

Correlative light and electron microscopy reveals the fine circuit structure underlying evidence accumulation in larval zebrafish

Authors

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Abstract

Accumulating information is a critical component of most circuit computations in the brain across species, yet its precise implementation at the synaptic level remains poorly understood. Dissecting such neural circuits in vertebrates requires precise knowledge of functional neural properties and the ability to directly correlate neural dynamics with the underlying wiring diagram in the same animal. Here we combine functional calcium imaging with ultrastructural circuit reconstruction, using a visual motion accumulation paradigm in larval zebrafish. Using connectomic analyses of functionally identified cells and computational modeling, we show that bilateral inhibition, disinhibition, and recurrent connectivity are prominent motifs for sensory accumulation within the anterior hindbrain. We also demonstrate that similar insights about the structure-function relationship within this circuit can be obtained through complementary methods involving cell-specific morphological labeling via photo-conversion of functionally identified neuronal response types. We used our unique ground truth datasets to train and test a novel classifier algorithm, allowing us to assign functional labels to neurons from morphological libraries where functional information is lacking. The resulting feature-rich library of neuronal identities and connectomes enabled us to constrain a biophysically realistic network model of the anterior hindbrain that can reproduce observed neuronal dynamics and make testable predictions for future experiments. Our work exemplifies the power of hypothesis-driven electron microscopy paired with functional recordings to gain mechanistic insights into signal processing and provides a framework for dissecting neural computations across vertebrates.

42

43 Introduction

44 In natural environments, behaviorally relevant signals are often noisy, fragmented, or conflicting. To
 45 navigate this complexity and make reliable decisions, animals must continuously accumulate sensory
 46 information across space and time. This fundamental computation for selecting appropriate actions
 47 has been observed in a wide range of species including flies (Groschner *et al.*, 2018), fish (Bahl and
 48 Engert, 2020; Dragomir, Štih and Portugues, 2020), rodents (Hanks *et al.*, 2015) and primates (Katz
 49 *et al.*, 2016). A classic approach for studying this process is through random dot motion
 50 kinematograms, where some flickering dots move coherently while others are randomly redrawn
 51 across the visual field. This stimulus has been used alongside single-neuron and population-level
 52 recordings to reveal ramping neural responses, with slopes correlated with coherence levels,
 53 indicative of sensory accumulation of evidence (Newsome, Britten and Movshon, 1989; Hanks and
 54 Summerfield, 2017). Recent findings suggest that this integration is distributed throughout the
 55 mammalian brain, involving both cortical and subcortical regions (Brody and Hanks, 2016). However,
 56 the detailed architecture—both at the synaptic and whole-brain levels—that transforms noisy sensory
 57 input into discrete motor actions in vertebrates remains unclear.

58 The zebrafish larva (*Danio rerio*) also responds to random dot motion, accumulating visual
 59 evidence of self-motion before initiating stabilizing motor commands (Bahl and Engert, 2020;
 60 Dragomir, Štih and Portugues, 2020). Its compact brain and genetic amenability make it a powerful
 61 model for investigating neural computations using light microscopy, enabling whole-brain functional
 62 circuit dissection that is not feasible in larger vertebrates. Previous research has highlighted the
 63 anterior hindbrain, where neurons display calcium dynamics indicative of visual evidence
 64 accumulation, as a key computational hub for this process (Bahl and Engert, 2020; Dragomir, Štih
 65 and Portugues, 2020). Several network predictions have been proposed: hindbrain neurons
 66 accumulate pretectal (Pt) sensory input by recurrent connectivity of excitatory neurons, generating
 67 persistent activity (Yang *et al.*, 2023). Faster-dynamics neurons in this region were suggested to
 68 establish a decision boundary, filtering out low-quality stimuli by inhibiting premature motor activation
 69 (Bahl and Engert, 2020). Originating from this area, motor command neurons provide excitatory and
 70 inhibitory inputs to distinct pools of reticulospinal neuron subtypes, each tuned to specific movement
 71 directions, thereby selecting the appropriate motor output (Orger *et al.*, 2008; Kubo *et al.*, 2014;
 72 Naumann *et al.*, 2016).

73 Volumetric electron microscopy techniques have made it possible to map synaptic connectivity
 74 with remarkable resolution in several invertebrate and vertebrate species (Witvliet *et al.*, 2021; Svava
 75 *et al.*, 2022; Turner *et al.*, 2022; Schlegel *et al.*, 2024; Shapson-Coe *et al.*, 2024). In *Drosophila*, this
 76 connectomic data, when combined with complementary methods such as electrophysiology,
 77 optogenetics, and behavioral analysis, can refine models of neural networks (Turner-Evans *et al.*,
 78 2020; Ammer *et al.*, 2023), predict neural dynamics (Lappalainen *et al.*, 2024; Shiu *et al.*, 2024), and
 79 elucidate the mechanistic basis of behavior (Dombrovski *et al.*, 2023; Shiu *et al.*, 2024). In vertebrates,
 80 neurons with similar functions can be scattered across regions, making it difficult to test proposed
 81 wiring schemes through sparse connectivity sampling from separate animals. A prime example is the
 82 zebrafish pretectum, where binocular and monocular neurons are intermingled in a non-topographic
 83 organization (Kubo *et al.*, 2014; Naumann *et al.*, 2016). Recent advances in functional connectomics
 84 in this model organism—combining in vivo calcium imaging with subsequent electron microscopy in
 85 the same animal—have made it possible to directly link functional neuronal activity with its underlying
 86 synaptic connectivity (Wanner and Friedrich, 2020; Friedrich and Wanner, 2021; Vishwanathan *et al.*,
 87 2024). This approach offers unprecedented insights into how connectomic motifs support neuronal
 88 responses, sensory processing, and ultimately behavior in the vertebrate brain.

Here, to unravel the circuit-level mechanisms of sensory evidence accumulation, we applied functional connectomics to the zebrafish hindbrain. We reconstructed 84 functionally identified neurons and 165 synaptic partners. Cellular-resolution volumetric registration to a common reference brain and cross-modality comparisons enabled us to refine and explicitly test previously proposed connectivity motifs (Naumann *et al.*, 2016; Bahl and Engert, 2020; Dragomir, Štih and Portugues, 2020). Our findings highlight recurrent connectivity and interhemispheric inhibition as fundamental motifs for sensory evidence accumulation, a structure reminiscent of a line attractor (Seung, 1996; Khona and Fiete, 2022). Moreover, we identified ipsilateral disinhibitory inputs from a small population of transiently active neurons. We propose that this disinhibition motif may play a key role in endowing the network with the ability to respond to a rapidly changing sensory environment while maintaining its ability to slowly filter relevant cues from noisy signals.

We complement our electron microscopy dataset by a library of functionally identified cell morphologies obtained through a two-photon-guided labeling strategy. Using such detailed structure-to-function knowledge, we further train a classifier algorithm, allowing us to predict functional properties based on neuronal morphology only. This approach enhances the utility of previously acquired EM datasets by enabling connectomic analysis of sparse neuronal circuits even in the absence of calcium imaging. While in the past we had proposed a potential network structure of the anterior hindbrain purely based on functional imaging, we can now constrain models using ground truth structural information. Our updated network model reproduces the experimentally observed neuronal dynamics and makes explicit predictions for new experiments to further probe circuit structure and function. These advances not only deepen our mechanistic understanding of vertebrate sensory-motor transformations but also establish a general new framework for applying connectomics to diverse neural circuits across species.

Results

Correlative electron and light microscopy in a neural circuit performing motion integration

To explore the relationship between structure and function in the anterior hindbrain, we first identified neurons based on their functional dynamics using two-photon calcium imaging (**Fig. 1a**, (Bahl and Engert, 2020)). To that end we used 7 days post-fertilization (dpf) transgenic larvae expressing a nuclear calcium indicator (Dana *et al.*, 2019) under the *elavl3* pan-neuronal promoter and red markers in the main inhibitory neuronal subtype (Satou *et al.*, 2013) as well as in vascular endothelial cells (Fujita *et al.*, 2011), *Tg(elavl3:H2B-GCaMP7f, gad1b:DsRed, kdr1:mCherryCAAX)*. We recorded neuronal responses evoked by left- and rightward moving dots of 100% coherence in six optical planes spaced by 12 μm along the dorso-ventral axis in a region spanning from the medial optic tectum to the caudal hindbrain. We performed 2D segmentation of the time-averaged recordings using a convolutional neural network (Weigert *et al.*, 2020) to obtain neuron-specific masks (**Methods**). While many diverse neurotransmitter types exist (Higashijima, Mandel and Fetcho, 2004), the transgenic *Gad1b+* label allowed us to assign inhibitory identity to cells, as GABA is the main inhibitory neurotransmitter in the zebrafish brain (Filippi, Mueller and Driever, 2014). Neurons displayed similar calcium dynamics as previously reported (**Extended Data Fig. 1a**, (Bahl and Engert, 2020)). Unbiased clustering revealed three main functional cell types. Based on their dynamics we named these cells motion integrator (MI), motion onset (MON), and slow motion integrator (SMI) neurons (**Fig. 1b**, **Extended Data Fig. 1a,b**, and **Methods**). Previously, we used labels based on the potential functional role of these cells (evidence integrator, dynamic threshold, and motor command neurons, respectively) during sensory-motor decision-making (Bahl and Engert, 2020). Out of 15017 functionally imaged neurons, we found 618, 108, and 339 neurons of each type, respectively with the largest fraction located in the anterior hindbrain (62%: 358, 24, and 275 neurons of each type, respectively, **Extended Data Fig. 1c** and **Methods**) but also located in the pretectum (Pt), midbrain

(Mb) and cerebellum (Cb) as well as other regions. Previous work suggests that the anterior hindbrain performs temporal integration of direction-selective pretectum whole-field motion inputs (Bahl and Engert, 2020). Compatible with these previous observations, we found that a large fraction of neurons in the anterior hindbrain were direction selective (DS) (75.6% of neurons had an absolute DS index > 0.5, **Extended Data Fig. 1d**) with generally slower dynamics than their pretectum and midbrain counterparts (**Extended Data Fig. 1e**).

Using the same larva, we performed bilateral enucleation to facilitate fixative diffusion and enhance ultrastructure and extracellular space preservation followed by a modified rOTO (reduced osmium tetroxide-thiocarbohydrazide-osmium) EM staining protocol (Tapia *et al.*, 2012; Hua, Laserstein and Helmstaedter, 2015) (**Methods**). We identified the region containing most of the neurites of the functional neuronal types using sparse hindbrain electroporations (Boulanger-Weill *et al.*, 2017) and c3pa-GFP photoactivation (Förster *et al.*, 2018) (**Extended Data Fig. 2a,b**) in separate age-matched larvae. We also performed X-ray computed tomography to ensure staining homogeneity and tissue integrity, and target the sectioning to specific neuronal circuits (**Extended Data Fig. 2c–g**). We then collected 4010 coronal sections using an automated tape ultra-microtome (Hayworth *et al.*, 2014) and performed multi-beam scanning EM (mSEM) at 4 x 4 x ~30 nm resolution (~416 x 265 x 112 μm , spanning from the medial midbrain to rhombomere 3, **Fig. 1d**) totaling 51.4TB of imaging data (**Methods**). Volumetric nanometer-precise alignment and connectome reconstruction were performed via a series of largely automated workflows, enabling high-quality neuronal morphology reconstruction ((Turner *et al.*, 2022), **Methods**). To find single-cell correspondences between two-photon and EM imaging, we performed registration using manually placed corresponding landmarks ((Bogovic *et al.*, 2016), **Methods**). This strategy yielded single-cell precision registration even in dense, low-contrast regions of the brain (**Fig. 1e** and **Extended Data Fig. 2h**). Fluorescently labeled blood vessels—which were not used as landmarks for the registration—allowed us to independently confirm the quality of the mapping (**Extended Data Fig. 2h**). Finally, the EM and registered two-photon datasets were uploaded into an online browsing platform (Dorkenwald *et al.*, 2023), enabling collaborative proofreading of morphology and connectivity of functionally identified neurons (**Methods**).

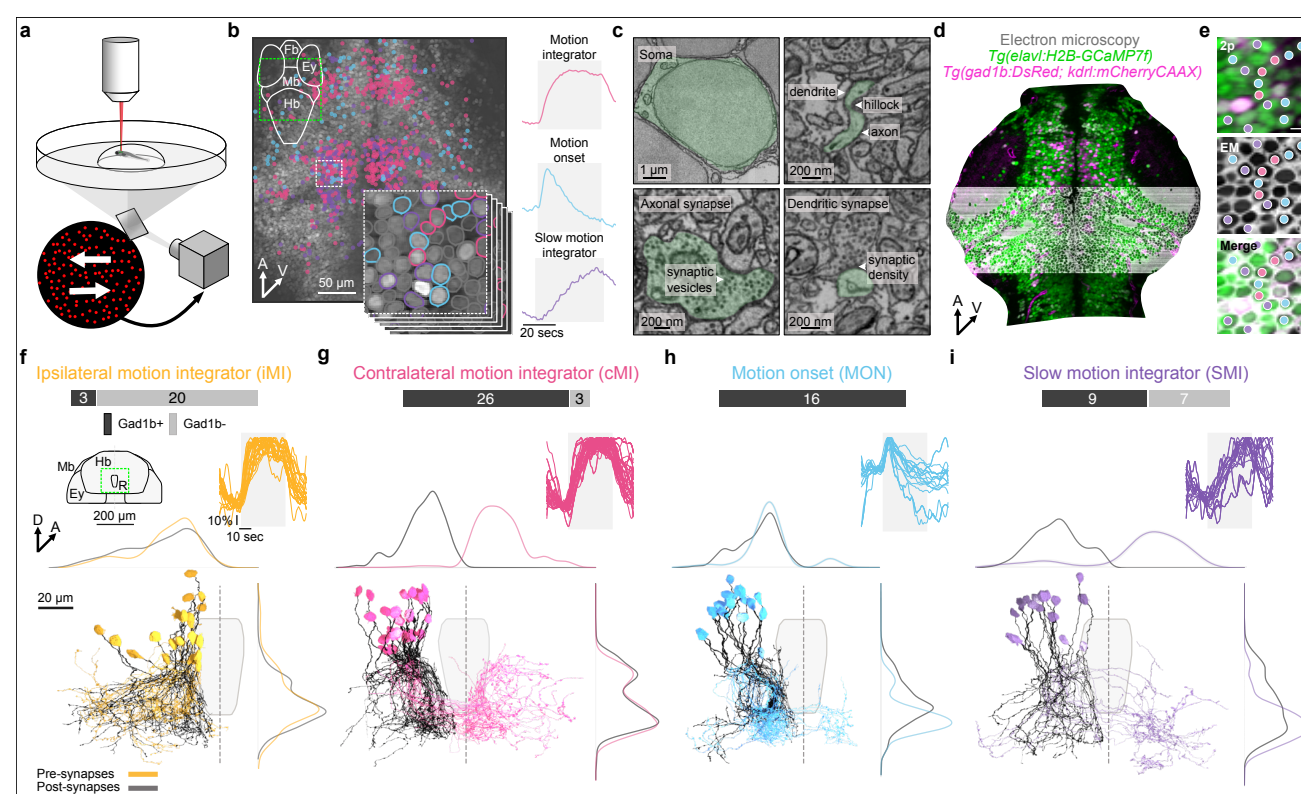


Fig. 1 | Correlative light and electron microscopy of neurons involved in motion evidence integration. **a**, Schematic of the two-photon imaging setup showing the bottom projection of coherently moving random dots. **b**, Left: spatial distribution of clustered neurons. The background grayscale image represents the average of the six functionally imaged planes. Top-left schematic shows coarse brain organization (dorsal-to-ventral view) and the location of the functionally imaged area (green dashed square). The white dashed square is magnified in the bottom-right snippets, which depict individual planes and are also shown in **(e)**. Neurons are circled based on their functional types, while non-clustered neurons are circled in gray. Right: normalized K-means-based regressors used for neuron clustering. Stimulus consists of 0%, 100% (gray shaded area), and 0% coherence. **c**, EM ultrastructural details of a reconstructed neuron. **d**, Single plane of the two-photon image stack mapped to the EM dataset. Magenta shows inhibitory neurons (Gad1b+) and blood vessels (kdr1+). Green shows nuclear-localized GCaMP7f. Gray indicates the EM dataset. **e**, Detailed alignment between the two-photon imaging (2P) and EM datasets. Scale bar: 5 μ m. Neurons from the clustered populations are indicated by colored dots. **f**, Structure-function relationship of functionally imaged and reconstructed neurons in tail-to-head view. Top: distribution of neurotransmitter identity shown as Gad1b-positive (likely inhibitory, black) or Gad1b-negative (presumably excitatory, gray). Left: schematic showing coarse brain organization and location of the reconstructed neurons below (green dashed square) surrounding outlines of the raphe (also shown below). Right: traces representing the normalized $\Delta F/F_0$ neuronal activity over time for motion in the preferred direction. Bottom: reconstructed ipsilateral motion integrator (iMI) neurons with somas and axons in orange and dendrites in black. The dashed line represents the midline. Surrounding plots are distributions of presynaptic (orange) and postsynaptic (black) synapses along the x (top) and y (right) axes. **g–i**, show identical representation for other neuron types. Abbreviations: Mb, midbrain; Hb, hindbrain; R, raphe; Ey, eye; A, anterior; D, dorsal; V, ventral. Neuron-type names, their abbreviations, and associated colors are used throughout the paper.

