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Original Article

Foot sole two-point discrimination is not associated with dynamic standing balance in healthy adults

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Abstract. [Purpose] To evaluate the association between foot sole two-point discrimination and dynamic standing balance. [Participants and Methods] This cross-sectional, observational study included 50 healthy adults. Participants were made to stand on a firm or foam surface with eyes open or closed, and the center of pressure length was measured for static standing balance and limits of stability for dynamic standing balance. Two-point discrimination and muscle strength were assessed using the two-point discrimination test and toe grip strength, respectively. We then analyzed the association with sensory-motor assessment and standing balance. [Results] Significant differences were observed for almost all factors between static and dynamic standing balance. Two-point discrimination was associated with static standing balance, and muscle strength was associated with dynamic standing balance on a firm floor. There was no significant association between two-point discrimination and dynamic standing balance. [Conclusion] These results indicate that foot sole two-point discrimination is not directly associated with dynamic standing balance in healthy adults. Therefore, postural stability must be evaluated considering the specific floor surfaces and sensory conditions in clinical situations, and assessment of dynamic standing balance based only on two-point discrimination should be avoided.

Key words: Standing balance, Two-point discrimination, Muscle strength

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INTRODUCTION

Standing balance is important for activities of daily living such as walking and reaching. Although many different theories have been suggested, standing balance is generally classified into static and dynamic standing balance¹).

Static standing balance represents the ability to stand unsupported controlling the center of mass without voluntary weight shift when the base of support (BOS) does not change by keeping both feet on the floor²). With static standing balance, the center of pressure (COP) must be kept in a comfortable position within the BOS during quiet standing. COP length represents the trajectory of COP displacement as recorded on a force platform, and is commonly used for balance quantification³). In healthy adults, the smaller the COP length, the more stable the static standing balance.

Dynamic standing balance involves a voluntary COP shift. Dynamic standing balance represents the ability to weight shift, controlling the center of mass within the BOS²). In dynamic standing balance, the limits of stability (LOS) test measures

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volitional control of the center of gravity⁴). LOS tests have been applied in clinical studies with Parkinson's disease patients, young children, and the elderly^{5–7}). The larger the LOS, the more stable the dynamic standing balance.

Regarding the association between static and dynamic balance, Hrysomallis et al. reported that performance in the static balance test was not reflective of performance in the dynamic balance test⁸). Karimi and Solomonidis⁹ and Sell¹⁰ likewise found no correlations between static and dynamic postural measures. Few reports have considered associations between static and dynamic standing balance.

Various factors are associated with standing balance, including cognitive, sensory, motor, and environmental factors. Lord et al. reported that quadriceps strength, touch, and vibration senses were predictors for static standing balance¹¹). Muscle strength and sensory functions have thus been considered important indicators for static standing balance.

Regarding muscle strength, a systematic review and meta-analysis by Muchlbauer et al. revealed weak correlations between measures of balance and muscle strength of the lower extremity in children, adolescents, and young, middle-aged, and old adults¹²).

For sensory functions, an upright bipedal stance is described as depending on sensory information from the visual, somatosensory, and vestibular systems¹³⁾. The clinical test of sensory integration and balance (CTSIB) was developed by Shumway–Cook and Horak to evaluate sensory contributions to balance¹⁴⁾. The CTSIB evaluates static postural stability under six distinct standing conditions: with eyes open, with eyes closed, and with the use of a dome to alter visual inputs on both firm and foam surfaces¹⁵⁾. The modified CTSIB (mCTSIB) was created because visual inputs from the dome were considered no different from the eyes-closed condition¹⁶⁾ The mCTSIB includes only four sway measures expressed with eyes open and eyes closed on firm and foam surfaces. The mCTSIB is the most popular method to explore the relative contributions of the somatosensory, visual, and vestibular systems to balance¹⁷⁾. Lord et al. reported correlations between sensory assessments and static standing balance using the mCTSIB, and most sensorimotor system measures were significantly associated with all sway measures¹¹⁾. In addition, estimates of the relative contributions of the visual, somatosensory, and vestibular systems to postural stability were calculated using sway measures¹¹⁾. Di Berardino et al. also reported on sensory ratios based on the mCTSIB¹⁸⁾. Lord et al. reported the somatosensory system as the most important system in the maintenance of static postural stability¹⁹⁾.

