



Article Critical Thickness of Free-Standing Nanothin Films Made of Melted Polyethylene Chains via Molecular Dynamics

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Abstract: The mechanical stability of nanothin free-standing films made of melted polyethylene chains was predicted via molecular dynamics simulations in the range of 373.15–673.15 K. The predicted critical thickness, t_c , increased with the square of the temperature, T, with additional chains needed as T increased. From T = 373.15 K up to the thermal limit of stability for polyethylene, t_c values were in the range of nanothin thicknesses (3.42–5.63 nm), which approximately corresponds to 44–55 chains per 100 nm². The density at the center of the layer and the interfacial properties studied (density profiles, interfacial thickness, and radius of gyration) showed independence from the film thickness at the same T. The polyethylene layer at its t_c showed a lower melting T (<373.15 K) than bulk polyethylene.

Keywords: critical thickness; polyethylene; molecular dynamics; radius of gyration; nanothin layers

1. Introduction

Polymeric membranes are a widespread separation technology used to solve many scientific and industrial problems. Commercial membranes used for gas separation are very thin, in the range of 100 to 500 nm, and the permeability to selectively separate gases increases as the thickness of the layer decreases [1–3]. Polyethylene membranes are permeated by gases with low critical temperatures independently of the pressure differential, while gases with high critical temperatures permeate the membranes in processes that are highly dependent on the pressure differential, which can indicate an affinity between small molecules and the polyethylene layer [4]. The solution–diffusion model is the most accepted transport mechanism of gases through a membrane [5,6], and it has three barriers: (1) adsorption of permeable gases at the polymer surface (commonly exposed to the permeable gas at a high pressure), (2) diffusion of the adsorbed gases in the polymer layer, and (3) desorption of permeated gases at the opposed interface (commonly exposed to the permeated bulk gas phase at a lower pressure). Therefore, if the thickness of the layer is decreased, the role of the second barrier is minimized.

Previous studies have shown that very thin layers of polymers [7] and atomistic systems [8] are mechanically unstable and break down into droplets below a certain critical thickness, t_c . Usually, the polymeric membranes are supported on porous substrates to enhance the mechanical stability of the system [9]. It is theorized that, in unsupported very-thin layers, attractive surface forces (disjoining pressures) increase the amplitude of capillary waves, causing the thin films to shatter, provided they are sufficiently thin. De Vries postulated that if the films are thinner than the t_c , the two surfaces will come



Citation: González-Mijangos, J.A.; Lima, E.; Guerra-González, R.; Ramírez-Zavaleta, F.I.; Rivera, J.L. Critical Thickness of Free-Standing Nanothin Films Made of Melted Polyethylene Chains via Molecular Dynamics. *Polymers* **2021**, *13*, 3515. https://doi.org/10.3390/ polym13203515

Academic Editor: Irshad Kammakakam

Received: 15 September 2021 Accepted: 7 October 2021 Published: 13 October 2021

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Copyright: © 2021 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). into contact due to the corrugations of the capillary waves, causing the film to break [10], and this theory have been utilized in several studies of layer stability [11–13]. Due to computational limitations, molecular simulations of thin layers are commonly carried out in simulation cells with very small interfacial areas, A_i , in the scale of a few nm², where the full extent of the capillary waves cannot manifest. Simulations on A_i as large as 600 nm × 600 nm [14] did not develop capillary waves or other thermal fluctuations large enough to break the films; therefore, other phenomena should arise at this peculiar state. Additionally, other phenomena occur as the thickness of the layer is reduced. Two important properties of the polyethylene layer shift to a lower *T*: the glass transition temperature, T_g [15–18], and the melting temperature, T_m [19,20], which indicate an effect of the layer thickness on its cohesivity.

In this paper, we investigated nanothin films (<100 nm) of melted polyethylene chains in a vacuum, without impurities or large thermal fluctuations, through molecular dynamics simulations. These simulations were used to predict the limits of mechanical stability over a wide range of *T* values, below the bulk T_m , and up to the limits of thermal stability. We examined interfacial and structural properties (layer and interface thickness, bulk liquid densities, and radius of gyration, R_g , distributions) for thin layers at their specific t_c values and compared their interfacial behaviors with those of wider layers.