Structure-function relationship of functionally identified neurons

Stereotypy is a core feature of vertebrate and invertebrate brains, rooted in genetic templates and consistent environments. However, it varies among neighboring microcircuits, meaning that the brain is not strictly composed of homogeneous, repeating units (Silberberg, Gupta and Markram, 2002). Instead, a flexible template enables diverse microcircuits to meet distinct functional demands across brain regions both at the morphological and connectomic levels. For example, *Drosophila* neurons show stereotyped yet variable cell and synapse numbers across hemispheres (Bates *et al.*, 2020; Schlegel *et al.*, 2021), and human neurons show morphological diversity across brain regions, age and gender (Han *et al.*, 2023). In the zebrafish optic tectum, neurons with similar transcriptional profiles can vary in shape, connectivity, and visual responses (Shainer *et al.*, 2025) suggesting a weak structure-to-function relationship in this region. To explore this aspect in the anterior hindbrain we reconstructed 52 MI neurons, 16 MON neurons, and 16 SMI neurons (located in rhombomeres 1–3) and identified their neurotransmitter identity (**Fig. 1f–i** and **Extended Data Fig. 3a–d**). To probe the connectivity of functionally identified neurons we trained convolutional neural networks to automatically detect synaptic clefts and assign presynaptic and postsynaptic partner neurons ((Macrina *et al.*, 2021), **Methods** and **Extended Data Fig. 4a–f**).

All of these neurons were unipolar, with the axon emerging from a primary dendrite projecting ventrally, a structure reminiscent of invertebrate neurons (Dorkenwald *et al.*, 2024; Schlegel *et al.*, 2024). We observed distinct patterns among the different neuron types: ipsilateral-projecting MI (iMI) neurons were predominantly Gad1b- (20/23), while contralateral-projecting MI (cMI) neurons were mostly Gad1b+ (26/29). MON neurons were exclusively Gad1b+ and primarily contralateral-projecting (12/16), whereas SMI neurons exhibited a mix of neurotransmitter and projection types, including 4 ipsilateral-projecting Gad1b+ neurons and 12 contralateral-projecting neurons (9 Gad1b+ and 3 Gad1b-) (**Fig. 1f–i**). iMI neurons were generally positioned closer to the midline compared to other types, with overlapping axons and dendrites; some axons extended beyond the volume caudally, rostrally, or both (**Fig. 1f** and **Extended Data Fig. 3a**). In contrast, cMI neurons were located more lateral, displaying clustered dendrites adjacent to the raphe, and had only a few axons leaving the volume (**Fig. 1g** and **Extended Data Fig. 3b**). MON neurons showed tightly clustered dendrites and axons (**Fig. 1h** and **Extended Data Fig. 3c**) with the majority of axonal synapses located on the

ipsilateral side. SMI neurons had more dispersed dendrites and axons along both the dorso-ventral and rostro-caudal axes (**Fig. 1i** and **Extended Data Fig. 3d**).

To quantify neuronal similarity we computed the NBLAST scores within and in-between neuronal types using previously established methods (Costa *et al.*, 2016) and a zebrafish neuron-specific calibration (**Methods**). NBLAST enables the clustering of vertebrate and invertebrate neurons based on their position and local geometry (Costa *et al.*, 2016). We found that NBLAST scores were not consistently higher within functional types than across functional types (**Extended Data Fig. 3e,f**) indicating that this metric does not reliably predict function from morphology alone. In summary, aside from MON neurons, functionally defined neurons that contribute to motion evidence accumulation in larval zebrafish exhibit loose morphological stereotypy and diverse morphological identities.

Distinct connectivity motifs across functionally identified neurons in the anterior hindbrain

Starting with the 84 functionally identified neurons, we automatically identified a total of 3,218 post-synapses (inputs) and 2,126 pre-synapses (outputs) (**Methods** and **Extended Data Fig. 4a–e**). Among these, 9.59% of randomly selected connected segments were successfully reconstructed (dendrites leading to a soma, or axons leading either to a soma or to the edge of the volume), resulting in the identification of 165 additional partners: 38 truncated axons and 127 neurons that had not been functionally imaged (**Fig. 2a**). To investigate connectivity motifs we generated a connectivity matrix that included only functionally identified neurons (**Fig. 2b**) and complemented it with truncated axonal partners terminating within the volume (**Extended Data Fig. 4f**). Distinct connectivity patterns emerged for each neuron type, both at the input and output levels (**Fig 2b–j** and **Extended Data Fig. 4f–n**).

iMI neurons broadly targeted all functional types with a strong preference for MON neurons (35% of synapses, **Fig. 2c**). Notably, approximately 6% of the output synapses targeted iMI neurons, suggesting recurrent connectivity within this neuronal subtype. Additionally, a large fraction of the inputs originated from either the rostral end of the imaged volume or from cMI neurons (22% each, **Fig. 2d** and **Extended Data Fig. 4g**). Previous studies have demonstrated co-activation of anterior hindbrain and pretectum neurons during whole-field visual motion, supporting the existence of anatomical connectivity between these regions (Naumann *et al.*, 2016; Chen *et al.*, 2018). While contributions from other areas cannot be excluded, our findings are consistent with the idea that iMI neurons temporally integrate inputs coming from the pretectum and then relay such signals to other neuron types in the anterior hindbrain.

cMI neurons inhibited all functional types on the contralateral side except MON neurons with a strong bias towards iMI and cMI neurons (22% and 16% respectively, **Fig. 2e**). They received similar amounts of disinhibitory ipsilateral inputs from MON neurons on the ipsilateral side, caudal axonal inputs and disinhibitory inputs from cMI cells on the contralateral hemisphere (15%, 18% and 13% respectively, **Fig. 2f** and **Extended Data Fig. 4h**). These observations provide anatomical confirmation of predicted interhemispheric inhibition within the anterior hindbrain refining turning behavior by processing pretectal inputs (Naumann *et al.*, 2016).

MON neurons targeted cMI neurons ipsilaterally in a disinhibitory manner (18%, **Fig. 2g** and **Extended Data Fig. 4i**) and received mixed inhibitory and excitatory inputs originating from other cells within the anterior hindbrain (41%, **Fig. 2h** and **Extended Data Fig. 4i**).

SMI neurons predominantly targeted caudally projecting neurons with myelinated axons (35%, both ipsilaterally and contralaterally, **Fig. 2i** and **Extended Data Fig. 4j**), suggesting that this cell type might have a role in motor execution—as we have previously proposed (Bahl and Engert, 2020). Consistent with this, one excitatory ipsilateral SMI neuron targeted three Rov3 reticulospinal neurons (**Fig. 2i**, and **Extended Data Fig. 4j,o**), a subtype implicated in lateralized responses to whole-field

motion (Orger *et al.*, 2008). SMI neurons received the greatest diversity of inputs, in nearly equal proportions: rostral axonal inputs (12%), caudal axonal inputs (9%), excitation from iMI neurons (7%), ipsilateral inhibition from MON neurons (7%), and contralateral inhibition from cMI neurons (9%, **Fig. 2j** and **Extended Data Fig. 4j**). Interestingly, we did not find any statistical differences between pre- and post-synapses sizes across functionally identified cell types (**Extended Data Fig. 4p,q**), suggesting balanced functional connection weights (Holler *et al.*, 2021) across cell types in the anterior hindbrain.

In summary, our sparse connectomic reconstructions in the hindbrain support a network model of bilateral inhibition across hemispheres mediated by cMI neurons, ipsilateral disinhibition driven by MON neurons, recurrent connectivity within iMI neurons, and direct inputs from SMI neurons to reticulospinal neurons, which drive lateralized movements. To provide the broader scientific community with an online platform to browse neurons from connectomic analyses, we further developed an open-source atlas containing molecular labels and anatomic regions (**Extended Data Fig. 5**, (Vohra *et al.*, in preparation)) to which we uploaded all reconstructed neurons and axonal segments (connected to functionally identified inputs and output partners).

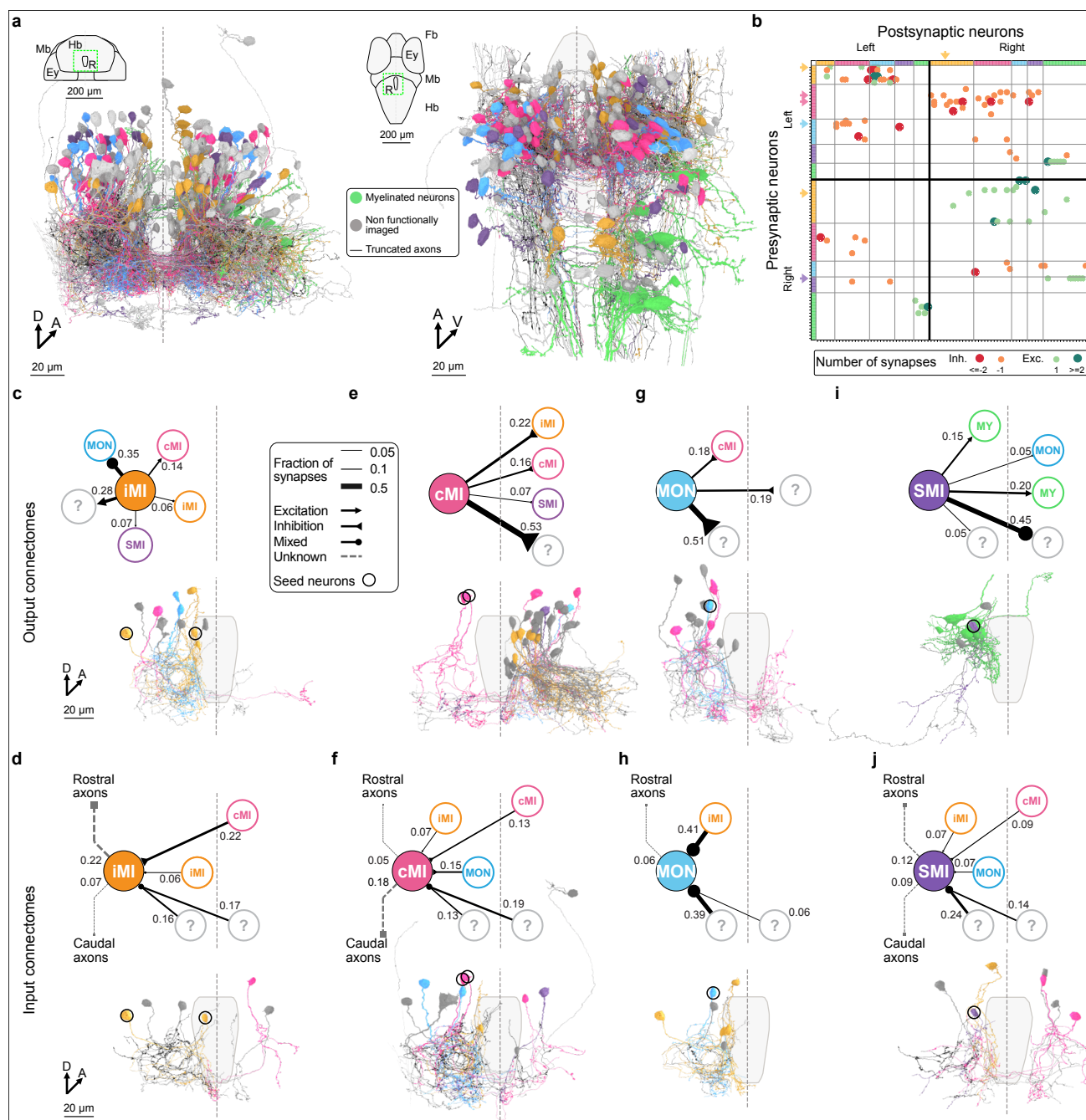


Fig. 2 | Connectomic analyses of functionally identified neuronal subtypes. **a**, All neurons reconstructed in this study: 84 functionally imaged neurons and connected partners: 38 truncated axons and 127 not functionally imaged neurons. Left panel: tail-to-head view, right panel: dorsal view. Top schematics show coarse brain organization and location of the reconstructed neurons below (green dashed square) surrounding outlines of the raphe (also shown below). **b**, Connectivity matrix with neurons sorted according to their functional types and hemispheres (thick black bars). Output (**c,e,g,i**) and input (**d,f,h,j**) connectomes. Top diagrams: Simplified connectivity motifs extracted from the connectivity matrix. Connections accounting for less than 5% of the total synapse number are not shown. Question marks represent non-functionally imaged neurons. The dashed line indicates the midline. Bottom: Representative example connectomes (tail-to-head view) for one or two seed cells. All neuronal parts (some, axon, and dendrites) are colored with the same color. Abbreviations: Mb, midbrain; Hb, hindbrain; R, raphe; Ey, eye; A, anterior; D, dorsal; V, ventral.

Two-photon-guided characterization of function, anatomy, and neurotransmitter identity

Many existing anatomical resources (Kunst *et al.*, 2019; Vishwanathan *et al.*, 2024) do not contain functional information about cell morphologies, limiting their usability for neural circuit dissections. Even for our CLEM dataset, time considerations during the initial two-photon imaging session limited

the acquisition of neural activity to only a few planes. Such data subsampling leads to a considerable fraction of reconstructed partners for which functional information is missing. To assign functional labels to these neurons, we sought to train classifiers to predict neuronal functional types based on morphology. In the ideal situation, such classifiers may even be trained and tested purely based on light microscopy experiments, providing a powerful strategy to enhance any, not just our current, EM- and light-based library of anatomical reconstructions. Our CLEM dataset provides a unique ground truth dataset for understanding the relationship between structure and function across anterior hindbrain cell types, allowing us to rigorously validate such classifiers.

Using two-photon excitation of photoactivatable GFP (Patterson and Lippincott-Schwartz, 2002; Förster *et al.*, 2018), we reconstructed the anatomy of functionally characterized neurons (Kramer *et al.*, 2019). We combined this approach with *in-situ* RNA hybridization, HCR FISH (Choi *et al.*, 2018), employing *gad1b* and *vglut2a* probes to selectively label GABAergic (inhibitory) and glutamatergic (excitatory) neurons, respectively (**Fig. 3a**). This strategy was applied across 47 larvae to generate a comprehensive multi-feature neuronal library that links functional dynamics, anatomy, and neurotransmitter identity—purely based on light microscopy experiments (**Fig. 3b–e**). Neuron functional types were determined through clustering analysis consistent with our CLEM experiment (**Fig. 1b, Methods**). Remarkably, the patterns observed in these experiments closely mirrored results from our CLEM dataset (compare **Fig. 3b–e** and **Extended Data Fig. 6a–d** with **Fig. 1f–i** and **Extended Data Fig. 3a–d**), validating the two approaches across multiple animals and imaging modalities.

