A microarray MEMS device for biolistic delivery of vaccine and drug powders

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Abbreviations: pDNA, Plasmid DNA; MEMS, MicroElectroMechanical System; CFD, Computational Fluid Dynamics; APC, Antigen Presenting Cells

We report a biolistic technology platform for physical delivery of particle formulations of drugs or vaccines using parallel arrays of microchannels, which generate highly collimated jets of particles with high spatial resolution. Our approach allows for effective delivery of therapeutics sequentially or concurrently (in mixture) at a specified target location or treatment area. We show this new platform enables the delivery of a broad range of particles with various densities and sizes into both in vitro and ex vivo skin models. Penetration depths of \sim 1 mm have been achieved following a single ejection of 200 μ g high-density gold particles, as well as 13.6 μ g low-density polystyrene-based particles into gelatin-based skin simulants at 70 psi inlet gas pressure. Ejection of multiple shots at one treatment site enabled deeper penetration of \sim 3 mm in vitro, and delivery of a higher dose of 1 mg gold particles at similar inlet gas pressure. We demonstrate that particle penetration depths can be optimized in vitro by adjusting the inlet pressure of the carrier gas, and dosing is controlled by drug reservoirs that hold precise quantities of the payload, which can be ejected continuously or in pulses. Future investigations include comparison between continuous versus pulsatile payload deliveries. We have successfully delivered plasmid DNA (pDNA)-coated gold particles (1.15 μ m diameter) into ex vivo murine and porcine skin at low inlet pressures of \sim 30 psi. Integrity analysis of these pDNA-coated gold particles confirmed the preservation of full-length pDNA after each particle preparation and jetting procedures. This technology platform provides distinct capabilities to effectively deliver a broad range of particle formulations into skin with specially designed high-speed microarray ejector nozzles.

Introduction

The development of new drug delivery methodologies focusing on precise targeting and control of the delivered payload has the potential to make significant contributions to the success of vaccines. Particle-mediated molecule delivery (*i.e.* biolistics) was first introduced as a promising non-invasive method for delivering payloads into cells or tissue in the mid-1980s, pioneered by Klein and colleagues, where genetic material was introduced initially into plants,^{1,2} later in animals,³ and finally in humans.⁴⁻⁶ Despite delivery challenges due to the skin's function as an effective physical barrier to pathogen entry, skin is an easily accessible, active immune organ providing an excellent site for vaccination due to its unique immunological and micro-vascular properties and extreme richness in antigen presenting cells (APCs) capable

of eliciting immune responses.⁷ Dendritic cells (DCs), including Langerhans cells (LCs), present in the dermis and epidermis layers of skin play critical roles in antigen presentation⁸ and are therefore usually the target cells in powder immunization in biolistic drug delivery strategies.9 Targeting those cells could result in a significantly improved immune response to vaccine delivery compared to intramuscular (IM) routes.¹⁰ With the biolistic delivery method, formulations of a drug or vaccine are generally carried by high-density, biocompatible metal microparticles and penetrate into the target tissue after being accelerated to high speeds using pressurized gas flow.¹¹ The delivery mechanism of particle-based delivery systems is purely physical and relies on mechanical forces to penetrate into cells or tissue and achieve the deposition of therapeutic molecules at the desired site. Various payloads have been delivered biolistically into tissue or cells in the

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past, including DNA,¹² RNA,¹³ and dyes.¹⁴ Following the original design of the gene gun, efforts were devoted to improving the delivery efficiency, dose, safety, and increased immunogenicity through the development of new device designs or improvements in previous designs. A commercially available version is the Helios® gene gun (Bio-Rad, Hercules, CA) used for direct gene transfer using small plastic tubes coated with particles as drug cartridges. Upon actuation, the drug particles are swept away from the tubes by pressurized helium¹⁵ for biolistic delivery to the target site. A family of devices, based on the Contoured Shock Tube (CST) design, have been subsequently developed¹⁶ and flow characteristics were studied.¹⁷ CST-based devices have been used to study the particle penetration mechanisms into excised human skin¹⁸ and biolistic delivery to animals¹⁹ and humans in phase I clinical trials.^{5,20} Other capillary-based gene guns have also been reported.²¹