While previous studies have revealed associations between sensory systems and static standing balance, associations between sensory systems and dynamic standing balance have not been elucidated. We rely on our sensory systems in daily life not only during static situations, but also in dynamic situations. For example, we perform voluntary COP movements during stepping and reaching in daily activities, relying on sensory inputs from the visual, somatosensory, and vestibular systems. In the present study, we assumed that for the sensory system, especially the somatosensory system, it would be desirable to conduct a two-point discrimination test (TPD) so that the participant can delicately self-recognize the range of COP movement. We hypothesized that TPD would be associated with dynamic standing balance not only during static standing balance. The aim of this study was to evaluate associations between TPD and dynamic standing balance. Clarification of such associations would allow the optimization of exercises for improving dynamic standing balance during daily life.

PARTICIPANTS AND METHODS

This investigation was a cross-sectional observational study. Participants stood on a force plate under four conditions following the mCTSIB¹⁵⁾. We then measured COP length and LOS. In addition, participants performed the TPD and measurement of toe grip strength (TGS) in the sitting position to assess discrimination ability at the plantar level and muscle strength to control plantar pressure. Each participant performed all measurements in a single day. Inclusion criteria were healthy adult males and females in their 20s to 30s who were able to hold a quiet standing posture with eyes closed and feet together on a foam rubber surface for 60 seconds. Exclusion criteria included psychiatric disorders, diabetes, orthopedic or peripheral nerve disease of the lower extremities, cranial nerve disease, history of otorhinolaryngological consultation for vertigo-related symptoms, and medications that affect cognitive function (e.g., sleeping pills, antidepressants, central nervous system depressants). This study was conducted with the approval of the ethics committee of the Geriatrics Research Institute (Gunma, Japan, approval no. 98). Participants were informed of the study in writing and orally, and written consent was obtained. Fifty participants were included in this study. The variables used in this study were basic background information (age, sex, height, and weight), TPD and TGS for sensorimotor assessments, COP length for static standing balance, and LOS for dynamic standing balance. TPD was measured based on previous studies^{20, 21)}. TPD (ball of the big toe, ball of the little toe, heel) of both feet was measured using a discriminator (NC12776; North Coast Inc., Morgan Hill, CA, USA). The discriminator was applied in the direction of the long axis of the corresponding site. The tip of the discriminator was inspected at 1-mm intervals while making two points of contact, and two correct answers of three tests was considered a correct response. To increase the accuracy of the inspection, contact was sometimes made at one point instead of two points. Measurements were calculated by averaging the values of three sites: ball of the big toe, ball of the little toe, and heel. The average of both feet was then calculated. TGS was also measured based on previous studies²²), using a toe muscle strength analyzer (Toe Strength Meter II; Takei Scientific Instruments, Niigata, Japan). TGS was measured in the sitting position with both feet. The position of the feet was adjusted to a position that was easy to grip with the toes. Each foot was measured three times, and the maximum value of the three times was averaged for the left and right feet as the index.

Static and dynamic standing balance were each measured with the force plate (Gravicorder GW-10; ANIMA, Tokyo, Japan). A total of four conditions were set: open and closed eye conditions for the visual system, and with and without foam rubber (Balance-pad Elite; SAKAImed, Tokyo, Japan) for the somatosensory system. These four conditions were performed in order of increasing difficulty: open eyes and no foam rubber (firm floor \times eyes open); closed eyes and no foam rubber (firm floor \times eyes closed); open eyes with foam rubber (foam floor \times eyes open); and closed eyes with foam rubber (foam floor \times eyes closed). The foam rubber was placed on the center of the force plate and did not touch the ground. For static standing balance, the task with open eyes was performed while the participant gazed at a mark 2 m away at eye level to minimize the effect of disturbance from the external environment. The total trajectory of COP in quiet standing barefoot on the force plate was taken as COP length, reflecting body sway in detail. We collected the path length of COP displacement in the mediolateral and anteroposterior axes. To evaluate static stability in standing balance, participants stood with feet together for 30 seconds in each condition. The sensory contribution was calculated using the inter-condition ratio of each COP length. Sensory ratios were calculated using the following formulas¹⁸.