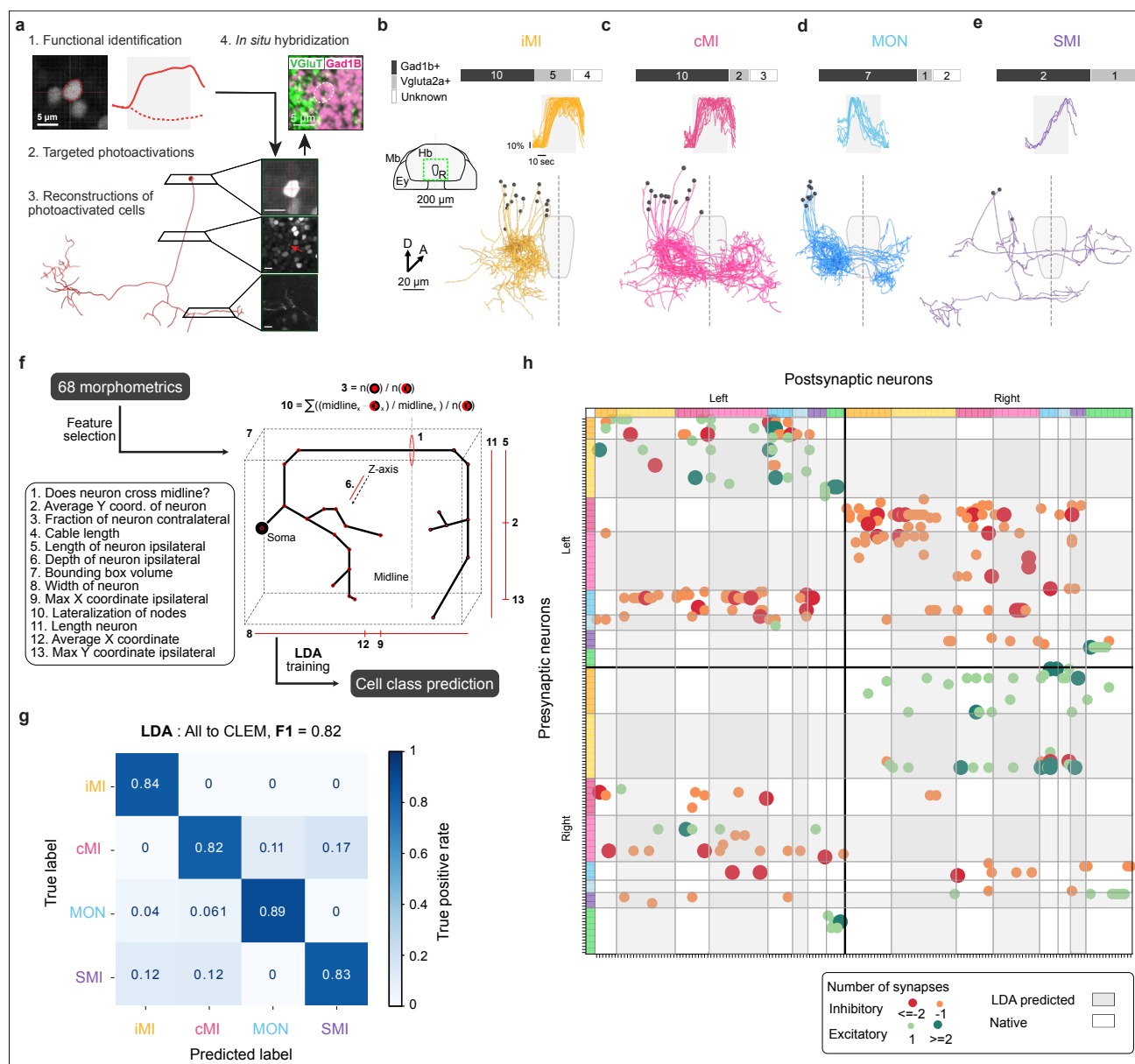


Fig. 3 | Single cell photoactivation and functional types predictions across datasets. **a**, Schematic of the functional identification process followed by single-cell photoactivation, *in situ* hybridization, and manual morphological reconstruction. **b**, Structure-function relationship of functionally imaged and photoactivated iMI neurons. Top: distribution of neurotransmitter identity shown as Gad1b-positive (black), Vglut2a-positive (gray) or unknown (white). Left: schematic showing coarse brain organization (tail-to-head view) and location of the reconstructed neurons below (green dashed square) surrounding outlines of the raphe (also shown below). Right: traces representing the normalized $\Delta F/F_0$ neuronal activity over time. Bottom: reconstructed iMI neurons with somas in black. The dashed line represents the midline. Abbreviations: Mb, midbrain; Hb, hindbrain; R, raphe; Ey, eye; A, anterior; D, dorsal; V, ventral. **c–e**, identical representation for other neuron types. **f**, Schematic of the features selection used for the linear discriminant analysis (LDA) to predict functional cell types. **g**, LDA confusion matrix of true positive rate using CLEM and photoactivated neurons as the ground truth and predicting CLEM cells. The prediction performance F1-score for the entire matrix is indicated in the plot title. **h**, Classifier-enhanced connectivity matrix of reconstructed EM neurons, sorted according to their functional types and hemispheres (thick black bars). The background of columns and rows of neurons whose functional type has been predicted through LDA are shaded in gray.

Structure-to-function classification

Our joint photoactivation and CLEM datasets comprise a library of 131 cells (42 iMI, 44 cMI, 26 MON, and 19 SMI), establishing a direct link between structure, function, and neurotransmitter identity. This dataset can serve as ground truth for training a classifier. Using a linear discrimination analysis

approach (LDA), we fitted a model that correlates morphological features with functional neuron type. LDA is a statistical method used for dimensionality reduction and classification, identifying a linear combination of features that optimally separates two or more classes by maximizing variance between classes while minimizing variance within classes. Analysis of the model parameter contribution (**Methods**) suggested that only a few metrics had strong predictive power (**Fig. 3f–g** and **Extended Data Fig. 6e, Methods**). Applying a cross-validation holdout strategy (**Methods**), we achieved a classifier predictive performance of 0.82 (F1-scores, **Fig. 3g**). This result indicates that our classifier can reliably predict the functional type of a neuron based solely on its morphology, even for cells it had not encountered during training. We further tested the classifier’s performance with smaller datasets, using cells from either the photoactivation experiments or our CLEM library. We still achieved predictive performance above 0.74 (F1-scores, **Extended Data Fig. 6f**). Remarkably, when training our classifier only on photoactivated cells and testing it on our CLEM ground truth library, we maintained an F1-score of 0.76 (**Extended Data Fig. 6f**). These findings demonstrate that a classifier exclusively trained on light microscopy experiments can provide a generalizable, powerful, and cost-effective method for functionally labeling neurons in morphological libraries where functional imaging is absent, largely benefiting our current EM dataset, as well as other existing resources. We benchmarked our approach against other established methods (Li *et al.*, 2017; Choi, Kim and Hyeon, 2023) and found that our method consistently outperformed them in predictive accuracy (**Extended Data Fig. 6g–i**).

Enhancing the CLEM dataset

A direct application of this approach is the enhancement of our correlated light and EM dataset. Within this dataset, we identified 108 pre- and postsynaptic reconstructed unmyelinated neurons that we had not functionally imaged during our initial two-photon session (**Fig. 1a, Fig. 2a**). Using our trained classifier, we predicted the functional types of 78.7% of the non-functionally imaged neurons, considerably enriching our library with additional labels, which allowed us to further populate the synaptic connectivity matrix of the anterior hindbrain (**Fig. 3h** and **Extended Data Fig. 7a–i**). Notably, the overall connectivity arrangement remained almost identical, confirming that our original dataset contains a representative subset of functionally imaged cells. These results also indicate that our classifier can generate similar conclusions about the structure and function relationship of neural networks compared to what is achievable with CLEM.

An anatomically and functionally constrained circuit model of a flexible neural integrator

We had previously proposed a neural circuit arrangement of the anterior hindbrain, in which temporal integration of motion evidence may be implemented via recurrent connectivity of integrator cells. These cells, we suggested, compete with a transiently active pool of inhibitory neurons, together initiating swimming decisions when excitation overcomes inhibition (Bahl and Engert, 2020). While in our previous model, we speculated about connectivity purely based on functional imaging, we now have detailed ground truth connectivity information by the identified EM connections of functionally identified cells (**Figs. 2** and **3**). To keep our new model tractable, we focused our analyses on the major contributors within the circuit, only considering identified connections constituting at least 10 % of the input or output synapses (**Fig. 2c–j** and **Extended Data Fig. 7**). We assigned excitatory and inhibitory labels based on the observed majority of connection types (**Figs. 1f–i** and **3b–e**). The resulting network connectivity matrix (**Fig. 4a**), allowed us to draw a putative circuit arrangement of the anterior hindbrain involved in the integration of visual motion cues and sensory-motor control (**Fig. 4b**). Key elements of this circuit arrangement are recurrent connectivity of excitatory iMI neurons (iMI⁺), implementing the temporal filtering of incoming input signals from the pretectum, delayed feedforward inhibition of MON cells, via inhibitory iMI neurons (iMI[−]), disinhibition of inhibitory cMI cells

(cMI⁻) via MON neurons, as well as interhemispheric inhibition via cMI⁻ cells. Based on the identified axons projecting from the rostral part into the circuit (**Extended Data Fig. 7a**), we modeled input to the circuit as excitatory connections from the pretectal region onto iMI⁺ and MON.

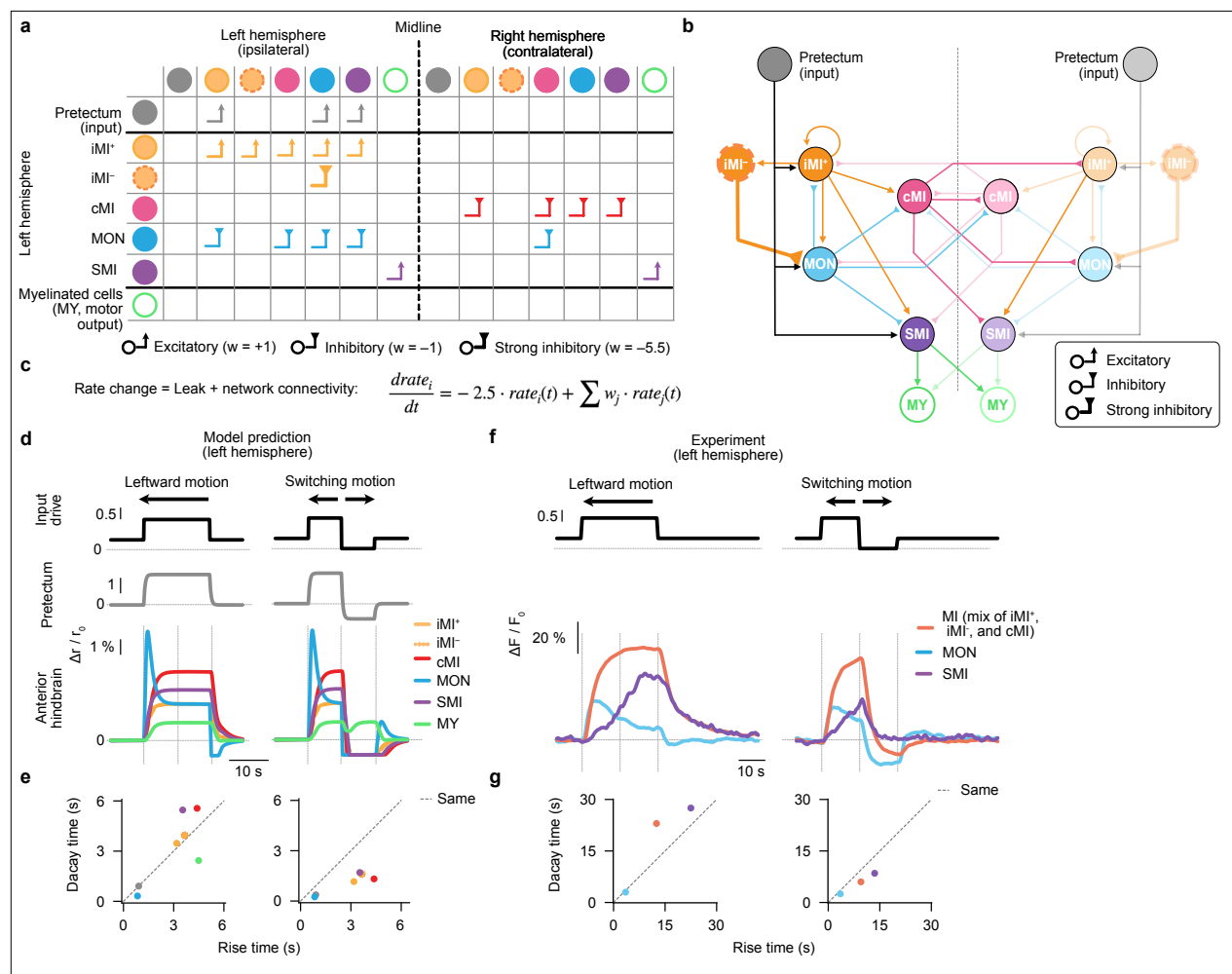


Fig. 4 | A connectome-constrained neural network model of the anterior hindbrain. **a**, Summary matrix of all identified connections with at least 10 % connectivity probability, based on our CLEM analyses. For simplicity, only connections originating on the left hemisphere are displayed. For neurons on the right hemisphere, the matrix is identical. Excitatory and inhibitory connections are indicated by arrowheads and triangles, respectively. **b**, Network model following the same connection scheme as in (a). **c**, Differential equation for neuron i . The full model contains 14 units (7 on each hemisphere, **Methods**), following connectivity weights w_j shown in (a), with equivalent leak factors (-2.5) across all cell types. **d**, Simulation results for two different stimulus configurations (leftward motion, left plot; switching motion, right plot). The input drive represents the stimulus direction on the left eye (positive for leftward motion, and slightly below baseline for rightward motion). Gray and colored lines indicate the dynamics of units on the left hemisphere. Responses on the contralateral hemisphere are in **Extended Data Fig. 8a**. **e**, Rise and decay times (**Methods**) of cell types for different stimulus configurations. When the direction suddenly changes for the switching motion stimulus (right plot), integrator cells turn off more rapidly than if the motion just stops (left plot). **f**, New two-photon imaging experiment following visual stimulation protocol in (d), showing average traces for each functional cell type (trial-, fish-, and cell-averaged, $n=4$ fish, 2 planes per fish, and 12 trials per plane). **g**, Same as in (e), but for experimental data. Decay dynamics of MI and SMI are faster for the switching motion stimulus (right plot) compared to when motion just stops (left plot).

In principle, the weight of all identified connections (= 144), the passive membrane biophysics, such as its leak constant (= 14)—or even complex activity-dependent conductances and plasticity features—of each cell type may be free model parameters and could be tuned to obtain the experimentally observed dynamics. We wanted to know to what extent a model behaves where these parameters are largely fixed. Given the observed equal distribution of synapse sizes (**Extended Data**

Fig. 4p,q), we chose the same weights in the network across cell types (see **Methods** for parameter choice). Assuming that all cells have the same membrane properties, we chose identical leaks across the network. Model simulations revealed dynamics resembling the ones observed in experiments (compare **Fig. 4d**, left with **Figs. 1f–i** and **3b–e**): For leftward motion, integrator cells in the left hindbrain had slower onset and offset dynamics than neurons in the simulated pretectum and MON neurons showed their characteristic transient response at the start of motion. On the contralateral hemisphere, model integrator cells showed clear motion opponent inhibition, with MON neurons rebounding at stimulus offset, also matching experiments (compare **Extended Data Figs. 8a** and **1f**, and (Bahl and Engert, 2020)). We further quantified the relationship between onset and offset dynamics for each cell type (**Fig. 4e**, left), revealing a mostly linear relationship, as expected from integrators with low-pass filter dynamics. The good qualitative agreement between our CLEM-constrained network model and our imaging data adds confidence that the proposed connectivity structure may indeed represent an important functional circuit motif in the anterior hindbrain.

After showing that our model can match the known activity dynamics in the anterior hindbrain, we sought to further challenge and validate our model by explicitly testing some of its predictions on new experimental data. We presented the model with a stimulus in which motion direction abruptly changes from leftward to rightward motion—a configuration that we had not previously used when developing our experimental and modeling pipelines (**Fig. 4d**, right). Our model predicted a rapid state-switching across hemispheres upon direction change, with faster offset dynamics than if motion just stops (compare **Fig. 4e**, left, and right). We next probed these predictions via two-photon imaging (**Fig. 4f**). We presented larvae with the same stimuli as in our model and classified neurons based on the response dynamics to the stimulus continuously moving in one direction (same regressors as in **Fig. 1b**, **Methods**). The location of resulting cell types in the brain resembled the known distribution pattern (compare **Extended Data Fig. 8d** and **Fig. 1b**). Across stimuli, response dynamics in the experiment closely resembled model predictions. Quantification of onset and offset times (**Fig. 4g**) showed that MI neurons turn off faster for switching motion, compared to when motion just stops, hence also agreeing with our model predictions (**Fig. 4e**).

Based on our circuit model, we further argued that the inhibitory signal of the transiently active MON cells on the contralateral side (**Extended Data Fig. 8a**) at such transition points may be responsible for the observed dynamics. Its transient activation via pretectal input may rapidly release inhibition via cMI neurons, thus switching off the contralateral hemisphere. To test these ideas, we used our model to clamp the activity rates of MON neurons on both hemispheres to zero (**Extended Data Fig. 8b**). Such an experiment would be challenging to do in real larval brains, given the number and sparse distribution of MON cells. Model manipulation with silenced MON neurons predicted faster integration across the network. It also largely abolished the difference between onset and offset times (**Extended Data Fig. 8c**), suggesting that MON neurons indeed seem to mediate these dynamics.

In summary, we find that our CLEM-constrained circuit model of the anterior brain can reproduce our experimentally observed dynamics of motion-sensitive cells in the anterior hindbrain. When motion direction abruptly changes, which is a realistic situation in natural environments, our model proposed that MON neurons allow the system to rapidly switch states, flexibly endowing the circuit with both slow integration capabilities and fast response times.

Discussion

In this study, we combined functional calcium imaging and electron microscopy to elucidate the circuit architecture underlying sensory evidence accumulation in the larval zebrafish anterior hindbrain. Although this dual approach has already been used (Briggman, Helmstaedter and Denk, 2011; Lee *et al.*, 2016; Vishwanathan *et al.*, 2017; Bae *et al.*, 2018; Wanner and Friedrich, 2020) we demonstrate its feasibility in a large inter-hemispheric vertebrate brain network (**Fig. 1**). Moreover, we use CLEM

as a tool to test and update existing hypothetical circuit models with anatomical information, which we then validate with new experiments. This allows us to refine existing hypotheses (Bahl and Engert, 2020; Dragomir, Štih and Portugues, 2020) regarding how neuronal connectivity supports the accumulation of visual motion cues over time.

