spectral decomposition, and classification procedures applied during real-time EEG analysis. We then calculated the average duration of each CST state, including 360 361 strong CST states, weak CST states, and under-confident states. We also calculated the 362 average time between consecutive similar states (i.e., the inter-state interval) and the 363 percentage of time that each CST state was present.

364

365 Performance of non-personalized classifiers. After data acquisition was complete, we evaluated 366 the performance of a single, general classifier trained using data from TMS-EEG-EMG training 367 datasets combined across all participants using similar procedures as that described for 368 personalized classification (see Personalized offline machine learning classification above). To 369 create training datasets, TMS-EEG-EMG data were compiled across N-1 participants (N = 370 sample size of 19). Testing datasets contained TMS-EEG-EMG data from the remaining held out participant. That is, we performed k-fold cross-validated grid search with k equal to N-1. 371 372 Given that each fold's testing set represented an individual participant, F1 performance values 373 were calculated for each fold and then compiled across participants.

374

375 <u>Pre-stimulus spectro-spatial EEG patterns for personalized strong and weak CST states.</u> We

also characterized differences in pre-stimulus EEG brain activity patterns present during

377 classifier-predicted strong versus weak CST states using 500 ms pre-stimulus EEG segments (-

[0.500 + x] to -[0 + x] ms before each TMS pulse, where x reflects the session-specific technical

delay of the real-time EEG streaming and analysis system). All analyses were performed at the

individual participant level. After segmenting EEG data, the same EEG preprocessing

381 procedures used during real-time EEG analysis were applied. All channels of preprocessed

EEG data were then spectrally decomposed using Welch's method using the same parameters 382 383 used during real-time EEG analysis. The resulting power spectra at each channel were natural 384 log-transformed and averaged across each CST state. The difference between power spectra obtained during strong and weak CST states at each channel was then calculated, and these 385 differences were binned by 1 Hz. This procedure generated a participant-specific matrix of 386 power spectral differences at each channel and frequency. To obtain a group-level 387 representation of differences in power spectra at each channel between CST states, we 388 averaged these matrices across participants. 389

390

391 Statistical analysis

All statistical analyses were performed using RStudio. Alpha was equal to 0.05 for all

comparisons, and all data are expressed as mean ± SEM.

394

395 <u>CST state targeting accuracy.</u> For each state and stimulation intensity, the percentage of trials 396 during which real-time, personalized brain state-dependent TMS accurately targeted the desired 397 CST state were compiled across participants and compared to theoretical chance (0.5) using 398 separate single-sample, right-tailed Wilcoxon signed-rank tests after confirming deviations from 399 normality using the Shapiro-Wilk test.

400

401 MEP amplitudes. We evaluated real-time personalized brain state-dependent variation in MEP 402 amplitudes regardless of the intensity used (110% and 120% RMT) or muscle from which they 403 were recorded (L. FDI and L. APB) using a trial-by-trial linear mixed-effects model. This model 404 included natural-log transformed MEP amplitudes as the response variable, STATE, INTENSITY, MUSCLE, and their two- and three-way interactions as fixed effects, pre-stimulus 405 background RMS EMG and inter-stimulus interval as continuous covariates, and PARTICIPANT 406 407 as random intercept. Model fits were visually inspected using histograms of residuals and quantile-quantile plots. The significance of fixed effects was determined using likelihood ratio 408

409 tests. Significant fixed effects were evaluated further using pairwise post hoc comparisons. All

410 post hoc comparisons were adjusted for multiple comparisons using the False Discovery Rate

411 correction (Benjamini & Hochberg, 1995). Given that we trained personalized classifiers using L.

412 FDI amplitudes elicited at 120% RMT, we also performed planned pairwise comparisons

between CST states for this muscle and intensity.

