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Achieving unlimited recording length in interference lithography via broad-beam scanning exposure with self-referencing alignment

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Large-area holographic gratings are of great importance in diverse fields including long-range interference metrology, high-resolution astronomical telescopes, and chirped-pulse-amplification systems. However, in conventional interference lithography, the recording length is limited by the aperture of the collimating lenses. Here we propose broad-beam scanning exposure which employs the latent grating generated continuously during scanning for real-time dynamic fringe locking and thus achieves unlimited recording length. This method is experimentally proved to make high-quality gratings, and is expected to be a new type of interference lithography.

Large-area diffraction gratings play an important role in long-range interference metrology¹, high-resolution astronomical telescopes², and chirped-pulse-amplification systems^{3,4}. In conventional interference lithography, the grating size is limited by the aperture of collimating lenses⁵. Since attaining collimating lenses with large aperture and low aberration is difficult both technologically and financially, it is impractical to make a monolithic large grating in conventional methods. As alternatives, mosaic exposure and scanning exposure have been proposed.

In mosaic exposure, a small-size interference field is used as a seal to print the periodic patterns on the large-size substrate step by step, as shown in Fig. 1(a). In this method, one area of the substrate is exposed by the small-size interference field at a time, and then the substrate moves to the next position for the next exposure. In order to keep the wavefront of adjacent exposure areas continuous, it is vital to adjust the phase and attitude of the exposure fringes relative to the substrate between adjacent exposures. In 1996 Turukhano *et al.* proposed a phase synthesis technique to make long grating scales⁶. They utilized narrow auxiliary gratings placed alongside the substrate for phase adjustment and did not consider attitude adjustment. In 2009 Chen *et al.* proposed step-and-align interference lithography to make mosaic gratings on large wafers⁷. They used three red-wavelength interferometers to measure the position and attitude of the substrate and adjusted the translation stage by a three-axis piezo-electric transducer positioned on it. The use of external interferometers separated the alignment and exposure systems, and might introduce drift errors. Recently our group proposed a mosaic technique using diffraction from the latent grating (the exposed but not developed volume grating) for phase and attitude adjustment^{8,9}. The use of the latent grating unified the adjustment and exposure systems, and hence eliminated potential drift errors. However, although mosaic exposure is simple and convenient to make large gratings, the mosaic seam between adjacent exposures degrades the grating quality and brings detrimental effects in use.

Besides mosaic exposure, scanning exposure is another effective method to make large gratings, where the substrate moves continuously through the exposure area. Narrow-beam scanning exposure was proposed by Schattenburg *et al.*^{10–15}, where a millimeter-diameter-size interference field was used as a ballpoint pen to write the grating lines on the moving substrate continuously, as shown in Fig. 1(b). The researchers first scanned the substrate along the grating grooves using the millimeter-size interference field. Then they moved the substrate a little along the grating vector (in the direction perpendicular to the grooves) for the next scanning. They measured the position of the substrate by a red-wavelength interferometer and adjusted the phase of the exposure fringes by acoustic optical modulators, to make the fringes “frozen” on the substrate all along during scanning. This system needs sophisticated and costly opto-electronic controls, so it is not easy to be implemented by others.

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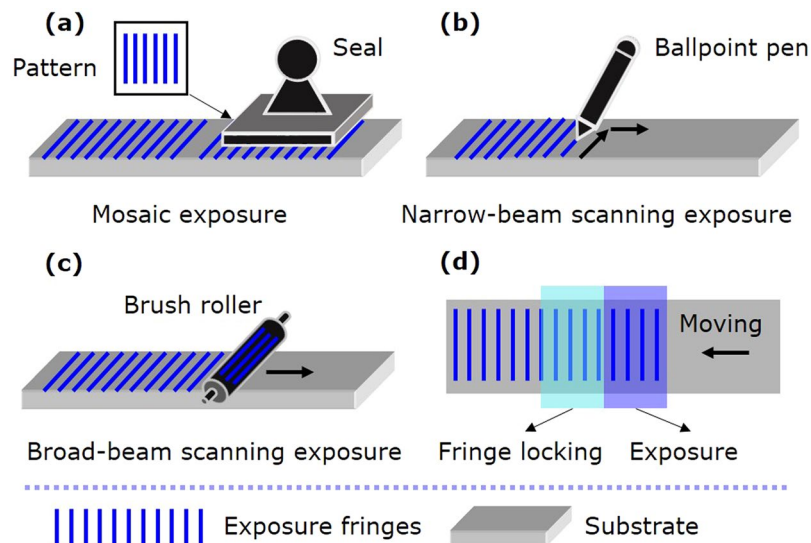


Figure 1. Schematic of different exposure methods. (a) Mosaic exposure. (b) Narrow-beam scanning exposure. (c) Broad-beam scanning exposure. (d) Main idea of this work.

Also, the separation of the measurement and exposure systems may introduce drift errors. Near-field scanning exposure was proposed by Jourlin *et al.*^{16–18}, where an expanded laser beam illuminated a transmission grating to generate interference fringes for exposure. They used a grating scale nearby to measure the position of the substrate, and modulated the intensity of the exposure interferogram accordingly. This system is compact and stable, but brings difficulties to suppress the diffraction of unwanted orders¹⁹. In 2015 we reported our work on broad-beam scanning exposure along the grating vector to make gratings with low stray light²⁰. In this method, one half of the interference field was used for exposure, and the other half was used to illuminate the reference grating alongside the substrate for phase and attitude alignment. As a consequence, the recording length was still limited by the size of the reference grating.

Here we develop an improved broad-beam scanning exposure method to achieve unlimited recording length, which takes advantage of the latent grating on the substrate itself for real-time dynamic fringe locking. The use of the latent grating unifies the alignment and exposure systems, and thus makes this method simple and stable. This method has been verified experimentally to make large gratings. Meanwhile, it maintains the advantage of scanning exposure to make gratings with straight grooves, smooth surface, and low stray light²⁰. This method is expected to be a new type of interference lithography.