Our findings provide the first mechanistic insights into how evidence accumulation of noisy visual motion cues is implemented within a recurrent neural network at the synaptic level. We identify interhemispheric inhibition and recurrent connectivity as key motifs of this circuit, a structure reminiscent of a line attractor (Seung, 1996; Khona and Fiete, 2022) (**Fig. 2**). Additionally, the presence of strong bilateral inhibitory interactions (including reciprocal inhibition), mediated by contralateral motion integrator neurons (cMIs) confirms previous predictions obtained in this region (Naumann *et al.*, 2016; Bahl and Engert, 2020) based solely on calcium imaging. These interactions were proposed to explain behavioral statistics of zebrafish larvae responding to whole-field motion. Reciprocal inhibitory connectivity has also been shown to underlie ring attractor networks encoding head direction in both vertebrates and invertebrates (Turner-Evans *et al.*, 2020; Petrucco *et al.*, 2023), raising the possibility that similar connectivity motifs contribute to sensory integration in the hindbrain. For example, cyclically connected populations of caudal hindbrain neurons contribute to persistent activity in neurons controlling horizontal eye movements (Vishwanathan *et al.*, 2024). While denser reconstructions may yet reveal such cyclic structures within the anterior hindbrain, our findings suggest that different motifs serve complementary roles in supporting persistent neuronal activity. Understanding how these motifs are specialized for their respective motor outputs will require further investigation. Our findings also complement earlier studies identifying rhombomere 1 of the hindbrain as an integrator of multiple sensory inputs such as luminance or gaze direction (Wolf *et al.*, 2017; Petrucco *et al.*, 2023). Whether the motion-sensitive neurons identified in this study may also integrate other sensory variables remains an open question.

We also demonstrate that MON neurons receive a mixture of excitatory and inhibitory inputs from two types of feed-forward connected iMI cells. Although the calcium dynamics were not sufficiently fast to disentangle the difference in onset time constant between these two populations, we propose that these neurons together provide first excitation and then delayed inhibition onto MONs, generating a transiently active activity pattern in these cells upon motion onset. A similar di-synaptic arrangement has been shown to generate fast, gated activity dynamics in the larval *Xenopus* visual system (Akerman and Cline, 2006). We also demonstrate that MON neurons provide strong ipsilateral inhibitory input to cMI neurons in an unexpected disinhibitory arrangement. Finally, our findings further support the idea that SMI neurons act as the final readout of the evidence accumulation process, directly targeting reticulospinal neurons responsible for executing movement. The strong, stereotyped connectivity between SMI neurons and caudal-projecting reticulospinal neurons aligns with previous studies demonstrating that these neurons drive laterally biased motor outputs (Orger *et al.*, 2008).

Linking neural morphology with function has long been a major challenge in vertebrate connectomics, but recent advances have successfully achieved this in the mouse visual cortex (The MICrONS Consortium *et al.*, 2021; Ding *et al.*, 2023). In our study, we trained and validated a classifier that predicts functional neuron types based solely on their anatomical features (**Fig. 3**). This approach significantly expands the utility of connectomic datasets, allowing functional inference in electron microscopy volumes where direct calcium imaging is not available. This validation provides strong support for the notion that functionally distinct neuronal populations exhibit conserved morphological features, at least within the anterior hindbrain of zebrafish. Future applications of this approach could extend to other brain regions and species, accelerating the functional annotation of large-scale connectomic datasets.

Finally, we incorporated our anatomical findings into a computational model of sensory integration, constrained by the observed connectivity patterns and neurotransmitter identities. By minimal tuning

of connection weights and biophysical parameters, we demonstrated that our network model circuit could reproduce the experimentally observed dynamics of our measured cell types in the anterior hindbrain. The success of this model suggests an unexpected functional role of MON neurons in enabling fast responses to abrupt transitions in visual stimulation direction – a situation that frequently occurs in the naturalistic environment of animals (**Fig. 4**). The identified circuit arrangement in the anterior hindbrain may thus endow animals with a robust, yet flexible, system that can slowly filter important signals from noise and, at the same time, supports the rapid resetting of sensory integrators to allow fast reactions to external stimuli. Traditionally, disinhibitory connectivity in the motor system has been understood as a mechanism for movement initiation. Indeed, in the basal ganglia, disinhibition releases the thalamus and brainstem from suppression, allowing motor commands to propagate to the cortex and muscles (Lanciego, Luquin and Obeso, 2012).

It remains unclear how individual neurons' biophysical properties as well as synaptic strengths are shaping the dynamics observed in our analysis. For example, our model could not reproduce the observed slower ramping dynamics in SMI neurons, nor their trial-to-trial variability (Bahl and Engert, 2020). We also required the inhibitory inputs from iMIs to be increased to generate the correct MON neuron dynamics, potentially suggesting specific receptor types in these cells. Future experiments using voltage recordings, electrophysiology, transcriptomic analyses, and selective ablations could further refine our understanding of how such circuits are implemented. Recent analyses of *Drosophila* connectomes have integrated biophysical measurements to refine circuit models (Ammer *et al.*, 2023; Shiu *et al.*, 2024), an approach that remains largely unexplored in zebrafish. Measuring the biophysical properties of individual neuron types will be essential for further constraining network models and understanding the computational principles underlying sensory-motor transformations (Bargmann and Marder, 2013).

The connectomes and analysis tools presented here are openly available to the community and linked to an integrated atlas of the zebrafish brain. Our dataset provides a comprehensive view of vertebrate hindbrain circuitry in the zebrafish, complementing existing connectomic resources, including reconstructions spanning rhombomeres 4 to 8 (Vishwanathan *et al.*, 2024) of the ocular motor integrator system (Vishwanathan *et al.*, 2017), and whole-brain EM volumes (Svara *et al.*, 2022; Petkova, Januszewski, et al., *in prep.*). Our light-microscopy-trainable classifier enables functional inference in electron microscopy volumes without requiring calcium imaging, providing a scalable, cost-effective approach for circuits tested across a wide range of experimental paradigms. Our strategy will accelerate high-throughput functional annotation of vertebrate brain networks, enabling further dissections of the computational principles underlying sensory-motor decision-making. More broadly, our findings lay the groundwork for applying connectomics to diverse neural circuits, bridging the gap between structure and function in the vertebrate brain.

Methods

Zebrafish

For the correlative light and EM experiment (CLEM, **Figs. 1 and 2**) we generated a triple transgenic *Tg(elavl3:H2B-GCaMP7^{+/+}*, *gad1b:dsRed^{+/+}* (Satou *et al.*, 2013), *kdr1:mCherryCAAX^{+/+}* (Fujita *et al.*, 2011)) larva obtained by crossing adult transgenic *Tg(elavl3:H2B-GCaMP7f*, *gad1b:DsRed*) and *Tg(elavl3:H2B-GCaMP7f*, *kdr1:mCherryCAAX*) lines in nacre background, *mitfa^{-/-}* (Lister *et al.*, 1999) yielding high GCaMP7 fluorescence. The *Tg(elavl3:H2B-GCaMP7f)^{u344Tg}* transgenic line was generated using standard methods (Dowell *et al.*, 2024). We raised small groups of 20–30 larvae in filtered fish facility water in Petri dishes (9 cm in diameter) on a 14 h light, 10 h dark cycle at a constant 28 °C. From 4 dpf onwards, we fed larvae with paramecia once per day. The experiment was performed on 7 dpf larvae. For sparse cell electroporations (**Extended Data Fig. 2a**), we incrossed

Tg(elavl3:H2B-GCaMP7f)^{u344Tg} lines and selected offspring based on green fluorescence. For the area photoactivation (**Extended Data Fig. 2b**), we incrossed *Tg(alpha-tub:c3pa-GFP^{+/+})^{a7437Tg}* (Bianco *et al.*, 2012) with *Tg(elavl3:H2B-GCaMP6s^{+/+})^{if5Tg}* (Freeman *et al.*, 2014) adults and selected offspring for green fluorescence. Animals were 7 dpf and 6 dpf old, respectively. For the combined functional recordings, single-cell photoactivation, and HCR FISH staining experiments (**Fig. 3**), we outcrossed *Tg(alpha-tub:c3pa-GFP^{+/+}; elavl3:h2b-GCaMP6s^{+/+})* and *Tg(alpha-tub:c3pa-GFP^{+/+})^{a7437Tg}* adults, selecting for larvae that are homozygous for *c3pa-GFP* and heterozygous for *h2b-GCaMP6s*. For the imaging experiment after our model prediction (**Fig. 4g**), we used incrossed *Tg(elavl3:GCaMP8s)*, a newly generated line expressing *GCaMP8s* in neurons. To generate the line, we injected the Tol2 vector transgene construct (Tol2-*elavl3:GCaMP8s* (Zhang *et al.*, 2023)), obtained from Janelia Research Campus, and transposase RNA into 1–4-cell-stage embryos. We then isolated transgenic lines by screening for high expression of bright green fluorescence in the central nervous system in the next generation. For the experiments shown in **Figs. 3** and **4g** experiments, larvae were raised in E3 water on a 14 h light, 10 h dark cycle at a constant 28 °C without feeding. All experiments were approved by the Harvard University and Konstanz University committees on the use of animals in research and training.

Visual stimuli

All visual stimuli during functional imaging consisted of ~1,000 dots (2 mm in diameter) moving at 1.8 cm s⁻¹, projected (60 Hz, P300 Pico Projector, AAXA) from below through mildly light-scattering parchment paper. Dots were shown in red on a black background to minimize interference of the visual stimulus with the functional *GCaMP* imaging. To ensure that the animals did not track individual dots to detect motion, each dot had a short lifetime (200 ms mean) and stochastically disappeared and immediately reappeared at a random location within the arena. One stimulation trial consisted of 40 s of 100% coherent motion either drifting leftward or rightward, interleaved by 20 s of 0% coherence before and after. For the CLEM experiment (**Fig. 1**), we also presented moving sine gratings drifting leftward or rightward, but did not include these stimulus trials in our analysis. For the imaging experiments in **Fig. 4g**, we presented animals with 30 s of 100 % coherence, with motion either running continuously or abruptly switching direction after 15 s. Stimuli across trials were interleaved with 40 s of 0% coherence. In all experiments, stimuli were shown in a random sequence.

Two-photon calcium imaging and analysis

The larva was fully embedded in a drop of agarose (UltraPure Low Melting Point Agarose, Invitrogen), at ~35 °C at the center of a Petri dish (9 cm in diameter, VWR). After the agarose was solidified the dish was filled with fish facility water and transferred into the measurement chamber of a custom-built two-photon microscope, operated by custom-written Python 3.7-based software (PyZebra2P). We used a femtosecond-pulsed laser (MaiTai Ti:Sapphire, Spectra-Physics) equipped with a set of x/y-galvanometers (Cambridge Technology), a 20x infrared-optimized objective (XLUMPLFLN, Olympus) to scan over the brain and two photomultipliers (green and red) amplified by two current preamplifiers (SR570, Stanford) to collect fluorophores emissions. We used frame acquisition rates of around 1 Hz. Laser power was measured to be ~13 mW at the specimen. Such power levels did not interfere with behavior in previous tail-free imaging experiments (Bahl and Engert, 2020). During functional imaging, the laser was tuned to 950 nm to collect *GCaMP7f* fluorescence. We sequentially imaged six planes spaced at 12 μm, centered on the anterior hindbrain region (336 x 336 μm at 0.48 x 0.48 μm resolution). In each plane, we showed from 2 to 9 visual stimulation trials. Immediately after the experiment, we anesthetized the fish by replacing the water with a 0.015% MS-222 (Sigma-Aldrich) solution in fish facility water. This procedure enabled us to acquire an additional motion artifact-free high-resolution stack at 1020 nm excitation (420 x 420 x 90 μm at 0.6 x 0.6 x 2 μm resolution) with simultaneous collection of *GCaMP7f* and *DsRed* fluorescence. The total imaging session lasted ~5 hours.

Activity recordings of each plane were first motion-corrected using NoRMCorre (Pnevmatikakis and Giovannucci, 2017) and temporally averaged. We used a convolutional neural network segmentation approach (StarDist) to perform high-accuracy segmentation of the nuclei in each plane (Weigert and Schmidt, 2022). Calcium dynamics for each nuclei mask were then extracted as $\Delta F/F_0$ traces using Python numpy array slicing. K-means clustering of functional cell types was performed on pooled activity traces from the CLEM experiment (**Fig. 1**) and all reconstructed neurons from our targeted photoactivations experiments (**Fig. 3**). The elbow method (Umargono, Suseno and S. K., 2019) suggested 4 functionally distinct clusters. These clusters were further isolated by two successive K-means clustering steps with 3 and 2 target clusters as parameters. The first iteration isolated MON dynamics, fast motion integrator dynamics (MI-1), and a third, slower group. The second iteration performed on this slower population revealed an additional motion integrator group (MI-2) as well as a slow motion integrator group (SMI). Thus, our clustering approach yielded 4 neuronal clusters with distinct temporal dynamics. For all cells in each cluster, we computed the average rise time until neuronal activity reaches 90% of the maximal response, revealing a clear separation of timescales across clusters (**Extended Data Fig. 1b**, only showing CLEM cells). We then computed 3 final regressors by pooling neurons belonging to the MI-1 and MI-2 clusters and averaging the activity of all neurons belonging to each clustered population. Neurons in the CLEM recording were then assigned to one of the 3 functional types by computing the correlation coefficient with individual regressors. Neurons whose correlation coefficient with a regressor was larger than 0.8 and that had a response of at least 20 % $\Delta F/F_0$ were assigned to the corresponding functional type. All other neurons remained unassigned.

Direction selectivity indexes (**Extended Data Fig. 1f**) were computed using standard methods (Boulanger-Weill *et al.*, 2017):

$$DSI = \frac{\max(R_R) - \max(R_L)}{\max(R_R) + \max(R_L)},$$

where $\max(R_R)$ and $\max(R_L)$ are the maximal $\Delta F/F_0$ response values during the entire rightward and leftward stimulation. Negative responses were set to 0.

In the imaging experiments presented in **Fig. 4g**, we used our newly generated fish line *Tg(elavl3:GCaMP8s)*. As GCaMP8s is expressed in the cytosol of cells we had to adjust the segmentation parameters. We employed cellpose3 (Stringer and Pachitariu, 2025) to segment neurons based on the time-averaged imaging stack, tuned to the following parameters for the standard cyto3 model: cell diameter = none; follow threshold = 0.7; cellprob threshold = -0.4; lower = 0; upper = 90.0, which generated very good segmentation results across the brain (**Extended Data Fig. 8d**). We then computed $\Delta F/F_0$ time traces from the resulting masks and used the same regressors and cell type classification strategy as for our other imaging experiments (**Figs. 1** and **3**). We then averaged all labeled cells per group to obtain response dynamics. For the continuous motion stimulus, we computed the time until neuronal activity reaches 90% of the maximal response during the time window of 30 s after motion onset. We chose the activity at the end of the stimulation period to compute the time until activity decayed to 10 % of that value. For the switching motion stimulus, we used the 15 s time point as a reference using the same approach.

Sparse electroporations and area photoactivations

Sparse electroporations were performed as in (Boulanger-Weill *et al.*, 2017). Briefly, 4 dpf larvae were embedded in a droplet of agarose and anesthetized with 0.015% MS-222 (Sigma-Aldrich) in fish water. The agarose next to the anterior hindbrain was removed using a microsurgical blade. The electroporations were performed under a fixed-stage upright microscope equipped with a long working distance objective (10x UPlanFL N 10X/0.30na, Olympus). The silver wire microelectrode and bath

electrode were mounted on micro-manipulators with the microelectrode holder containing an additional side port to apply air pressure with a syringe. Borosilicate glass capillaries (1.2 mm outer diameter, 0.68 mm inner diameter, with filament by World Precision Instruments) were pulled using a pipette puller (PC-10, Narishige, set at 68/58 °C) to obtain a 1 μ m tip diameter. Pipettes were filled with 2 μ L of cmv:lyn-tdTomato plasmid DNA solution and inserted into the anterior hindbrain of larvae. The lyn tag enables high-efficiency targeting of the red fluorescent protein to the cell's membrane and is thus ideal for studying neuronal morphology (Kunst *et al.*, 2019). Following optimized protocols (Zou, Friedrich and Bianco, 2016), two or three stimulation bursts (around 0.5 s per burst, consisting of 2 ms pulses at 200 Hz at 28 V) were delivered using a square pulse stimulator (Sd9, Grass Technologies) and monitored using digital oscilloscope (TDS 2014, Tektronix). After the electroporations, larvae were freed from the agarose and kept isolated for 2 days. At 6 dpf, we then performed two-photon functional imaging of GCaMP6s (see previous section) to measure the response dynamics of the labeled cells to random dot motion. For subsequent morphological imaging of electroporated cells, we then anesthetized the fish and imaged at 1030 nm to collect dual-color z-stacks at high spatial resolution (0.46 x 0.46 x 1.5 μ m) of both GCaMP and td-Tomato. Morphological imaging data was filtered (3D Gaussian blur, sigma 1.0 in x, y, and z) in Fiji (Schindelin *et al.*, 2012). Labeled neurons were then semi-automatically traced with the open-source reconstruction software neuTube (Feng, Zhao and Kim, 2015), using default settings and optimal node resampling. We then saved cells as .swc files. Using the GCaMP6s channel we then generated a transform per larva, allowing us to map reconstructed electroporated cells to a reference brain (Randlett, Wee, E. A. Naumann, *et al.*, 2015).