415 MEP variability. A linear mixed-effects model was also used to evaluate real-time personalized 416 brain state-dependent MEP amplitude variability for both intensities (110% and 120% RMT) and 417 muscles (L. FDI and L. APB). This model included natural-log transformed MEP amplitude coefficients of variation as the response variable, STATE, INTENSITY, MUSCLE, and their two-418 419 and three-way interactions as fixed effects, trial-averaged pre-stimulus background RMS EMG and trial-averaged inter-stimulus intervals as continuous covariates, and PARTICIPANT as the 420 421 random intercept. Model fits were visually inspected using histograms of residuals and guantilequantile plots. The significance of fixed effects was determined using likelihood ratio tests. 422 Significant fixed effects were further characterized via pairwise post hoc comparisons using the 423 424 False Discovery Rate correction. 425 Temporal characteristics of CST states. The mean duration of each state, the proportion of time 426 spent in each state, and the time between consecutive similar states were each compared 427 across CST states using separate Kruskal-Wallis rank sum tests for each response variable 428 429 after confirming deviations from normality using the Shapiro-Wilk test. Pairwise post hoc comparisons were performed using two-sample, two-tailed Wilcoxon Signed Rank tests followed 430 431 by correction for multiple comparisons using the False Discovery Rate correction. 432 433 Comparing personalized and non-personalized classifier performance. F1 scores indicating 434 personalized and non-personalized classifier performance were compared using two-sample, 435 paired Wilcoxon Signed Rank tests after confirming deviations from normality using the Shapiro-436 Wilk test. 437 Relationships between personalized classifier performance and brain state-dependent variation 438 in MEP amplitudes. For each participant, we calculated the percentage difference in MEP 439 amplitudes elicited during strong versus weak CST states and strong versus random CST states 440 at the same muscle and stimulation intensity used during classifier training (L. FDI MEP 441 amplitudes at 120% RMT). These percentage difference values were then regressed against F1 442 scores obtained from each participant's personalized classifier using separate Spearman's 443 correlations after confirming deviations from normality using the Shapiro-Wilk test. 444 445 Results

446 **Results**

447 CST state targeting accuracy

- 448 We first examined the ability of our machine learning-based EEG-triggered TMS system to
- identify personalized CST states in real-time by calculating the percentage of all trials during
- 450 which it accurately targeted the desired CST state at each stimulation intensity (Figure 2).
- 451 Targeting accuracy significantly exceeded chance for strong and weak CST states at 120% and
- 452 110% RMT (p < 0.001 for all). For 120% RMT, targeting accuracy was on average $94.5 \pm 1.1\%$
- and $89.5 \pm 2.7\%$ for strong and weak CST states, respectively. For 110% RMT, targeting
- 454 accuracy was on average $95.1 \pm 1.8\%$ and $83.1 \pm 6.3\%$ for strong and weak CST states,
- 455 respectively.
- 456



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Figure 2. Real-time personalized CST state targeting accuracy. Targeting accuracy of realtime EEG-triggered TMS for personalized strong and weak CST states at 120% and 110% RMT. Asterisks reflect statistically significant comparisons between targeting accuracy and chance level for each combination of state and stimulation intensity. Squares denote group averages, dots denote data from individual participants, error bars denote SEM, and the dashed horizontal grey line denote the theoretical chance level (50%).

- 465
- 466 MEP amplitudes
- 467 After confirming accurate real-time targeting of personalized CST states, we next evaluated
- differences in MEP amplitudes elicited in real-time during personalized strong, weak, and
- random CST states regardless of the intensity used (110% and 120% RMT, Figure 3) or the
- 470 muscle from which they were recorded (L. FDI and L. APB). A linear mixed-effects model
- 471 revealed a significant main effect of STATE (likelihood ratio test: F = 11.7, p < 0.001),

INTENSITY (likelihood ratio test: F = 28.1, p < 0.001), and MUSCLE (likelihood ratio test: F = 472 473 25.4, p < 0.001), as well as a significant two-way interaction between STATE and INTENSITY 474 (likelihood ratio test: F = 5.7, p = 0.003). Post hoc pairwise comparisons revealed that at 120% RMT, MEPs elicited in real-time during personalized strong CST states were significantly larger 475 than those elicited in real-time during personalized weak (p = 0.036) and random CST states (p 476 < 0.001). At 120% RMT, MEPs elicited during personalized weak CST states were also 477 significantly larger than those elicited during random CST states (p = 0.001). At 110% RMT, 478 MEPs did not differ between personalized strong, weak, or random CST states (p > 0.33 for all). 479 480 Planned comparisons for L. FDI MEPs elicited at 120% RMT showed that MEP amplitudes were larger during personalized strong than weak CST states and during personalized strong than 481 random CST states (p < 0.03 for both) but did not differ between personalized weak and 482 random CST states (p = 0.257). See Table 1 for percentage differences in MEP amplitudes 483

484 elicited between states.