Results

Main idea. In this method, broad beam means that the exposure area has a width equal to the substrate width in the grating groove direction and a centimeter-scale length in the grating vector direction. Therefore, the interference field is used as a brush roller to paint the grating structures continuously on the moving substrate from beginning to end, as shown in Fig. 1(c). To avoid fringe smearing during scanning, it is vital to keep the exposure interference fringes stationary relative to the substrate, which is named fringe locking. The latent grating on the exposed area of the substrate can reflect the phase and attitude of the interference fringes relative to the substrate, so it is used for dynamic fringe locking as shown in Fig. 1(d). Since the latent grating is generated continuously on the substrate itself during scanning exposure, this type of interference lithography can achieve unlimited recording length. This is the main idea of our work.

Scanning exposure system. Figure 2 shows the scanning exposure system. The x , y , and z axes are respectively along the directions of grating vector, grating groove, and normal of substrate surface. The photoresist-coated substrate Sub and a prefabricated reference grating G_0 are mounted abreast with their front surfaces coplanar. They are clamped together on a motorized translation stage (not shown in the figure) that can move along the x axis. When the shutter K is open, the laser beam is divided by the polarizing beam splitter (PBS) into two beams. The half-wave plate WP_1 adjusts their intensity ratio, while WP_2 makes the transmitted beam have the same polarization state as the reflected one. The two beams are directed by the mirrors M_1 , M_2 , M_3 and modulated by the acoustic optical modulators AOM₁ and AOM₂. The -1 st-order diffraction beams from AOM₁ and AOM₂ are respectively expanded and cleaned up by the spatial filters SF₁ and SF₂, collimated by the lenses L_1 and L_2 , and become two broad coherent beams B_1 and B_2 . B_1 and B_2 are respectively limited by the optical diaphragms D_1 and D_2 to form rectangular cross sections.

Two attenuators A_1 and A_2 are used to divide the optical system into an exposure sub-system and a fringe locking sub-system. As shown in Fig. 2, A_1 is a parallel plate with a transmissivity of 10^{-2} , and A_2 is a plate with a wedge angle $\alpha = 18^\circ$ and a transmissivity of 10^{-5} . A_1 divides the beam B_1 into three sub-beams named B_{R1} , B_{L1} , and B_{E1} (the subscript R stands for “reference”, L stands for “latent”, and E stands for “exposure”), while A_2 divides

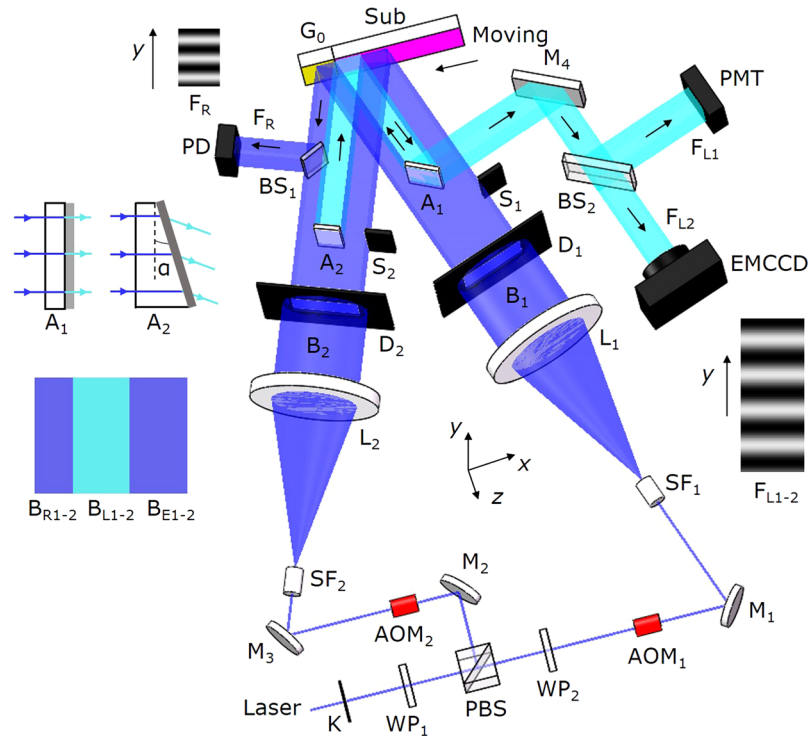


Figure 2. Illustration of experimental setup. K: Shutter; PBS: Polarizing beam splitter; WP₁₋₂: Half-wave plate; AOM₁₋₂: Acoustic optical modulator; M₁₋₄: Mirror; SF₁₋₂: Spatial filter; L₁₋₂: Collimating lens; D₁₋₂: Optical diaphragm; S₁₋₂: Baffle; A₁₋₂: Attenuator; BS₁₋₂: Beam splitter; PD: Photoelectric detector; PMT: Photomultiplier; EMCCD: Electron-multiplying charge-coupled device; G₀: Reflective reference grating; Sub: Photoresist-coated substrate; F_R: Interference fringes generated by the reference grating G₀; F_{L1-2}: Interference fringes generated by the latent grating; B_{R1-2}, B_{L1-2}, and B_{E1-2}: Sub-beams (the subscript R stands for “reference”, L stands for “latent”, and E stands for “exposure”). B_{L1} and B_{L2} are drawn in the lighter color to indicate that their intensities are attenuated by A₁ and A₂.

B₂ into B_{R2}, B_{L2}, and B_{E2}. The sub-beams B_{E1} and B_{E2} generate interference fringes on the substrate for exposure, while B_{R1}, B_{R2}, B_{L1}, and B_{L2} are used for fringe locking during exposure.