2. Methodology

The liquid–vacuum interface of melted polyethylene chains was studied directly through the simulation of a thin layer of liquid in a vacuum using the molecular dynamics method. The system was expected to behave similarly to ionic liquid films with very low vapor pressure and thermal degradation at high T values [21,22]. We simulated layers at T values of 373.15, 473.15, 573.15, and 673.15 K, below the bulk T_m of linear polyethylene (403.65 K for a molecular weight of 100.5 kg/mol) [20], beyond the highest T_g reported (253 K) [23,24], up to T values near the limit of thermal stability (losses of 5% of the weight at 695.55 K, and the maximum loss begins at 747.45 K) [25,26]. The simulation cell consisted of a parallelepiped with $A_i = 145 A \times 145 A$, which was large enough to contain a stretched chain in each lateral direction, had a variable length in the inhomogeneous direction (depending on the number of chains simulated), and contained between 93 and 1568 C₂₀₀ polyethylene chains. Chains of 200 carbon units were chosen as a tradeoff between computation time and chain size; larger chains required a larger A_i to find the t_c . The chosen A_i is not large enough to avoid size effects; based on the results for atomistic systems at a T close to the triple point, a simulation cell ~20 times larger the lateral length used in this work is needed to minimize the size effects [8,14]; it is estimated that our calculations for t_c will have underpredictions of ~30% at temperatures close to the shifted T_m .

The initial systems consisted of ordered, stretched, and oriented chains that were parallel to the interfacial surface, with a chain–chain separation of 5 Å in all directions. The initial position of the sites in the configuration were obtained using an in-house code with randomly distributed velocities. The chains were brought to the liquid–vacuum equilibrium slowly over a period of 1 ns, and the mechanical stability was studied using additional simulations in the NVT ensemble (constant number of molecules, rigid volume of simulation cell, and constant average *T*) ensemble, with a timestep of 1 fs. The thermostat used was that of Nosé [27], implemented in the Large-scale Atomic/Molecular Massively Parallel Simulator (LAMMPS) [28].

The chains interacted through the TraPPE potential [29], which is a united atom potential that considers the CH_3 and CH_2 functional groups as Lennard–Jones sites of interaction. The non-bonded Lennard–Jones sites interacted through their corresponding potential,

$$U_{LJ} = 4\pi\varepsilon_{ij} \left[\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - \left(\frac{\sigma_{ij}}{r_{ij}} \right)^6 \right]$$
(1)

where r_{ij} represents the reduced separation between Lennard–Jones sites i and j. σ_{ij} and ε_{ij} are parameters dependent on the interaction site; for unlike sites, standard arithmetic (σ_{ij}) and geometric (ε_{ij}) combining rules were used. We used a long cutoff radius, $r_c = 7.5 \sigma_{CH_3-CH_3}$, to consider all potential interactions and avoid the use of long-range corrections at the end of the simulations, or approximated corrections during the simulation, which masks the true dynamics of the system [8,14,30]. The use of a short r_c with long-range corrections can lead to correct predictions of some liquid–vapor and liquid–vacuum equilibrium properties, but the dynamics of the system are dependent on the r_c employed [14,21]. The TraPPE potential for linear alkanes uses harmonic potentials for bond and angle bending and a cosine function on the dihedral angles [31]. The TraPPE potential has been employed to study the structural conformations of single polyethylene (C₃₀–C₁₅₀) [34] and polyethylene blends (C₃₂₀) [35]. The use of the TraPPE potential to study the crystallization process of polyethylene (C₁₉₂) has produced results that are in better agreement with experiments compared to when other potentials are used [36].

Liquid interfaces are dynamic, and under vacuum or surrounded by vapor phases, they breathe; the thickness of the layer and the thickness of each interface expands and contracts in a characteristic periodical behavior. Therefore, to properly characterize the distributions of their structural properties we need to demarcate the different regions of the layer: bulk liquid-like and interfacial regions. A commonly used delimiting point of the interfacial regions is the location in the inhomogeneous direction of the Gibbs dividing surface, which is commonly used in binary and multicomponent phase equilibria (including a solvent) to delimit homogeneous fluid phases (vapor or liquid). In this paper, the Gibbs dividing surface delimits the liquid-like regions from the homogeneous vacuum. For each interface (the free-standing layer has 2 liquid–vacuum interfaces), the Gibbs dividing surface is the point in the interface that divides each interfacial region into two sub-regions (one rich and another poor in solvent), and the criteria for the location of the point is that the sub-region poor in solvent will contain an amount of solvent equal to the amount of solvent "lost" (compared to the bulk phase) in the sub-region rich in solvent. For one-component systems, the only component is considered as the solvent of the system.