485

Muscle	Intensity	Strong versus weak CST state	Strong versus random CST state
FDI	120% RMT	23.7 ± 7.5%	43.1 ± 17.5%
FDI	110% RMT	-3.0 ± 8.0%	12.0 ± 13.8%
APB	120% RMT	21.3 ± 11.8%	60.9 ± 21.2%
APB	110% RMT	13.2 ± 14.1%	48.6 ± 30.5%

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Table 1. Percentage difference in MEP amplitudes elicited during personalized strong versus
 weak CST states and personalized strong versus random CST states for each muscle and
 stimulation intensity.

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Figure 3. MEP amplitudes elicited during personalized strong, weak, and random CST 495 states in real-time. (A) MEP amplitudes recorded from the L. FDI and L. APB muscles during 496 real-time, classifier-predicted personalized strong, weak, and random CST states at 120% and 497 110% RMT. MEP amplitudes recorded from (B) L. FDI at 120% RMT, (C) L. FDI at 110% RMT, 498 (D) L. APB at 120% RMT, (E) L. APB at 110% RMT. Triple asterisks reflect significant STATE x 499 INTENSITY interaction. Single asterisks reflect significant pairwise post hoc comparisons for the 500 501 STATE x INTENSITY interaction. Squares denote group averages, circles denote data from individual participants, and error bars reflect SEM. 502 503

504 MEP variability

505 We next examined MEP amplitude variability during personalized strong, weak, and random

- 506 CST states by comparing coefficients of variation calculated from trial-by-trial MEP amplitudes
- 507 across CST states at both intensities (120% and 110% RMT) and both muscles (L. FDI and L.
- APB, Figure 4). Linear-mixed effects models identified a significant main effect of STATE (F = 508

3.36, p = 0.037), INTENSITY (F = 87.6, p < 0.001), and MUSCLE (F = 52.03, p < 0.001). Post 509

- hoc pairwise comparisons showed that MEP amplitude variability was significantly lower during 510
- personalized strong than weak CST states (p = 0.04). However, MEP amplitude variability did 511
- not differ between personalized weak and random CST states or between personalized strong 512
- and random CST states (p > 0.07 for both). MEP amplitudes elicited at 120% RMT were less 513

variable than those elicited at 110% RMT (p < 0.001) and MEP amplitudes recorded from L. FDI



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Figure 4. Variability of MEP amplitudes elicited during personalized strong, weak, and 519 random CST states in real-time. (A) Coefficients of variation calculated from trial-by-trial MEP 520 amplitudes recorded from the L. FDI and L. APB muscles during real-time, classifier-predicted 521 522 personalized strong, weak, and random CST states at 120% and 110% RMT. Coefficients of 523 variation calculated from trial-by-trial MEP amplitudes recorded from (B) L. FDI at 120% RMT, (C) L. FDI at 110% RMT, (D) L. APB at 120% RMT, and (E) L. APB at 110% RMT. Triple 524 525 asterisks reflect the significant main effects of STATE, MUSCLE and INTENSITY, and single asterisks reflect significant pairwise post hoc comparisons for the main effect of STATE. 526 Squares denote group averages, circles denote data from individual participants, and error bars 527 denote SEM. 528

529

530 Temporal characteristics of CST states

531 We also evaluated the temporal characteristics of personalized strong and weak CST states by

applying each participant's classifier to their resting EEG recording. When examining the

- 533 percentage of time during which either strong, weak, or under-confident CST states were
- 534 detected by personalized classifiers (Figure 5A), a Kruskal-Wallis test revealed a significant
- effect of STATE (p = 0.002). Post hoc pairwise comparisons showed that the proportion of time
- spent per state did not differ between strong and weak CST states (p = 0.125) but was

significantly lower for under-confident than weak or strong CST states (p < 0.027 for both).