Sensory ratio:

Visual (Vis): (firm floor × eyes open) / (foam floor × eyes open),

Somatosensory (Som): (firm floor × eyes open) / (firm floor × eyes closed),

Vestibular (Vest): (firm floor \times eyes open) / (foam floor \times eyes closed),

The values obtained were converted into percentages (sensory contribution rate):

%Visual (%Vis): 100 × Vis/(Vis + Som + Vest),

%Somatosensory (%Som): $100 \times \text{Som}/(\text{Vis} + \text{Som} + \text{Vest})$,

%Vestibular (%Vest): 100 × Vest/(Vis + Som + Vest)

The method of measuring dynamic standing stability was based on the method of Maktof et al.²³). To assess dynamic stability in standing balance, participants performed maximum voluntary body leaning tasks in both anteroposterior and mediolateral directions with a 10-cm width stance. The choice of which task to perform first (anteroposterior or mediolateral) was randomized. For the anteroposterior directional task, maximum voluntary body leaning to the heel for 4 seconds, maximum voluntary body leaning to the midpoint for 4 seconds, maximum voluntary body leaning to the midpoint for 4 seconds, maximum voluntary body leaning to the midpoint for 4 seconds were performed. For the mediolateral task, the same tasks as above were performed toward the medial and lateral ball of the little toe. During voluntary body leaning, participants were conscious of the corresponding area of the foot. The midpoint was determined as the participant's subjective fixed position during static standing while monitoring the COP trajectory. These tasks were repeated three times in 60 seconds. A timekeeper counted the seconds and the participant performed the tasks accordingly.

In the voluntary body leaning task, participants were required to keep the body rigid and to rotate around the ankle joints and the foot in contact with floor. Specifically, hip flexion, upper extremity abduction, and trunk lateral flexion were limited. LOS was taken as the voluntary body leaning distance in the anteroposterior and mediolateral lengths. Mediolateral length was measured between the fifth metatarsal heads of the right and left feet, and anteroposterior length was measured between the top of the longest toe and the heel. LOS was calculated as the percentage of COP length compared to foot length.

In statistical analyses, two-way analysis of variance was performed using COP length and LOS indices for two eye conditions (open and closed eyes) × two surface conditions (with and without foam rubber). Pearson's correlation analysis was performed between sensory assessments and standing balance index. Multiple regression analysis was performed between sensorimotor assessments and standing balance. All statistical analyses were performed using SPSS version 25.0 (IBM Corp., Armonk, NY, USA), with values of p<0.05 considered significant.

RESULTS

Basic information, TPD, and TGS are presented in Table 1. Mean (\pm standard deviation) participant characteristics were: age, 28.0 \pm 4.7 years; height, 167.4 \pm 8.7 cm; and weight, 61.2 \pm 10.4 kg. The results of standing balance and sensory

Table 1. Participant characteristics and measurement results in this study (N=50)

Variable	Mean \pm standard deviation
Age (years)	28.0 ± 4.7
Sex (M/F)	29/21
Height (cm)	167.4 ± 8.7
Body weight (kg)	61.2 ± 10.4
Dominant foot (right/left)	48/2
TPD (mm)	13.9 ± 2.8
TGS (kg)	16.3 ± 6.3

N: number of participants; M: male; F: female; TPD: two-point discrimination test; TGS: toe grip strength.

contributions are presented in Table 2. Significant interactions were seen between each condition, with a significant main effect except for eye effect in the anteroposterior direction of dynamic standing balance. Since significant interactions were identified, we analyzed each factor with paired t-tests. Significant differences were seen between almost all factors except between eyes opened and eyes closed on the foam surface. Sensory contributions were dominated by the somatosensory system. Correlations between COP length and LOS are shown in Table 3. No significant correlation was found between COP length and LOS. The results of multiple regression analysis with TPD and TGS as independent variables and standing balance as the dependent variable are shown in Table 4. TPD was associated with static standing balance on the firm floor, and TGS was associated with dynamic standing balance on the firm floor. No significant correlations were identified between

Table 2.	Results of	static and	dvnamic	standing	balance	under ea	ach sensory	condition