In this paper, we describe a biolistic method with distinct characteristics that uses MEMS (Micro Electro Mechanical Systems)-based devices with a multitude of micron-size ejection nozzles arrayed in parallel to provide needle-free injections. Our device creates continuous and finely tunable jets of drug particles that have been gently entrained into high-speed gas jets, enabling an explosion-free biolistic delivery system. We demonstrate that our device design offers unique characteristics by providing particle jets with high spatial resolution, allowing sequential or concurrent delivery of particles with a variety of densities, and enabling controlled penetration profiles.

Device Operating Principle and Design

Our MEMS device consists of an array of microchannels that is assembled in a prototype test cell with gas and payload inlets for device testing and performance characterization (Fig. 1A, B). As conceptually illustrated in Figure 1C, pressurized gas at the inlet causes high-speed gas jets to form inside the channels. A Venturi structure inside each channel causes rapid acceleration of the flowing gas after the constriction, which is accompanied by a localized sharp drop in pressure. Depending on the design of the Venturi structure, this pressure drop can reach sub-atmospheric levels. Figure 1D shows this concept where the pressure profiles along the center of a channel were obtained for different Venturi designs by computational fluid dynamics (CFD) simulations (Fluent).²² By placing the payload reservoir inlet next to the subatmospheric pressure zone, drug particles are pulled out of the reservoir and gently entrained into the high speed gas jets.²³

For the entrained particles to reach the high speeds of the gas jets, a minimum channel length is required after the Venturi constriction. The required length and time to accelerate the drug particles to a given fraction of the speed of the gas jet can be obtained using the fluid mechanics drag model for a spherical particle. The equation of motion at intermediate Reynolds number is²⁴

$$m\dot{v} = 3\pi\mu d(u-v) \left\{ 1 + \frac{1}{6} \left(\frac{\rho_f d(u-v)}{\mu} \right)^{\frac{2}{3}} \right\}$$
(1)



Figure 1. MEMS device with parallel microchannel arrays and device working principle. (**A**) MEMS device assembled in a prototype test cell with gas and payload inlets. (**B**) Scanning electron microscope (SEM) image of the fabricated device showing the parallel channels with Venturi structure and inlet of therapeutic particles. (**C**) Schematic illustration of operation for one channel. Pressurized gas is supplied to the inlet of the channel and accelerated after the Venturi constriction followed by particle entrainment using the mild suction generated by a brief gas pressure drop. (**D**) CFD simulation of pressure profile for different widths w_t of the Venturi neck ($w_t = w, w_t = w/2$, and $w_t = w/4$ where w is the channel width) along a 4 mm long channel with a cross section of $64 \times 64 \ \mu\text{m}^2$. (**E**) CFD simulation of velocity profile along a 6.5 mm long channel with a cross-section of $600 \times 600 \ \mu\text{m}^2$. Simulations in D and E used air as the pressurized gas and did not include particles.

where m, v, d are the particle mass, velocity, and diameter, respectively and μ , ρ_f and u are the gas viscosity, density, and speed, respectively. Using equation (1) we estimate a minimum acceleration length of a few millimeters for 50 μ m diameter particles with 1000 kg/m³ density to reach 99% of the gas speed after being entrained into the channel. The exact length depends on the speed of the gas, which in turn depends on the inlet pressure and the channel cross section. Figure 1E shows CFD simulation results of the gas speed at the centerline of the channel with a cross-section of $600 \times 600 \ \mu\text{m}^2$ confirming that the speed of the gas remains high after passing through the Venturi structure, allowing for higher final particle speeds. Therefore, the device can create continuous and finely tunable arrays of well-collimated beams of particles that may be accelerated to high velocities.