To obtain more realistic profiles, we allowed the system to move in the inhomogeneous direction and calculated density profiles every 100 steps. In the end, we averaged the profiles by correcting the positions of the profiles according to the position in the inhomogeneous direction of the center of the layer, which was calculated as the midpoint between the two positions of the Gibbs dividing surface, z_{Gds} . This allowed us to obtain more realistic profiles of the calculated properties. To obtain the positions of z_{Gds} , each of the density profiles (calculated using bins of 0.1 Å) were adjusted to the hyperbolic tangent expression commonly used in liquid–vacuum phase equilibrium studies [21,22]:

$$\rho(z) = \frac{1}{2}\rho_l \left[1 - tanh\left(\frac{z - z_{Gds}}{d}\right) \right]$$
(2)

where ρ_l is the average bulk density of the liquid phase. *d* is a measure of the thickness of the interface and describes the length in the inhomogeneous direction, where the density changes from the bulk liquid-like phase to zero in the vacuum. The "10–90" interfacial thickness, $t_i = 2.1790d$ [37,38], represents the interfacial region in the density profile where the density changes from 10% ($z_{10\%}$) to 90% ($z_{90\%}$) of the average bulk ρ_l .

Molecular dynamics simulations of thin fluid layers of melted chains of Lennard– Jones sites representing the behavior of linear polyethylene (C_{200}) were performed in an inhomogeneous arrangement to predict the t_c at which the thin layers were at the limit of mechanical stability at a given *T* (Figure 1); narrower layers than those at the t_c shrank, and nano-sized holes formed in the layer (Figure 1). The simulation cell was under periodic boundary conditions and represented a thin layer of infinite A_i .



Figure 1. Normal views of the representation of a thin layer (interfaces grow infinitely on the paper plane) of linear polyethylene (C_{200}), made of Lennard–Jones sites in equilibrium at T = 473 K. The simulation cell used $A_i = 145 A \times 145 A$. Thin layers with 102 or more chains (left) were stable up to 0.1 µs, while layers with 101 or fewer chains (right) contracted and developed stable nano-sized holes.

The search for the minimum number of chains that form stable layers was by trial and error. We started with a stable layer with 200 chains, in which we removed a few chains from the interface and equilibrated the system for 10 ns. If the layer was stable, we continued and eliminated a few chains more, and allowed the system to again reach equilibrium (for additional simulations of 10 ns); otherwise, we used the last stable layer. We repeated this procedure, eliminating a progressively lower number of chains (close to the t_c , we eliminated only 1 chain at each step) until we encountered the thinnest, most stable liquid layer that would not retract itself to form nano-sized holes. Once we found the number of chains required at t_c , we tested the equilibrium and performed additional simulations (100 ns) on the stable thin layer to verify its stability at longer times, because some of the layers became unstable at periods longer than 70 ns; when this happened, we simulated the system with 1 more chain and verified again its stability for 100 ns, until we found the stable system. In a previous publication, we predicted the t_c of atomistic Lennard-Jones free-standing thin layers [8], but those systems did not require long periods to become unstable; they only needed a few ns to become either stable or unstable, and remained stable or unstable for longer periods (100 ns). We focused on investigating systems that maintain mechanical stability and have the smallest possible liquid thickness, which corresponds to the t_c of mechanical stability.

The equilibration of the system was studied through time profiles of the studied properties, including the total energy of the layer; the system is considered equilibrated because the studied properties reached a plateau, with values oscillating around a constant value. Some properties such as total energy equilibrated faster, but the time of equilibration of the system is established when all properties reached a plateau. To avoid local minima states, additional tests of equilibration were performed through perturbations of A_i ; we increased A_i to 5% of its original value in a period of 1 ns and returned to the original A_i value in an additional period of 1 ns. After the perturbation finished, the properties returned to their original values. We tried several initial configurations within our computational restrictions, but most of them failed to produce a stable layer (Figure 2a); the initial configuration that always produced stable layers contained non uniform distributions of chains (Figure 2b). We expected that the tests and perturbations performed, along with the long periods of simulation (100 ns), will produce layers unbiased by the initial configuration.