Fringe locking technique. The simplified steps of scanning exposure are as follows. First move away the attenuators A₁ and A₂, and use the sub-beams B_{L1} and B_{L2} to do stationary exposure on an area of the substrate while using the reference grating G₀ for fringe locking. After that, insert the attenuators into the optical paths and use the latent grating generated on the exposed area for fringe locking. Then move the substrate to pass through the interference field formed by B_{E1} and B_{E2} for scanning exposure. As scanning proceeds, new latent gratings are generated continuously on the newly-exposed area, and they substitute the old ones in subsequent fringe locking.

In stationary exposure, to avoid environmental disturbance, we do phase locking using the reference grating G₀. As shown in Fig. 2, G₀ is illuminated by the sub-beams B_{R1} and B_{R2}. The 0th order of B_{R1} and the -1st order of B_{R2}, diffracted by G₀, form a set of interference fringes F_R. F_R is reflected by the beam splitter BS₁ and projected onto the photoelectric detector (PD). We use PD to measure the intensity V_R of one point on F_R as the phase information. The difference ε between V_R and the target value V_{R0} is fed to the PID controller, as shown in Fig. 3(a). The output voltage U is converted to a frequency signal Δf and amplified to change the frequency of AOM₁ for phase compensation, until $\varepsilon = 0$. In this way, the phase is locked during stationary exposure.

Here we focus on the dynamic fringe locking technique in scanning exposure. As shown in Fig. 2, when the attenuators A₁ and A₂ are inserted into the optical paths, the latent grating is illuminated by the attenuated sub-beams B_{L1} and B_{L2}. The +1st order of B_{L1} and the 0th order of B_{L2}, diffracted by the latent grating, form a set of interference fringes, which is named latent interference fringes. The latent interference fringes are reflected by A₁ and M₄, and divided into F_{L1} and F_{L2} by the beam splitter BS₂. F_{L1} is projected onto the photomultiplier (PMT), while F_{L2} is recorded by the electron-multiplying charge-coupled device (EMCCD). We use the latent interference fringes F_{L1} and F_{L2} together for phase and attitude locking.

In order to get high response frequency and low intensity dependence, we utilize PMT and EMCCD together for phase locking. When the substrate moves, to avoid fringe smearing, the scanning formula $\Delta f = v/d^{10}$ should be strictly satisfied, where Δf is the frequency difference between the two beams, v is the moving speed of the substrate, and d is the period of the exposure interference fringes. If the scanning formula is not satisfied, the latent interference fringes will have a phase shift. Similarly, we use PMT to measure the real-time intensity V_p of the detection point P on F_{L1}, get the error ε between V_p and the target value V_{p0}, and then feed it back to AOM₁ for phase compensation, as shown in Fig. 3(a).