Results

In vitro studies

The two devices used in this study ('Device A' and 'Device B') have nozzle cross-sectional dimensions of 400 \times 400 μ m² and 1000 \times 400 μ m², respectively. Both devices had a single nozzle enabled for ejections to ensure ease of testing. Specific particle and device details are summarized in Table 1. In vitro particle penetration studies were carried out using gelatin-based targets as simulant of skin tissue. Gelatin-based materials have been demonstrated to be simple yet effective in vitro models for characterizing intradermal powder delivery.²⁵ Such gelatin preparations are reproducible, optically clear for convenient payload visualization post-treatment, and remain stable in storage. For biolistic delivery, particles are filled in individual reservoirs that correspond to the desired dose and are introduced into the inlet port of the device through a capillary tube. Particle penetration profiles can be controlled by fine-tuning design features including nozzle size and length as well as tuning operational parameters such as ejection mode (continuous vs. pulsed), loading, and operating pressure. Payload dosing is controlled by the loading method of particles into the capillary tube and selecting the appropriate number of shots. The design of the devices enables automatic (passive) loading of particles continuously or in pulses via the vacuum generated at the payload inlet. Therefore, specified quantities of material can be ejected at a single shot and the duration of the device "on" time (i.e., the time for which the

 Table 1. Summary of devices and particles used in *in vitro* penetration studies

Devices	Nozzle cross-section	
Device A Device B	$400 \times 400 \ \mu m^2$ $1000 \times 400 \ \mu m^2$	
Particles	Density (kg/m ³)	Size (μ m)
Polystyrene-based particles Tungsten pDNA-coated gold	~1050 ~19250 ~19300	5–7 (avg. 6) avg. 1 0.8–1.5 (avg. 1.15)

pressurized gas is flowing) can be adjusted to eject all of the material for one dose in a single shot, or to deliver it in pulses.

Particle penetration studies

To adapt the developed devices for delivering payload to biological targets, the performance of the devices was characterized based on different sets of ejection conditions (*i.e.* inlet gas pressure, and continuous or pulsed ejections). Subsequently, the delivery of various types of particles into the gelatin-based skin simulant was assessed. After ejection of the particles, the maximum depth of penetration into the gel was quantified by microscopy and image analysis. Figure 2 shows the penetration depth of different particles with various densities from ~1050 kg/m³ to ~19300 kg/m³ (Table 1). Gold and tungsten were used as higher density particles in these experiments. It is important to note that tungsten particles possess a density that closely matches that of gold and thus were used as mock particles solely for device characterization purposes; thus they were not used in biological studies.

The devices ejected 200 μ g of high-density particles and ~13.6 μ g of low density particles from 40 nl reservoirs when operated at 70 psi with a single shot using a single nozzle in less than 1 s. All types of particles show more than 1 mm penetration into gelatin following a single ejection of the dose (Figure 2A, B, and C). Particle penetration reached ~3 mm after ejection in 5 pulses of 200 μ g dose each, for a total of 1 mg dosing at a similar gas pressure of 70 psi (a representative penetration profile is shown in Fig. 2G).

Controlling the penetration depth

It is desirable to tune the penetration depth of particles for targeting specific cells or layers of tissue. Particle penetration depths were assessed after performing single ejections into gelatin-based targets while the device was operated using various inlet gas pressures. Figure 3A demonstrates the cross-sectional images of the penetration depth profiles after the ejection of 200 μ g tungsten particles at 45 psi, 65 psi, and 70 psi inlet gas pressures. Repeatable ejections and penetration depths were achieved with controlled payload quantities. Also, the footprints of ejections were smaller than 1 mm² for all the conditions used and may be tuned in different designs. The results confirm that penetration depth of particles in gel can be tuned by adjusting the inlet gas pressure. Similar results were observed with other types of particles (data not shown). We demonstrated earlier (Fig. 2G) that multiple ejections at one location increase the penetration depth and total dose of particles in the gel.