538 Overall, personalized strong CST states were present 33.6 ± 5.9% of the time, personalized

539 weak CST states were present 48.4 ± 6.5% of the time, and under-confident CST states were

540 present $17.8 \pm 2.6\%$ of the time.

541

542 When evaluating the mean duration of strong, weak, or under-confident CST states detected by

543 personalized classifiers (Figure 5B), a Kruskal-Wallis test did not show any significant effect of

- 544 STATE. Personalized strong CST states lasted on average 0.89 ± 0.14 s, personalized weak 545 CST states lasted on average 2.05 ± 1.15 s, and under-confident CST states lasted on average
- 546 0.75 ± 0.06 s.
- 547

548 When examining the mean time between consecutive strong, weak, or under-confident CST 549 states detected by personalized classifiers (Figure 5C), a Kruskal-Wallis test did not reveal a 550 significant effect of STATE. On average, 0.93 ± 0.16 s elapsed between consecutive strong 551 CST states, 1.0 ± 0.45 s elapsed between consecutive weak CST states, and 1.97 ± 1.28 s 552 elapsed between consecutive under-confident CST states.

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Figure 5. Temporal characteristics of personalized CST states present during resting
 EEG recordings. (A) Percentage of time spent in each CST state. (B) Average duration of each
 CST state. C) Time between consecutive CST states. Squares denote group averages, circles
 denote data from individual participants, and error bars denote SEM. Asterisks indicate
 significant post hoc pairwise comparisons between CST states.

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564 Personalized versus non-personalized classifier performance

565 Personalized classifier F1 values were on average 0.68 ± 0.01, while non-personalized classifier

- 566 F1 values were on average 0.69 ± 0.01. F1 values did not differ across classifier types (p =
- 567 0.33; see Supplementary Figure 1).
- 568

569 Relationships between personalized classifier performance and brain state-dependent variation

- 570 *in MEP amplitudes*
- 571 Overall, L. FDI MEP amplitudes elicited at 120% RMT during personalized strong CST states
- were $23.7 \pm 7.5\%$ and $43.1 \pm 17.5\%$ larger than those elicited during personalized weak and
- random CST states, respectively (see Table 1). The percentage difference in MEP amplitude
- between CST states did not correlate with personalized F1 values (percentage difference
- 575 between strong and weak CST states versus F1 values: R = 0.14, p = 0.56; percentage
- 576 difference between strong and random CST states versus F1 values: R = 0.12, p = 0.63; see
- 577 Supplementary Figure 2).
- 578

579 Spectro-spatial characteristics of personalized CST states

580 We characterized the spectro-spatial characteristics of pre-stimulus EEG activity present during

- real-time classifier-predicted personalized strong versus weak CST states. At the individual
- 582 level, each participant exhibited qualitatively unique differences in pre-stimulus EEG power
- 583 between personalized strong and weak CST states across the scalp (see Supplementary Figure
- 3). For example, participant #13 showed higher right parieto-occipital alpha power during strong
- than weak CST states, while participant #14 exhibited higher right frontal beta power and lower
- 586 whole-scalp theta power during strong than weak CST states. At the group-level, right centro-
- 587 parietal alpha power and whole-scalp theta power were generally higher during personalized
- strong than weak CST states, and TP9 and TP10 showed stronger theta, alpha, and beta power
- 589 during strong versus weak CST states.
- 590



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Figure 6. Group-level differences in pre-stimulus spectro-spatial EEG patterns
 corresponding to personalized strong and weak CST states identified in real-time. Group
 average differences in natural log-transformed power between EEG activity during personalized
 strong and weak CST states. See Supplementary Figure 3 for individual participant data. Note
 that dark blue values reflect 0, which indicates no difference in power between states.