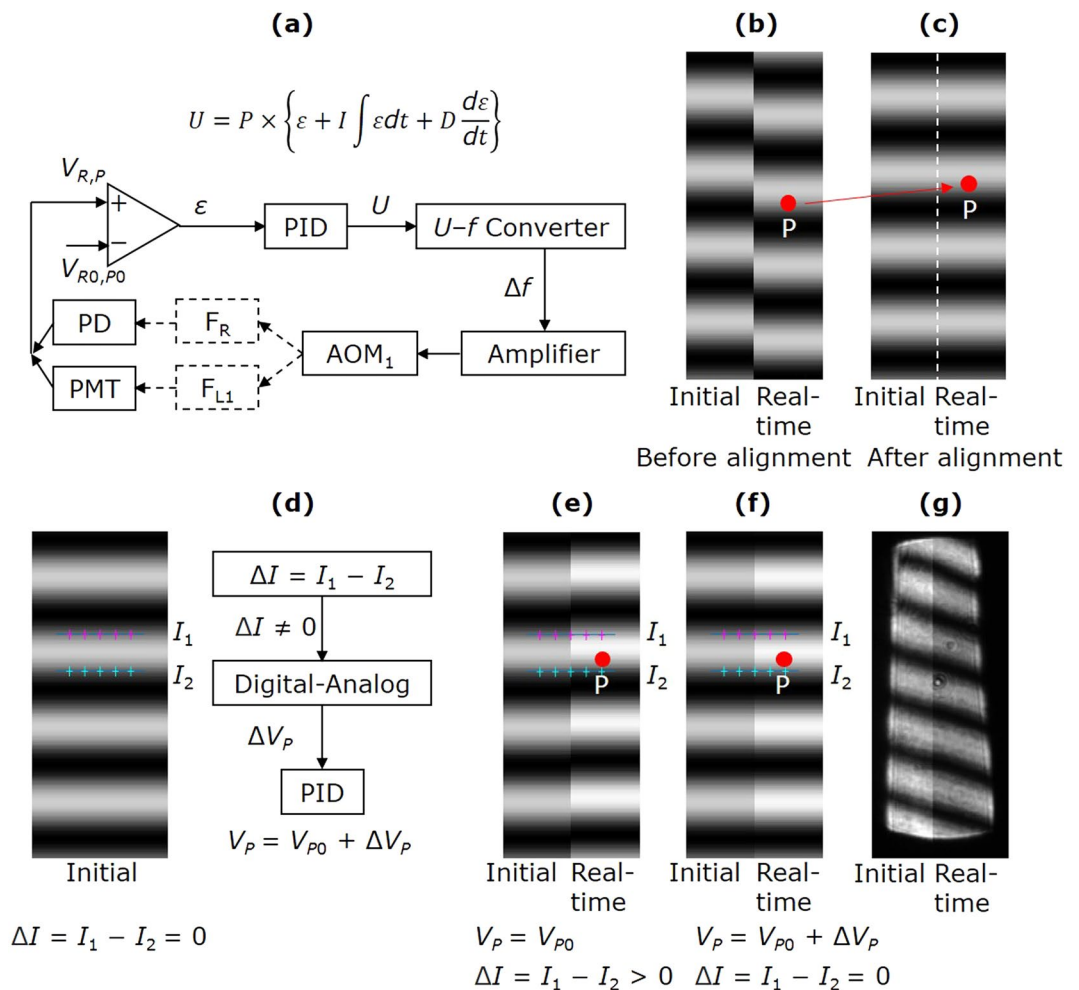


Figure 3. Fringe locking technique. (a) Phase locking loop using PD or PMT. (b) Phase misalignment between the initial and real-time latent interference fringes when the position of the detection point P is not suitable. (c) Phase alignment between the initial and real-time latent interference fringes after adjusting the position of the detection point P along the y axis. (d) Phase locking loop using EMCCD. (e) Phase misalignment when the intensity of the latent interference fringes increases. V_p is locked to V_{p0} , and the real-time average gray level difference $\Delta I > 0$. (f) Phase alignment after phase locking using EMCCD. $V_p = V_{p0} + \Delta V_p$, and $\Delta I = 0$. (g) Actual latent interference fringes recorded during scanning exposure. The real-time and initial latent interference fringes are aligned well although the intensity changes obviously.

Two points should be noted when using PMT for phase locking. First, the target value V_{p0} of phase locking will affect the locking sensitivity and stability. Second, after phase locking, the real-time latent interference fringes should be aligned with the initial ones to keep the wavefront continuous between the scanning and stationary exposure areas.

First we choose a suitable target value V_{p0} . If the scanning formula $\Delta f = v/d$ is not satisfied, the intensity V_p varies as a sinusoidal curve and has the largest derivative in the mid-value of its range. We set $\Delta f = 1$ Hz before locking to find the maximum and minimum values of V_p , and then set $V_{p0} = (V_{pmax} + V_{pmin})/2$. In this case, locking V_p to V_{p0} is sensitive and stable.

Then we align the fringes. Right after stationary exposure, we use EMCCD to record the initial latent interference fringes F_{L2} , and then lock V_p to V_{p0} as mentioned above. At this time, the real-time and initial latent interference fringes are usually misaligned as shown in Fig. 3(b). We move PMT along the y axis to adjust the position of the detection point P while comparing the real-time and initial latent interference fringes from EMCCD, until they are aligned as shown in Fig. 3(c). In this case, we can realize good alignment as well as sensitive and stable locking.

In another aspect, since this phase locking is based on the intensity of one single point, it is easy to be affected by the intensity variation of the latent interference fringes, which is inevitable due to the non-uniformity of the photoresist thickness. In order to eliminate the influence of the intensity variation, we use EMCCD to adjust the target value V_{p0} . An image-processing program is used to extract the phase information from the latent interference fringes F_{L2} . The program samples two rows of points that are symmetrical about one arbitrary fringe in the initial image, as shown in Fig. 3(d). Then the program calculates the average gray level I_1 of the pink points and

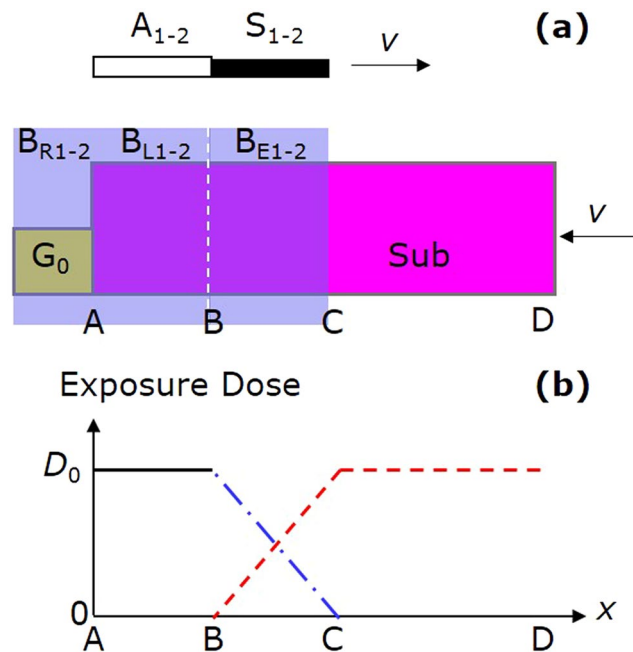


Figure 4. Linear exposure technique. (a) Exposure procedure. The pink and yellow rectangles denote the substrate and the reference grating G_0 respectively. The blue rectangles denote the sub-beams B_{R1-2} , B_{L1-2} , and B_{E1-2} . The gray rectangle denotes the attenuators A_{1-2} . The black rectangle denotes the baffles S_{1-2} . (b) Exposure dose distribution. The black solid, blue dash-dotted, and red dashed lines respectively denote the exposure doses during stationary, linear, and scanning exposures.

I_2 of the blue points. Because of symmetry, the average gray level difference $\Delta I = I_1 - I_2 = 0$. Moreover, as long as the phase does not shift, ΔI will be zero no matter how the average intensity changes. During scanning exposure, when the intensity of the latent interference fringes changes, for example increases as shown in Fig. 3(e), if V_p is still locked to V_{p0} , the real-time fringes will shift up, resulting in $\Delta I = I_1 - I_2 > 0$. Then the program outputs a voltage ΔV_p to the PID controller, which locks V_p to $V_{p0} + \Delta V_p$ and thus pulls the fringes back. The locking loop repeats until $\Delta I = 0$, as shown in Fig. 3(f). Figure 3(g) shows the actual latent interference fringes recorded during scanning exposure. It is seen that although the average intensity of the fringes varies obviously, the phases of the real-time and initial fringes are still aligned, which verifies the intensity independence of phase locking.