Ejection efficiency

Estimating the ejection efficiencies of the devices enables better dose planning for maintaining the therapeutic drug concentration above minimum efficacy levels. Plasmid DNA (pDNA)coated gold particles at a concentration of 10 μ g plasmid per 1 mg gold were loaded into the devices in precise quantities and ejected in 5 consecutive pulses into the gelatin-based targets at an operating pressure of 70 psi. Particles were extracted from the gel and the ejection efficiency—defined as the ratio of the amount of



Figure 2. Cross-sectional images of particles penetration profiles after ejection into gelatin at 70 psi inlet pressure. Device A ($400 \times 400 \ \mu m^2$ channel cross-section) was used for ejections in (**A-D**, **G**) and Device B ($1000 \times 400 \ \mu m^2$ channel cross-section) was used for ejection in (**E**) where both devices had a single nozzle enabled for ejections. The ejection dose was ~13.6 μ g for low-density particles shown in (**A**), 200 μ g for high-density particles shown in B and C, ~215 μ g for mixture of particles shown in (**D and E**) and a total of 1mg for multiple ejections shown in G. (**A**) Penetration of low-density polystyrene-based particles with density of ~1050 kg/m³. (**B**) Penetration of tungsten particles with density of ~19250 kg/m³. (**C**) Penetration of gold particles with density of ~19300 kg/m³ that were coated with pDNA at 10 μ g DNA in 1 mg of gold. (**D and E**) Penetration of a mixture of low and high density particles. (**F**) Maximum penetration of particles in a-e (n = 3). The error bars represent one standard deviation from measured values. (**G**) Penetration of pDNA-coated gold particles after 5 sequential ejections for 1 mg dose delivery.



Figure 3. Operating pressure effect on particle penetration after ejection into gelatin. (**A**) Representative cross-sectional images of tungsten particles penetration into gelatin samples using Device A at various operating pressures. (**B**) Maximum penetration of tungsten particles (200 μ g dose) increases while the inlet pressure increases following single ejection (n = 3). (**C**) Device ejection efficiency defined as the extracted pDNA-coated gold particles from the gel after ejection of defined quantities of particles in 5 consecutive pulses at 70 psi (n = 6). The error bars represent one standard deviation from measured values.

gold particles harvested from the gel post-ejection (not depth specific) to the total amount initially loaded to the device—was derived. Efficiencies of ejections were 60% and 56% for Device A and B, respectively (**Fig. 3C**). The losses during this process may be associated with several factors, such as non-ideal recovery of particles from the treated gel samples or particles not being captured in the target. To achieve therapeutic effect thresholds of vaccines or therapies, the ejection efficiencies of the devices should be factored in the loading quantity of payload to achieve required dosing.

Plasmid DNA integrity

To test the effect of particle preparation, loading, and jetting on the integrity of pDNA coated on gold particles, samples from each step of the process were collected, pDNA was eluted in TE buffer and run on a 1% agarose gel. With the inlet pressure set at 70 psi, 5 shots of pDNA-coated gold particles (approximately 1 mg total) were ejected and captured in a 15 ml tube containing 0.5 ml glycerol. Figure 4 shows the agarose gel analysis data in various steps of particle preparation and jetting using both devices A and B. The results of agarose gel electrophoresis show that full-length pDNA was preserved at each step of particle preparation. This confirms that high speed ejection of particles does not affect the integrity of pDNA. However, the analysis shows a change in the ratio of the supercoiled conformation to all conformations present in gWiz plasmid (*i.e.*, relaxed circular, linear, and supercoiled) during particle processing (i.e. suspending and dispersing before loading) and jetting.

Ex vivo studies

Delivery of pDNA-coated gold particles into ex vivo skin

For further clinical applications it is important to demonstrate the feasibility of our devices for biolistic delivery of therapeutics into tissues without any detectable tissue damage. Therefore, device performance was assessed on *ex vivo* skin models that included both epidermis and dermis layers. Both murine and porcine skin samples were stretched to replicate live skin tension in order to better mimic *in vivo* conditions in our study. Prior