598 Discussion

- 599 In this study, we developed a first-of-its-kind machine learning-driven real-time EEG-TMS
- system that delivers TMS during personalized brain activity patterns reflecting strong and weak
- 601 CST activation in healthy humans at rest. We report that this system accurately targets
- 602 personalized strong and weak CST states, such that MEPs elicited during personalized strong
- 603 CST states were significantly larger than those elicited during personalized weak and random
- 604 CST states. Although this pattern of results was present for both L. FDI and L. APB muscles, it
- was only evident when evaluating the same stimulation intensity used to train personalized
- classifiers (i.e., 120% RMT). Additionally, personalized strong and weak CST states were
- 607 present ~35% and ~50% of the time, respectively, and typically lasted for ~1-2 seconds. Group-
- 608 level spectro-spatial differences in pre-stimulus EEG activity showed that whole-scalp theta
- 609 power and right centro-parietal alpha power were higher during personalized strong than weak
- 610 CST states. Overall, our results demonstrate the feasibility and efficacy of real-time
- 611 personalized brain state-dependent TMS targeting the human CST and are a key step towards
- 612 future interventional studies using this novel decoding-based brain stimulation technique.

613 Recent studies have shown that MEP amplitudes are ~10-20% larger during optimal than 614 nonoptimal sensorimotor rhythm phases (Bergmann et al., 2019; Ozdemir et al., 2022; Suresh & 615 Hussain, 2023; Zrenner et al., 2018), with some studies reporting no difference (Madsen et al., 2019b). In the current study, we trained personalized classifiers to discriminate between EEG 616 patterns during which TMS elicited large and small MEPs (i.e., personalized strong and weak 617 CST states) using single-pulse TMS-EEG-EMG datasets acquired from L. FDI at 120% RMT. 618 619 MEPs elicited in real-time at this same muscle and intensity were ~24% and ~43% larger than those elicited in real-time during corresponding weak and random CST states, respectively. The 620 621 magnitude of state-dependent MEP amplitude variation observed here exceeds that reported in previous phase-dependent single-pulse TMS studies. MEPs elicited from the L. APB muscle at 622 623 120% RMT showed a similar pattern of results (see Figure 4), indicating that classifiers trained 624 to identify personalized strong and weak CST states generalize across intrinsic hand muscles. 625 Given that the two muscles evaluated here are both functionally related (i.e., involved in 626 grasping behaviors) and topographically adjacent within the sensorimotor cortex, the personalized CST states targeted here either capture dynamic fluctuations in excitability of 627 functionally-coupled cortical muscle representations, spatially-coupled cortical muscle 628 representations, or both. In contrast, classifiers trained using TMS-EEG-EMG datasets acquired 629 630 at 120% RMT did not reliably elicit larger MEPs in real-time during personalized strong versus 631 weak or random CST states at 110% RMT. That is, personalized classifiers did not generalize 632 across stimulation intensities. This lack of generalization may be due to differences in the motor 633 cortical interneuronal circuits activated by TMS at 120% and 110% RMT. Given that higher 634 intensity TMS elicits a greater number of indirect waves as well as direct waves (Lazzaro et al., 2014), the personalized EEG patterns identified from our training dataset may be specific to the 635 636 precise combination of descending corticospinal volleys elicited at 120% RMT. Future studies could improve the flexibility and generalizability of machine learning-driven real-time EEG-TMS 637 638 by training personalized classifiers on TMS-EEG-EMG datasets acquired from multiple muscles 639 at multiple intensities.

640

To date, studies examining brain state-dependency of CST activation have either not reported trial-by-trial variation in MEP amplitudes across different brain states (Bergmann et al., 2019; Hussain et al., 2019; Thies et al., 2018; Wischnewski et al., 2022; Zrenner et al., 2018) or identified no differences (Ozdemir et al., 2022). Here, we show brain state-dependency of MEP amplitude variability for the first time, reporting that trial-by-trial variation in MEP amplitudes is significantly lower during personalized strong than weak CST states. In addition to more