For area photoactivation (**Extended Data Fig. 2b**), fish were anesthetized with 0.015% MS-222 (Sigma-Aldrich), and c3pa-GFP was photoactivated using cycles of 40 short pulses of 200 ms at 1 Hz at a laser wavelength of 750 nm, following established protocols (Kramer *et al.*, 2019). After 1–3 initial trial pulses to check whether any adjacent cells were photoactivated and to readjust the region of interest if necessary, the whole protocol consisting of 15 cycles was executed, with five-minute intervals between two activation cycles. Photoactivation was targeted over a 50 x 40 μ m region containing neurons with motion integration dynamics in the anterior hindbrain.

Sample preparation for the EM imaging

For the CLEM experiment, we used a protocol modified from (Tapia *et al.*, 2012) to enhance extracellular space preservation which improves synapse detection (Pallotto *et al.*, 2015) and permits single-cell resolution imaging using X-ray tomography. Unless noted, all steps were performed at room temperature (RT). Immediately after the two-photon stack acquisition, the larva, was still anesthetized and embedded in agarose. We replaced the water with a dissection solution (64 mM NaCl, 2.9 mM KCl, 10 mM HEPES, 10 mM glucose, 164 mM sucrose, 1.2 mM MgCl₂, 2.1 mM CaCl₂, pH 7.5) supplemented with 0.02% tricaine (Hildebrand *et al.*, 2017). We then cut small slits in the agarose to expose the eyes and performed bilateral enucleations to enhance extracellular space preservation and heavy metal staining. We used a custom-made hook that was carefully inserted behind the eyes to prevent brain damage. The larva was immediately transferred to a fixation solution at 4°C (2.5% glutaraldehyde, 0.1M cacodylate buffer supplemented with 4.0% mannitol at pH 7.4). Cacodylate buffer: 0.3M sodium cacodylate, 6mM CaCl₂, pH 7.4. To improve the fixation, the tissue was rapidly microwaved (cat. no. 36700, Ted Pella, equipped with a power controller, steady-temperature water recirculator, and cold spot) in the fixative solution (this step lasted <5 min after initial transfer into fixative). The microwaving sequence was performed as in (Tapia *et al.*, 2012): at power level 1 (100 W) for 1 min on, 1 min off, 1 min on then to power level 3 (300 W) and fixed for 20 s on, 20 s off, 20 s on, three times in a row. Fixation was then continued overnight at 4°C in the same solution. The following day, the sample was then washed again in 0.5x cacodylate buffer (3 exchanges, 30 min each before osmication (2% OsO₄ in 0.5x cacodylate buffer, 90 min). After a quick wash (< 1 min) in 0.5x cacodylate buffer the sample was reduced in 2.5% potassium ferrocyanide in

0.5x cacodylate buffer for 90 min then washed with filtered H₂O (3 exchanges, 30 min each) and then incubated with 1% (w/v) thiocarbohydrazide (TCH) in filtered H₂O (and filtered with a 0.22 µm syringe filter before use) for 45 min to enhance staining (Hua et al., 2015). Due to poor dissolution of TCH in water, the solution was heated at 60 °C for ~90 min with occasional shaking before filtering and then placed at RT for 5 min before the incubation step. The sample was then washed with filtered H₂O (3 exchanges, 30 min each) before the second osmication (2% OsO₄ in filtered H₂O, 90 min) and then washed again (3 exchanges, 30 min each). Then, en-bloc staining was performed overnight using 1% uranyl acetate in filtered water at 4 °C. The solution was sonicated for 90 min and filtered with a 0.22µm syringe filter before use. Steps involving uranyl acetate were performed in the dark. The following day, samples were then washed with filtered H₂O (3 exchanges, 30 min each). Next, the samples were dehydrated in serial dilutions of ethanol (25%, 50%, 75%, 90%, 100%, 100% for 10 min each step) and then in propylene oxide (PO) (100%, 100%, 30 min, each step). Infiltration was performed using LX112 epoxy resin with BDMA (21212, Ladd) in serial PO dilution steps, each lasting 4h (25% resin/75% PO, 50% resin/50% PO, 75% resin/25% PO, 100% resin, 100% resin). Samples were mounted in fresh resin in a mouse brain support tissue (Hildebrand *et al.*, 2017) with the head exposed to facilitate cutting and prevent the sample from sinking to the bottom of the resin molds. Mouse tissue was fixed using standard procedures (Fang et al., 2018) and then cut into 2–3 mm wide cubes which were pierced using a puncher (0.75 mm, 57395, EMS) to insert the larva. The cubes were stained along with fish samples using the protocol described above except that the uranyl acetate overnight step was performed at RT. The samples were then cured with support tissue for 3 days at 60°C. For all steps, a rotator was used. Aqueous solutions were prepared with water passed through a purification system (Arium 611VF, Sartorius Stedim Biotech). The protocol lasted 5 consecutive days including surgery, fixation, staining, and resin embedding followed by 3 days of resin curing.

X-ray computed tomography

To achieve high contrast X-ray and mSEM imaging we sequentially optimized OsO₄ staining duration, X-ray imaging, and voltage and performed deep learning-based X-ray reconstruction (**Extended Data Fig. 2e,f**). The OsO₄ staining was optimized first in previous batches of samples to yield the mSEM staining protocol described previously. The imaging voltage and post-processing were optimized in the main sample described in this study. In total this sample was imaged for ~300 hours which did not interfere with mSEM imaging. For each sample, the block was trimmed to expose the head of the fish for imaging (Xradia 520 Versa, ZEISS). To assess the imaging quality, we computed a modified version of Michelson's contrast that was robust to noise at multiple sections along the main axis of the larvae:

$$\text{Contrast} = \frac{I_{\max} - I_{\min}}{I_{\max} + I_{\min}}$$

Where I_{\max} and I_{\min} are the average intensity values over the 80th and below the 20th percentile respectively. We also computed the signal-to-noise ratio (SNR) at the same locations according to (Joy, 2002). X-ray tomography stacks were post-processed using a deep neural network product included in the Xradia software.

Sample sectioning and mSEM image acquisition

After X-ray imaging, the block was re-embedded in resin and cured for 3 days at 60 °C and trimmed in a diamond shape (Hildebrand *et al.*, 2017). 4010 sections ranging from 30 to 35 nm were automatically collected on carbon-coated tape using a custom tape collection device (ATUM) (Hayworth *et al.*, 2014) mounted to a commercial ultramicrotome. The tape was cut into strips and deposited on 30 silicon wafers that were post-stained (Hildebrand *et al.*, 2017). Wafers were then mounted on the 61-beam mSEM stage (MultiSEM 505, ZEISS) and each section's position was determined using a reflected light microscope to guide the high-resolution imaging. Imaging was

performed at 4 x 4 nm pixel resolution using secondary electron emission using a dwell time of 400 ns per pixel. The quality of each section was assessed using previously described methods (Shapson-Coe *et al.*, 2024).

mSEM image alignment, stitching, rendering, neuronal morphology proofreading

We trained convolutional neural networks to detect defects and classify locations that contain tissue for each montaged section. We used self-supervised convolutional neural networks to generate dense displacement fields between sections (Popovych *et al.*, 2024), and then hierarchically minimized the elastic energy in the set of all displacement fields to produce an aligned image. We created an “image mask” that contained defects and locations that were classified as misaligned. We trained convolutional neural networks that we used to segment cells, detect synaptic clefts, compute their sizes, and assign presynaptic and postsynaptic objects from the cell segmentation at each cleft (Macrina *et al.*, 2021). Cell segmentation and synapse detection and assignment used the aligned image with locations in the “image mask” set to black. We refined the detection of synaptic clefts and reduced false positives by visually inspecting two dendrites and one axon and classified predicted synapses as true positive, false positive, and identified false negative missing synapses (**Extended Data Fig. 4b-d**). We performed a Receiver Operating Characteristic (ROC) curve analysis to establish a size threshold that minimizes false positives (**Extended Data Fig. 4e**). This analysis determined that a synapse size threshold of 44 voxels effectively excluded 90% of the false positive synapses, providing a reliable criterion for refining the dataset and improving prediction accuracy. Finally, cell segmentation was ingested into the ChunkedGraph proofreading system so that morphological errors could be manually corrected, and synapses were ingested into an annotation table for consistent analysis (Dorkenwald *et al.*, 2023).

Multimodal, reference brain registrations and cell type determination

Matching of neuronal identities from the 2P functionally imaged planes to the EM volume was performed in two successive manual steps using the Fiji plugin Bigwarp (Bogovic *et al.*, 2016). We first manually registered functional imaging planes to a higher z-resolution two-photon image stack (z-steps = 2 µm, containing green and red fluorescence) using manually selected 844 landmarks. The SNR of this stack was enhanced using content-aware image restoration (Weigert *et al.*, 2018). We then registered this higher resolution two-photon image stack to a downsampled mSEM stack (0.512, 0.512, 0.480 µm/pixel) using manually selected 771 landmarks. This EM stack was downloaded from Neuroglancer (<https://github.com/google/neuroglancer>) using Cloudvolume (Silversmith *et al.*, 2022). These two registration steps generated two deformation fields which were successively applied to the 2P functionally imaged planes using Bigwarp (in linear deformation mode) and manually checked exhaustively. The segmented neuronal masks were also deformed using these two steps (in nearest neighbor mode). Deformed planes of green and red fluorescence (8-bit image stacks) and segmented masks were uploaded to Neuroglancer using Cloudvolume enabling collaborative reconstruction and cell type determination of the neurons of interest. To determine whether neurons were inhibitory, we manually traced a mask surrounding the neuron's nuclei in the green channel and computed the average corresponding red fluorescence. Neurons with values superior to 10 % of the maximum red signal (25 in 8-bit scale) were considered inhibitory. Regions containing k-means clustered neurons (**Extended Data Fig. 1c**) were determined by automatically registering the 2P functionally imaged planes to the z-brain reference brain (Randlett, Wee, E. A. Naumann, *et al.*, 2015) using ANTs (Avants, Tustison and Johnson, 2015). For regional annotations, we downloaded anatomical masks from the mapzebrain atlas platform (Kunst *et al.*, 2019) and mapped them into the z-brain coordinate system (Randlett, Wee, E. A. Naumann, *et al.*, 2015) using ANTs (Avants, Tustison and Johnson, 2015).

Finally, neurons traced in Neuroglancer were downloaded using Navis (Schlegel *et al.*, 2025) and automatically registered to the z-brain reference brain (Randlett, Wee, E. A. Naumann, *et al.*, 2015).

To register cells from our downsampled mSEM stack to the z-brain reference brain, we manually selected 207 landmarks in the mSEM stack and the *Tg(elavl3:H2B-RFP)* confocal stack in the z-brain coordinate system to generate a bridge transform via Fiji Bigwarp. All neurons presented in this paper have been registered to the z-brain reference brain (Randlett, Wee, E. A. Naumann, *et al.*, 2015) and are available on our online platform.

Two-photon photoactivation and neurotransmitter identity of functionally identified cells

We selected larvae for green fluorescent nuclear expression and embedded animals in a droplet of low-melting point agarose in a Petri dish with a diameter of 6 cm. The fluorescence of the H2B-GCaMP6s makes the identification of c3pa-GFP difficult – at this stage, c3pa-GFP is not yet photoactivated and thus very dim. To enable screening for c3pa-GFP, we initially performed a brief activation experiment in the two-photon microscope, labeling a small region in the dorsal rostral tectum. We only continued with the animals that showed some sign of tectal photoactivation patterns after a maximum of 5 rounds of photoactivation. Morphologies originating from this area largely remained local and did not overlap with the photoactivated neurons in the hindbrain. In a few cases, neurons descended into the anterior hindbrain neuropil, coming close to the photoactivated cells but did not interfere with our tracing. To accommodate larvae to the experiment and minimize motion artifacts and plane shifts during imaging, we initially presented animals for 15 minutes with random dot motion before starting the functional characterizations.

To quickly identify cell types, we then imaged a single plane in the anterior hindbrain for 15 – 30 minutes while presenting random dot motion. Using a custom-written Python script, we aligned recordings to the onset of motion and averaged stacks across trials. Using Fiji (Schindelin *et al.*, 2012) we defined a small movable region of interest with the size of a cell to manually explore the stack for neuronal dynamics matching the known cell type dynamics (Bahl and Engert, 2020). This analysis step took less than 5 minutes per fish.

For each identified cell we then conducted targeted photoactivation at 760 nm. Using a custom-written scanning waveform generator in PyZebra2P, we used a small activation spiral (less than 0.5 μm in diameter) focused onto the center of the nucleus of the cell. Due to the point spread function of our microscope ($\sim 1 \mu\text{m}$ along the horizontal plane, and $\sim 4 \mu\text{m}$ along the vertical axis), we were able to activate c3pa-GFP in the cytosol without affecting neighboring neurons. Following recent protocols (Kramer *et al.*, 2019), we used short activation pulses of 200 ms in length and 100 ms interpulse interval. The required laser power at the specimen and the pulse counts for effective photoactivation varied widely across fish. Some fish only required as few as 20 pulses (ca. 6 seconds) at 5 mW to activate cells, whereas other fish often required up to 1000 pulses (ca. 5 min) at 8 mW. We attribute this difference to variations in expression levels as some experimental fish are heterozygous and some fish are homozygous for c3pa-GFP.

Following successful photoactivation, we anesthetized the fish by replacing the water in the Petri dish with a 0.015% MS-222 solution. After 15 minutes of anesthesia, we then imaged a high-resolution stack (100 planes, $0.4 \mu\text{m} \times 0.4 \mu\text{m} \times 2 \mu\text{m}$; 90 s per plane) of the hindbrain and midbrain to capture as much of the photoactivated cell's neurite morphology as possible. This step took around 2.5 hours per animal.

To determine the neurotransmitter identity of the labeled cell, we performed HCR RNA-FISH (Choi *et al.*, 2018) on the same fish immediately after the imaging session. To this end, we cut out a small block of agarose containing the anesthetized fish and directly fixed the sample in ice-cold 4% PFA for 12–16 hours overnight at 4 °C. We then followed recent protocols optimized for zebrafish larvae (Shainer *et al.*, 2023). We used probe sets against *gad1b* (probe set size 30, #NM_194419.1) and *vglut2a* (*slc17a6b*, probe set size 20 #NM_001128821), with B1 and B2 amplifiers, respectively. We used the B1-546 amplifier fluorophore and the B2-405 amplifier fluorophore, thus fluorescently labeling *gad1b*-positive cells in red and *vglut2a*-positive cells in blue.

After the procedure, we placed the still agarose-embedded fish into the same two-photon microscope where it had been imaged before. The PFA fixation and HCR RNA-FISH protocol considerably reduced the fluorescence of a photoactivated c3pa-GFP cell. Cells were still identifiable because they were slightly more fluorescent than neighboring non-photoactivated neurons. Neurites in the photoactivated cells were however not visible anymore after the procedure. To further validate the identity of the cell, we used landmarks such as the arrangement of neighboring nuclei or neuropil structures with distinguishable distances to the labeled cells. We acquired two separate high-resolution volume scans around the photoactivated cell body. Our custom-built microscope can only simultaneously image green and red fluorescence or green and blue fluorescence, with a manual replacement of a filter cube in the collection optics path between imaging sessions. As we acquired green fluorescence in both sessions, we could identify our target cells in both imaging stacks to extract the expression levels of both *gad1b* and *vglut2a* within the cytosolic ring around the nucleus. Labels were largely exclusive to each other, allowing us to confidently assign neurotransmitter identity based on which label was stronger. We labeled cells where both *gad1b* and *vglut2a* signals were indistinguishable from background fluorescence as ‘undefined’.

The custom-designed two-photon microscope used for these experiments was largely similar to the one explained above used for the CLEM experiment. However, this system used a tunable MaiTai® DeepSee (Spectra-Physics) laser source with a built-in pre-chirp unit, a Nikon 25x Objective (N25X-APO-MP), and a more sensitive Hamamatsu GaAsP PMT (H16201P-40-S3) for the green channel. These features significantly improved the imaging quality of green signals and later facilitated the reconstruction of photoactivated neurons. Reconstructions were performed in Fiji using the SNT semi-automated tracing tool (Arshadi *et al.*, 2021).