Figure 2. Normal view to the interfacial surface of the representation of uniform (**a**) and non-uniform (**b**) initial configurations of a thin layer of linear polyethylene (C_{200}) made of Lennard–Jones sites. The simulation cell used $A_i = 145 A \times 145 A$ with periodic boundary conditions (continuous black line).

3. Results

Among the properties available for investigation in these very thin layers using molecular dynamics simulations, we studied how the density changes along the two interfaces generated in the liquid–vacuum system, the possibility of adsorption at the interfaces, the width of the homogeneous zone corresponding to the bulk liquid, any distortion in the structure of the chains due to vicinity of the interfaces, and predicted the limits of mechanical stability.

3.1. Density Profiles

Figure 3a shows the density profiles of two thin liquid layers of melted polyethylene chains (C₂₀₀) with thicknesses corresponding to their t_c values at 373.15 K and 673.15 K. At 373.15 K, the critical layer consisted of 96 chains, while at 673.15 K, the critical layer needed 116 chains to form a mechanically stable free-standing layer at the same A_i . For comparison, we also show a thin layer at 673.15 K with a thickness wider than the corresponding thin layer at its t_c . The total density profiles did not exhibit adsorption at the interfaces, probably due to the long length of the chains. Similar density profiles have been reported in the literature for large linear alkanes [39–41]. We observed that the system at the lower *T* did not develop a central zone characterized by a flat density, which corresponds to the homogeneous bulk liquid. Meanwhile, the system at the higher *T* had a sufficiently wide thickness to develop a thin bulk liquid-like. When compared with wider thin layers, such as the one shown in Figure 3a, at the same *T* (673.15 K), we found that the average ρ_l at the center of the thin layer (-1 Å, 1 Å) at its t_c reached the same value as the bulk ρ_l of wider layers; this observation was also made for thin layers at the lower *T* of 373.15 K.

End CH₃ sites are freer to move and associate than backbone CH₂ sites. We wonder if CH₃ sites preferred to accumulate in a specific region of the layers, and how such an accumulation affects the properties of the layers. Density profiles of only the end CH₃ sites of the polyethylene chains are shown in Figure 3b. Density profiles for backbone CH₂ sites should be very similar to the total profiles, because they represent 99.5% of the total sites. At the higher *T* of 673.15 K, the CH₃ profiles showed the same trend as the density profiles of the whole system, the only difference being that the CH₃ profiles reached positions farther away from the bulk liquid (magnified in Figure 3b due to the scale used in the *y*-axis). At the lower *T* of 373.15 K, the density profile showed two peaks of adsorption at the interfaces, which likely indicates that, at this *T*, the system was all interfacial, the system could be considered as two united interfaces, and the adsorption at the interfaces was the result of low mobility of the CH_3 sites at this lower *T*. The peaks showed the system's maxima at regions outside the bulk liquid-like regions, where some CH_2 sites are present, and probably indicate that CH_3 sites are phobic to the nature of the bulk liquid-like region. The two peaks of density reached values that represent only 1% of the total bulk liquid-like density, even though they are 0.5% of the total number of sites; therefore, its effect on other properties should also be very limited. The valley between the interfaces likely indicates a barrier for the CH_3 sites exchange in this region; crossing from one interfacial peak to the other may require more thermal energy than is available at this *T*.



Figure 3. (a) Density profiles for the whole system and (b) density profiles for only the end CH₃ groups as a function of the inhomogeneous position within the simulation cell at their corresponding t_c , for systems of polyethylene chains (C₂₀₀) at T = 373.15 K (black) and T = 673.15 K (red). Each point represents the average density over 1 ps of simulation. Blue points correspond to a thin layer at 673.15 K with a larger number of chains than the layer at its t_c . Vertical dashed and dotted red lines represent $z_{90\%}$ and $z_{10\%}$, respectively, for the layer at 673.15 K and at its t_c .