647 strongly activating the CST, these findings suggest that TMS also more consistently activates 648 the CST when delivered during personalized strong CST states, which may benefit effect sizes 649 of future TMS interventions targeting these states. Surprisingly, however, MEP amplitude variability did not differ between strong and random CST states, nor did it differ between weak 650 and random CST states. This may be because we evaluated MEP amplitudes during random 651 CST states using conventional brain state-independent TMS, rather than a mixture of high and 652 653 low CST states. Consistent with reports that MEP amplitudes are less variable at higher 654 stimulation intensities (Darling et al., 2006; Schaworonkow et al., 2019), we observed that MEPs were less variable at 120% than 110% RMT. Finally, MEPs recorded from L. APB were more 655 656 variable than those recorded from L. FDI, likely because the scalp TMS site was optimized 657 based on L. FDI rather than L. APB responses.

658

The defining feature of brain state-dependent TMS interventions is that individual TMS pulses 659 660 are only delivered when the desired brain activity pattern is detected in real-time. As a result, the brain states targeted by such interventions must occur frequently enough that the desired 661 number of TMS pulses can be delivered within a feasible timeframe. When delivering real-time 662 663 single-pulse TMS during personalized strong and weak CST states in the current study, inter-664 stimulus intervals ranged on average between ~7-10 seconds. In addition to the frequency with 665 which personalized CST states occurred, these inter-stimulus intervals are directly influenced by 666 the minimum allowable inter-stimulus interval (here, 3 seconds) and the number of consecutive 667 CST states our real-time EEG analysis system required before TMS delivery (here, 10 668 consecutive states). To better quantify the temporal characteristics of personalized strong and 669 weak CST states without these methodological constraints, we applied each participant's 670 personalized classifier to their resting EEG data using a sliding window approach. This analysis revealed that the temporal characteristics of personalized strong and weak CST states did not 671 672 differ. On average, personalized strong and weak CST states were present 35-50% of the time and lasted for ~1-2 seconds; ~1 second elapsed between consecutive similar CST states. Thus, 673 674 personalized strong and weak CST states appear to be sufficiently frequent and adequately prolonged to be targeted with repeated TMS pulses during an intervention. To finely tune inter-675 676 stimulus intervals during TMS interventions, future studies can modify the number of 677 consecutive CST states that the real-time EEG analysis algorithm must detect before triggering 678 TMS pulses.

680 A major advantage of our approach is that it requires no prior knowledge regarding which EEG 681 activity patterns reflect strong versus weak CST activation in each participant. To characterize 682 the spectro-spatial EEG patterns present during personalized strong and weak CST states, we performed participant-specific contrasts between EEG power spectral activity recorded during 683 real-time targeting of strong and weak states. Consistent with our personalized approach, these 684 685 contrasts identified unique whole-scalp EEG activity patterns that discriminated between personalized strong and weak CST states in individual participants (see Supplementary Figure 686 3 for details). Given that whole-scalp EEG signals likely capture the influence of long-range 687 inter- and intra-hemispheric projections to motor cortical interneurons and CST neurons, whole-688 689 scalp EEG may be particularly useful for identifying personalized CST states. For example, 690 previous work suggests that long-range projections can modulate corticospinal output 691 (Bestmann & Krakauer, 2015), including those originating from the supplementary motor area (Arai et al., 2012), premotor cortex (Münchau et al., 2002), dorsolateral prefrontal cortex (Hasan 692 693 et al., 2013), and cerebellum and basal ganglia via thalamic nuclei (Sommer, 2003). Group-level 694 spectro-spatial characteristics revealed that right centro-parietal alpha power and whole-scalp 695 theta power were generally higher during personalized strong than weak CST states. The 696 centro-parietal alpha activity identified in the current study is broadly consistent with recent 697 reports that corticospinal output rhythmically fluctuates at alpha frequencies (Metsomaa et al., 698 2021) and relates to alpha activity near the stimulated cortex and parieto-occipital regions 699 (Ermolova et al., 2024). The consistency in these group-level findings across studies suggest 700 that the use of personalized classifiers to identify strong and weak CST states may not be truly 701 necessary, at least in healthy adults. To explore this possibility, we built a single non-702 personalized classifier that could discriminate between strong and weak CST states using TMS-703 EEG-EMG training datasets acquired from all participants. Surprisingly, the performance of 704 personalized and non-personalized classifiers did not differ, suggesting that personalization may 705 not be essential for brain state-dependent TMS in healthy adults. However, it is important to 706 note that the non-personalized classifier was trained using substantially more data than 707 personalized classifiers, which likely improved its performance. Further, this non-personalized classifier's ability to accurately identify CST states in real-time remains untested. Finally, a key 708 709 goal of brain state-dependent TMS is to improve the therapeutic efficacy of poststroke TMS 710 interventions. Given the heterogeneity of lesion characteristics (Chen et al., 2000; Luft et al., 2004; Shelton & Reding, 2001), recovery-related adaptive plasticity (Grefkes & Ward, 2014; 711 712 Stinear et al., 2007), and alterations in sensorimotor oscillatory dynamics after stroke (Hussain