Zebrafish-optimized NBLAST probability matrix

We used NBLAST (Costa *et al.*, 2016) to compute a matrix of morphological similarity of cells within our CLEM dataset (**Extended Data Fig. 3e**). One of the major functions of the NBLAST algorithm is the 2-dimensional scoring matrix (10 x 21) which provides a raw score of whether two neurons belong to a similar cell type. The row of the scoring matrix represents the dot product of the tangent vectors whereas columns represent the range of distances in micrometers. The default matrix is derived from a dataset of *Drosophila* neurons and is sensitive to several factors, including dataset type, neuron size, preprocessing methods, and the volume analyzed. To match the algorithm to our data, we computed a zebrafish-optimized scoring matrix using the CLEM dataset. The training of such a matrix requires matching and nonmatching sets of neurons (Costa *et al.*, 2016). We used our four functionally and morphologically distinct cell types (iMI, cMI, MON, SMI) as matching sets. Non-matching sets of neurons are drawn randomly from our CLEM dataset. The consistency of the matrix is assured by using the n-fold (n=4). The detailed method and further advancements are provided in an upcoming atlas paper (Vohra *et al.*, *in preparation*).

Morphology-based prediction of neuronal functional types

With the unique availability of two ground truth datasets of structure and function relationship (**Fig. 1** and **Fig. 3**), we sought to employ and train a classifier to predict a functional cell type based on anatomical structure. Such a classifier will be useful for predicting functional response properties of cells in anatomical libraries for which functional imaging has not been performed, including existing EM reconstruction databases. To this end, first mapped all reconstructed neurons to a common reference atlas (Randlett, Wee, E. a Naumann, *et al.*, 2015), using custom-written Python scripts and ANTs (Avants, Tustison and Johnson, 2015). For neurons originating from the CLEM experiment (**Fig. 1**), we applied the same Bigwarp-based generated ANTs transforms that we used to map cell bodies into the reference brain (see section above). For neurons originating from the two-photon guided photoactivation experiments (**Fig. 3**), we used the h2b-GCaMP6s channel to generate a transform between each stack against the corresponding reference stack.

Reconstructed neurons from the CLEM experiment were downloaded as high-resolution geometry (.obj) files. These files are simple text files containing a list of surface vectors describing volumetric meshes, allowing us to apply our ANTs transforms to map geometries into the z-brain coordinate system. Using the *skeleton* package and the TEASAR algorithm (Sato *et al.*, 2000) in Python, we skeletonized .obj files to 1.5 μ m spacing and saved results as .swc files. This procedure ensured that all neurons originating from different experiments and modalities ended up in the same coordinate system with the same spatial tracing resolution, a prerequisite for the development of our classifier.

As our NBLAST matrix does not show a clear separability of cell types, we decided to build our classifier using a feature-based approach. To this end, we exhaustively extracted 68 morphometrics from each skeletonized neuron (**Extended Data Table 1**). All features were normalized by subtracting the mean and scaling to unit variance across cells. To identify the most relevant of these features for predicting functional cell types, we first selected feature subsets of different sizes. To this end, we conducted feature ranking with reverse feature elimination using *sklearn.feature_selection.RFE* in Python with “AdaBoostClassifier” as the learning estimator. For a given target feature subset size (1 – 68), the algorithm starts at the maximum number of features (68). It then uses the specified estimator to evaluate the importance of features by fitting the model and then iteratively removes the least significant feature until it reaches the desired target feature subset size. For each resulting feature subset, we then extracted a predictive F1-score of how these features could be used to classify cell types. Specifically, we split our cells (including both data from the CLEM and photoactivation experiments) in a ratio of 70% train and 30% test. As a classifier algorithm, we chose Linear Discriminant Analysis (LDA) with solver ‘lsqr’ (least squares solution). Performing the LDA training and prediction step 100 times with different randomly selected training and test sets, allowed us to compute the predictive F1-score as a function of the feature subset size (**Extended Data Fig. 6e**). We then selected the feature combination with the highest predictive performance as the final feature set (**Fig. 3f**). We used this feature subset for all further cell type classifications.

Many cells identified through our pre- and post-synaptic connectomic reconstructions had their soma in regions that were not covered by our 2P multi-plane imaging session. To compute the performance of our classifier when predicting the functional type in such cases, we performed a ‘leave one out cross-validation’ step on our ground truth datasets. To assess the quality of the classifier using maximal and cross-modality training data, we combined both the CLEM and photoactivation experiments. We iteratively chose one of our known CLEM cells and trained our classifier on all remaining ground truth cells. Comparing the classifier prediction of the left-out CLEM cell with its true functional type, allowed us to compute a confusion matrix, indicating the probability that a functional prediction of a given EM cell is correct (**Fig. 3g**). We finally repeated the training on all available ground truth cells (data from the CLEM and photoactivation experiments) to generate the final classifier used to predict the functional response properties of EM cells that we had not imaged (**Fig. 3h**). Our trained cell type classifier should be applicable to also enhance other morphological resources, containing anatomical reconstructions of neurons in the larval zebrafish anterior hindbrain.

Notably, the LDA classifier will place any target cell, even when it looks completely different from the training dataset, into one of our defined 4 categories. To rule out such incorrect predictions, we identified outliers within the predicted cells’ morphometric features using an isolation forest algorithm (*sklearn.IsolationForest*) and the local outlier factor (*sklearn.LocalOutlierFactor*). We trained these outlier removal methods with the morphometric features of our functionally identified cells from both the CLEM and photoactivation experiments.

We finally compared our morphology-based neuronal type prediction method to previously established approaches (Li *et al.*, 2017). To do so, we computed persistence vectors and their sampled versions (Li *et al.*, 2017) for each neuron using *navis.persistence_vectors* and trained a linear discriminant analysis classifier (*sklearn.LinearDiscriminantAnalysis*) to predict functional types (**Extended Data Fig. 6g, h**). Similarly, we calculated form factors (Choi, Kim and Hyeon, 2023) for

each neuron using *navis.form_factor* and trained another linear discriminant analysis classifier to predict functional types (**Extended Data Fig. 6i**).

Network modeling

We simulated the network model of the anterior hindbrain via an array of 14 first-order coupled differential equations (7 cell types on each hemisphere). We fed stimulus input drives into the first processing layer (pretectum) on the left and right sides, respectively. Input drives had a baseline activity of 0.5. A stimulation level of 100% random dot motion coherence to the left was simulated as increasing the input drive on the left by +1, and reducing it by 0.5 on the right side (**Fig. 4d**). For motion to the right, the input drive was adjusted accordingly. We did not attempt to build a biophysically realistic network model of the pretectum (Kubo *et al.*, 2014; Naumann *et al.*, 2016; Wang *et al.*, 2019). The activity was then further processed in the interhemispheric anterior hindbrain network. To keep the model simple and parameter space low, we fixed excitatory weights to +1, and inhibitory weights to -1. Because we found the connection between iMI⁻ and MON to be prominent in our data (**Extended Data Fig. 7a,b**), we here used a stronger inhibitory weight of -5.5. We modeled all cells with the same leak factor of -2.5, without assuming any specific biophysical features across the network. (**Fig. 4c**). Smaller leak factors than this value led to unstable network behaviors. Larger leak values led to overall faster dynamics. As our experimental measurement relies on GCaMP8s calcium imaging (**Fig. 4c**)—which represents a largely low-pass filtered version of the true neuronal activity—we did not aim to quantitatively match the time scales between the model and experiment. The self-recurrency of iMI neurons effectively reduced the leak of this cell type, explaining the slower integration dynamics compared to the input from the pretectum. Many neurons in the network model inherit these dynamics, explaining the overall slower temporal dynamics in the hindbrain. We used the Euler method (time step $dt = 0.01$ s). The full model follows these rules to update the firing rates:

Left hemisphere:

$$\begin{aligned} dPI_l^+ &= -2.5 \cdot PI_l^+ + Stim_l(t) \\ diMI_l^+ &= -2.5 \cdot iMI_l^+ + 1.0 \cdot PI_l^+ + 1.0 \cdot iMI_l^+ - 1.0 \cdot MON_l^- - 1.0 \cdot CMI_r^- \\ diMI_l^- &= -2.5 \cdot iMI_l^- + 1.0 \cdot iMI_l^+ \\ dCMI_l^- &= -2.5 \cdot CMI_l^- + 1.0 \cdot iMI_l^+ - 1.0 \cdot MON_l^- - 1.0 \cdot CMI_r^- - 1.0 \cdot MON_r^- \\ dMON_l^- &= -2.5 \cdot MON_l^- + 1.0 \cdot PI_l^+ + 1.0 \cdot iMI_l^+ - 5.5 \cdot iMI_l^- - 1.0 \cdot MON_l^- - 1.0 \cdot CMI_r^- \\ dSMI_l &= -2.5 \cdot SMI_l + 1.0 \cdot PI_l^+ + 1.0 \cdot iMI_l^+ - 1.0 \cdot MON_l^- - 1.0 \cdot CMI_r^- \\ dMY_l &= -2.5 \cdot MY_l + 1.0 \cdot SMI_l + 1.0 \cdot SMI_r \end{aligned}$$

Right hemisphere:

$$\begin{aligned} dPI_r^+ &= -2.5 \cdot PI_r^+ + Stim_r(t) \\ diMI_r^+ &= -2.5 \cdot iMI_r^+ + 1.0 \cdot PI_r^+ + 1.0 \cdot iMI_r^+ - 1.0 \cdot MON_r^- - 1.0 \cdot CMI_l^- \\ diMI_r^- &= -2.5 \cdot iMI_r^- + 1.0 \cdot iMI_r^+ \\ dCMI_r^- &= -2.5 \cdot CMI_r^- + 1.0 \cdot iMI_r^+ - 1.0 \cdot MON_r^- - 1.0 \cdot CMI_l^- - 1.0 \cdot MON_l^- \\ dMON_r^- &= -2.5 \cdot MON_r^- + 1.0 \cdot PI_r^+ + 1.0 \cdot iMI_r^+ - 5.5 \cdot iMI_r^- - 1.0 \cdot MON_r^- - 1.0 \cdot CMI_l^- \\ dSMI_r &= -2.5 \cdot SMI_r + 1.0 \cdot PI_r^+ + 1.0 \cdot iMI_r^+ - 1.0 \cdot MON_r^- - 1.0 \cdot CMI_l^- \\ dMY_r &= -2.5 \cdot MY_r + 1.0 \cdot SMI_r + 1.0 \cdot SMI_l \end{aligned}$$

with $rate(t) = rate(t-1) + drate \cdot dt$. We prevented negative activity rates by setting values to zero, whenever they became negative in the updating loop. To generate the activity rate plots in **Fig. 4d**, we computed rates relative to baseline (averaging 10 s before motion onset), matching our imaging analysis of fluorescent data for better comparisons between model and experiment. To

compute rise times, we measured the delay to 90% of the maximal rate per cell type. To compute decay times, we picked the value at the end of the stimulation period and computed the delay until the signal reached 10 % of this value. In the MON silencing experiment (**Extended Data Fig. 8b**), we clamped $\text{MON}_l^-(t) = 0$ and $\text{MON}_r^-(t) = 0$.

Data availability

All neurons described in this paper are browsable in FishExplorer: <https://fishexplorer.zib.de/sandbox/>.

Github code: https://github.com/arminbahl/Hb_structure_function

Funding

A.B. and F.K. were supported through the Emmy Noether Program (BA 5923/1-1), the Zukunftskolleg Konstanz, as well as the German Excellence Strategy (EXC 2117-422037984). J.B.W., F.K., G.F.P.S., F.E., and J.W.L. received funding from the Institutes of Health U19 Program (U19NS104653 and 1R01NS124017-01). J.B.W. received funding from the Philippe Foundation Inc. F.E. was also supported by the Simons Foundation (SCGB 542973 and NC-GB-CULM-00003241-02). G.F.P.S. received funding from the Swiss National Science Foundation (Fellowships P2EZP3_188017 and P500PB_203130).

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Acknowledgments

We thank Zetta AI for alignment, cell segmentation, synapse detection & assignment, and hosting CAVE. We are grateful to Thomas Macrina for his assistance with connectome analysis, Paul Teufel for his initial help with segmentation, Zachary Miller for his contributions to manual registration, and Hillary Jean-Gilles for her help with tracing.

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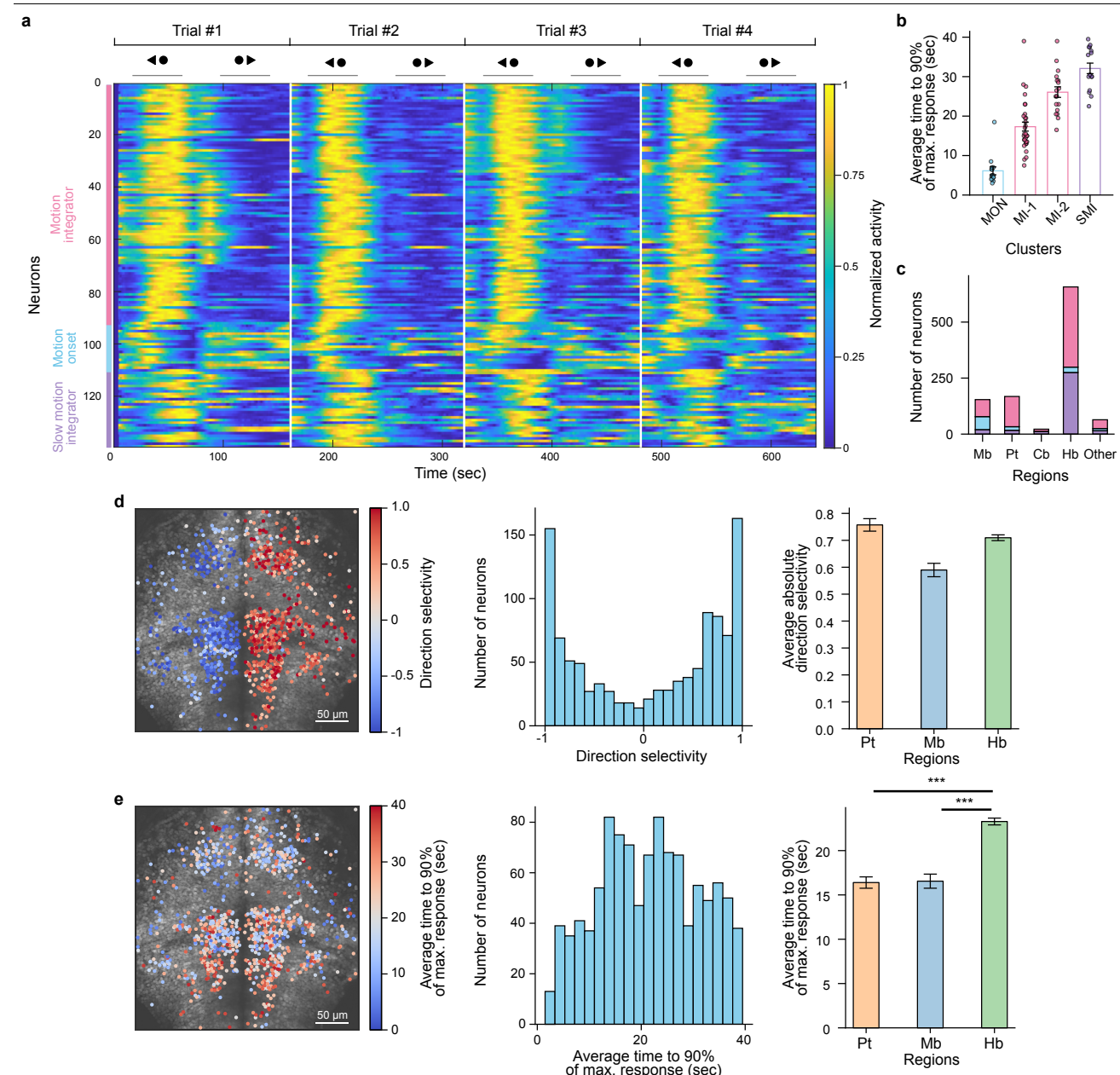
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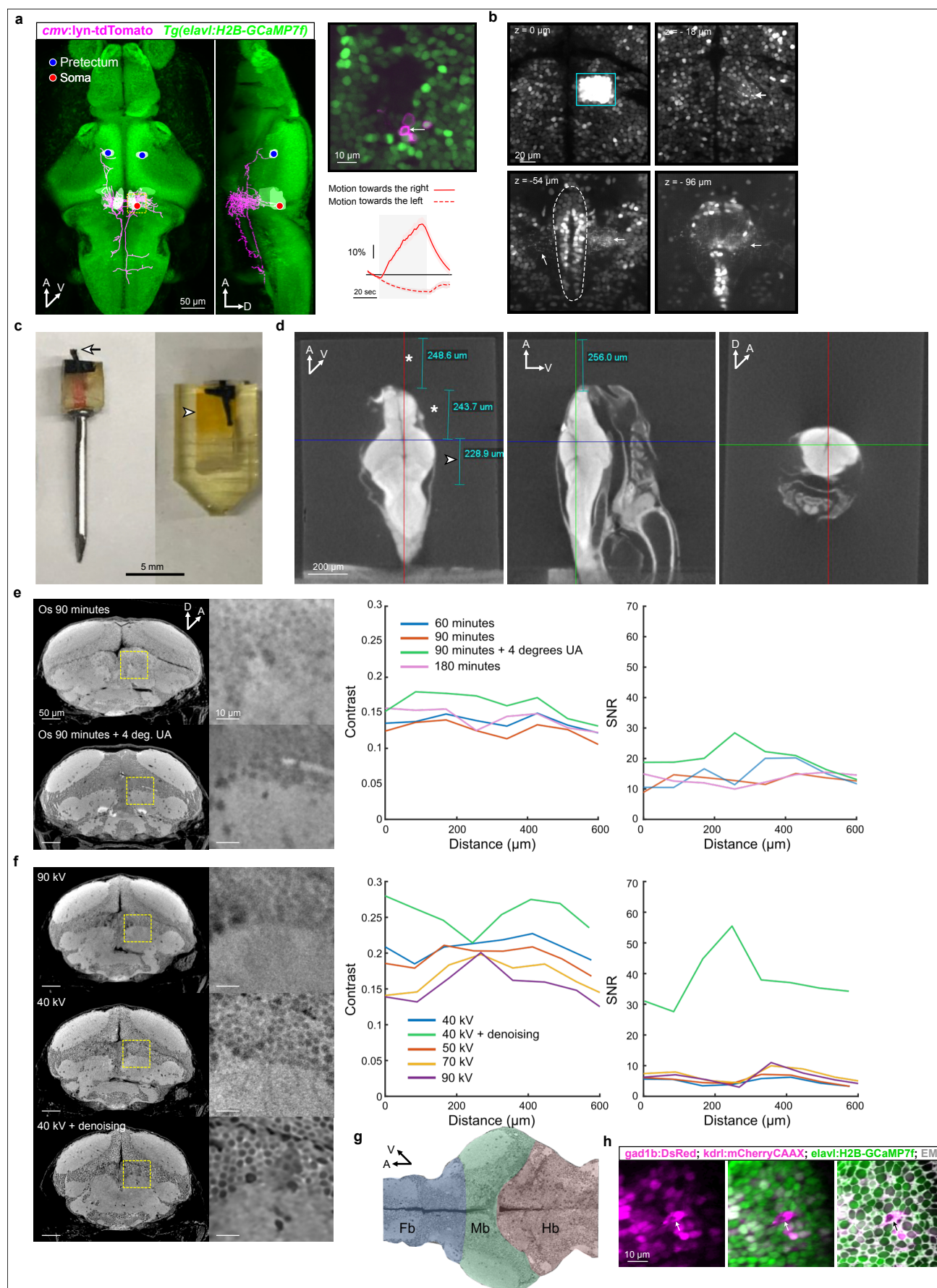
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Extended Data