1 2 3 4 5 6 7 8 9 10 11 12 Relaxed circular Linear Supercoiled A3 A Bunden and an and a second and a s



work has shown that hydration in ex vivo skin models influences the penetration depth of particles following the biolistic ejections.²⁶ Therefore, to maintain consistency in ex vivo skin hydration, the freshly excised skin tissues were exposed to phosphate buffered saline (PBS) soaked fabric before each ejection. We ejected pDNA-coated gold particles onto freshly excised murine and porcine skin tissues mounted over a soft gel substrate. Studying penetration of particles using ex vivo mouse skin models facilitates comparison of performance with prior biolistic ejectors as murine animal models have been widely used for immunological studies²⁷⁻²⁹ and porcine skin has often been used in jet injecting penetration studies³⁰ due to its similarity to human skin structure.³¹ Figure 5A demonstrates a schematic diagram of the experimental setup where Device B was operated at low pressures (less than 30 psi) to eject pDNA-coated gold particles with approximately 10 μ g pDNA per 1 mg gold. Figure 5B and C are histology images of the mouse skin tissue stained with hematoxylin and eosin (H&E) and visualized using bright and dark field microscopy revealing particles penetrating more than 100 μ m into the skin. Ejection in porcine skin (Fig. 5D) shows the potential for deep particle penetration even under low device operating pressure.

Discussion

This paper describes a biolistic delivery platform with distinct capabilities and investigates particle penetration using *in vitro* skin simulant and *ex vivo* skin models.

As depicted in **Figure 2**, ejection of drug particles using our devices generates highly collimated focused beams of particles (particle jets) impinging into the substrate, demonstrating very different penetration profiles from those using previously developed biolistic ejectors featuring diverging particle trajectories and shock-tube based approaches.^{18,32,33} The collimated particle delivery method is advantageous and opens up new therapeutic strategies as the particle landing locations may be precisely and repeatedly defined. For example, as shown in **Figure 2D and E**, co-delivery of various payloads is possible at one location,

sequentially or as a mixture, with micrometer precision. Therefore, because the particle landing location is accesrepeatedly sible during multiple sequential ejections via each device nozzle, these devices may enable the mixing and reaction of compounds at the delivery site that could potentially simplify drug formulation pro-The collimated cesses. particle delivery technology may be especially advantageous for intracellular delivapplicable in ery, the



Figure 5. Delivery of pDNA-coated gold particles into the *ex vivo* skin models. (**A**) Schematic diagram of a single nozzle of a device operating to deliver pDNA-coated gold particles into the freshly excised skin placed over a gel as a soft substrate. Schematic is not to scale. (**B**) Histology of mouse skin tissue by hematoxylin and eosin (H&E) staining after ejected with gold particles, visualized by bright field microscopy. (**C**) Dark field microscopy of histology sample in B reveals the glowing gold particles penetrated into the skin. (**D**) Histology of pig skin tissue by H&E staining after bombardment visualized by dark field microscopy.

transdermal delivery of nucleic acid-based therapies, or in applications where microscale spatial precision is required to accurately target functional particles at desired locations and depths in the skin.

It is important to note that all the ejections reported here as shown in Figure 2 have used only a single nozzle of the multinozzle devices. Depending on the application, an entire array of nozzles can be used in parallel (Fig. 1) to achieve hundreds of simultaneous ejections in less than one second at a desired spatial resolution down to tens of micrometers, allowing uniform distribution of particles with defined profiles at defined depths with defined distances from each other, capabilities different from previous single nozzle ejectors. Moreover, for large area delivery applications, our device architecture (with micron size channels) could enable configurations where target skin is being scanned/ rastered automatically while the payload is ejected on-demandvery similar to printing ink on paper where printer head is moving along the paper and marking specified patterns. This device configuration will be investigated in future for therapeutic delivery applications.

Penetration results shown in Figure 2A demonstrate significant potential for the delivery of low-density particles at relevant depths and hence 'pure' drug particles. As such, the need for highdensity carriers (*i.e.*, gold particles) may be eliminated. This is an important advantage of the developed ballistic drug delivery symmetrical ejection nozzle (*i.e.* equal cross-sectional height and width) may be responsible for better penetration depths achieved by Device A at those pressures. The optimal penetration performance of Device B was achieved at 60 psi operating pressure in these *in vitro* tests. Thus, Device B is likely more suitable for penetrations into softer tissues.