Besides the phase error, the angular errors of the translation stage lead to the attitude errors of the substrate relative to the exposure fringes. The rotation of the substrate about the z axis (the pitch angle of the stage) gives rise to an error in groove direction, meaning a spacing variation of the latent interference fringes. It can be compensated by shifting the pinhole of SF_2 along the y axis. The rotation of the substrate about the y axis (the yaw angle of the stage) leads to an error in grating period, meaning a tilt of the latent interference fringes. It can be compensated by shifting the pinhole of SF_2 in the direction perpendicular to the beam in the x - z plane. Since this error is second-order of the small rotation angle, it is omitted in experiments. The movements of the substrate along the y and z axes and the rotation about the x axis have no influence on exposure. The attitude errors are also extracted from the latent fringe images and compensated by adjusting the exposure fringes accordingly. Since the algorithm is similar to phase locking, here we will not give more details.

From above it is seen that the dynamic fringe locking technique has high locking stability and low intensity dependence. With this technique, the latent interference fringes are kept stationary during scanning exposure. In other words, the exposure fringes are “frozen” on the substrate.

Linear exposure technique. Linear exposure is another key technique in order to make the exposure dose uniform. When talking about the exposure doses, we do not consider the non-uniformity of the beams themselves.

As shown in Fig. 4(a), before exposure the baffles S_1 and S_2 block B_{E1} and B_{E2} respectively, and the attenuators A_1 and A_2 are not in the optical paths. When exposure starts, we move S_1 and S_2 along the $+x$ direction, and use B_{L1} , B_{L2} and the unblocked parts of B_{E1} and B_{E2} to expose the areas AB and BC. The moving speed of the baffles satisfies $v = b_E/T$, where b_E is the length of B_{E1-2} , and T is the exposure time. As shown in Fig. 4(b), when this exposure ends, the exposure dose of the area AB is a constant D_0 as the black solid line shows, while that of the area BC changes from D_0 to 0 linearly as the blue dash-dotted line shows. Then we insert A_1 and A_2 into the optical paths to get the latent interference fringes. After that, we start to move the substrate in a speed v and use B_{E1} and B_{E2} for scanning exposure. During scanning exposure, the exposure doses of the areas BC and CD are shown as the red dashed lines in Fig. 4(b). Therefore, the total exposure doses of the areas AB, BC, and CD are all equal to D_0 . In this way, we can make gratings with a uniform exposure dose along the grating vector direction. Moreover, using

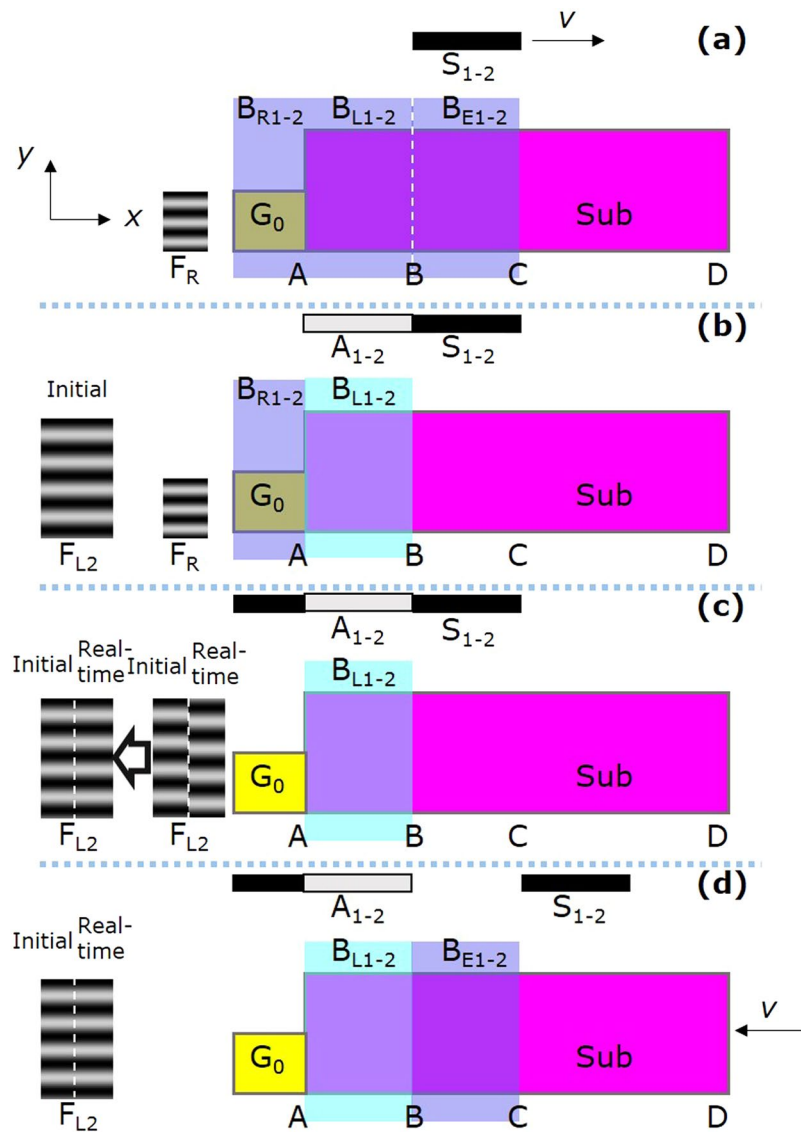


Figure 5. Scanning exposure procedure. (a) Stationary and linear exposures. (b) Initial latent interference fringes recording. (c) Dynamic fringe locking preparation. (d) Scanning exposure.

this exposure procedure can avoid the mosaic seam between the areas AB and BC. We refer to the areas AB, BC, and CD as the stationary, linear, and scanning exposure areas.

