

Implementation of a Robotic System in Our Everyday Practice: Key Considerations Based on Preliminary Experience

Charalampos Varnava, MD*†‡; Philipp Wiebringhaus, MD, MHBA*†‡; Tobias Hirsch, MD*†‡; Maximilian Kueckelhaus, MD, MBA*†‡

Robotic microsurgery may be one of the breakthrough technologies within the field of plastic surgery.¹⁻⁴ Although robotic microsurgery offers significant potential, its adoption and utilization are still evolving. Through the implementation of the Symani system [Symani Surgical System, Medical Microinstruments (MMI), Pisa, Italy] at our institution, we gained valuable insights on overcoming the difficulties encountered, which we present in this viewpoint (Fig. 1).

To establish a training center, we encountered a challenge with certain rooms having doorways that were too small to accommodate the robot. Overcoming this obstacle necessitated the collaboration and support of the clinic administrator, who needed to be informed and have a thorough understanding of the significance of the project.

One inevitable barrier to overcome is the skepticism within the group regarding the benefits of the new product. Surgeons often develop expertise in specific techniques through years of training and practice, and introducing new techniques may require additional training or relearning, which can be time-consuming and challenging. Mastering new techniques often involves a learning curve,⁵ which can lead to potential errors or complications during the initial stages of implementation. It is understandable that the initial reaction may be reluctance, as surgeons have a responsibility to prioritize patient safety and ensure the best possible outcomes.

However, embracing new techniques and advancements in the field of plastic surgery is crucial for the evolution of the discipline in favor of patients. To strike a

balance between these opposing forces, it is important to involve the entire team in the process. Informing them about the benefits of this progress for patients, the clinic, and their collective and individual growth is essential. Avoiding restrictions on the use of the system to a single individual allows for greater flexibility and utilization by the team. Developing a comprehensive plan for training a specific number of surgeons through repetitive use of the system and subsequently expanding the training to the entire group will ensure widespread adoption and competence. Clearly communicating the plan is necessary to encourage active participation and engagement in the procedure.

A surgeon's eligibility to conduct a surgery on a patient required a minimum proficiency in performing anastomoses on synthetic vessels. Conducting multiple training sessions to familiarize the team with the system will enhance their proficiency. When selecting the initial cases for system implementation, it is advisable to choose them conservatively. Although the advantages of the system were more pronounced in anastomoses involving small-diameter vessels, we recommend to begin using the system in the operating theater with a larger 2-mm anastomosis, as opposed to starting with the smallest perforator-to-perforator anastomosis. Engaging the expertise of an experienced microsurgeon for the anastomosis, rather than relying on a resident, will contribute to successful outcomes. Initiating surgery with a team you are comfortable working with facilitates the process. During the initial phase, which could vary among different teams, having a representative from the company present at the clinic to provide technical assistance, if needed, can be beneficial. After the initial phase, ensuring access to someone who can be contacted for assistance at any time is recommended.

Charalampos Varnava

Division of Plastic Surgery
Department of Trauma, Hand and Reconstructive Surgery
University Hospital Muenster
Albert-Schweitzer-Campus 1
48149 Muenster
Germany

E-mail: charalampos.varnava@ukmuenster.de

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From the *Division of Plastic Surgery, Department of Trauma, Hand and Reconstructive Surgery, University Hospital Muenster, Muenster, Germany; †Department of Plastic, Reconstructive and Aesthetic Surgery, Hand Surgery, Fachklinik Hornheide, Muenster, Germany; and ‡Institute of Musculoskeletal Medicine, University of Muenster, Muenster, Germany.

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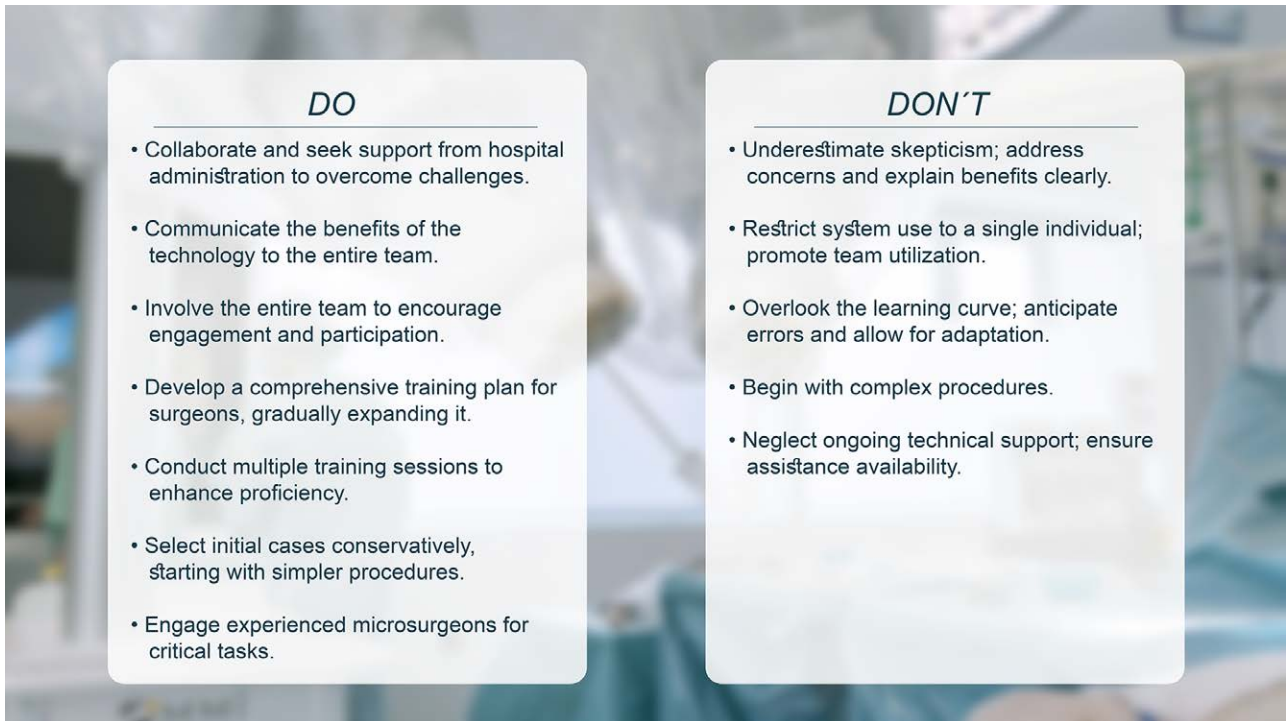


Fig. 1. Key considerations for implementing robotic microsurgery in plastic surgery.

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