Depending on the application requirements, smaller and larger dosing is possible using our delivery technology. Dosing is determined by the quantities loaded and can be regulated by the size of the reservoir. Dose delivery can be controlled in 2 ways: a) by the individual reservoir size and selecting the number of ejection pulses, b) by the duration of a continuous ejection from a large reservoir. The quantity of payload entrained per pulse should be optimized to avoid overloading the ejection nozzle, which may negatively affect particle velocity inside the nozzle.

Full-length pDNA was preserved during ejection of pDNAcoated gold particles from the device, although the ratio of the supercoiled conformation to all conformations was reduced. It is not evident if this change in conformation will have a direct effect in eliciting an immune response using these particles. Although prior studies have suggested that optimal transfection and immnogenicity are achieved by injecting the supercoiled conformation of pDNA, the relaxed circle and linear plasmids have also been shown to be immunogenic as DNA vaccines in animals.³⁴ This effect requires further investigations in the future.

approach as the delivery dosing efficiency will dramatically increase, which could eliminate the potential toxicities and known inefficiencies associated with using non-therapeutic carrier particles. We speculate that such focused beams of particles may be the enabler for pure drug particle delivery at depths approaching those achieved by high-density gold carrier particles. Further studies are currently being planned to verify this effect in vivo.

The two device designs used in this work led to distinct capabilities that could be tailored to different applications. As shown in **Figure 3B**, Device A provides superior penetration depths into gelatin-based samples than Device B at 45 and 70 psi. Better collimation provided with Device A, having 2.5 times smaller cross-sectional area than Device B as well as more

To demonstrate the potential for the developed biolistic delivery system to be further developed into a powerful in vivo-relevant therapeutic tool, the ex vivo skin models were setup in an attempt to mimic in vivo conditions and were jetted with gold carrier particles coated with pDNA. The ejections of these particles into the ex vivo skin tissues were performed in low pressures (<30 psi) and showed penetration depths of more than 100 μ m in mouse skin. The design of our devices allows for operation in much higher inlet gas pressures (>30 psi) that results in a substantial increase in the velocity of entrained particles by the accelerated carrier medium after the Venturi structure. This effect has been demonstrated in vitro (Fig. 3) where particle penetration depths were tuned by increasing the operating inlet pressures. In human skin applications, this device characteristic may enable targeting drug particles into specific cells or tissue ondemand, an effect that will be studied in further detail in the future. Local skin reactions to a particle-based immunization have been reported in a phase 1 clinical study using CSTbased particle delivery devices operated with a nominal gas pressure of ~ 650 psi.²⁰ In that study, biolistic ejections were found safe with mild self-limiting local skin reactions that resolved after 14-28 days where pain, tingling, or paresthesia were reported infrequent. Another clinical study reported that every patient felt less pain after receiving biolistic ejection with their devices (gas pressure at ~464 psi) compared to traditional intramuscular injection.³⁵ Such information for the biolistic technology described in this paper will be useful in human skin applications. It is likely that skin mechanoreceptors, especially low threshold skin's Merkel's discs to play a role in sensing the applied pressure during ejection and skin's Pacinian corpuscles to produce sensation of vibration or tickle for transient disturbances at frequencies in the range of 250-350 Hz which may happen during biolistic ejections.³⁶

Data presented in this work suggests that the developed biolistic technology platform may create new therapeutic strategies and paradigms for effective delivery of a broad range of particle formulations of drugs or vaccines into human skin. The collimated jets demonstrated in this work may open a new therapeutic route for highly localized non-invasive treatments and immunizations that can be adapted to a number of therapeutic applications as the devices and their operating parameters can be designed and optimized to achieve specific delivery goals such as penetration depths for specific targets. Possible clinical applications for this technology may be in the areas of mass immunization performing many ejections from a large reservoir of therapeutics, delivery of vaccines for infectious disease including pandemics, cancer immunotherapy for targeting antigen presenting cells (APCs), melanoma skin cancer treatment, delivery of immunosuppressive treatments, and co-delivery of antigens and immunomodulatory agents antagonizing the immunosuppressive environment of different diseases to achieve effective immune responses. Because this technology allows the delivery of a wide range of particles with various densities, it may also find applications in delivery of cosmetic products into the skin or mucosal tissue, which benefit from precise targeting and controlled penetration depths, as well

as delivery of nutritional/nourishing substances, long-term sunscreen, medications for wound healing or other dermatological conditions.