3.2. Bulk Liquid Density

By using systems with 288 C_{200} chains and the same A_i , which form wider thin layers than those at their t_c (more than double the number of chains), we estimated the average bulk ρ_l and its standard deviations, which are shown in Figure 4 as a function of *T*. Experimental results for the ρ_l of linear polyethylene at 0.1 MPa are also shown in Figure 4 [42]. Ideally, we should have compared our results with measurements in a vacuum, but due to the lack of experiments in vacuum or ultravacuum conditions, we compared our results to the available experimental data at the lowest reported pressure (0.1 MPa), which we expected would be close to the measurements at vacuum conditions. The results obtained from the simulations successfully quantitatively reproduced the available experimental results and their trends at *T* in the range of 473.15–673.15 K.



Figure 4. Bulk ρ_l of thin liquid layers of melted polyethylene chains (C₂₀₀) in a liquid–vacuum equilibrium as a function of *T*. Black circles represent the results of this work using simulations. The blue circle represents a system simulated at a smaller r_c (2.5 $\sigma_{CH_3-CH_3}$). Error bars represent the standard deviation of the data. Red circles represent experimental results of Sato et al. for linear polyethylene at 0.1 MPa [Adapted from Ref. [42] with permission from Elsevier under License Number 5163721342541 (7 October 2021)].

Between 394 and 414.1 K, the experimental data had a discontinuity, which has been attributed to the transition to molten states; such a transition was not observed in the simulation result at 373.15 K, which followed the trend observed in this work at higher *T* values. The simulated results were obtained after 100 ns of equilibration of the layers, but we observed that, at a *T* in the range of 473.15–673.15 K, the layers equilibrated in shorter periods (10 ns), while the system at 373.15 K required the full 100 ns to equilibrate, which indicates that the system at this *T* was likely near or at the region of metastability. It is also well known that the thickness of polymer layers affects the T_g [15–18] and T_m [19,20], so the observed trend in this work may indicate that the T_m at nanothin thicknesses was lower than the *T* reported in the experimental work at bulk liquid conditions (403.65 K for a molecular weight of 100.5 kg/mol) [19,20]. Previously reported simulations using the TraPPE potential have quantitively agreed with the experimental T_m (using C₅₀ chains) [43] and T_g (using C₁₉₂ chains) [36] bulk values.

The system is not expected to crystallize under simulation, because bulk simulations studying the specific heat of crystalizing melts have shown that crystallization starts at T values below 350 K, with a maximum in the specific heat at 325 K when the cooling rate is of 0.05 K/ns and starts to crystalize below 325 K for a heating rate of 0.5 K/ns [36]. To our knowledge, there are no reported simulations at lower heating rates (probably due to computational restrictions), which will increase the crystallization temperatures.

We also investigated the effect of a smaller ($r_c \cdot (2.5 \sigma_{CH_2-CH_2})$), which is commonly employed in simulations as a tradeoff due to the computational restrictions of many large systems; the system becomes less cohesive due to a large number of unaccounted interactions, and the ρ_l reduces (thickness becomes larger) by up to 22% of the value predicted using the full potential.

3.3. Radius of Gyration at the Interfaces

The interfaces of the thin layers at their t_c were characterized by histograms (calculated using 200 bins) of the R_g . Guided by the results of the density profiles at these critical conditions, the layers could be regarded as the union of two interfaces, and all chains were

considered in the histograms. The histograms for the components, lateral and normal to the interfacial surface, and the total value of R_g for the critical thin layers at 373.15 and 673.15 K are plotted in Figure 5a,b, respectively. The histograms of R_g could be characterized as right-skewed distributions with long tails. The distributions of the lateral components of R_g overlapped each other at 673.15 K, while at 373.15 K, there was a small mismatch close to the top of the distribution, probably indicating that the system was not fully equilibrated even after 100 ns of simulation. A comparison of the lateral distributions of R_g at both T values revealed an overlapping of the distributions. The comparison between the distributions of R_g in the normal direction at both T values showed a more physically intuitive behavior; the mode of the two distributions were the same, but a shorter peak and a longer tail were observed at the larger T (673.15 K), which resulted in a larger average value at 673.15 K. The mode in the normal direction were lower by approximately 1.7 Å than those observed in the tangential direction. The distributions of the total R_g showed small differences; the mode and mean values grew by around 1 Å when the T changed from 373.15 to 673.15 K. Similar changes in the total R_g have been reported in atomistic simulations of bulk linear polyethylene [44]. The distributions obtained in this work can be interpreted as a deformation of the chain coils in the normal direction to the interfacial surface. Such a deformation increased as the T values were lowered. The deformation of the chains in the normal direction as a function of the film thickness has been reported previously from experiments of thin film polymers expanding freely on the surface of water [45], and also observed in the free surface of supported polymers [46]. The lateral and normal snapshots of a chain coil with R_g values corresponding to the modes of their corresponding distributions (373.15 K) showed that chains are contained in well-defined interfaces, and they cover only part of the layer in the normal direction, even though they had space within the layer to expand in that direction; therefore, the observed deformations in the normal direction are probably due to the interaction with the closest interface.