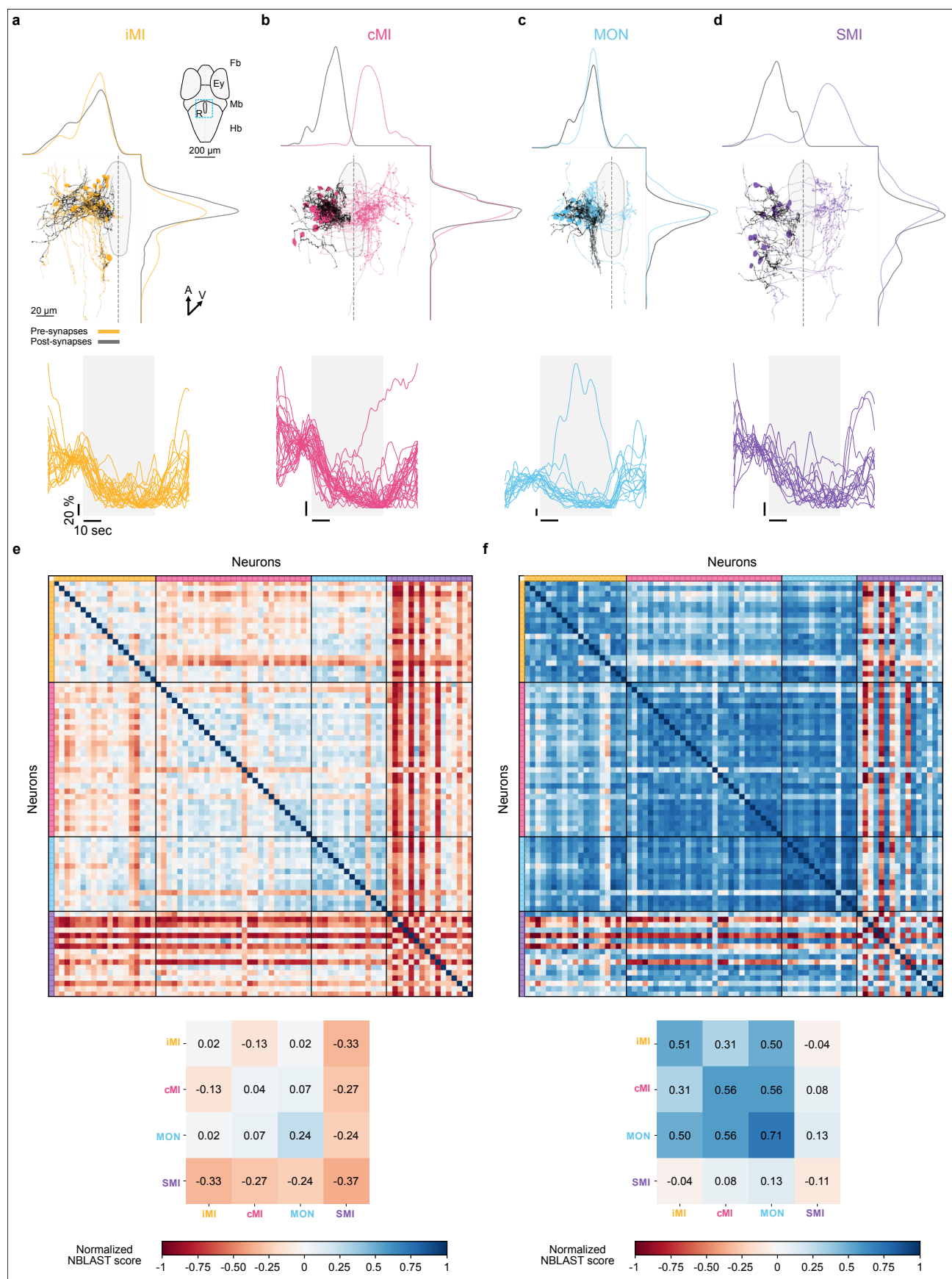


Extended Data Fig. 1 | Detailed analysis of neuronal functional recordings. (a) Raster plot of representative examples of direction-selective neurons belonging to the three functional classes. Four example trials, both for left- and rightward moving dots. Upper arrows represent the direction of motion and gray bars represent the stimulation epochs. Neurons are organized according to their functional responses (see left colored bars). Individual trials are separated by horizontal white bars. **(b)** Rise time to reach 90% of the maximal response for each k-means cluster. Each dot represents a single neuron. MON, motion onset neurons; MI-1, fast motion integrators; MI-2, intermediate motion integrators; SMI, slow motion integrators. **(c)** Distribution of neurons across brain regions and cluster types. **(d)** Left: spatial distribution of direction selectivity values for the three functional classes. Middle: histogram of direction selectivity values for the same population. Right: average values for neurons grouped by brain region. *** indicates $p < 0.001$ (two-sided t-test), **(e)** Same as **(d)** but for representing the time to reach 90% of the maximal response. Mb, midbrain; Pt, pretectum; Cb, cerebellum; Hb, hindbrain; Oth, other regions.



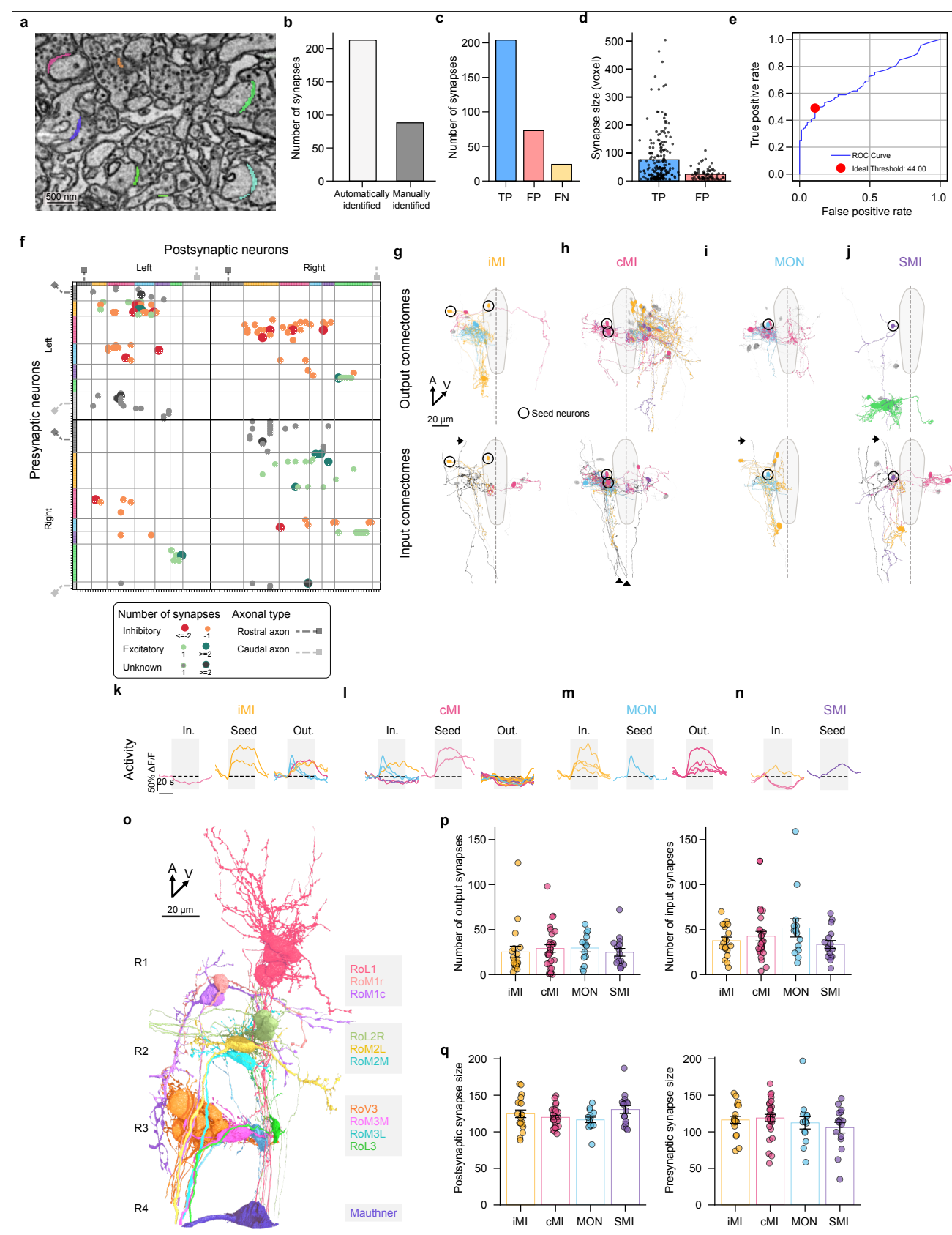
Extended Data Fig. 2 | Sample preparation and region of interest identification. (a) hindbrain sparse electroporations. Left panels: reconstructed neurons registered to a reference brain indicating soma and Pt locations. Note the projection pattern of the cells towards the Pt and ipsilateral and contralateral anterior hindbrain. The dashed yellow square is magnified in the top-right snippet. Right panels: two-photon single-plane image showing the somas of the electroporated neurons

together with response dynamics to rightward and leftward moving dots for one neuron (indicated by the white arrow). The activity responses are reminiscent of an evidence integrator. Activity traces show the average responses for 4 trials (SEM indicated by the red shaded area). Stimulation epoch is denoted by the shaded gray area. **(b)** Photoactivation of a group of neurons in the anterior hindbrain in *Tg(elavl3:H2B-GCaMP6s, gad1b:loxP-DsRed-loxP-GFP, alpha-tub:c3pa-GFP)* (cyan square). Cells project ventrally, ipsilaterally, and contralaterally close to the raphe (dashed outline at $z=-54\ \mu\text{m}$ from the photoactivation plane). Neuronal projections are indicated by the white arrows. **(c)** Left: A resin-embedded larva with the cast around the head trimmed (white arrow) for enhanced X-ray penetration. Right. Another larva re-embedded in resin after X-ray tomography before ultramicrotome sectioning. The limit between the two resin casts is denoted by the arrowhead. **(d)** Orthogonal X-ray tomography views of the main larva used in this study. The first panel shows the edges of the region of interest determined before the sections collection. By performing direct measurements using the X-ray microscope software we precisely targeted the sections collection by trimming away the unnecessary resin and tissue (white asterisks), keeping only the region of interest (white arrowhead) containing the anterior hindbrain and most of the identified neuronal projections **(a,b)**. **(e)** First step of contrast and signal to noise ratio (SNR) improvement achieved by varying the Osmium (Os) incubation duration and incubating the Uranyl Acetate (UA) at 4°C instead of room temperature. Left panels: Representative X-ray tomography cross sections along the main axis of the larva and high-resolution snippets (corresponding to dashed yellow squares). Right panels: Contrast and SNR computed along the main axis of the fish, see **Extended Data Fig. 2g**. Each line represents the average of two fish per condition. **(f)** Similar to **(i)** showing the improvement by changing the X-ray imaging power. Notice the dose-dependent improvement as the power is lowered from 90 to 40 kV. **(g)** Reference fish imaged with X-ray (dorsal section plane) indicating where the contrast and SNR measurements were performed. Distances correspond to the upper plots. Fb, forebrain; Mb, midbrain; Hb, hindbrain. **(h)** Images showing the alignment between the 2P and EM datasets confirming the precise correspondence of a blood vessel cross-section (indicated by a white arrow) across imaging modalities. Abbreviations: A, anterior; D, dorsal; V, ventral.

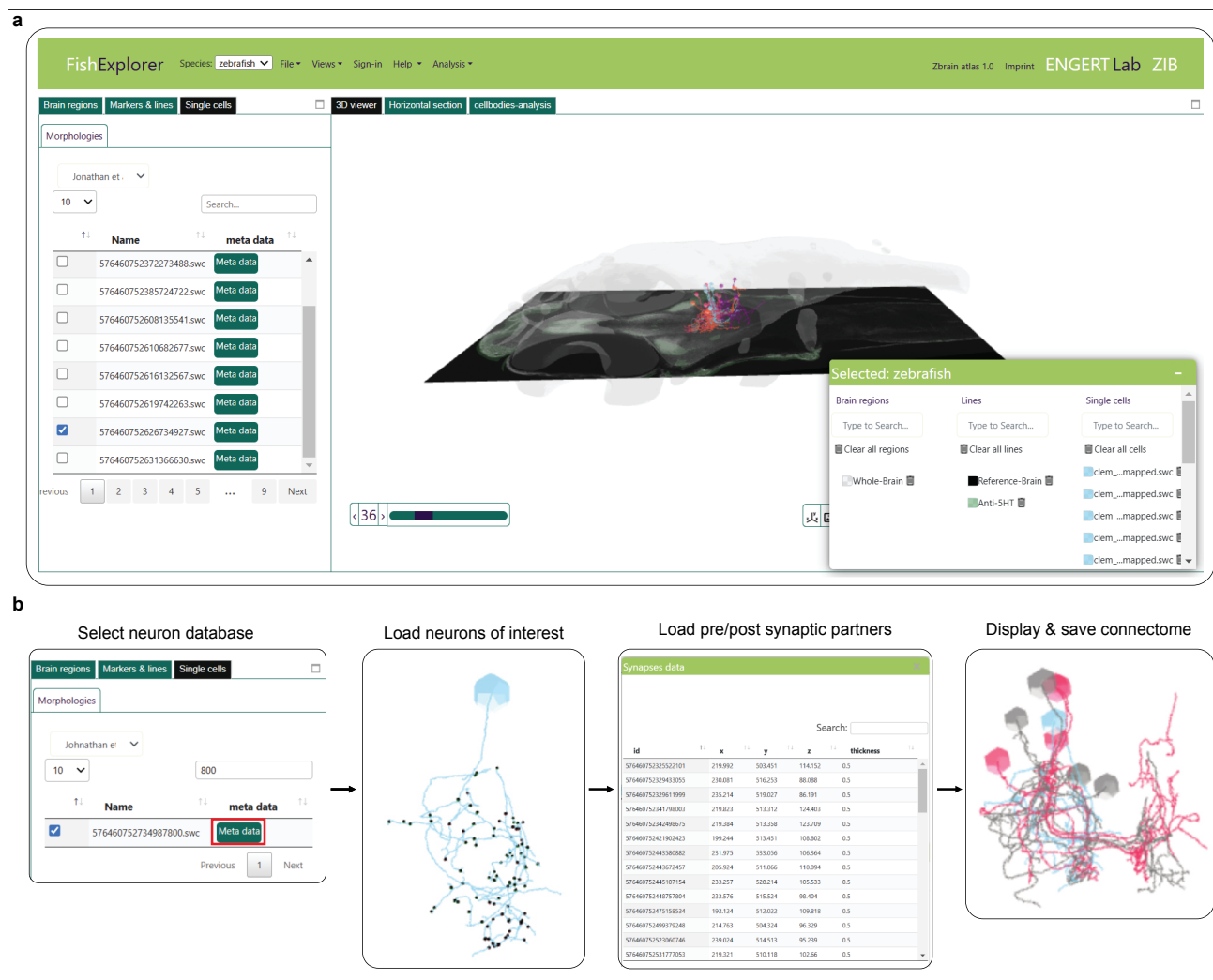


Extended Data Fig. 3 | Structure-function relationship and morphological diversity within and in-between clusters.
(a) Structure-function relationship of functionally imaged and reconstructed iMI neurons as in Fig. 1f-i but in dorsal view. Somas and axons are colored in orange and dendrites in black. Dashed line represents the midline. Surrounding plots are distribution of presynaptic (orange) and postsynaptic (black) synapses along the x (top) and y (right) axes. Right: schematic showing coarse brain organization (dorsal-to-ventral view) and location of the reconstructed neurons below (blue dashed square) surrounding outlines of the raphe (also shown below). Right: traces representing the normalized $\Delta F/F_0$ neuronal

activity over time for motion in the opposite, null direction. **(b-d)** shows identical representation for other neuron types. All neurons are registered to a reference brain (Randlett, Wee, E. a Naumann, *et al.*, 2015). Abbreviations: Mb, midbrain; Hb, hindbrain; R, raphe; Ey, eye; A, anterior; V, ventral. **(e-f)** Top matrices: Normalized NBLAST matrix organized by functional types using morphological similarity distances computed using *Drosophila* neurons **(e)** and the functionally identified neurons in this study **(f)**. Bottom : averaged NBLAST scores within and across functional types.