Several other aspects of this technology remain to be explored in future *in vivo* studies. One area involves the induction of antibody responses or reporter gene expression in animal models following biolistic delivery using our microarrayed devices and comparing the responses when active materials are in the form of high and low density particles. Given the spatial precision capability of our platform, another area of future investigation involves the *in vivo* exploration of co-delivery and therefore co-location of various types of therapeutic particles at the delivery site to enhance or modulate the responses. Additionally, comparison between continuous versus pulsatile payload delivery and the delineation of specific applications for which pulsatile or continuous ejection is better suited are areas to be explored in future.

Methods and Materials

Device fabrication and assembly

The fabrication of the devices involved standard MEMS processing techniques including photolithography for patterning the channels and Venturi structures, followed by deep-reactive ion etching (DRIE) for creating the desired structures in silicon. Similarly, the payload inlet holes were created by backside alignment, photolithographic patterning, and DRIE etching of the holes in silicon. The channels were then sealed by glass cover chips using anodic bonding. Gas inlet ports were created by drilling into the cover glass. The overall dimensions of the device and the number of channels in each device may be designed based on the application requirements, and can be fine-tuned as needed. The typical overall dimensions of individual devices were 10 \times 10 \times 0.5 mm³. The devices were then assembled into a prototype test cell (Fig. 1A) to provide an interface between the device inlets and controlled pressurized gas as well as individual drug reservoirs through a capillary tube that was assembled onto the device payload inlet. The drug particles were supplied from drug reservoirs to the end of the capillary tube. Payload particles were allocated into drug reservoirs using a squeegee process.

Production of pDNA-coated particles

pDNA-coated gold particles were prepared as described in the Bio-Rad Helios Gene Gun System Instruction Manual except that 100% ethanol was used in place of polyvinylpyrrolidone (PVP).³⁷ The goal was to obtain well-separated particles and therefore PVP was omitted because it acts as an adhesive during the gene gun cartridge preparation process.³⁷ To prepare DNA-coated gold particles at a concentration of 10 μ g DNA/mg gold, 50 mg of 0.8–1.5 μ m (average 1.15 μ m) diameter spherical gold particles (Alfa Aesar Cat. No. 39817) were mixed with 0.5 ml 0.05 M spermidine (Sigma Aldrich Cat. No. 85558). The mix was sonicated for 5 min in an ultrasonic bath. While vortexing the mixture, 500 μ g of gWiz-SEAP pDNA diluted in TE buffer (Sigma Aldrich Cat. No. 78280) to 1 mg/ml from the stock solution (Aldevron Cat. No. 5005) was added dropwise. The gold, spermidine, and DNA

mix was vortexed and 0.5 ml 1 M CaCl₂ (Sigma Aldrich Cat. No. C4901) was added dropwise to precipitate the DNA onto the gold particles. After 15 minutes incubation at room temperature, the DNA-coated gold particles were spun down by brief centrifugation at 5,000 RCF, liquid was aspirated, and the gold was washed 3 times with 1 ml cold 100% ethanol (Sigma Aldrich Cat. No. E7023) each time. The gold particles were suspended in 1 ml 100% ethanol, transferred to a 75 × 50 mm glass slide and dried at room temperature in a fume hood. Aggregates of gold particles were mechanically separated before loading the dispersed gold particles into the reservoirs from where they were loaded into the device via capillary.

Preparation of gelatin-based skin simulant

Skin simulant samples were prepared using a gelatin/glycerol mixture (weight ratio 3.5/6.5) using gelatin from porcine skin for microbiology with a Bloom strength of 180 (Sigma Aldrich Cat. No. 48722) and glycerol for molecular biology (Fisher Scientific Cat. No. BP2291). These methods follow those described previously in the literature.²⁵ Deionized water and glycerol were independently warmed to ~55°C. Gelatin powder was added to the warmed deionized water to produce a 10% (w/w) solution. Appropriate amounts of the 10% gelatin solution and glycerol were combined to achieve the 3.5/6.5 gel/gly weight ratio. The mixture was stirred and degassed for 5 min at ~55°C, and subsequently poured into Petri dishes to cool and dry in a chemical hood for 72 hours at ambient conditions. Each gelatin preparation was then peeled, flipped, and allowed to dry for another day in the chemical hood. Circular samples (~12 mm diameter and ~5 mm thickness) of the prepared skin simulant were then mounted onto glass microscope slides for each jetting experiment.