The scanning exposure procedure is shown in Fig. 5. After stationary and linear exposures [Fig. 5(a)] we get the initial latent interference fringes, and record them using EMCCD [Fig. 5(b)]. Then we prepare for the dynamic fringe locking [Fig. 5(c)] and start scanning exposure [Fig. 5(d)], until the whole substrate moves out of the exposure interference field. More details can be found in Methods.

Experimental results. To prove the feasibility of this exposure method, we made gratings with different photoresist thickness and duty cycles (the ratio of the linewidth to the grating period). Gratings were fabricated on quartz substrates of a size $200\text{ mm} \times 100\text{ mm}$. A chromium film of about 120 nm thick was coated on the substrates. The grating period $d = 570\text{ nm}$, which was determined by the exposure wavelength λ_E and the half-angle θ between the beams B_1 and B_2 as $d = \lambda_E / (2\sin\theta)$. The duty cycle was determined by the exposure dose and the development time²¹.

Figure 6(a) shows the photograph of a grating with a photoresist thickness of 150 nm . The whole grating is bright and uniform by appearance. We randomly chose three sample points on different exposure areas and observed their microstructures by the atomic force microscope (AFM), as shown in Fig. 6(b–d). The average duty cycles of the stationary, linear, and scanning exposure areas are respectively 0.41 , 0.40 , and 0.41 in the measurement area of $5\text{ }\mu\text{m} \times 5\text{ }\mu\text{m}$. Similarly, the photograph of a grating with a photoresist thickness of 340 nm is shown in Fig. 7(a), and the microstructures of the randomly-chosen sample points are shown in Fig. 7(b–d). The average duty cycles of the stationary, linear, and scanning exposure areas are respectively 0.52 , 0.53 , and 0.51 in

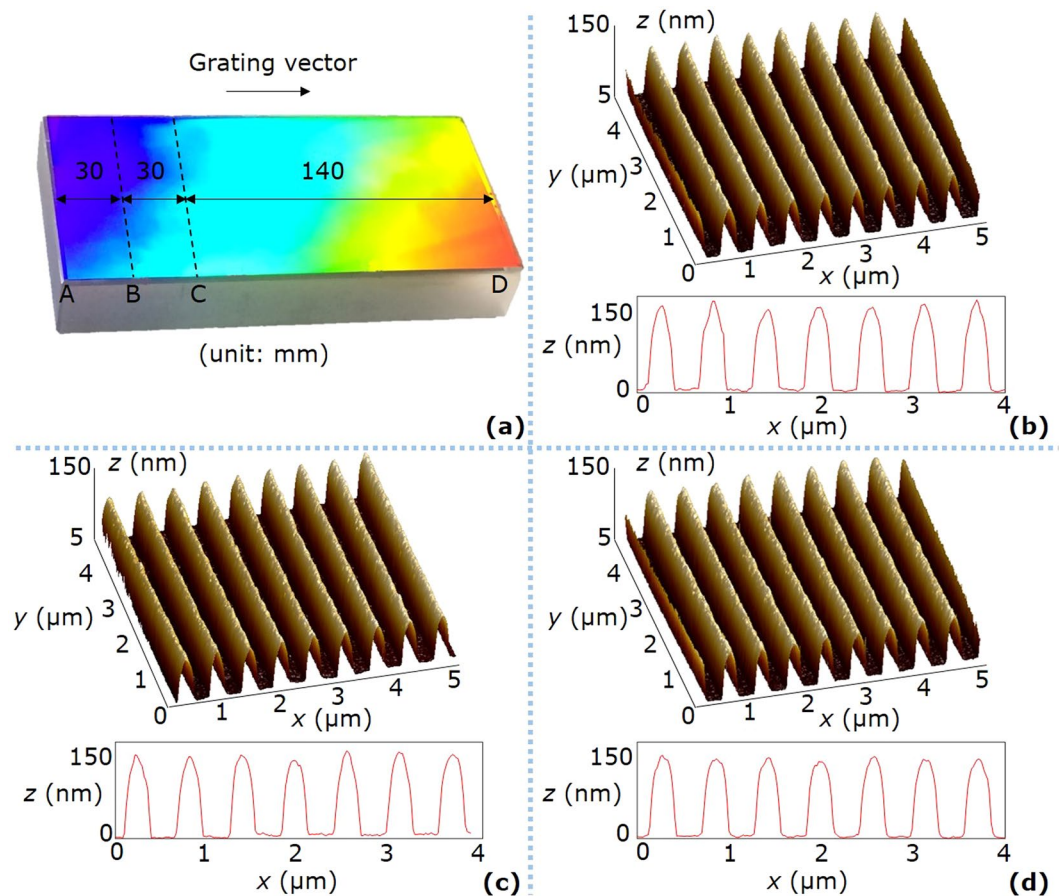


Figure 6. Photograph and AFM images of the grating with a photoresist thickness of 150 nm. (a) Photograph of the grating. AB is the stationary exposure area of a size 30 mm \times 100 mm, BC is the linear exposure area of a size 30 mm \times 100 mm, and CD is the scanning exposure area of a size 140 mm \times 100 mm. (b) AFM image of the sample point on the area AB. The average (AVE) and standard deviation (STD) of the duty cycles are respectively 0.41 and 0.02. (c) AFM image of the sample point on the area BC. The AVE and STD of the duty cycles are respectively 0.40 and 0.02. (d) AFM image of the sample point on the area CD. The AVE and STD of the duty cycles are respectively 0.41 and 0.01. For (b–d), the measurement area is 5 μ m \times 5 μ m, and the groove structures in the mid-line of the measurement area are shown at the bottom of each sub-figure.

the measurement area of 5 μ m \times 5 μ m. Therefore, from both macro and micro perspectives, the grating structures in the stationary, linear, and scanning exposure areas do not have obvious difference, proving that the fabricated gratings have good uniformity.