			Surface condition	× Visual condition		
		Firm floor × Eyes open	Firm floor \times Eyes closed	Foam floor \times Eyes open	Foam floor \times Eyes closed	
COP len	ngth / Height (×100)	21.3 ± 4.3	$32.0\pm7.8^\dagger$	$44.8\pm10.2^{\ddagger}$	$94.4\pm25.6^{\dagger\ddagger}$	
LOS	AP (%)	58.4 ± 6.7	$53.4\pm7.2^{\dagger}$	$45.6\pm7.3^{\ddagger}$	$46.8\pm7.8^{\ddagger}$	
	ML (%)	62.9 ± 9.3	$56.0\pm9.9^\dagger$	$51.9\pm9.5^{\ddagger}$	$49.4\pm9.5^{\dagger\ddagger}$	
Floor×Eyes		COPI	ength*	LOS(AP)*	LOS(ML)*	
Floor ef	fect	COPI	ength*	LOS(AP)*	LOS(ML)*	
Eyes eff	fect	COPI	ength*	LOS(AP)	LOS(ML)*	
Sensory (×100, V	/ ratio /is/Som/Vest)		48.7 ± 10.3 / 68.2	± 12.3 / 23.7 ± 6.1		
2	/ contribution rate %Som/%Vest)		34.7 ± 5.1 / 48.6	± 5.0 / 16.7 ± 2.8		

Values are the mean \pm standard deviation.

*Two-way ANOVA, p<0.05.

floor \times eyes, interaction; floor effect, main effect (floor); eyes effect, main effect (eyes).

[†]: t-test, p<0.05 eyes closed vs. eyes opened; [‡]: t-test, p<0.05 foam floor vs. firm floor.

COP: center of pressure; LOS: limits of stability; AP: anteroposterior; ML: mediolateral; Vis: visual; Som: somatosensory; Vest: vestibular.

Table 3. Correlation coefficients between static and dynamic standing balance

	Surface condition × Visual condition								
	Firm floor × Eyes open Firm floor × Eyes closed Foam floor × Eyes open Foam floor × Eyes closed								
	LOS								
	AP	ML	AP	ML	AP	ML	AP	ML	
COP length / Height	0.10	0.07	0.02	0.02	-0.12	0.06	-0.03	0.05	

Values are Pearson's correlation coefficient.

COP length: center of pressure length; LOS: limits of stability; AP: anteroposterior; ML: mediolateral.

Table 4. Results of multiple regression analysis between standing balance and sensory-motor measurement

	Surface condition × Visual condition									
		Firm floor ×	Eyes open	Firm floor \times	Eyes closed	Foam floor	× Eyes open	Foam floor >	Foam floor \times Eyes closed	
		COP length / Height								
\mathbb{R}^2		0.1	4*	0.20*		0.0	0.03		0.07	
β	TPD	0.3	8*	0.4	0.42*		0.18		0.26	
	TGS	-0.0	2	0.08		0.0	0.00		-0.01	
					L	OS				
		AP	ML	AP	ML	AP	ML	AP	ML	
\mathbb{R}^2		0.11	0.13*	0.10	0.07	0.04	0.11	0.06	0.08	
β	TPD	-0.08	0.18	-0.08	0.02	0.06	0.27	0.25	0.18	
	TGS	0.35*	0.26	0.32*	0.26	0.16	0.12	-0.05	0.16	

*p<0.05.

COP length: center of pressure length; LOS: limits of stability; AP: anteroposterior; ML: mediolateral; TPD: two-point discrimination test; TGS: toe grip strength.

somatosensory ratio or somatosensory contribution rate and TGS or TPD. Correlations between sensory ratio and LOS are shown in Table 5. No significant correlation was found between sensory ratios and LOS.

DISCUSSION

The most interesting result in this study was the absence of any association between TPD and dynamic standing balance. If associations existed between TPD and LOS, we would use sensory practices to prevent falls in clinical situations. However, we cannot recommend performing sensory practices simply to improve dynamic standing balance. Since LOS was associated with various functions, we must integrate the sensory and motor systems using the central nervous system²⁴). To improve dynamic standing balance, motor-sensory skills may need to be learned using repeated activities in actual performance using the central nervous system.