et al., 2020; Johnston et al., 2023; Lopez-Larraz et al., 2017), personalized classifiers may be
essential for accurate poststroke brain state-dependent TMS.

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Limitations to this study also exist. First, therapeutic TMS interventions are often delivered over 716 717 multiple days, but the between-day generalizability of personalized classifiers developed here 718 has yet to be tested. Our method requires a large, participant-specific TMS-EEG-EMG training 719 dataset to build each participant's unique classifier and acquiring a new training dataset on each 720 treatment day is likely not clinically feasible. However, between-participant generalization of 721 machine learning classifiers used for brain-computer interfaces can be improved by using 722 advanced statistical matching procedures that do not require any calibration for each participant 723 (Kumar et al., 2024). Similar procedures could be applied to improve the between-day 724 generalizability of personalized classifiers developed here. Second, some participants showed poor state targeting accuracy for weak CST states, suggesting that weak states may be less 725 726 reliable than strong CST states. Although most therapeutic applications of the machine learning-727 driven TMS approach developed here are likely to focus on increasing CST transmission by targeting strong CST states, the stability and persistence of weak CST states requires further 728 729 investigation. Finally, the performance of the personalized classifiers developed here is lower 730 than reported in conventional brain-computer interface paradigms but is consistent with multiple 731 recent studies that used machine learning to identify EEG patterns reflecting strong and weak 732 CST states, both from our group (Hussain et al., 2022) and others (Ermolova et al., 2024; 733 Metsomaa et al., 2021). The overall higher performance of brain-computer interface classifiers 734 compared to our approach likely relates to the volitional modulation of EEG signals in such 735 contexts, typically via motor imagery (Perdikis & Millan, 2020; Tonin et al., 2022). Further, we 736 observed that classifier performance did not correlate with the difference in CST activation 737 between personalized strong and weak CST states. This lack of relationship may be caused by 738 variation in spinal motoneuron depolarization that is not represented within EEG signals. 739 Regardless, brain state-dependent TMS interventions are most effective when delivered during 740 EEG activity patterns associated with large MEPs (Baur et al., 2020; Zrenner et al., 2018), indicating that MEP amplitude differences between targeted CST states are likely more 741 742 important for inducing strong neuroplastic effects than classifier performance per se. 743 In conclusion, here we demonstrate for the first time that personalized brain activity patterns 744

reflecting strong and weak CST activation can be accurately captured in real-time using

746 machine learning-driven whole scalp EEG-triggered TMS in healthy adults. Specifically, we

- 747 report that CST activation was greater during personalized strong than weak and random CST
- states and was also more consistent during personalized strong than weak CST states.
- 749 Personalized strong and weak CST states lasted for ~1-2 seconds at a time and ~1 second
- rso elapsed between similar consecutive states, suggesting that personalized CST states could be
- repeatedly targeted with TMS during future interventional applications. Individual participants
- also exhibited unique spectro-spatial EEG patterns that differed between strong and weak CST
- states; these patterns are likely to be even more heterogeneous poststroke. Overall, our
- findings represent a key step towards using personalized brain state-dependent TMS
- techniques to characterize and promote poststroke CST function.

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