We used the Zygo interferometer to measure the non-flatness of the substrate and the spacing error²² of the grating in Fig. 6. The measurement area is 187 mm \times 87 mm. The non-flatness distribution of the substrate is shown in Fig. 8(a), whose peak-valley (PV) and root-mean-square (RMS) values are 0.110 λ and 0.021 λ , respectively. The spacing error distribution of the grating is shown in Fig. 8(b), whose PV and RMS values are 0.133 λ and 0.023 λ , respectively. These wavefront measurement results show the high quality of the fabricated grating.

Above-mentioned experimental results prove the feasibility of this method in fabricating large-area gratings.

Discussion

First, we analyze the fringe locking frequency and resolution. The bandwidth of the PID controller is 100 kHz. Due to the electronic noise, the intensity signal fluctuation is 100 mV. In experiments, we have $V_{Pmax} = 2.0$ V, $V_{Pmin} = 0.6$ V, and the target value $V_{P0} = (V_{Pmax} + V_{Pmin})/2 = 1.3$ V. So the signal fluctuation of 100 mV means a phase variation $\Delta\varphi = 100 \times 10^{-3} \times 2/(2.0 - 0.6) = 0.045\pi$. Therefore, the phase is locked to V_{P0} with a resolution of 0.045 π every 10 μ s. The refresh frequency of ΔV_P is 1 Hz. The latent interference fringes recorded by EMCCD have a spacing of 30 pixels, while the image algorithm can recognize the mismatch of one pixel. Therefore, the target value is finely adjusted at a frequency of 1 Hz with a resolution of $1/30 \times 2\pi = 0.067\pi$. The refresh frequency of attitude locking is 20 Hz. The recorded latent interference fringes have a height of 200 pixels. When the substrate is rotated $\Delta\theta_z$ about the z axis, the spacing variation equals $\Delta e = e_0^2 \Delta\theta_z/d$, where the fringe spacing $e_0 = 10$ mm, $\Delta e/e_0 = 1/200$, and $d = 570$ nm. Therefore, the attitude is aligned at a frequency of 20 Hz with a resolution of $\Delta\theta_z = 1/200/10 \times 570 \times 10^{-6} = 0.3 \mu\text{rad} = 0.06''$.

Second, we remark on the applicable range of our method regarding the grating period. The theoretical minimal grating period satisfies $d = \lambda_g/2 = 199$ nm, when the half-angle θ between the beams B_1 and B_2 equals 90°.

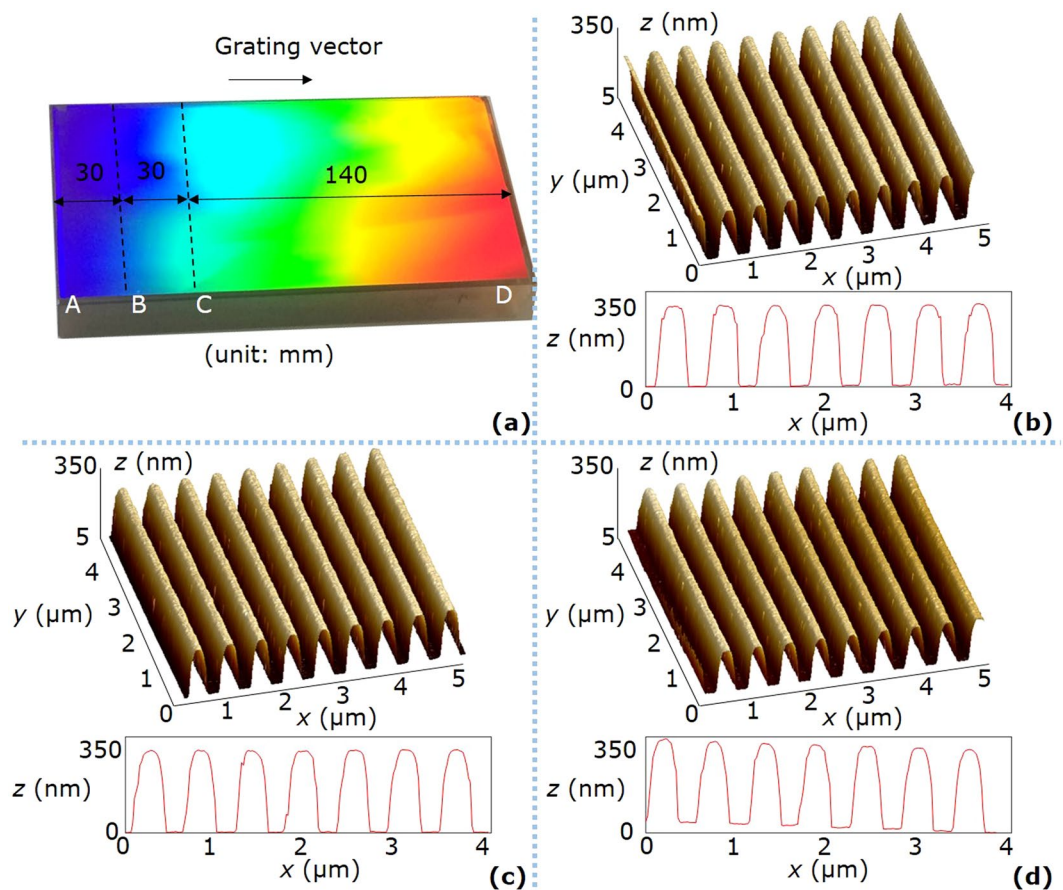


Figure 7. Photograph and AFM images of the grating with a photoresist thickness of 340 nm. (a) Photograph of the grating. AB is the stationary exposure area of a size 30 mm × 100 mm, BC is the linear exposure area of a size 30 mm × 100 mm, and CD is the scanning exposure area of a size 140 mm × 100 mm. (b) AFM image of the sample point on the area AB. The AVE and STD of the duty cycles are respectively 0.52 and 0.01. (c) AFM image of the sample point on the area BC. The AVE and STD of the duty cycles are respectively 0.53 and 0.01. (d) AFM image of the sample point on the area CD. The AVE and STD of the duty cycles are respectively 0.51 and 0.01. For (b–d), the measurement area is 5 μm × 5 μm, and the groove structures in the mid-line of the measurement area are shown at the bottom of each sub-figure.