Decreases in sensory information were accompanied by increases in COP length and decreases in LOS. This was attributed to the paucity of material to adequately control the COP. In other words, this was due to a lack of sensory information. The present systematic demonstration that LOS becomes smaller as sensory information decreases was a novel finding in this study. The somatosensory system showed a higher sensory ratio than the other sensory systems. Such dominance of the somatosensory system is consistent with findings from previous studies. Di Berardino et al. reported the somatosensory contribution rate as $44.9 \pm 7.1\%$ on a monolayer rubber foam pad¹⁸. The somatosensory contribution was $48.6 \pm 4.9\%$ in this study. These results underscore the importance of somatosensory perception in the standing position.

Multiple regression analysis indicated that TPD was related to static postural control ability on a firm surface. Lord et al. reported that the proprioceptive sensation is a predictor of sway on the floor¹⁹. However, LOS was less affected by the TPD in the present study, suggesting that LOS is less involved in the sensory aspect. We believe this is because LOS contains a complex sensory system that is constantly changing and difficult to quantify.

The results of the multiple regression analysis suggest that TGS is influential in dynamic standing postural control. Binda et al. reported that the ability to move the center of gravity correlated with lower limb muscle strength and fear of falling²⁵. The present results support those of Binda et al.; namely, that expansion of LOS may require an increase in TGS. We must clarify the differences in the sensory and motor aspects of static and dynamic standing balance to develop suitable standing balance exercises.

The results of correlations between static or dynamic standing balance, sensory ratio, and sensorimotor assessment suggest that no relationship exists between these indices. Many previous studies have shown no significant relationship between static balance and dynamic balance. Sell¹⁰⁾ and Gonçalves et al.²⁶⁾ reported no significant relationship between static and dynamic balance in healthy young participants. Rizzato reached the same conclusion for healthy older participants²⁷⁾. In addition, Hrysomallis reported no correlations between one-leg standing on a firm surface and stepping on a foam surface⁸⁾. The present findings support those reports.

Somatosensory information is reportedly more important in older individuals and people with cataracts, and balance disorders²⁸⁾. We believe that it is necessary to conduct exercises that focus on somatosensory information, such as performing tandem stance and standing on one leg on foam rubber²⁹⁾. In addition to strengthening the muscles of the lower extremities to reduce the risk of falls and improve physical performance, we would like to see consideration given to exercises that focus on somatosensory perception for balance disorders.

The present results showed that sensory ratios were not associated with LOS. In other words, the results suggest that sensations in static and dynamic standing should be considered separately. We believe it is important to consider whether the function to be improved is static or dynamic when considering what measures to implement.

As key limitations to this study, the sample size for analysis was small, and only healthy adults were included. The present study also only examined a portion of static and dynamic balances. For example, we did not examine cases in which the

				Vis	Som	Vest	%Vis	%Som	%Vest
LOS Surface condition	Surface	face Firm floor × Eyes open	AP	-0.07	0.19	0.17	-0.22	0.12	0.17
		ML	0.00	0.03	0.01	0.01	-0.02	0.02	
	Firm floor × Eyes closed	AP	-0.12	0.22	0.07	-0.25	0.22	0.06	
	Visual		ML	-0.14	0.13	-0.03	-0.18	0.20	-0.03
condition	Foam floor × Eyes open	AP	0.08	-0.04	0.15	0.05	-0.16	0.18	
		ML	0.03	0.13	0.08	-0.08	0.06	0.04	
	Foam floor \times Eyes closed	AP	0.05	0.04	0.16	-0.02	-0.05	0.13	
			ML	0.09	0.06	0.01	0.07	-0.05	-0.05

Table 5. Association between sensory contribution and dynamic standing balance

Values are Pearson's correlation coefficient.

LOS: limits of stability; AP: anteroposterior; ML: mediolateral; Vis: visual; Som: somatosensory; Vest: vestibular.

position or size of the BOS changed. In addition, we were unable to measure muscle activity in the trunk or proximal lower extremities, nor brain activity. Further, the present study classified balance by the presence or absence of spontaneity in the same BOS in the standing position with both feet on the floor, but other methods of classifying balance should be examined from various angles. Another limitation of this study is that we have not been able to examine touch and vibration senses other than two-point discrimination. In future studies, we must clarify the sensory side of dynamic standing balance in patients with sensory disorders and fall risks. Once the contributions of sensory systems to dynamic standing balance are better elucidated, we can consider programs to better prevent falls and enhance physical performance.

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