Figure 5. Histograms of the R_g of thin liquid layers of melted polyethylene chains (C₂₀₀) at their t_c in a liquid–vacuum equilibrium at (**a**) 373.15 K and (**b**) 673.15 K. Black and red points represent the components in the lateral directions to the interfacial surface, blue points represent components normal to the interfacial surface, and green points represent the total values of R_g . Vertical lines represent the mode of the distributions. Snapshots in (**a**) represent normal and lateral views of a chain with R_g values equal to the mode values of its correspondent distribution (highlighted with red spheres). The rest of the chains are represented with gray lines.

To compare the values of R_g obtained at the t_c with those at bulk liquid phases, we computed the R_g profiles for nanothin layers containing 288 C₂₀₀ chains, which repre-

sented layers with more than double the number of chains at the t_c at the same T. The profiles for the components of R_g and its total value at 673.15 K and at its t_c are shown in Figure 6a,c, respectively. The profiles were averaged over the total period of properties estimation (10 ns). Compared to the density profiles, the R_g profiles were not uniform, because the R_g calculation produced only one point per chain at its center of mass, and the density profiles produced 200 points (corresponding to the CH_2 and CH_3 sites). Only bins in the profiles with more than 1% of the average number of chains in the bulk ρ_l were plotted. The position in the normal direction to the surface interface, at which the R_g value was assigned, corresponded to the center of mass of the chain. The lateral components remained constant along the axis in the normal direction, while the average magnitude of the normal component was constantly reduced in the interfacial region. The reduction in the average normal R_g reached around 4.4 A at the outermost layer of the interface plotted. Molecular simulations at the free surface of supported polymer films have revealed a similar behavior: deformations of the chain coil in the normal direction at interfaces with very low sensitivity to T and insensitivity to the bulk ρ_l [46]. The profile for the total R_g showed the same behavior as the component in the lateral directions, with an average value in the center of the layer of 18.67 ± 0.14 Å.



Figure 6. R_g profiles as a function of the inhomogeneous position within the simulation cell at thickness layers wider than the corresponding t_c for systems of 288 polyethylene chains (C₂₀₀) at T = 673.15 K, simulated using a r_c of (**a**) $7.5 \sigma_{CH_3-CH_3}$ and (**b**) $2.5 \sigma_{CH_3-CH_3}$. Black and red points represent the lateral R_g , while blue points represent the normal R_g . (**c**) Total R_g profiles for systems simulated using $r_c = 7.5 \sigma_{CH_3-CH_3}$ (orange) and $r_c = 2.5 \sigma_{CH_3-CH_3}$ (green). Vertical dashed and dotted lines in (**a**) and (**c**) represent z_{Gds} and $z_{90\%}$, respectively.

We compared the R_g profiles to those obtained using a smaller r_c of 2.5 $\sigma_{CH_3-CH_3}$, and the components and total value of R_g are shown in Figure 6b,c, respectively. The profiles behaved very similarly to those using a longer r_c , and they were wider due to the lower cohesivity and density of the system (Figure 4). The total R_g showed a slightly higher average value in the center of the layer of 18.77 \pm 0.15 Å, and the maximum deformation of the chains in the normal direction was approximately only 2.1 Å. The insensitivity of the total R_g to the bulk ρ_l of both systems at different r_c values indicates that interactions within each chain (intrachain) were probably insensitive to r_c (the same r_c was used for inter- and intra-chain interactions). Interactions between different chains are sensitive to r_c and dictated the density of the layer. The smaller variation of the deformation in the normal direction using a smaller r_c was likely the result of unaccounted bulk and interfacial chain–chain interactions.