Harvesting of animal skin

Animal subjects and veterinary expertise were provided by PMI - Preclinical Medevice Innovations. The method for harvesting skin samples follows those described previously in literature.30 Skin samples from porcine and murine subjects were collected within 2 hours post-euthanasia. Excised porcine skin was obtained from the abdominal skin area lateral to the mammary glands of a given Yorkshire pig (weight range 80 - 90 kg). Murine skin was obtained from dorsal and ventral areas of balb/c mice (approx. 6 weeks old). In each case, depilatory cream (Nair) was applied to the described areas for 10-15 min followed by a thorough rinsing and cleaning with warm, damp wipes to remove all residual depilatory cream. Sharp or abrasive tools were avoided during this process in order to limit damage to the skin. The importance of stretching skin samples to original dimensions in ex vivo ejection studies was highlighted previously.38 Here, to replicate live skin tension in both murine and porcine skin samples a surgical marking pen was used to trace a pre-measured template directly on the skin so that the samples could be stretched to the appropriate original dimensions during subsequent jetting experiments. Skin was cut and underlying fat, if present, was removed using a surgical scalpel. Skin pieces were rinsed and moistened with phosphate buffered saline and stored in a cool environment to be used for ejection experiments within a few hours.

Jetting of payload particles

Three different types of payload particles were ejected from devices: pDNA-coated gold particles (prepared in-house), 1 μ m average diameter tungsten particles (Noah Technologies Corporation Cat. No. 17128), and polystyrene-based particles from a custom formulation obtained from XRCC (Xerox Research Center of Canada). Devices were oriented such that particles would be jetted along a horizontal axis toward a target substrate mounted perpendicular to the jetting direction, approximately 1 mm from the nozzle exit. Either the prepared skin simulant or harvested skin served as the target substrate. Controlled duration of pressurized helium or air at selected pressures was introduced into the device to entrain and propel the payload toward the target substrate.

Characterization of the depth of particle penetration in gel

To visualize a cross-section of the trajectory of the penetrated payload, a surgical blade (Feather[®] SafeshieldTM Disposable no. 10 Scalpel, VWR Cat. No. 102097-798) was used to carefully slice the gelatin sample in a direction parallel to the particle penetration pathways approximately 2 mm away from the jetted site by positioning the blade perpendicular to the impingement surface. This exposed surface of the cross-section was mounted onto a coverslip to maintain a flat plane for bright field microscopy using an Olympus BH-2 microscope with $5 \times$ and $10 \times$ Neo-SPlan objectives. All images were processed using ImageJ[®] software to quantify the linear distance from the impingement surface to the deepest penetrated particles.

Histological processing and analysis of skin samples

After particle ejection into the excised skin samples, the area was marked, gently rinsed with phosphate buffered saline to remove any excess particles on the skin surface, and cut using 4 mm diameter biopsy punches. Each biopsy sample was fixed in neutral buffered 10% formalin (Fisher Scientific Cat. No. 23305510) at room temperature for at least 48 hours. Subsequent paraffin-embedding, sectioning, and hematoxylin and eosin staining were performed by Histo-Tec Laboratory (Hayward, CA). Each biopsy sample was sectioned to reveal cross-sections of the payload penetration trajectory such that one prepared histology slide would capture the tissue penetration from the impingement surface to the deepest deposited particles. Prepared histology slides were analyzed using bright and dark field microscopy using a Nikon Eclipse LV100 microscope with a Nikon LU Plan $50 \times$ ELWD objective.

Disclosure of Potential Conflicts of Interest

No potential conflicts of interest were disclosed.

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