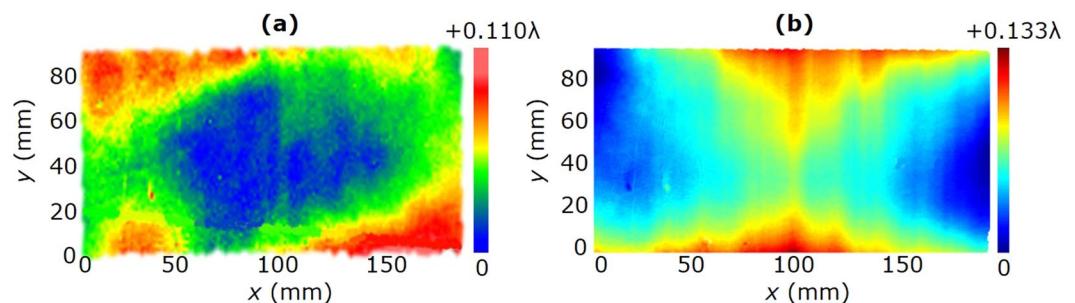


Figure 8. Wavefront measurement results. (a) Non-flatness of the substrate. The PV and RMS values are respectively 0.110λ and 0.021λ . (b) Spacing error of the grating. The PV and RMS values are respectively 0.133λ and 0.023λ . For both (a,b), the measurement area is 187 mm × 87 mm.

However, to make such a small-period grating, the scanning exposure system demands higher stability, thus we may need to increase the fringe locking frequency and accuracy. The maximal grating period is limited only by the spatial layout constraint of the exposure system. The need for a very small half-angle θ is in conflict with the desirable aperture size of the collimating lenses and the available length of the optical table.

Third, we compare the broad-beam scanning exposure with the previous methods. Compared with the mosaic exposure method, this method eliminates the seams of mosaic gratings which have detrimental effects in grating

applications. Compared with previous scanning exposure methods, this method employs the latent grating for dynamic fringe locking, which unifies the exposure and alignment systems and does not need sophisticated controls.

It is necessary to note that although we only made gratings of a size 200 mm × 100 mm in experiments, this method has no recording length limit in principle due to the use of the latent grating. Its recording length only depends on the length of the substrate.

In conclusion, we develop a broad-beam scanning exposure method which eliminates the recording length limit in conventional interference lithography. It takes advantage of the latent grating to adjust the phase and attitude of the exposure fringes relative to the substrate in real time, so it is a self-referencing method. Its feasibility in grating fabrication has been proved experimentally. Therefore, this method is simple and effective, and is expected to be a new type of interference lithography.

Methods

Scanning exposure procedure. The detailed scanning exposure procedure is as follows.

- (1) Do stationary and linear exposures.
Do stationary exposure using the unattenuated sub-beams B_{L1-2} for a time T . The phase locking is performed with F_R . As soon as the exposure starts, move the baffles S_{1-2} along the $+x$ direction in a speed $v = b_E/T$ to do linear exposure using B_{E1-2} .
- (2) Record the initial latent interference fringes.
Insert S_{1-2} again to block B_{E1-2} , and insert the attenuators A_{1-2} to generate latent interference fringes. Continue phase locking using F_R and record the initial latent interference fringes F_{L2} by EMCCD. Use the image-processing program to extract the phase and attitude information from the initial image.
- (3) Prepare for dynamic fringe locking.
Stop phase locking using F_R and block B_{R1-2} . Set $\Delta f = 1$ Hz to obtain the reading range of V_p from PMT, and set V_p to be the mid-value of the range. Lock V_p to V_{p0} using the PID controller, and then move PMT along the y axis while comparing the real-time and initial latent interference fringes from EMCCD, until they are aligned.
- (4) Do scanning exposure.
Move away S_{1-2} . Move the substrate and G_0 together along the $-x$ direction in a speed v for scanning exposure while locking the latent interference fringes using PMT and EMCCD. Exposure ends until the entire substrate moves out of the illumination of B_{E1-2} .
- (5) Development.
After development we obtain a grating of a long size along the x axis.

Experimental parameters. The exposure light source was a semiconductor laser of a wavelength 397.5 nm, a power 600 mW, and a coherence length longer than 100 m. The collimating lenses were biconvex spherical lenses of a focus length 1080 mm and an aperture diameter 180 mm. The length b_R of B_{R1-2} was 20 mm. The length b_L of B_{L1-2} was 30 mm. The length b_E of B_{E1-2} was 30 mm. The translation stage had a travel range of 350 mm along the x axis with a pitch angle of $6''$ and a yaw angle of $2''$ for the whole range. The nano-positioning stage, on which SF_2 was mounted, had a travel range of 20 μm along the y axis. The reference grating G_0 was prefabricated by stationary exposure in this system, with a usable area of 20 mm × 20 mm.

Positive photoresist Shipley 9912 was used. For the grating with a photoresist thickness of 150 nm, the exposure time T was 80 s, and the scanning speed $v = b_E/T = 0.375$ mm/s. For the grating with a photoresist thickness of 340 nm, T was 200 s, and v was 0.150 mm/s.

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Author Contributions

L.Z. proposed the idea and supervised and conducted the study. D.M. and L.Z. designed the experimental setup. D.M. and Y.Z. constructed the experimental setup, performed the experiments, and assessed the results. D.M. wrote the main manuscript text and prepared all the figures. All authors reviewed and revised the manuscript.

Additional Information

Competing Interests: The authors declare that they have no competing interests.

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