The effect of the layer thickness on interfacial R_g distributions was evaluated through a comparison of the distributions of R_g at two different thicknesses at the same T. In Figure 7, the distributions of R_g for the total value and its components are shown for thicknesses at its t_c (116 chains) and for a thicker layer with 288 chains, both at a T of 673.15 K. For the thicker layer, we accounted for the chains located not only at the interface defined as t_i , but also deeper in the bulk liquid, where the normal components of R_g started to deform: $(-\infty, -28 \text{ Å})$ for the left interface and $(28 \text{ Å}, \infty)$ for the right interface. The distributions of the total value and the components in the lateral directions did not change, but the distribution in the normal direction increased in magnitude close to the region of the mode and decreased the number of chains with higher values. This can be interpreted as a slight increment in the number of molecules that were highly deformed in this region, which was the result of the increment of the thickness of the layer. This effect would likely disappear at a larger thickness once the cohesivity of the liquid layer reached a saturation value.



Figure 7. Histograms of R_g of thin liquid layers of melted polyethylene chains (C_{200}) in a liquid– vacuum equilibrium at their t_c at 673.15 K. Black and red points represent the components in the lateral directions to the interfacial surface, blue points represent the normal direction, and green points represent the total values. Continuous lines represent the histograms for the interfacial chains of a wider thin layer than the layer at its t_c containing 288 chains; the color code in continuous lines is the same as the lines of points. Vertical lines represent the mode of the distributions.

3.4. Critical Thickness

A measurement of the thickness of thin layers at their limit of mechanical stability was obtained by adjusting the density profiles, averaged every 100 fs using Equation (2). From these adjustments, we obtained 100,000 values (10 ns of properties evaluation) for two parameters that characterized the components of the system (interfaces and "bulk" liquid zone): t_{Gds} and t_i . t_{Gds} is the separation in the normal direction between the z_{Gds} values of the interfaces. t_{Gds} and t_i increased as T increased and are shown in Figure 8a,b, respectively. The increase in t_{Gds} was not only due to the change of density due to increasing T, but additional chains were also needed to mechanically stabilize the thin layer. The data obtained for both properties showed normal distributions. The standard deviations for t_i are plotted in Figure 8b as the errors in the measurements (for t_{Gds} ; the deviations are smaller than the symbols); the standard deviations also increased with T. The sets of data for both properties adjusted well to empiric quadratic expressions on T. At the largest T studied, where the interfacial thickness was at a minimum, the characteristic values were 25.76 Å (t_{Gds}) and 8.23 Å (t_i). If comparisons were made with experimental measurements, it would likely be difficult to determine experimentally where the interfaces ended due to the breathing of the interfaces. Depending on the sensitivity of the experimental technique, different values could be reported. Based on this probable experimental uncertainty, we proposed a criterion for the prediction of t_c in a range of separations between the two interfaces, at surfaces at each interface located between $10\% (t_{Gds} + t_i)$ and 90% of the bulk ρ_l ($t_{Gds} - t_i$). The experimental detection of layers with less than 10% of the total ρ_l would likely be very difficult to achieve due to the dynamics of the interfaces (breathing). At 373.15 K, t_c would be in the range of 17.67–34.20 Å. Both thicknesses, $t_{Gds} - t_i$ and $t_{Gds} + t_i$, are represented in Figure 3a by the vertical limits for the thin layer at its t_c at 673.15 K. The proposed criterion was based on the importance of long-range dispersion forces (van der Waals) at the interfaces, which create disjoining pressures between the interfaces and were more influential as the thickness of the layers decreased [11,47-50]. The range of values for t_c at 373.15 K represented between 4.5 and 8.7 times the value of the Lennard–Jones parameter $\sigma_{CH_3-CH_3}$. The minimum in the Lennard–Jones potential is at $2^{1/6}\sigma \sim 1.12\sigma$, and the separation between contiguous sites is around this value. Therefore, at 373.15 K, each interface of the bulk layer could be viewed as two monolayers, with the outermost monolayer moving freely into the vacuum, up to distances corresponding to two monolayers (~ $2.24\sigma_{CH_3-CH_3}$). At 673.15 K, t_c was in the range of 6.2–14.3 times $\sigma_{CH_3-CH_3}$ and could be viewed as interfaces consisting of three monolayers, with the outermost monolayer moving into the vacuum up to distances corresponding to four monolayers.