Extended Data Fig. 4 | Details of automated synapses predictions and functional dynamics of reconstructed connectomes examples. (a) Raw EM image with automatically detected synaptic clefts in color. (b) Histogram showing the number of automatically identified and manually identified synapses by visually inspecting two dendrites and one axon. (c) Classification of automatically predicted synapses as true positives, false positives (not synapses) and false negatives (missing synapses). (d) Comparison of synapse sizes between true positives and false positives. (e) Receiver Operating Characteristic (ROC) curve analysis establishing a size threshold at 44 voxels to exclude 90% of false positive synapses. (f) Connectivity matrix with neurons and connected axons sorted according to their functional types and hemispheres (thick black bars separate the left and right hemispheres). Rostral axons, truncated at the rostral end of the imaging volume, terminate within the volume, while caudal axons are truncated at the caudal end of the volume and also terminate within it. Axons that traverse the entire imaging volume are not shown. (g-h) Representative example connectomes (dorsal view) for one or two seed cells with corresponding activity related to **Fig. 2c-j**. All neuronal parts (some, axon and dendrites) are colored identically. All neurons are registered to a reference brain (Randlett, Wee, E. a Naumann, *et al.*, 2015). Black arrows and arrowheads represent example rostral and caudal axons, respectively. (k-n) Activity traces for the neurons shown in this figure (g-j) and **Fig. 2c-j** with visual stimulation epochs indicated by gray shaded areas. Dashes black lines correspond to $\Delta F/F=0$. (o) Rendering of identified reticulospinal neurons belonging to rhombomeres 1 to 4 (R1-4). (p) Histograms showing the distributions of synapses numbers and sizes (q) for each functionally identified cell type. Error bars represent standard error of the mean (SEM). Individual dots represent single neurons.



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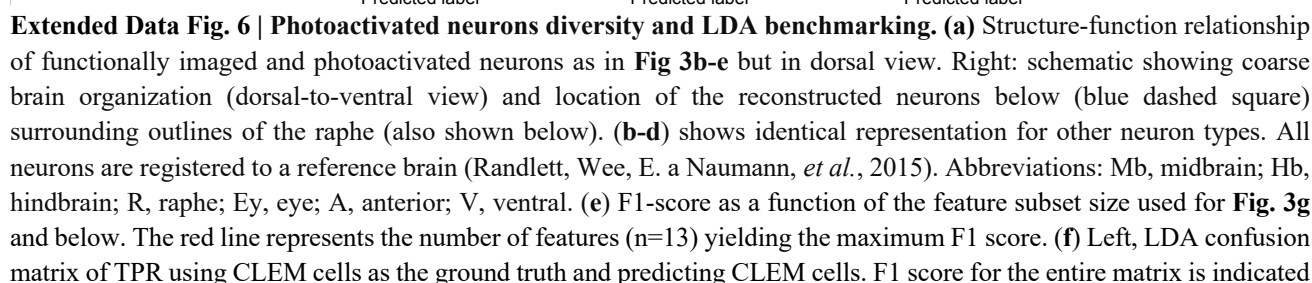
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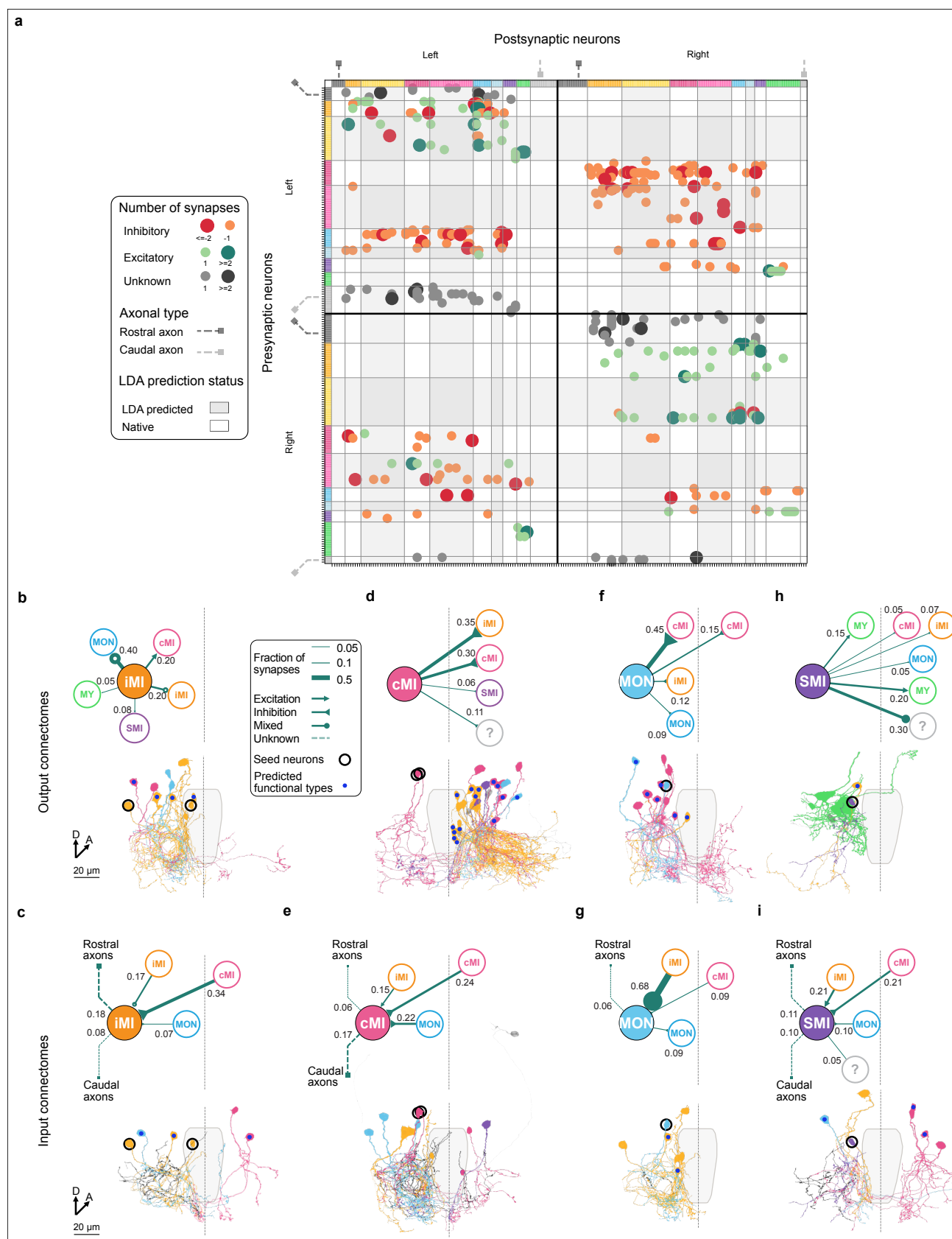
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Extended Data Fig. 5 | Details of automated synapses prediction and online neurons and connectome visualization.

(a) Multi-modal and multi species web based atlas platform contains annotations of all anatomical brain subdivisions and XX registered transgenic lines for deeper analyses. **(b)** Flowchart to visualize single neurons and connectomes in FishExplorer. To visualize single cells and connectomes users should first select the neuron of interest by selecting the appropriate dataset (correlated light and EM, photoactivated neurons, EM whole-brain Atlas) and tracer. To display the connectomes of a cell, users should then click the meta information button in the front of the neuron name highlighted by the red rectangle. The window shows meta information, input and out partners will appear on screen. Next, the user can load all the output partners by clicking the ‘load all output’ button. The researchers can also save and share their current analysis ‘scene’ of connectomes with the community.

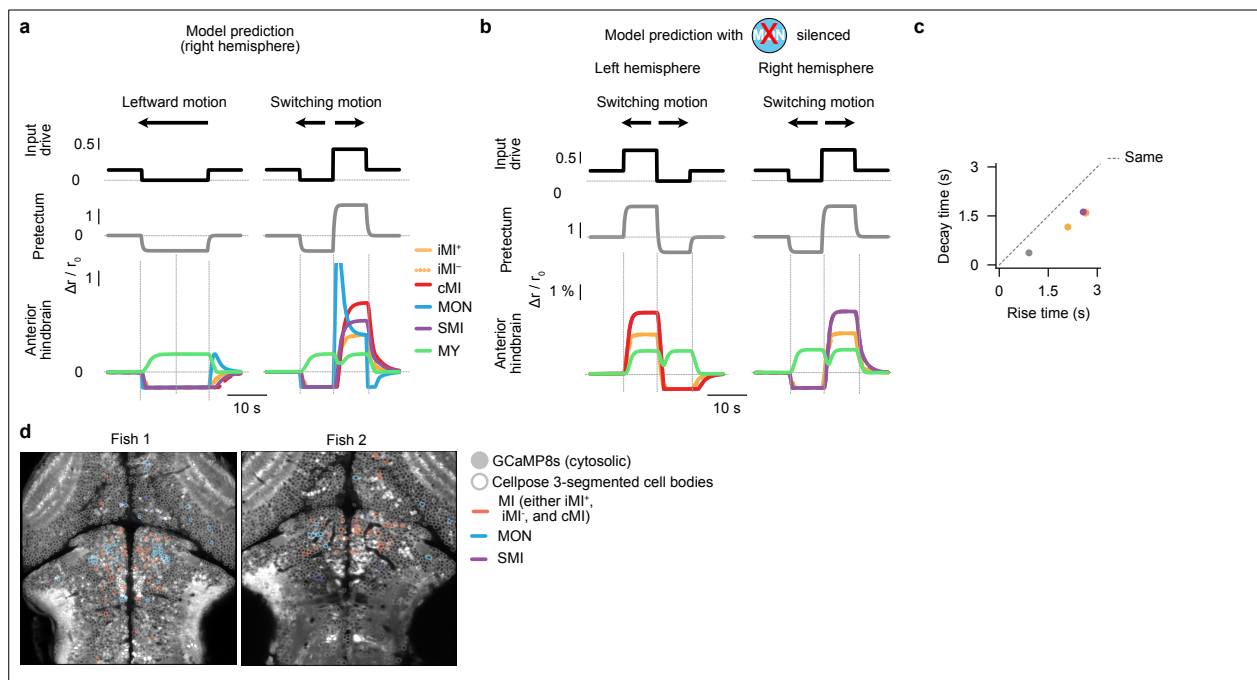


1358 in the title. Middle same as left but using PA as ground truth and predicting CLEM cells. Right, same as left but using PA
1359 as ground truth and predicting PA cells. LDA, linear discriminant analysis; RF, random forest. (g-i) Prediction of functional
1360 types using other established methods (persistence samples, persistence vectors and form factors metrics, respectively).
1361 Display is identical as (f).



Extended Data Fig. 7 | Enhanced connectome of the zebrafish anterior hindbrain. **a**, Connectivity matrix with neurons and connected axons sorted according to their functional types and hemispheres (thick black bars). Rostral axons, truncated at the rostral end of the imaging volume, terminate within the volume, while caudal axons are truncated at the caudal end of the volume and also terminate within it. Axons that traverse the entire imaging volume are not shown. **b–i**, Top diagrams: simplified connectivity motifs extracted from the connectivity matrix containing predicted and native identities. Connections accounting for less than 5% of the total synapse number are not shown. Bottom diagrams: Representative example connectomes (dorsal view) for one or two seed cells related to **Fig. 2c–j**. All neuronal parts (some, axon and

dendrites) are colored identically. All neurons are registered to a reference brain (Randlett, Wee, E. a Naumann, *et al.*, 2015).



Extended Data Fig. 8 | Simulated contralateral dynamics of anterior hindbrain cell types, ablation simulations, and raw imaging stacks. a, Same as in Fig. 4d, but for cells on the right brain hemisphere, when the motion stimulus starts moving to the left. **b**, Switching motion stimulus, as in Fig. 4d, for left and right brain hemispheres, for a network model in which MON cells have been silenced (rates clamped to zero). **c**, Rise and decay times (Methods) for all remaining model cells for dynamics in the left hemisphere (cMI dot, red, is behind SMI dot, magenta). **d**, Raw average two-photon imaging planes of 2 example larvae, exemplifying the expression of *Tg(elavl3:GCaMP8s)* and cellpose3 segmentation results (gray contours). Segmented and functionally assigned cell types, highlighted in colored cell body contours.

Extended Data Table 1 | All extracted 68 neuron morphometrics used to generate our functional cell type classifier.

#	Name	Extraction strategy
1	number of contralateral branches	custom code
2	number of ipsilateral branches	custom code
3	cable length	navis
4	bbox volume	navis
5	x_extent	navis
6	y_extent	navis
7	z_extent	navis
8	x average	custom code
9	y average	custom code
10	z average	custom code
11	soma x	custom code
12	soma y	custom code
13	soma z	custom code
14	tortuosity	navis
15	n_leafs	navis
16	n_branches	navis
17	n_ends	navis
18	n_edges	navis
19	main_branchpoint	navis
20	n_persistence_points	navis
21	max_strahler_index	navis
22	sholl_distance_max_branches	navis
23	sholl_distance_max_branches_cable_length	navis
24	sholl_distance_max_branches_geosidic	navis
25	sholl_distance_max_branches_geosidic_cable_length	navis
26	main_path_longest_neurite	custom code
27	main_path_total_branch_length	custom code
28	first_major_branch_longest_neurite	custom code
29	first_major_branch_total_branch_length	custom code
30	first_branch_longest_neurite	custom code
31	first_branch_total_branch_length	custom code
32	cable_length_2_first_branch	navis
33	z_distance_first_2_first_branch	navis
34	biggest_branch_longest_neurite	custom code
35	biggest_branch_total_branch_length	custom code
36	longest_connected_path	custom code
37	n_nodes_ipsi_hemisphere	custom code
38	n_nodes_contra_hemisphere	custom code
39	n_nodes_ipsi_hemisphere_fraction	custom code
40	n_nodes_contra_hemisphere_fraction	custom code
41	x_location_index	custom code
42	fraction_contra	custom code
43	y_extent_ipsi	custom code
44	z_extent_ipsi	custom code
45	max_x_ipsi	custom code
46	max_y_ipsi	custom code
47	max_z_ipsi	custom code
48	min_x_ipsi	custom code
49	min_y_ipsi	custom code
50	min_z_ipsi	custom code
51	max_x_contra	custom code
52	max_y_contra	custom code
53	max_z_contra	custom code
54	min_x_contra	custom code
55	min_y_contra	custom code
56	min_z_contra	custom code
57	avg_delta_death_birth_persistence	navis
58	median_delta_death_birth_persistence	navis
59	std_delta_death_birth_persistence	navis
60	z_extent_contra	custom code
61	y_extent_contra	custom code
62	midline crossing x	custom code
63	midline crossing y	custom code
64	midline crossing z	custom code
65	crossing angle	custom code
66	crossing angle 2D	custom code
67	morphology (ipsilateral or contralateral)	custom code
68	neurotransmitter (exc., inh., or unknown)	custom code

The list of all 68 morphometrics we extracted from each cell to build our functional cell type classifier. We used the navis package to compute features directly from .swc files and developed custom code to further extend feature space. Through a feature ranking with reverse feature elimination algorithm (see **Methods**), we identified 7 feature to be the best predictor of function (highlighted in red).