Figure 8. (a) t_{Gds} (black circles) of thin liquid layers of melted polyethylene chains (C₂₀₀) in a liquidvacuum equilibrium as a function of *T*. Standard deviations are smaller than the symbols. The black line represents the adjustment to a quadratic function on *T*. (b) t_i (black circles) as a function of *T*. The solid line represents the adjustment to a quadratic function on *T*. The bars represent standard deviations of the measurements. Red and blue lines in (a) represent $t_{Gds} - t_i$ and $t_{Gds} + t_i$, respectively.

4. Conclusions

Molecular dynamics simulations under vacuum conditions predicted t_c values for freestanding melted and linear polyethylene C₂₀₀ chains as small as 1.77–3.42 nm at 373.15 K (depending on where the thickness was measured) and as high as 2.45–5.63 nm at *T* values near the limit of thermal stability (673.15 K). The required thickness to maintain mechanical stability increased with the square of *T*. The t_c not only increased due to the reduction in the layer density as *T* increased, but additional chains were also needed to ensure mechanical stability; approximately 44 chains per 100 nm² at 373.15 K and 55 chains at 673.15 K. At the t_c , the system was mostly formed by two united interfaces with interfacial thicknesses between 0.83 nm at 373.15 K and 1.59 nm near the limit of thermal stability.

The layer thickness did not affect interfacial behavior, because the interfaces at the t_c developed the same average density profiles and interfacial thicknesses as wider layers. There was not a proper bulk liquid at the t_c as there was in wider layers, but at the center of the layer (-1 Å, 1 Å), the density reached values equal to those found in the average bulk liquid of wider layers, which reproduced experimental values previously reported. The liquid density of the layer at 373.15 K followed the trend observed in this work at higher values of *T*, indicating that the melting point of these nanothin layers was affected by the thickness of the layer and should be below 373.15 K.

The distributions of the R_g showed the independence of the interfacial dynamics of the chains with the layer thickness, and they also demonstrated a deformation in the normal direction of the chain coils, probably due to the high attraction between the two conjoined interfaces. The mode of the right-skewed distributions of the R_g was independent of T; as T increased, the right tail of the distribution also increased, producing larger average values.

The studied systems did not show capillary waves large enough to be the factor that make the layers to break. The studied structural and interfacial properties did not show an enhancement (or reduction) as the thickness of the layer was reduced, not even when they reached its critical thickness; therefore, in future work, we will investigate the role of other properties as the interfacial forces on the mechanical stability at the critical thickness.

Author Contributions: Conceptualization, J.A.G.-M. and J.L.R.; Data curation, J.A.G.-M., E.L. and J.L.R.; Formal analysis, J.A.G.-M., E.L. and J.L.R.; Funding acquisition, R.G.-G. and J.L.R.; Investigation, J.A.G.-M., R.G.-G. and J.L.R.; Methodology, F.I.R.-Z. and J.L.R.; Project administration, J.L.R.; Software, R.G.-G. and J.L.R.; Supervision, F.I.R.-Z. and J.L.R.; Validation, J.A.G.-M. and J.L.R.; Visualization, J.A.G.-M., R.G.-G. and J.L.R.; Writing—original draft, E.L., F.I.R.-Z. and J.L.R.; Writing—review & editing, J.L.R. All authors have read and agreed to the published version of the manuscript.

Funding: This research was funded by CONACYT—México (Grant INFR-2016-01-268652) and Universidad Michoacana de San Nicolás de Hidalgo.

Institutional Review Board Statement: Not applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: The data presented in this study are available on request from the corresponding author.

Acknowledgments: We thank CONACYT (México) for an infrastructure fellowship and a graduate scholarship. We also thank Universidad Michoacana de San Nicolás de Hidalgo for research funds.

Conflicts of Interest: The authors declare no conflict of interest.

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